
Simba

Simba Documentation

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Contents

1	Videos	3
2	Features	461
3	Testing	463
4	Design goals	465
5	Indices and tables	467
	Python Module Index	469

Simba is an Embedded Programming Platform. It aims to make embedded programming easy and portable.

Simba is written in C.

Project homepage: <https://github.com/erimoq/simba>

Transmit CAN frames between a Nano32 and an Arduino Due. More videos are available on the [Videos](#) page.

Getting Started

Installation

There are three build systems available; *PlatformIO*, *Arduino IDE* and *Simba build system*. The *Simba build system* has more features than the other two. It supports executing test suites, generating code coverage, profiling and more. Still, if you are familiar with *Arduino IDE* or *PlatformIO*, use that instead since it will be less troublesome.



PlatformIO

Install *Simba* in [PlatformIO](#).

1. Install the [PlatformIO IDE](#).
2. Start the *PlatformIO IDE* and open *PlatformIO* -> *Project Examples* and select *simba/blink*.
3. Click on *Upload* (the arrow image) in the top left corner.
4. The built-in LED blinks!
5. Done!



Arduino IDE

Install *Simba* in the [Arduino IDE 1.6.10](#) as a third party board using the Boards Manager.

1. Open *File* -> *Preferences*.

2. Add these URL:s to *Additional Boards Manager URLs* (click on the icon to the right of the text field) and press *OK*.

```
https://raw.githubusercontent.com/eerimoq/simba-releases/master/arduino/avr/  
↪package_simba_avr_index.json  
https://raw.githubusercontent.com/eerimoq/simba-releases/master/arduino/sam/  
↪package_simba_sam_index.json  
https://raw.githubusercontent.com/eerimoq/simba-releases/master/arduino/esp/  
↪package_simba_esp_index.json  
https://raw.githubusercontent.com/eerimoq/simba-releases/master/arduino/esp32/  
↪package_simba_esp32_index.json
```

3. Open *Tools -> Board: ... -> Boards Manager...* and type *simba* in the search box.
4. Click on *Simba by Erik Moqvist version x.y.z* and click *Install* and press *Close*.
5. Open *Tools -> Board: ... -> Boards Manager...* and select one of the Simba boards in the list.
6. Open *File -> Examples -> Simba -> blink*.
7. Verify and upload the sketch to your device.
8. The built-in LED blinks!
9. Done!

Simba build system

The *Simba* development environment can be installed on *Linux (Ubuntu 14)*.

1. Execute the one-liner below to install *Simba*.

```
$ mkdir simba && \  
  cd simba && \  
  sudo apt install ckermit valgrind cppcheck cloc python python-pip doxygen git_  
↪lcov && \  
  sudo apt install avrdude gcc-avr binutils-avr gdb-avr avr-libc && \  
  sudo apt install bossa-cli gcc-arm-none-eabi && \  
  sudo apt install make unrar autoconf automake libtool gcc g++ gperf \  
    flex bison texinfo gawk ncurses-dev libexpat-dev \  
    python-serial sed libtool-bin pmccabe help2man \  
    python-pyelftools unzip && \  
  sudo pip install pyserial xpect readchar sphinx breathe sphinx_rtd_theme && \  
  (git clone --recursive https://github.com/pfalcon/esp-open-sdk && \  
   cd esp-open-sdk && \  
   make) && \  
  wget https://github.com/eerimoq/simba-releases/raw/master/arduino/esp32/tools/  
↪xtensa-esp32-elf-linux$(getconf LONG_BIT)-1.22.0-59.tar.gz && \  
  tar xf xtensa-esp32-elf-linux$(getconf LONG_BIT)-1.22.0-59.tar.gz && \  
  rm xtensa-esp32-elf-linux$(getconf LONG_BIT)-1.22.0-59.tar.gz && \  
  git clone --recursive https://github.com/eerimoq/simba
```

2. Setup the environment.

```
$ cd simba  
$ source setup.sh
```

2. Build and upload the blink example to your device. Replace `<my-serial-port>` with your serial port name.

```
$ cd examples/blink
$ make -s BOARD=nano32 SERIAL_PORT=<my-serial-port> upload
```

3. The built-in LED blinks!
4. Done!

Note: Some boards, such as the *SPC56D Discovery*, require a specific toolchain to build. Such cases are documented on the individual board documentation page.

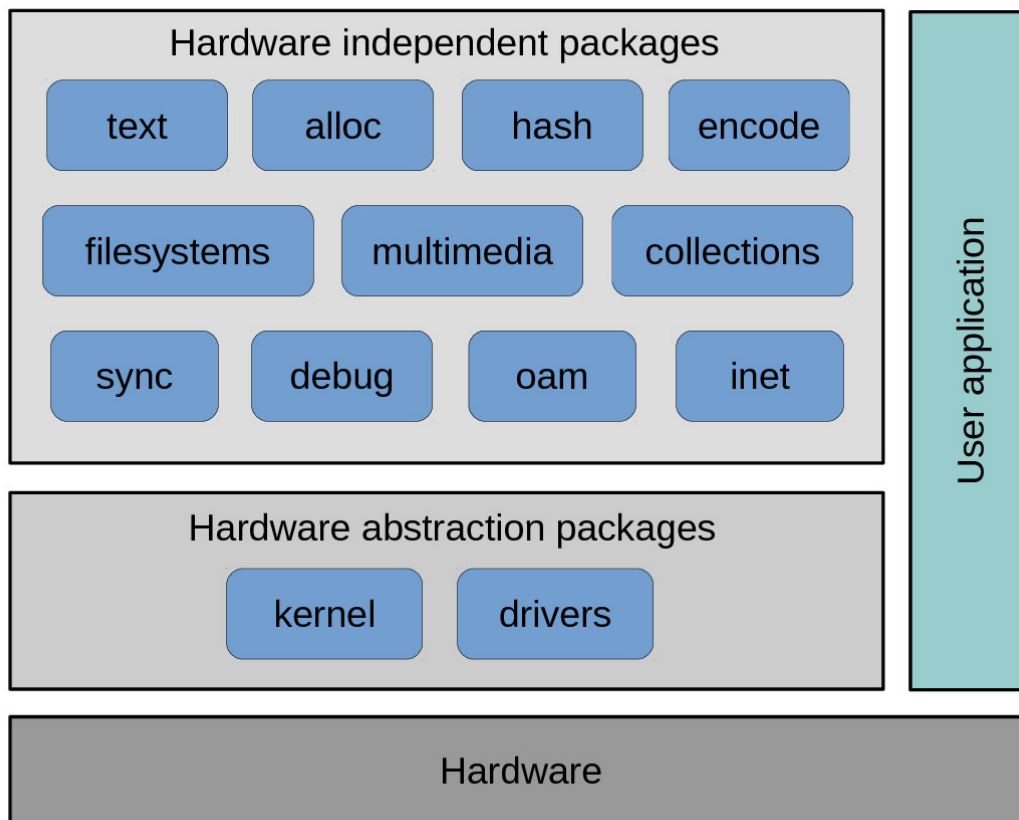
User Guide

This guide is intended for users of the Simba Embedded Programming Platform and the *Simba build system*. Parts of the guide is applicable to other build systems as well, in particular the configuration section.

The Simba installation guide can be found on the *Getting Started* page.

Software architecture

Below is a picture of all packages and their relation to the hardware. At the bottom is the hardware. On top of the hardware is the kernel and drivers packages, which exports a hardware independent interface that other packages and the user application can use. The user application on the right can use any package, and in rare cases directly access the hardware registers.



Contents:

Environment setup

The first step is always to setup the *Simba* environment. It's a simple matter of sourcing a setup-script in the *simba* root folder.

This step only applies to the *Simba build system*, and not to the *Arduino IDE* or *PlatformIO*.

```
$ cd simba/simba
$ source setup.sh
```

Hello World application

Let's start with the *Simba* "Hello World" application. It exemplifies what an application is and how to build and run it. It consists of two files; `main.c` and `Makefile`.

main.c

`main.c` defines the application entry function `main()`.

```
#include "simba.h"

int main()
```

```
{
    /* Initialize modules and start the scheduler. */
    sys_start();

    std_printf(FSTR("Hello world!\n"));

    return (0);
}
```

Makefile

Makefile contains build configuration of the application.

```
NAME = hello_world
BOARD ?= linux

RUN_END_PATTERN = "Hello world!"
RUN_END_PATTERN_SUCCESS = "Hello world!"

SIMBA_ROOT = ../..
include $(SIMBA_ROOT)/make/app.mk
```

Build and run

Compile, link and run it by typing the commands below in a shell:

```
$ cd examples/hello_world
$ make -s run
<build system output>
Hello world!
$
```

Cross-compile, link and then run on an Arduino Due:

```
$ cd examples/hello_world
$ make -s BOARD=arduino_due run
<build system output>
Hello world!
$
```

Applications, packages and modules

Simba has three software components; the application, the package and the module.

Application

An application is an executable consisting of zero or more packages.

```
myapp
- main.c
- Makefile
```

Development workflow

Build and run often! More to be added, hopefully.

Package

A package is a container of modules.

A package file tree **must** be organized as seen below. This is required by the build framework and *Simba* tools.

See the inline comments for details about the files and folders contents.

```
mypkg
- mypkg
|   - doc                      # package documentation
|   - __init__.py
|   - src                      # package source code
|       - mypkg
|       |   - module1.c
|       |   - module1.h
|       |   - mypkg.h          # package header file
|       |   - mypkg.mk         # package makefile
|   - tst                      # package test code
|       - module1
|           - main.c
|           - Makefile
- setup.py
```

Development workflow

The package development workflow is fairly straight forward. Suppose we want to add a new module to the file tree above. Create `src/mypkg/module2.h` and `src/mypkg/module2.c`, then include `mypkg/module2.h` in `src/mypkg.h` and add `mypkg/module2.c` to the list of source files in `src/mypkg.mk`. Create a test suite for the module. It consists of the two files `tst/module2/main.c` and `tst/module2/Makefile`.

It's often convenient to use an existing modules' files as skeleton for the new module.

After adding the module `module2` the file tree looks like this.

```
mypkg
- mypkg
|   - doc
|   - __init__.py
|   - src
|       - mypkg
|       |   - module1.c
|       |   - module1.h
|       |   - module2.c
|       |   - module2.h
|       |   - mypkg.h
|       |   - mypkg.mk
|   - tst
|       - module1
|           - main.c
|           - Makefile
|       - module2
```



```
|         - main.c
|         - Makefile
- setup.py
```

Now, build and run the test suite to make sure the empty module implementation compiles and can be executed.

```
$ cd tst/module2
$ make -s run
```

Often the module development is started by implementing the module header file and at the same time write test cases. Test cases are not only useful to make sure the implementation works, but also to see how the module is intended to be used. The module interface becomes cleaner and easier to use if you actually start to use it yourself by writing test cases! All users of your module will benefit from this!

So, now we have an interface and a test suite. It's time to start the implementation of the module. Usually you write some code, then run the test suite, then fix the code, then run the tests again, then you realize the interface is bad, change it, change the implementation, change the test, change, change... and so it goes on until you are satisfied with the module.

Try to update the comments and documentation during the development process so you don't have to do it all in the end. It's actually quite useful for yourself to have comments. You know, you forget how to use your module too!

The documentation generation framework uses doxygen, breathe and sphinx. That means, all comments in the source code should be written for doxygen. Breathe takes the doxygen output as input and creates input for sphinx. Sphinx then generates the html documentation.

Just run make in the doc folder to generate the html documentation.

```
$ cd doc
$ make
$ firefox _build/html/index.html    # open the docs in firefox
```

Namespaces

All exported symbols in a package must have the prefix `<package>_<module>_`. This is needed to avoid namespace clashes between modules with the same name in different packages.

There cannot be two packages with the same name, for the namespace reason. All packages must have unique names! There is one exception though, the three *Simba* packages; kernel, drivers and slib. Those packages do *not* have the package name as prefix on exported symbols.

```
int mypackage_module1_foo(void);
int mypackage_module2_bar(void);
```

Module

A module is normally a header and a source file.

Configuration

Standard Library

The *Library Reference* is configured at compile time using defines named `CONFIG_*`. The default configuration includes most functionality, as most application wants that. If an application has special requirements, for example memory constraints, it has to be configured to remove unnecessary functionality.

Search order

Highest priority first.

Simba build system

1. Command line as `CDEFS_EXTRA="<configuration variable>=<value>"`.
2. A file named `config.h` in the application root folder.
3. The default configuration file, `src/config_default.h`.

PlatformIO

1. The variable `build_flags` in `platformio.ini` as `build_flags = -D<configuration variable>=<value>`.
2. A file named `config.h` in the application source folder `src`.
3. The default configuration file, `src/config_default.h`.

Arduino IDE

1. A file (also called a *tab*) named `config.h` in the sketch.
2. The default configuration file, `src/config_default.h`.

Variables

All configuration variables are listed below. Their default values are defined in `src/config_default.h`.

Defines

`CONFIG_SYS_CONFIG_STRING` 1

`CONFIG_SYS_SIMBA_MAIN_STACK_MAX` 4096

Main thread stack size for ports with a fixed size main thread stack.

`CONFIG_SYS_RESET_CAUSE` 1

Read, and when needed clear, the reset cause at startup.

`CONFIG_SYS_PANIC_KICK_WATCHDOG` 0

Kick the watchdog in `sys_panic()` before writing to the console.

CONFIG_ASSERT 1

Assertions are used to check various conditions during the application execution. A typical usage is to validate function input arguments.

CONFIG_ASSERT_FORCE_FATAL 1

Force all assertions to be fatal.

CONFIG_FATAL_ASSERT 1

Enable fatal assertions, `FATAL_ASSERT*()`.

CONFIG_PANIC_ASSERT 1

Enable panic assertions, `PANIC_ASSERT*()`.

CONFIG_DEBUG 1

Include more debug information.

CONFIG_LINUX_SOCKET_DEVICE 0

Enable linux driver implementations as TCP sockets. Can be used to simulate driver communication in an application running on linux.

CONFIG_ADC 0

Enable the adc driver.

CONFIG_ANALOG_INPUT_PIN 0

Enable the analog_input_pin driver.

CONFIG_ANALOG_OUTPUT_PIN 0

Enable the analog_output_pin driver.

CONFIG_CAN 0

Enable the can driver.

CONFIG_CAN_FRAME_TIMESTAMP 1

Timestamp received CAN frames.

CONFIG_CHIPID 0

Enable the chipid driver.

CONFIG_RANDOM 0

Enable the random driver.

CONFIG_LED_7SEG_HT16K33 0

Enable the led_7seg_ht16k33 driver.

CONFIG_SHT3XD 0

Enable the sht3xd driver.

CONFIG_DAC 0

Enable the dac driver.

CONFIG_DS18B20 0

Enable the ds18b20 driver.

CONFIG_DS3231 0

Enable the ds3231 driver.

CONFIG_ESP_WIFI 0

Enable the esp_wifi driver.

CONFIG_EXTI 0

Enable the exti driver.

CONFIG_FLASH 0

Enable the flash driver.

CONFIG_I2C 0

Enable the i2c driver.

CONFIG_I2C_SOFT 0

Enable the i2c_soft driver.

CONFIG_MCP2515 0

Enable the mcp2515 driver.

CONFIG_NRF24L01 0

Enable the nrf24l01 driver.

CONFIG_OWI 0

Enable the owi driver.

CONFIG_PIN 0

Enable the pin driver.

CONFIG_PWM 0

Enable the pwm driver.

CONFIG_PWM_SOFT 0

Enable the pwm_soft driver.

CONFIG_SD 0

Enable the sd driver.

CONFIG_SPI 0

Enable the spi driver.

CONFIG_UART 1

Enable the uart driver.

CONFIG_UART_SOFT 0

Enable the uart_soft driver.

CONFIG_USB 0

Enable the usb driver.

CONFIG_USB_DEVICE 0

Enable the usb_device driver.

CONFIG_USB_HOST 0

Enable the usb_host driver.

CONFIG_WATCHDOG 0

Enable the watchdog driver.

CONFIG_MODULE_INIT_RWLOCK 1

Initialize the module at system startup.

CONFIG_MODULE_INIT_FS 1

Initialize the fs module at system startup.

CONFIG_MODULE_INIT_SETTINGS 1

Initialize the settings module at system startup.

CONFIG_MODULE_INIT_STD 1

Initialize the std module at system startup.

CONFIG_MODULE_INIT_SEM 1

Initialize the sem module at system startup.

CONFIG_MODULE_INIT_TIMER 1
Initialize the timer module at system startup.

CONFIG_MODULE_INIT_LOG 1
Initialize the log module at system startup.

CONFIG_MODULE_INIT_CHAN 1
Initialize the chan module at system startup.

CONFIG_MODULE_INIT_THRD 1
Initialize the thrd module at system startup.

CONFIG_MODULE_INIT_ADC 0
Initialize the adc driver module at system startup.

CONFIG_MODULE_INIT_ANALOG_INPUT_PIN 0
Initialize the analog_input_pin driver module at system startup.

CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN 0
Initialize the analog_output_pin driver module at system startup.

CONFIG_MODULE_INIT_CAN 0
Initialize the can driver module at system startup.

CONFIG_MODULE_INIT_CHIPID 0
Initialize the chipid driver module at system startup.

CONFIG_MODULE_INIT_RANDOM 0
Initialize the random driver module at system startup.

CONFIG_MODULE_INIT_DAC 0
Initialize the dac driver module at system startup.

CONFIG_MODULE_INIT_DS18B20 0
Initialize the ds18b20 driver module at system startup.

CONFIG_MODULE_INIT_DS3231 0
Initialize the ds3231 driver module at system startup.

CONFIG_MODULE_INIT_ESP_WIFI 0
Initialize the esp_wifi driver module at system startup.

CONFIG_MODULE_INIT_EXTI 0
Initialize the exti driver module at system startup.

CONFIG_MODULE_INIT_FLASH 0
Initialize the flash driver module at system startup.

CONFIG_MODULE_INIT_I2C 0
Initialize the i2c driver module at system startup.

CONFIG_MODULE_INIT_I2C_SOFT 0
Initialize the i2c_soft driver module at system startup.

CONFIG_MODULE_INIT_MCP2515 0
Initialize the mcp2515 driver module at system startup.

CONFIG_MODULE_INIT_NRF24L01 0
Initialize the nrf24l01 driver module at system startup.

CONFIG_MODULE_INIT_OWI 0
Initialize the owi driver module at system startup.

CONFIG_MODULE_INIT_PIN 0

Initialize the pin driver module at system startup.

CONFIG_MODULE_INIT_PWM 0

Initialize the pwm driver module at system startup.

CONFIG_MODULE_INIT_PWM_SOFT 0

Initialize the pwm_soft driver module at system startup.

CONFIG_MODULE_INIT_SD 0

Initialize the sd driver module at system startup.

CONFIG_MODULE_INIT_SPI 0

Initialize the spi driver module at system startup.

CONFIG_MODULE_INIT_UART 1

Initialize the uart driver module at system startup.

CONFIG_MODULE_INIT_UART_SOFT 0

Initialize the uart_soft driver module at system startup.

CONFIG_MODULE_INIT_USB 0

Initialize the usb driver module at system startup.

CONFIG_MODULE_INIT_USB_DEVICE 0

Initialize the usb_device driver module at system startup.

CONFIG_MODULE_INIT_USB_HOST 0

Initialize the usb_host driver module at system startup.

CONFIG_MODULE_INIT_WATCHDOG 0

Initialize the watchdog driver module at system startup.

CONFIG_MODULE_INIT_BUS 1

Initialize the bus module at system startup.

CONFIG_MODULE_INIT_INET 1

Initialize the inet module at system startup.

CONFIG_MODULE_INIT_PING 1

Initialize the ping module at system startup.

CONFIG_MODULE_INIT_SOCKET 1

Initialize the socket module at system startup.

CONFIG_MODULE_INIT_NETWORK_INTERFACE 1

Initialize the network_interface module at system startup.

CONFIG_MODULE_INIT_SSL 0

Initialize the ssl module at system startup.

CONFIG_MODULE_INIT_UPGRADE 0

Initialize the upgrade module at system startup.

CONFIG_FS_CMD_DS18B20_LIST 1

Debug file system command to list all DS18B20 sensors on the bus.

CONFIG_FS_CMD_ESP_WIFI_STATUS 0

Debug file system command to print the Espressif WiFi status.

CONFIG_FS_CMD_FS_APPEND 1

Debug file system command to append to a file.

CONFIG_FS_CMD_FS_COUNTERS_LIST 1
Debug file system command to list all counters.

CONFIG_FS_CMD_FS_COUNTERS_RESET 1
Debug file system command to set all counters to zero.

CONFIG_FS_CMD_FS_FILESYSTEMS_LIST 1
Debug file system command to list all registered file systems.

CONFIG_FS_CMD_FS_LIST 1
Debug file system command to list all registered file systems.

CONFIG_FS_CMD_FS_FORMAT 1
Debug file system command to format a file system.

CONFIG_FS_CMD_FS_PARAMETERS_LIST 1
Debug file system command to list all parameters.

CONFIG_FS_CMD_FS_READ 1
Debug file system command to read from a file.

CONFIG_FS_CMD_FS_REMOVE 1
Debug file system command to remove a file.

CONFIG_FS_CMD_FS_WRITE 1
Debug file system command to write to a file.

CONFIG_FS_CMD_I2C_READ 1
Debug file system command to read from a i2c bus.

CONFIG_FS_CMD_I2C_WRITE 1
Debug file system command to write to a i2c bus.

CONFIG_FS_CMD_LOG_LIST 1
Debug file system command to list all log objects.

CONFIG_FS_CMD_LOG_PRINT 1
Debug file system command to create a log entry and print it. Mainly used for debugging.

CONFIG_FS_CMD_LOG_SET_LOG_MASK 1
Debug file system command to set the log mask of a log object.

CONFIG_FS_CMD_NETWORK_INTERFACE_LIST 1
Debug file system command to list all network interfaces.

CONFIG_FS_CMD_PIN_READ 1
Debug file system command to read the current value of a pin.

CONFIG_FS_CMD_PIN_SET_MODE 1
Debug file system command to set the mode of a pin.

CONFIG_FS_CMD_PIN_WRITE 1
Debug file system command to write a value to a pin.

CONFIG_FS_CMD_PING_PING 1
Debug file system command to ping a host.

CONFIG_FS_CMD_SERVICE_LIST 1
Debug file system command to list all services.

CONFIG_FS_CMD_SERVICE_START 1
Debug file system command to start a service.

CONFIG_FS_CMD_SERVICE_STOP 1

Debug file system command to stop a services.

CONFIG_FS_CMD_SETTINGS_LIST 1

Debug file system command to list all settings.

CONFIG_FS_CMD_SETTINGS_READ 1

Debug file system command to read the value of a setting.

CONFIG_FS_CMD_SETTINGS_RESET 1

Debug file system command to reset the settings to their original values.

CONFIG_FS_CMD_SETTINGS_WRITE 1

Debug file system command to write a value to a setting.

CONFIG_FS_CMD_SYS_CONFIG 1

Debug file system command to print the system configuration.

CONFIG_FS_CMD_SYS_INFO 1

Debug file system command to print the system information.

CONFIG_FS_CMD_SYS_UPTIME 1

Debug file system command to print the system uptime.

CONFIG_FS_CMD_SYS_PANIC 1

Debug file system command to force a panic of the system.

CONFIG_FS_CMD_SYS_REBOOT 1

Debug file system command to reboot the system.

CONFIG_FS_CMD_SYS_BACKTRACE 1

Debug file system command to print a backtrace.

CONFIG_FS_CMD_SYS_RESET_CAUSE 1

Debug file system command to print the system reset cause.

CONFIG_FS_CMD_THRD_LIST 1

Debug file system command to list threads' information.

CONFIG_FS_CMD_THRD_SET_LOG_MASK 1

Debug file system command to set the log mask of a thread.

CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER 1

Debug file system command to enter the application.

CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE 1

Debug file system command to erase the application.

CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID 1

Debug file system command to check if the application is valid.

CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER 1

Debug file system command to enter the bootloader.

CONFIG_FS_CMD_USB_DEVICE_LIST 1

Debug file system command to list all USB devices.

CONFIG_FS_CMD_USB_HOST_LIST 1

Debug file system command to list all USB devices connected to the USB host.

CONFIG_FS_CMD_NVM_READ 1

Debug file system command to read for non-volatile memory.

CONFIG_FS_CMD_NVM_WRITE 1

Debug file system command to write for non-volatile memory.

CONFIG_FS_PATH_MAX 64

The maximum length of an absolute path in the file system.

CONFIG_MONITOR_THREAD 1

Start the monitor thread to gather statistics of the scheduler.

CONFIG_MONITOR_THREAD_PERIOD_US 2000000

Default period of the monitor thread in microseconds.

CONFIG_PREEMPTIVE_SCHEDULER 0

Use a preemptive scheduler.

CONFIG_PROFILE_STACK 1

Profile the stack usage in runtime. It's a cheap operation and is recommended to have enabled.

CONFIG_SETTINGS_AREA_SIZE 256

Size of the settings area. This size *MUST* have the same size as the settings generated by the settings.py script.

CONFIG_SETTINGS_BLOB 1

Enable the blob setting type.

CONFIG_SHELL_COMMAND_MAX 64

Maximum number of characters in a shell command.

CONFIG_SHELL_HISTORY_SIZE 768

Size of the shell history buffer.

CONFIG_SHELL_MINIMAL 0

Minimal shell functionality to minimize the code size of the shell module.

CONFIG_SHELL_PROMPT "\$ "

The shell prompt string.

CONFIG_SOCKET_RAW 1

Raw socket support.

CONFIG_SPIFFS 0

SPIFFS is a flash file system applicable for boards that has a reasonably big modifiable flash.

CONFIG_FAT16 1

FAT16 is a file system.

CONFIG_FILESYSTEM_GENERIC 1

Generic file system.

CONFIG_START_CONSOLE CONFIG_START_CONSOLE_UART

Start the console device (UART/USB CDC) on system startup.

CONFIG_START_CONSOLE_DEVICE_INDEX 0

Console device index.

CONFIG_START_CONSOLE_UART_BAUDRATE 38400

Console UART baudrate.

CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE 32

Console UART baudrate.

CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE 0

Console USB CDC control interface number.

CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN 2

Console USB CDC input endpoint.

CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT 3

Console USB CDC output endpoint.

CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNECTION 1

Wait for the host to connect after starting the console.

CONFIG_START_FILESYSTEM 0

Configure a default file system.

CONFIG_START_FILESYSTEM_ADDRESS 0

Configure a default file system start address.

CONFIG_START_FILESYSTEM_SIZE 65536

Configure a default file system size.

CONFIG_START_NVM 1

Configure a default non-volatile memory.

CONFIG_NVM_SIZE 2040

Non-volatile memory size in bytes.

CONFIG_NVM_EEPROM_SOFT 1

Use the software EEPROM implementation in the non-volatile memory module.

CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE 16384

Non-volatile memory software EEPROM block 0 size. Must be a multiple of
`CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE`.

CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE 16384

Non-volatile memory software EEPROM block 1 size. Must be a multiple of
`CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE`.

CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE (`CONFIG_NVM_SIZE + 8`)

Non-volatile software EEPROM chunk size. Must be a power of two.

CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX 0

Non-volatile software EEPROM flash device index.

CONFIG_START_NETWORK 0

Setup the ip stack and connect to all configured networks.

CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT 30

WiFi connect timeout is seconds.

CONFIG_START_NETWORK_INTERFACE_WIFI_SSID MyWiFiSSID

SSID of the WiFi to connect to.

CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD MyWiFiPassword

Password of the WiFi to connect to.

CONFIG_START_SHELL 1

Start a shell thread communication over the console channels.

CONFIG_START_SHELL_PRIO 30

Shell thread priority.

CONFIG_START_SHELL_STACK_SIZE 768

Shell thread stack size in words.

CONFIG_START_SOAM 0

Start a SOAM thread communication over the console channels.

CONFIG_START_SOAM_Prio 30

SOAM thread priority.

CONFIG_START_SOAM_STACK_SIZE 840

SOAM thread stack size in words.

CONFIG_STD_OUTPUT_BUFFER_MAX 16

Maximum number of bytes in the print output buffer.

CONFIG_FLOAT 1

Use floating point numbers instead of intergers where applicable.

CONFIG_SYSTEM_TICK_FREQUENCY 100

System tick frequency in Hertz.

CONFIG_SYSTEM_INTERRUPTS 1

Use interrupts.

CONFIG_SYSTEM_INTERRUPT_STACK_SIZE 0

Interrupt stack size in bytes. Set to a value greater than zero to enable the interrupt stack.

CONFIG_THRD_CPU_USAGE 1

Calculate thread CPU usage.

CONFIG_THRD_DEFAULT_LOG_MASK LOG_UPTO(INFO)

Default thread log mask.

CONFIG_THRD_ENV 1

Each thread has a list of environment variables associated with it. A typical example of an environment variable is “CWD” - Current Working Directory.

CONFIG_THRD_IDLE_STACK_SIZE 1024

Stack size of the idle thread.

CONFIG_THRD_MONITOR_STACK_SIZE 1024

Stack size of the monitor thread.

CONFIG_THRD_SCHEDULED 1

Count the number of times each thread has been scheduled.

CONFIG_THRD_STACK_HEAP 0

Enable the thread stack heap allocator.

CONFIG_THRD_STACK_HEAP_SIZE 0

Size in bytes of the thread stack heap.

CONFIG_THRD_TERMINATE 1

Threads are allowed to terminate.

CONFIG_USB_DEVICE_VID 0x2341

USB device vendor id.

CONFIG_USB_DEVICE_PID 0x8037

USB device product id.

CONFIG Emacs_COLUMNS_MAX 80

Number of colums in Emacs text editor.

CONFIG Emacs_ROWS_MAX 24

Number of rows in Emacs text editor.

CONFIG Emacs_HEAP_SIZE 32768

Heap size of the emacs text editor.

CONFIG_SYSTEM_TICK_SOFTWARE 0

System tick using a software timer instead of a hardware timer. Suitable for ESP8266 to enable software PWM.

CONFIG_HTTP_SERVER_SSL 0

Add support to wrap the HTTP server in SSL, creating a HTTPS server.

CONFIG_HARNESS_SLEEP_MS 300

Sleep in the test harness before executing the first testcase.

CONFIG_HARNESS_EXPECT_BUFFER_SIZE 512

Maximum buffer size the expect function can handle.

CONFIG_HARNESS_HEAP_MAX 2048

Size of the harness heap, required for harness_mock_write() and harness_mock_read().

CONFIG_HARNESS MOCK_VERBOSE 1

Verbose mock framework.

CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE 128

Size of the HTTP server request buffer. This buffer is used when parsing received HTTP request headers.

CONFIG_CRC_TABLE_LOOKUP 1

Use lookup tables for CRC calculations. It is faster, but uses more memory.

CONFIG_SPC5_BOOT_ENTRY_RCHW 1

CONFIG_SPC5_RAM_CLEAR_ALL 1

CONFIG_TIME_UNIX_TIME_TO_DATE 1

Include the function time_unix_time_to_date().

CONFIG_SOAM_EMBEDDED_DATABASE 0

Embed the SOAM database in the application.

CONFIG_SYS_LOG_MASK LOG_UPTO(INFO)

System module log mask.

CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ 16000000

The external oscillator frequency in Hertz.

CONFIG_FLASH_DEVICE_SEMAPHORE 1

Semaphore protected device access in the flash driver module.

CONFIG_EEPROM_SOFT_SEMAPHORE 1

Semaphore protected software eeprom accesses.

CONFIG_EEPROM_SOFT_CRC_32 0

CONFIG_EEPROM_SOFT_CRC_CCITT 1

CONFIG_EEPROM_SOFT_CRC CONFIG_EEPROM_SOFT_CRC_32

Software eeprom crc algorithm.

lwIP

Use `config.h` to fully configure lwIP and all of its modules. You do not need to define every option that lwIP provides; if you do not define an option, a default value will be used. Therefore, your `config.h` provides a way to override much of the behavior of lwIP.

By default *Simba* overrides a few of the variables in `src/inet/lwipopts.h`.

Module support (Code size)

Enabling and disabling modules

You can tune your code size by only compiling the features you really need. The following is a list of what gets compiled in “out of the box” with lwIP.

Default inclusions:

- ARP (LWIP_ARP)
- IP and fragmentation (IP_FRAG) and reassembly (IP_REASSEMBLY)
- Raw IP PCB support (LWIP_RAW)
- UDP (LWIP_UDP) and UDP-Lite (LWIP_UDPLITE)
- TCP (LWIP_TCP) – this is a big one!
- Statistics (LWIP_STATS)

Default exclusions:

- DHCP (LWIP_DHCP)
- AUTOIP (LWIP_AUTOIP)
- SNMP (LWIP_SNMP)
- IGMP (LWIP_IGMP)
- PPP (PPP_SUPPORT)

If you would like to change this, then you just need to set the options listed below. For example, if you would like to disable UDP and enable DHCP, the following `config.h` file would do it:

```
/* Disable UDP */
#define LWIP_UDP 0

/* Enable DHCP */
#define LWIP_DHCP 1
```

Memory management (RAM usage)

Memory pools

In an embedded environment, memory pools make for fast and efficient memory allocation. lwIP provides a flexible way to manage memory pool sizes and organization.

lwIP reserves a fixed-size static chunk of memory in the data segment, which is subdivided into the various pools that lwIP uses for the various data structures. For example, there is a pool just for struct `tcp_pcb`'s, and another pool just for struct `udp_pcb`'s. Each pool can be configured to hold a fixed number of data structures; this number can be changed in the `config.h` file by changing the various `MEMP_NUM_*` values. For example, `MEMP_NUM_TCP_PCB` and `MEMP_NUM_UDP_PCB` control the maximum number of `tcp_pcb` and `udp_pcb` structures that can be active in the system at any given time.

It is also possible to create custom memory pools in addition to the standard ones provided by lwIP.

Dynamic allocation: mem_malloc

lwIP uses a custom function `mem_malloc` for all dynamic allocation; therefore, it is easy to change how lwIP uses its RAM. There are three possibilities provided out-of-the-box:

1. (default) lwIP's custom heap-based `mem_malloc`. By default, lwIP uses a statically-allocated chunk of memory like a heap for all memory operations. Use `MEM_SIZE` to change the size of the lwIP heap.
2. C standard library `malloc` and `free`. If you wish to have lwIP use the standard library functions provided by your compiler/architecture, then define the option `MEM_LIBC_MALLOC`.
3. Memory pools. lwIP can also emulate dynamic allocation using custom memory pools (see that chapter for more information). This involves the options `MEM_USE_POOLS` and `MEMP_USE_CUSTOM_POOLS` and a new custom file `lwippools.h`.

Understanding/changing memory usage

lwIP uses memory for:

- code (depending on your system, may use ROM instead of RAM)
- statically allocated variables (some initialized, some not initialized)
- task stack
- dynamically allocated memory
 - heap
 - memp pools

Unless you use a C library heap implementation (by defining `MEM_LIBC_MALLOC` to 1), dynamically allocated memory must be statically allocated somewhere. This means you reserve a specific amount of memory for the heap or the memp pools from which the code dynamically allocates memory at runtime.

The size of this heap and memp pools can be adjusted to save RAM:

There are 3 types of pbufs:

- REF/ROM, RAM and POOL. `PBUF_POOL_SIZE * PBUF_POOL_BUFSIZE` only refers to type POOL.
- RAM pbufs are allocated in the memory defined by `MEM_SIZE` (this memory is not used much aside from RAM pbufs) - this is the *heap* and it is allocated as `mem_memory`.
- REF/ROM pbufs as well as pcbs and some other stuff is allocated from dedicated pools per structure type. The amount of structures is defined by the various `MEMP_NUM_` defines. Together, this memory is allocated as `memp_memory` and it *includes* the pbuf POOL.

However, if you define `MEMP_MEM_MALLOC` to 1 in your `config.h`, *every* piece of dynamically allocated memory will come from the heap (the size of which is defined by `MEM_SIZE`). If you then even define `MEM_LIBC_MALLOC` to 1, too, lwIP doesn't need extra memory for dynamically allocated memory but only uses the C library heap instead. However, you then have to make sure that this heap is big enough to run your application.

To tweak the various `MEMP_NUM_` defines, define `LWIP_STATS=1` and `LWIP_STATS_DISPLAY=1` and call `stats_display()` to see how many entries of each pool are used (or have a look at the global variable `lwip_stats` instead).

Fine-tuning even more

To see the options that you can set, open `3pp/lwip-1.4.1/src/include/lwip/opt.h`. This file is fully commented and explains how many of the options are used.

Build system

The *Simba* build system is based on *GNU Make*.

Targets

Name	Description
all	Compile and link the application.
clean	Remove all generated files and folders.
new	clean + all
upload	all + Upload the application to the device.
console	Open a serial console on /dev/arduino with baudrate BAUDRATE.
run	all + upload + Wait for application output.
run-debugger	Run the application in the debugger, break at main.
report	Print the test report from a previous run.
test	run + report
release	Compile with NASSERT=yes.
size	Print application size information.
help	Show the help.

Variables

There are plenty of make variables used to control the build process. Below is a list of the most frequently used variables. The advanced user may read the make files in `make`.

Name	Description
SIMBA_ROOT	Path to the <i>Simba</i> root folder.
BOARD	The BOARD variable selects which board to build for. It can be assigned to one of the boards listed here . For example, the command to build for <i>Arduino Due</i> is <code>make BOARD=arduino_due</code> .
BAU-DRATE	Serial port baudrate used by console and run targets.
SE-RIAL_PORT	Serial port used by console and run targets.
VERSION	The application version string. Usually on the form <major>.<minor>.<revision>.
SET-TINGS_INI	Path to the settings file.
INC	Include paths.
SRC	Source files (.c, .asm, .rs).
CFLAGS_EXTRA	Extra flags passed to the compiler.
LD-FLAGS_EXTRA	Extra flags passed to the linker.
NASSERT	Build the application without assertions.

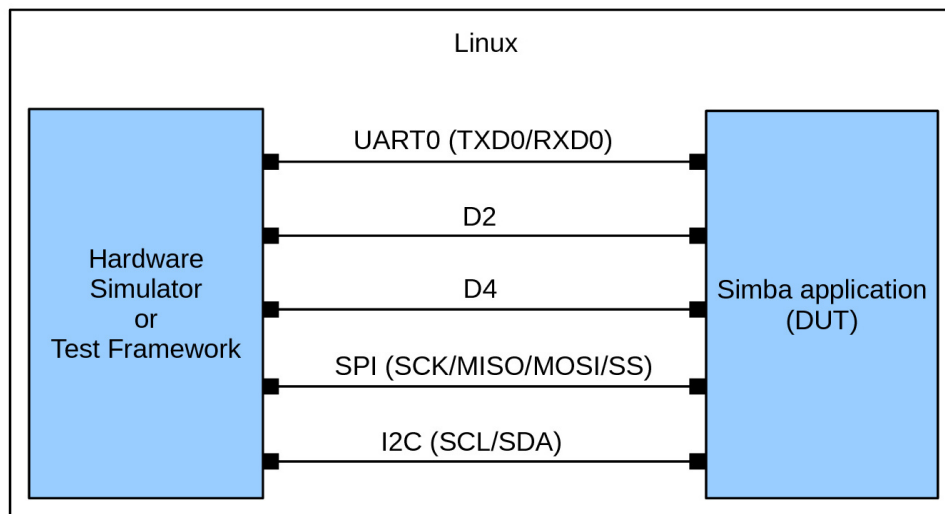
Socket devices

The Linux socket device drivers implementation allows an external program to simulate the hardware. The external program communicates with the Simba application using TCP sockets, one socket for each device.

The Python script `socket_device.py` can be used to monitor and send data to a device.

Arduino Mega example

In this example `socket_device.py` is the hardware simulator (to the left in the image below), and `socket_device` is the Simba application (to the right in the image below). The five horizontal lines each represents input and output of one



■ = TCP socket

device.

First build and

run the linux application with the Arduino Mega pinout...

```
$ make BOARD=linux PINOUT=arduino_mega run
```

...and then, in a second terminal, monitor digital pin 2, d2.

```
> socket_device.py pin d2
Connecting to localhost:47000... done.
Requesting pin device d2... done.
$
14:48:10.004512 pin(d2) RX: high
14:48:52.535323 pin(d2) RX: high
14:49:20.123124 pin(d2) RX: low
```

Alternatively, monitor all devices at the same time with the monitor make target.

```
$ make BOARD=linux PINOUT=arduino_mega monitor
socket_device.py monitor
Connecting to localhost:47000... done.
Requesting uart device 0... done.
...
Connecting to localhost:47000... done.
Requesting pin device 2... done.
Connecting to localhost:47000... done.
```



```

Requesting pin device 4... done.
...
$
14:51:50.531761 pin(2) RX: low
14:51:50.541784 uart(0) RX: b'\n'
14:51:51.178744 pin(4) RX: high

```

Python modules

There are two Python modules in the folder `bin/socket_device` in the Simba repository. Both modules implements the same interface as the default Python module/package with the same name, and can be used to communicate over a socket device instead of using the hardware.

- `serial.py` implements the `pyserial` interface.
- `can.py` implements the `python-can` interface.

Use the environment variable `PYTHONPATH` to import the socket device modules instead of the default modules/packages.

```

> export PYTHONPATH=$(readlink -f ${SIMBA_ROOT}/bin)
> export PYTHONPATH=${PYTHONPATH}:${readlink -f ${SIMBA_ROOT}/bin/socket_device}
> bpython3
>>> import serial
>>> serial
<module 'serial' from '/home/erik/workspace/simba/bin/socket_device/serial.py'>
>>> import can
>>> can
<module 'can' from '/home/erik/workspace/simba/bin/socket_device/can.py'>
>>>

```

Protocol

At startup the Simba application creates a socket and starts listening for clients on TCP port 47000.

Devices

These drivers supports the socket device protocol at the moment. More to be added when needed.

Uart

The UART socket is equivalent to a serial port, it streams data to and from the application.

Pin

Sends high or low when written to given device. Input is not supported yet.

Pwm

Sends `frequency=<value>` and `duty_cycle=<value>` when set on given device.

Can

Sends and receives frames on the format `id=<id>,extended=<extended>,size=<size>,data=<data>`. `<id>` and `<data>` are hexadecimal numbers not prefixed with 0x. `size` and `<extended>` is a decimal integers.

```
> socket_device.py can 0
Connecting to localhost:47000... done.
Requesting can device 0... done.
$ id=00000005,extended=1,size=2,data=0011<Enter>
14:57:22.344321 can(0) TX: id=00000005,extended=1,size=2,data=0011
14:57:22.346321 can(0) RX: id=00000006,extended=1,size=2,data=0112
```

I2c

Sends and receives data on the format `address=<address>,size=<size>,data=<data>`. `<address>` is an decimal integer, while `<size>` and `<data>` is a hexadecimal numbers.

```
> socket_device.py i2c 0
Connecting to localhost:47000... done.
Requesting i2c device 0... done.
$
14:57:22.346321 i2c(0) RX: address=0006,size=0003,data=1a2b3c
```

Device request message

This message is sent to the Simba application to request a device.

```
+-----+-----+-----+
| 4b type | 4b size | <size>b device |
+-----+-----+-----+

`device` is the device name as a string without NULL termination.

TYPE  SIZE  DESCRIPTION
-----
  1    n   Uart device request.
  3    n   Pin device request.
  5    n   Pwm device request.
  7    n   Can device request.
  9    n   I2c device request.
 11    n   Spi device request.
```

Device response message

This message is the response to the request message.

```
+-----+-----+-----+
| 4b type | 4b size | 4b result |
+-----+-----+-----+

`result` is zero(0) on success, and otherwise a negative error
code.
```

Defined error codes are:

ENODEV(19): No device found matching requested device name.

EADDRINUSE(98): The requested device is already requested and in use.

TYPE	SIZE	DESCRIPTION

2	4	Uart device response.
4	4	Pin device response.
6	4	Pwm device response.
8	4	Can device response.
10	4	I2c device response.
12	4	Spi device response.

Developer Guide

This guide is intended for developers of the Simba Embedded Programming Platform. Users are advised to read the *User Guide* instead.

Contents:

Boards and mcus

A board is the top level configuration entity in the build framework. It contains information about the MCU and the pin mapping.

In turn, the MCU contains information about available devices and clock frequencys in the microcontroller.

See `src/boards/` and `src/mcus` for available configurations.

Only one MCU per board is supported. If there are two MCU:s on one physical board, two board configurations have to be created, one for each MCU.

The porting guide *Porting* shows how to port *Simba* to a new board.

Threads and channels

A thread is the basic execution entity. A scheduler controls the execution of threads.

A simple thread that waits for an event from another thread.

```
#include "simba.h"

struct event_t event;

void *my_thread_main(void *arg_p)
{
    uint32_t mask;

    while (1) {
        mask = 0x1;
        event_read(&event, &mask, sizeof(mask));
    }
}
```

```
    std_printf(FSTR("Event received!\r\n"));
}

return (NULL);
}
```

Threads usually communicates over channels. There are many kinds of channels; queue, socket and event, to mention a few. All three implementing the same abstract channel interface (see [src/sync/chan.h](#)). This abstraction makes channel very powerful as a synchronization primitive. They can be seen as limited functionality file descriptors in linux.

The most common channel is the *queue* — *Queue channel*. It can be either synchronous or semi-asynchronous. In the synchronous version the writing thread will block until all written data has been read by the reader. In the semi-asynchronous version the writer writes to a buffer within the queue, and only blocks all data does not fit in the buffer. The buffer size is selected by the application.

File tree

This is the file tree of the Simba repository.

```
simba                - this directory
- 3pp                - third party products
- bin                - executables and scripts
- doc                - documentation source
- environment        - environment setup
- examples            - example applications
- LICENSE            - license
- make                - build and run files
- README.rst         - readme
- setup.sh           - setup script
- src                - source code directory
|   - alloc           - alloc package
|   - boards          - board configurations
|   - collections     - collections package
|   - debug           - debug package
|   - drivers         - drivers package
|   - encode          - encode package
|   - filesystems     - filesystems package
|   - hash            - hash package
|   - inet            - inet package
|   - kernel          - kernel package
|   - mcus            - mcu configurations
|   - multimedia     - multimedia package
|   - oam             - oam package
|   - sync            - sync package
|   - text            - text package
|   - simba.h         - includes all package headers
|   - simba.mk        - build system configuration
- tst                - test suites
|   - alloc           - alloc package test suite
|   - collections     - collections package test suite
|   - debug           - debug package test suite
|   - drivers         - drivers package test suite
|   - encode          - encode package test suite
|   - filesystems     - filesystems package test suite
|   - hash            - hash package test suite
|   - inet            - inet package test suite
```

- kernel	- kernel package test suite
- multimedia	- multimedia package test suite
- oam	- oam package test suite
- sync	- sync package test suite
- text	- text package test suite
- VERSION.txt	- `Simba` version

Testing

To ensure high code quality each release is tested extensively by many test suites. The test suites are executed both on native Linux and on many of the supported boards. See *Test suites* for a list of all test suites that are executed before each release.

The native Linux test suites are executed automatically on each commit.

Test result: <https://travis-ci.org/eerimoq/simba>

Code coverage: <https://codecov.io/gh/eerimoq/simba>

Unit tests

Each module shall have unit tests to verify that the implementation works as expected and that future refactoring does not break legacy.

All unit tests except low level drivers and networking are hardware independent. This makes it possible to use common Linux tools (gcov, valgrind, gdb, etc.) to debug and gather statistics of a module, which is very useful.

For low level drivers where the majority of the code is hardware specific (*ports* folder), testing on real hardware is important. It's preferable to have a hardware independent test suite with stubbed interfaces for drivers without any port specific code, and having an example application in *examples* to test on real hardware.

All unit tests are found in the *tst* folder.

Hardware setup

Below is a picture of all supported boards connected to a USB hub. The USB hub is connected to a linux PC (not in the picture) that executes test suites on all boards.

A short description of the setup:

- The DS3231 device (on the breadboard to the left) is connected over i2c to the *Arduino Mega*.
- CAN0 is connected to CAN1 on the *Arduino Due*. The CAN driver is tested by sending frames between the two CAN devices.
- The UART of the *STM32VLDISCOVERY* board is connected to a serial to USB adaptor. DTR on the adaptor is used to reset the board.
- The *ESP-12E Development Board* also has a serial to USB adaptor connected. RTS is used to set the board in flashing mode (GPIO0) and DTR is used to reset the board (REST).

Test suites

Below is a list of all test suites that are executed before every release. They are listed per board.

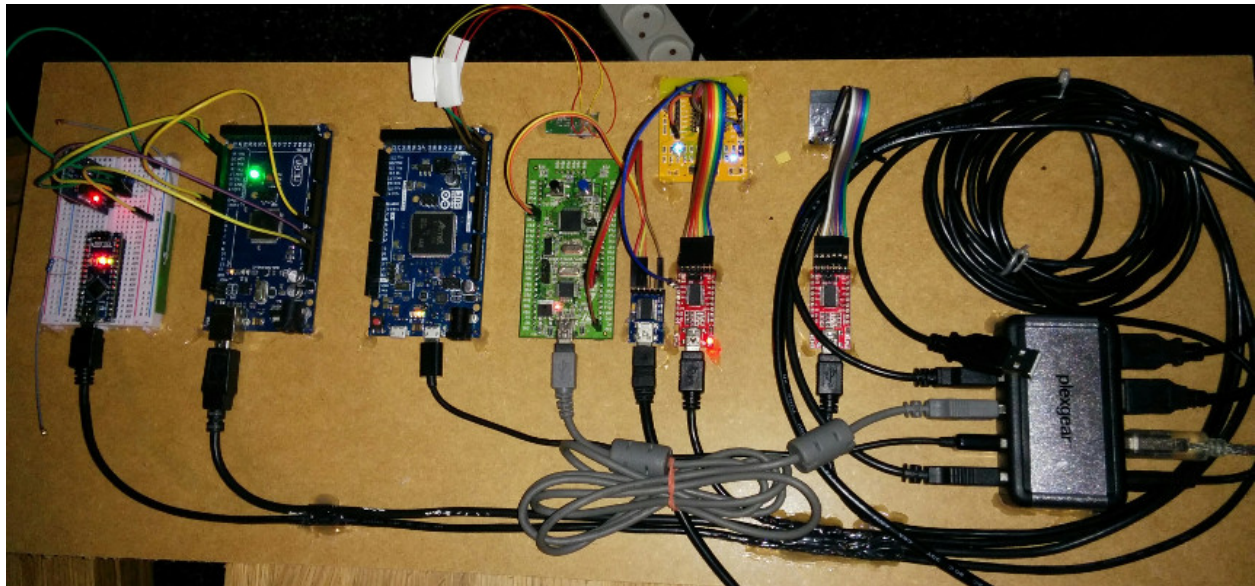


Fig. 1.1: The boards are (from left to right): *Arduino Nano*, *Arduino Mega*, *Arduino Due*, *STM32VLDISCOVERY*, *ESP-12E Development Board* and *ESP-01*

Arduino Due

- kernel/sys
- kernel/thrd
- kernel/time
- kernel/timer
- sync/bus
- sync/event
- sync/queue
- sync/rwlock
- sync/sem
- collections/binary_tree
- collections/bits
- collections/fifo
- collections/hash_map
- alloc/circular_heap
- alloc/heap
- text/configfile
- text/std
- text/re
- debug/log

- oam/settings
- oam/shell
- filesystems/fs
- filesystems/spiffs
- encode/base64
- encode/json
- hash/crc
- hash/sha1
- drivers/chipid
- drivers/can
- drivers/flash

Arduino Mega

- kernel/sys
- kernel/thrd
- kernel/time
- kernel/timer
- sync/bus
- sync/event
- sync/queue
- sync/rwlock
- sync/sem
- collections/binary_tree
- collections/bits
- collections/fifo
- collections/hash_map
- alloc/circular_heap
- alloc/heap
- text/configfile
- text/std
- text/re
- debug/log
- oam/settings
- oam/shell
- filesystems/fat16
- filesystems/fs

- encode/base64
- hash/crc
- hash/sha1
- inet/http_websocket_client
- inet/http_websocket_server
- inet/inet
- inet/mqtt_client
- inet/ping
- drivers/adc
- drivers/analog_input_pin
- drivers/ds3231
- drivers/sd
- drivers/pin

Arduino Nano

- drivers/ds18b20
- drivers/analog_output_pin
- drivers/exti
- drivers/owi

Arduino Pro Micro

- kernel/sys
- kernel/thrd
- kernel/timer

Arduino Uno

ESP-01

ESP-12E Development Board

- kernel/sys
- kernel/thrd
- kernel/timer

ESP32-DevKitC

Adafruit HUZZAH ESP8266 breakout

Linux

- kernel/sys
- kernel/thrd
- kernel/time
- kernel/timer
- sync/bus
- sync/chan
- sync/event
- sync/queue
- sync/rwlock
- sync/sem
- collections/binary_tree
- collections/bits
- collections/circular_buffer
- collections/fifo
- collections/hash_map
- alloc/circular_heap
- alloc/heap
- text/configfile
- text/emacs
- text/std
- text/re
- debug/log
- debug/harness
- oam/nvm
- oam/service
- oam/settings
- oam/shell
- oam/soam
- oam/upgrade
- oam/upgrade/http
- oam/upgrade/kermit
- oam/upgrade/uds

- filesystems/fat16
- filesystems/fs
- filesystems/spiffs
- encode/base64
- encode/json
- hash/crc
- hash/sha1
- inet/http_server
- inet/http_websocket_client
- inet/http_websocket_server
- inet/inet
- inet/isotp
- inet/mqtt_client
- inet/ping
- inet/slip
- inet/ssl
- inet/tftp_server
- multimedia/midi

Maple-ESP32

Nano32

- kernel/sys
- kernel/thrd
- kernel/timer
- sync/bus
- sync/event
- sync/queue
- sync/rwlock
- sync/sem
- collections/binary_tree
- collections/bits
- collections/fifo
- collections/hash_map
- alloc/circular_heap
- text/std
- text/re

- debug/log
- oam/shell
- encode/base64
- encode/json
- hash/crc
- hash/sha1
- inet/http_websocket_client
- inet/http_websocket_server
- inet/inet
- inet/mqtt_client_network
- inet/network_interface/wifi_esp
- inet/ping
- filesystems/fs
- filesystems/spiffs

NodeMCU

- kernel/sys
- kernel/thrd
- kernel/timer
- sync/bus
- sync/event
- sync/queue
- sync/rwlock
- sync/sem
- collections/binary_tree
- collections/bits
- collections/fifo
- collections/hash_map
- alloc/circular_heap
- text/std
- text/re
- debug/log
- oam/shell
- encode/base64
- encode/json
- hash/crc

- hash/sha1
- inet/http_websocket_client
- inet/http_websocket_server
- inet/inet
- inet/mqtt_client
- inet/network_interface/wifi_esp
- inet/ping
- drivers/pin
- drivers/random
- filesystems/fs
- filesystems/spiffs

Particle IO Photon

- kernel/sys
- kernel/thrd
- kernel/time
- kernel/timer
- sync/bus
- sync/event
- sync/queue
- sync/rwlock
- sync/sem
- collections/binary_tree
- collections/bits
- collections/fifo
- collections/hash_map
- alloc/circular_heap
- text/std
- text/re
- debug/log
- oam/shell
- encode/base64
- encode/json
- hash/crc
- hash/sha1
- inet/http_websocket_client

- `inet/http_websocket_server`
- `inet/inet`
- `inet/mqtt_client`
- `inet/ping`

SPC56D Discovery

- `kernel/sys`
- `kernel/thrd`
- `kernel/time`
- `kernel/timer`
- `sync/bus`
- `sync/event`
- `sync/queue`
- `sync/rwlock`
- `sync/sem`
- `collections/binary_tree`
- `collections/bits`
- `collections/fifo`
- `collections/hash_map`
- `alloc/circular_heap`
- `text/std`
- `text/re`
- `debug/log`
- `oam/shell`
- `oam/soam`
- `encode/base64`
- `encode/json`
- `hash/crc`
- `hash/sha1`
- `drivers/eeprom_soft`

STM32F3DISCOVERY

STM32VLDISCOVERY

- `kernel/sys`
- `kernel/thrd`

- kernel/timer
- sync/bus
- sync/event
- sync/queue
- sync/rwlock
- sync/sem
- collections/binary_tree
- collections/bits
- collections/fifo
- collections/hash_map
- alloc/circular_heap
- text/std
- text/re
- debug/log
- oam/shell
- encode/base64
- encode/json
- hash/crc
- hash/sha1
- inet/http_websocket_client
- inet/http_websocket_server
- inet/inet
- inet/mqtt_client
- inet/ping
- drivers/pin
- drivers/random

WEMOS D1 mini

Releasing

Follow these steps to create a new release:

1. Write the new version in `VERSION.txt`. The version should have the format `<major>.<minor>.<revision>`.

Increment `<major>` for non-backwards compatible changes.

Increment `<minor>` for new features.

Increment `<revision>` for bug fixes.
2. Write the new version in `package.json`. This file is used by *PlatformIO 3* to find the current *Simba* release.

3. Run the test suites and generate the documentation and other files.

```
make -s -j8 test-all-boards
make -s -j8 release-test
```

4. Commit the generated files and tag the commit with <major>.<minor>.<revision>.
5. Generate files for Arduino and PlatformIO releases. The generated archives and Arduino manifests are copied to the release repository.

```
make -s release
```

6. Add, commit and push the Simba Arduino releases in the release repository.

```
(cd ../simba-releases && \
git add arduino/*/*.zip platformio/*.zip && \
git commit && \
git push origin master)
```

7. Start a http server used to download package manifests in the Arduino IDE.

```
(cd make/arduino && python -m SimpleHTTPServer)
```

8. Start the Arduino IDE and add these URL:s in Preferences.

```
http://localhost:8000/avr/package_simba_avr_index.json
http://localhost:8000/esp/package_simba_esp_index.json
http://localhost:8000/esp32/package_simba_esp32_index.json
http://localhost:8000/sam/package_simba_sam_index.json
```

9. Install all four packages and run the blink example for each one of them.
10. Commit and push.
11. Add, commit and push the Simba Arduino package manifests in the release repository.

```
(cd ../simba-releases && \
git add arduino/*/*.json && \
git commit && \
git push origin master)
```

12. Done.

Porting

Adding a new board

Often the board you want to use in your project is not yet supported by *Simba*. If you are lucky, *Simba* is already ported to the MCU on your board. Just create a folder with you board name in [src/boards/](#) and populate it with the `board.h`, `board.c` and `board.mk`. Also, create board documentation in [doc/boards/](#), and add a pinout image in [doc/images/boards/](#).

The same files as a file tree:

```
simba/
+-- doc/
|   +-- boards/
|       |   +-- <board-name>.rst
```

```
|   +-- images/
|       +-- boards/
|           +-- <board-name>-pinout.jpg
+-- src/
    +-- boards/
        +-- <board-name>.h
        +-- <board-name>.c
        +-- <board-name>.mk
```

If *Simba* is not ported to your MCU, the kernel and drivers has to be ported.

Kernel

Porting the kernel is a matter of configuring the system tick timer and implement a few locking primitives. If you are familiar with your CPU, the port can be implemented quickly.

A kernel port is roughly 400 lines of code.

Kernel ports are implemented in [src/kernel/ports](#).

Drivers

The required work to port the drivers depends of which drivers you are intrested in. The more drivers you have to port, the longer time it takes, obviously.

A drivers port is roughly 200 lines of code per driver.

Drivers ports are implemented in [src/drivers/ports](#).

Boards

The boards supported by *Simba*.

Arduino Due

- *sd* — *Secure Digital memory*
- *spi* — *Serial Peripheral Interface*
- *uart* — *Universal Asynchronous Receiver/Transmitter*
- *usb* — *Universal Serial Bus*
- *usb_host* — *Universal Serial Bus - Host*

Library Reference

Read more about board specific functionality in the *Arduino Due* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The [minimal-configuration](#) application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The [default-configuration](#) application is built with the default configuration, including a lot more functionality. See the list of [Default system features](#) above for a summary.

Application	Flash	RAM
minimal-configuration	6144	1672
default-configuration	128000	10194

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	1
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	1
CONFIG_CHIPID	1
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	1
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	0
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	0
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
Continued on next page	

Table 1.1 – continued from previous page

Name	Value
CONFIG_FLASH	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1

Continued on next page

Table 1.1 – continued from previous page

Name	Value
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	1
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	1
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	1
CONFIG_MODULE_INIT_DAC	1
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	0
CONFIG_MODULE_INIT_ESP_WIFI	0
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	0
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	1
CONFIG_MODULE_INIT_NETWORK_INTERFACE	0
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	0
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	0
CONFIG_MODULE_INIT_RANDOM	0
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	1
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	0
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	0
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	1
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	1
CONFIG_MODULE_INIT_WATCHDOG	0
CONFIG_MONITOR_THREAD	1

Continued on next page

Table 1.1 – continued from previous page

Name	Value
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	0
CONFIG_RANDOM	0
CONFIG_SD	1
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	1
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	115200
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNENTION	1
CONFIG_START_FILESYSTEM	1
CONFIG_START_FILESYSTEM_ADDRESS	0x000e0000
CONFIG_START_FILESYSTEM_SIZE	32768
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	1536
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	1536
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0

Continued on next page

Table 1.1 – continued from previous page

Name	Value
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	384
CONFIG_THRD_MONITOR_STACK_SIZE	512
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	0
CONFIG_USB	1
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	1
CONFIG_WATCHDOG	0

Homepage

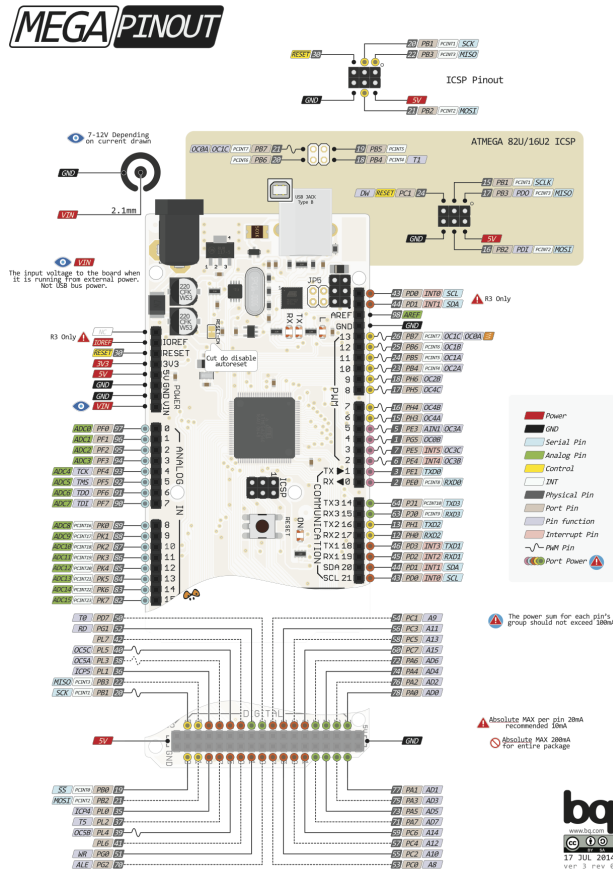
<https://www.arduino.cc/en/Main/ArduinoBoardDue>

Mcu

sam3x8e

Arduino Mega

Pinout



Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- *Debug shell.*

Drivers

Supported drivers for this board.

- *adc* — Analog to digital conversion
- *analog_input_pin* — Analog input pin
- *analog_output_pin* — Analog output pin
- *ds18b20* — One-wire temperature sensor
- *ds3231* — RTC clock
- *exti* — External interrupts
- *i2c* — I2C

- *i2c_soft* — *Software I2C*
- *mcp2515* — *CAN BUS chipset*
- *nrf24l01* — *Wireless communication*
- *owi* — *One-Wire Interface*
- *pin* — *Digital pins*
- *pwm* — *Pulse width modulation*
- *pwm_soft* — *Software pulse width modulation*
- *sd* — *Secure Digital memory*
- *spi* — *Serial Peripheral Interface*
- *uart* — *Universal Asynchronous Receiver/Transmitter*
- *uart_soft* — *Software Universal Asynchronous Receiver/Transmitter*
- *watchdog* — *Hardware watchdog*

Library Reference

Read more about board specific functionality in the *Arduino Mega* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The *minimal-configuration* application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The *default-configuration* application is built with the default configuration, including a lot more functionality. See the list of *Default system features* above for a summary.

Application	Flash	RAM
minimal-configuration	1734	279
default-configuration	64414	4005

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	1
CONFIG_ASSERT	1
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0

Continued on next page

Table 1.2 – continued from previous page

Name	Value
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	0
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	0
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1

Continued on next page

Table 1.2 – continued from previous page

Name	Value
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	1
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	1
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	0
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	0
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	0
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	1
CONFIG_MODULE_INIT_NETWORK_INTERFACE	0
CONFIG_MODULE_INIT_NRF24L01	1

Continued on next page

Table 1.2 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	0
CONFIG_MODULE_INIT_PWM	1
CONFIG_MODULE_INIT_PWM_SOFT	1
CONFIG_MODULE_INIT_RANDOM	0
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	1
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	0
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	1
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	1
CONFIG_MONITOR_THREAD	1
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	1
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	256
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	1
CONFIG_PWM_SOFT	1
CONFIG_RANDOM	0
CONFIG_SD	1
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0

Continued on next page

Table 1.2 – continued from previous page

Name	Value
CONFIG_SOCKET_RAW	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	0
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	38400
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNECTION	1
CONFIG_START_FILESYSTEM	0
CONFIG_START_FILESYSTEM_ADDRESS	0
CONFIG_START_FILESYSTEM_SIZE	65536
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	768
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	840
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	156
CONFIG_THRD_MONITOR_STACK_SIZE	256
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	1

Continued on next page

Table 1.2 – continued from previous page

Name	Value
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	1

Homepage

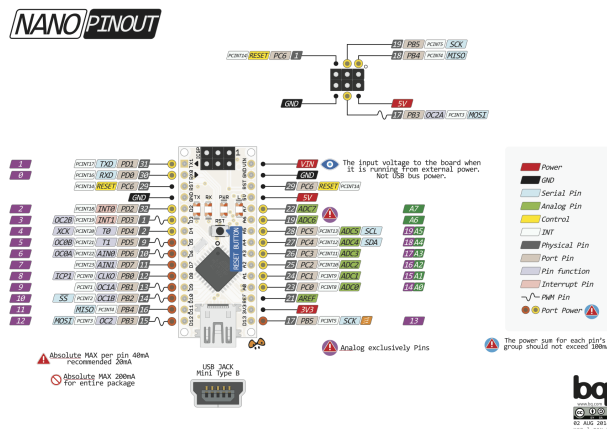
<https://www.arduino.cc/en/Main/ArduinoBoardMega>

Mcu

atmega2560

Arduino Nano

Pinout



Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*

Drivers

Supported drivers for this board.

- *adc — Analog to digital conversion*
- *analog_input_pin — Analog input pin*

- *analog_output_pin* — Analog output pin
- *ds18b20* — One-wire temperature sensor
- *ds3231* — RTC clock
- *exti* — External interrupts
- *i2c* — I2C
- *i2c_soft* — Software I2C
- *mcp2515* — CAN BUS chipset
- *nrf24l01* — Wireless communication
- *owi* — One-Wire Interface
- *pin* — Digital pins
- *pwm* — Pulse width modulation
- *pwm_soft* — Software pulse width modulation
- *sd* — Secure Digital memory
- *spi* — Serial Peripheral Interface
- *uart* — Universal Asynchronous Receiver/Transmitter
- *uart_soft* — Software Universal Asynchronous Receiver/Transmitter
- *watchdog* — Hardware watchdog

Library Reference

Read more about board specific functionality in the *Arduino Nano* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The [minimal-configuration](#) application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The [default-configuration](#) application is built with the default configuration, including a lot more functionality. See the list of *Default system features* above for a summary.

Application	Flash	RAM
minimal-configuration	1548	279
default-configuration	13320	1038

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	1
Continued on next page	

Table 1.3 – continued from previous page

Name	Value
CONFIG_ASSERT	0
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	0
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	0
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	0
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	0
CONFIG_FS_CMD_FS_COUNTERS_LIST	0
CONFIG_FS_CMD_FS_COUNTERS_RESET	0
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	0
CONFIG_FS_CMD_FS_FORMAT	0
CONFIG_FS_CMD_FS_LIST	0
CONFIG_FS_CMD_FS_PARAMETERS_LIST	0
CONFIG_FS_CMD_FS_READ	0
CONFIG_FS_CMD_FS_REMOVE	0
CONFIG_FS_CMD_FS_WRITE	0
CONFIG_FS_CMD_I2C_READ	0
CONFIG_FS_CMD_I2C_WRITE	0
CONFIG_FS_CMD_LOG_LIST	0
CONFIG_FS_CMD_LOG_PRINT	0
CONFIG_FS_CMD_LOG_SET_LOG_MASK	0
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	0
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	0
CONFIG_FS_CMD_PIN_SET_MODE	0

Continued on next page

Table 1.3 – continued from previous page

Name	Value
CONFIG_FS_CMD_PIN_WRITE	0
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	0
CONFIG_FS_CMD_SETTINGS_READ	0
CONFIG_FS_CMD_SETTINGS_RESET	0
CONFIG_FS_CMD_SETTINGS_WRITE	0
CONFIG_FS_CMD_SYS_BACKTRACE	0
CONFIG_FS_CMD_SYS_CONFIG	0
CONFIG_FS_CMD_SYS_INFO	0
CONFIG_FS_CMD_SYS_PANIC	0
CONFIG_FS_CMD_SYS_REBOOT	0
CONFIG_FS_CMD_SYS_RESET_CAUSE	0
CONFIG_FS_CMD_SYS_UPTIME	0
CONFIG_FS_CMD_THRD_LIST	0
CONFIG_FS_CMD_THRD_SET_LOG_MASK	0
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	0
CONFIG_FS_CMD_USB_HOST_LIST	0
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	16
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	1
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	1
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	0
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	0
CONFIG_MODULE_INIT_FS	1

Continued on next page

Table 1.3 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	0
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	1
CONFIG_MODULE_INIT_NETWORK_INTERFACE	0
CONFIG_MODULE_INIT_NRF24L01	1
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	0
CONFIG_MODULE_INIT_PWM	1
CONFIG_MODULE_INIT_PWM_SOFT	1
CONFIG_MODULE_INIT_RANDOM	0
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	1
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	0
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	1
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	1
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	1
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	256
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	1
CONFIG_PWM_SOFT	1
CONFIG_RANDOM	0
CONFIG_SD	1
CONFIG_SETTINGS_AREA_SIZE	256

Continued on next page

Table 1.3 – continued from previous page

Name	Value
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	1
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	0
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	38400
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	0
CONFIG_START_FILESYSTEM_ADDRESS	0
CONFIG_START_FILESYSTEM_SIZE	65536
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	0
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	768
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	840
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	0
CONFIG_SYS_LOG_MASK	-1
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	0
CONFIG_THRD_IDLE_STACK_SIZE	156
CONFIG_THRD_MONITOR_STACK_SIZE	256

Continued on next page

Table 1.3 – continued from previous page

Name	Value
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	1
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	1

Homepage

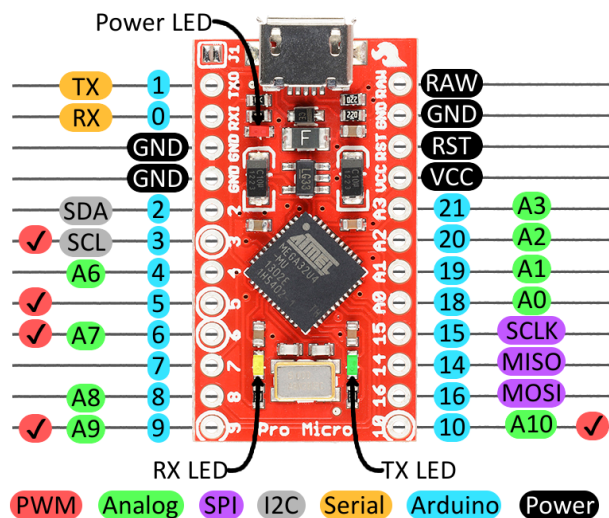
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Mcu

atmega328p

Arduino Pro Micro

Pinout



Enter the bootloader

Recover a bricked board by entering the bootloader.

1. Power up the board.

2. Connect RST to GND for a second to enter the bootloader and stay in it for 8 seconds.

Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*

Drivers

Supported drivers for this board.

- *adc — Analog to digital conversion*
- *analog_input_pin — Analog input pin*
- *analog_output_pin — Analog output pin*
- *ds18b20 — One-wire temperature sensor*
- *ds3231 — RTC clock*
- *exti — External interrupts*
- *i2c — I2C*
- *i2c_soft — Software I2C*
- *mcp2515 — CAN BUS chipset*
- *nrf24l01 — Wireless communication*
- *owi — One-Wire Interface*
- *pin — Digital pins*
- *pwm — Pulse width modulation*
- *pwm_soft — Software pulse width modulation*
- *sd — Secure Digital memory*
- *spi — Serial Peripheral Interface*
- *uart — Universal Asynchronous Receiver/Transmitter*
- *uart_soft — Software Universal Asynchronous Receiver/Transmitter*
- *usb — Universal Serial Bus*
- *usb_device — Universal Serial Bus - Device*
- *watchdog — Hardware watchdog*

Library Reference

Read more about board specific functionality in the *Arduino Pro Micro* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The [minimal-configuration](#) application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The [default-configuration](#) application is built with the default configuration, including a lot more functionality. See the list of [Default system features](#) above for a summary.

Application	Flash	RAM
minimal-configuration	6578	520
default-configuration	15084	1165

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	1
CONFIG_ASSERT	0
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	0
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	0
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	0
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	0
CONFIG_FS_CMD_FS_COUNTERS_LIST	0
Continued on next page	

Table 1.4 – continued from previous page

Name	Value
CONFIG_FS_CMD_FS_COUNTERS_RESET	0
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	0
CONFIG_FS_CMD_FS_FORMAT	0
CONFIG_FS_CMD_FS_LIST	0
CONFIG_FS_CMD_FS_PARAMETERS_LIST	0
CONFIG_FS_CMD_FS_READ	0
CONFIG_FS_CMD_FS_REMOVE	0
CONFIG_FS_CMD_FS_WRITE	0
CONFIG_FS_CMD_I2C_READ	0
CONFIG_FS_CMD_I2C_WRITE	0
CONFIG_FS_CMD_LOG_LIST	0
CONFIG_FS_CMD_LOG_PRINT	0
CONFIG_FS_CMD_LOG_SET_LOG_MASK	0
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	0
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	0
CONFIG_FS_CMD_PIN_SET_MODE	0
CONFIG_FS_CMD_PIN_WRITE	0
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	0
CONFIG_FS_CMD_SETTINGS_READ	0
CONFIG_FS_CMD_SETTINGS_RESET	0
CONFIG_FS_CMD_SETTINGS_WRITE	0
CONFIG_FS_CMD_SYS_BACKTRACE	0
CONFIG_FS_CMD_SYS_CONFIG	0
CONFIG_FS_CMD_SYS_INFO	0
CONFIG_FS_CMD_SYS_PANIC	0
CONFIG_FS_CMD_SYS_REBOOT	0
CONFIG_FS_CMD_SYS_RESET_CAUSE	0
CONFIG_FS_CMD_SYS_UPTIME	0
CONFIG_FS_CMD_THRD_LIST	0
CONFIG_FS_CMD_THRD_SET_LOG_MASK	0
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	0
CONFIG_FS_CMD_USB_HOST_LIST	0
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	16
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0

Continued on next page

Table 1.4 – continued from previous page

Name	Value
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	1
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	1
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	0
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	0
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	0
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	1
CONFIG_MODULE_INIT_NETWORK_INTERFACE	0
CONFIG_MODULE_INIT_NRF24L01	1
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	0
CONFIG_MODULE_INIT_PWM	1
CONFIG_MODULE_INIT_PWM_SOFT	1
CONFIG_MODULE_INIT_RANDOM	0
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	1
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	0
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	1
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	1
CONFIG_MODULE_INIT_USB_DEVICE	1
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	1

Continued on next page

Table 1.4 – continued from previous page

Name	Value
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	1
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	256
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	1
CONFIG_PWM_SOFT	1
CONFIG_RANDOM	0
CONFIG_SD	1
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	1
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	0
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_USB_CDC
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	38400
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	0
CONFIG_START_FILESYSTEM_ADDRESS	0
CONFIG_START_FILESYSTEM_SIZE	65536
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	0
CONFIG_START_SHELL_PRIO	30

Continued on next page

Table 1.4 – continued from previous page

Name	Value
CONFIG_START_SHELL_STACK_SIZE	768
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	840
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	0
CONFIG_SYS_LOG_MASK	-1
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	0
CONFIG_THRD_IDLE_STACK_SIZE	156
CONFIG_THRD_MONITOR_STACK_SIZE	256
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	1
CONFIG_USB	1
CONFIG_USB_DEVICE	1
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	1

Homepage

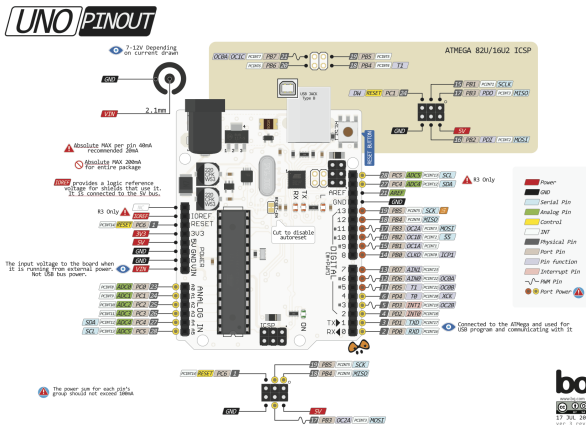
<https://www.sparkfun.com/products/12640>

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atmega32u4

Arduino Uno

Pinout



Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*

Drivers

Supported drivers for this board.

- *adc — Analog to digital conversion*
- *analog_input_pin — Analog input pin*
- *analog_output_pin — Analog output pin*
- *ds18b20 — One-wire temperature sensor*
- *ds3231 — RTC clock*
- *exti — External interrupts*
- *i2c — I2C*
- *i2c_soft — Software I2C*
- *mcp2515 — CAN BUS chipset*
- *nrf24l01 — Wireless communication*
- *owi — One-Wire Interface*
- *pin — Digital pins*
- *pwm — Pulse width modulation*
- *pwm_soft — Software pulse width modulation*
- *sd — Secure Digital memory*
- *spi — Serial Peripheral Interface*
- *uart — Universal Asynchronous Receiver/Transmitter*

- *uart_soft* — *Software Universal Asynchronous Receiver/Transmitter*
- *watchdog* — *Hardware watchdog*

Library Reference

Read more about board specific functionality in the *Arduino Uno* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The *minimal-configuration* application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The *default-configuration* application is built with the default configuration, including a lot more functionality. See the list of *Default system features* above for a summary.

Application	Flash	RAM
minimal-configuration	1548	279
default-configuration	13320	1038

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	1
CONFIG_ASSERT	0
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_ETH_COLUMNS_MAX	80
CONFIG_ETH_HEAP_SIZE	32768
CONFIG_ETH_ROWS_MAX	24
CONFIG_ESP_WIFI	0
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1

Continued on next page

Table 1.5 – continued from previous page

Name	Value
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	0
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	0
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	0
CONFIG_FS_CMD_FS_COUNTERS_LIST	0
CONFIG_FS_CMD_FS_COUNTERS_RESET	0
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	0
CONFIG_FS_CMD_FS_FORMAT	0
CONFIG_FS_CMD_FS_LIST	0
CONFIG_FS_CMD_FS_PARAMETERS_LIST	0
CONFIG_FS_CMD_FS_READ	0
CONFIG_FS_CMD_FS_REMOVE	0
CONFIG_FS_CMD_FS_WRITE	0
CONFIG_FS_CMD_I2C_READ	0
CONFIG_FS_CMD_I2C_WRITE	0
CONFIG_FS_CMD_LOG_LIST	0
CONFIG_FS_CMD_LOG_PRINT	0
CONFIG_FS_CMD_LOG_SET_LOG_MASK	0
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	0
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	0
CONFIG_FS_CMD_PIN_SET_MODE	0
CONFIG_FS_CMD_PIN_WRITE	0
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	0
CONFIG_FS_CMD_SETTINGS_READ	0
CONFIG_FS_CMD_SETTINGS_RESET	0
CONFIG_FS_CMD_SETTINGS_WRITE	0
CONFIG_FS_CMD_SYS_BACKTRACE	0
CONFIG_FS_CMD_SYS_CONFIG	0
CONFIG_FS_CMD_SYS_INFO	0
CONFIG_FS_CMD_SYS_PANIC	0
CONFIG_FS_CMD_SYS_REBOOT	0
CONFIG_FS_CMD_SYS_RESET_CAUSE	0
CONFIG_FS_CMD_SYS_UPTIME	0
CONFIG_FS_CMD_THRD_LIST	0
CONFIG_FS_CMD_THRD_SET_LOG_MASK	0
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	0

Continued on next page

Table 1.5 – continued from previous page

Name	Value
CONFIG_FS_CMD_USB_HOST_LIST	0
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	16
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	1
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	1
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	0
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	0
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	0
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	1
CONFIG_MODULE_INIT_NETWORK_INTERFACE	0
CONFIG_MODULE_INIT_NRF24L01	1
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	0
CONFIG_MODULE_INIT_PWM	1
CONFIG_MODULE_INIT_PWM_SOFT	1
CONFIG_MODULE_INIT_RANDOM	0
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	1
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	0
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1

Continued on next page

Table 1.5 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	1
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	1
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	1
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	256
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	1
CONFIG_PWM_SOFT	1
CONFIG_RANDOM	0
CONFIG_SD	1
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	1
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	0
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	38400
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNECTION	1
CONFIG_START_FILESYSTEM	0
CONFIG_START_FILESYSTEM_ADDRESS	0

Continued on next page

Table 1.5 – continued from previous page

Name	Value
CONFIG_START_FILESYSTEM_SIZE	65536
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	0
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	768
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	840
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	0
CONFIG_SYS_LOG_MASK	-1
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	0
CONFIG_THRD_IDLE_STACK_SIZE	156
CONFIG_THRD_MONITOR_STACK_SIZE	256
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	1
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	1

Homepage

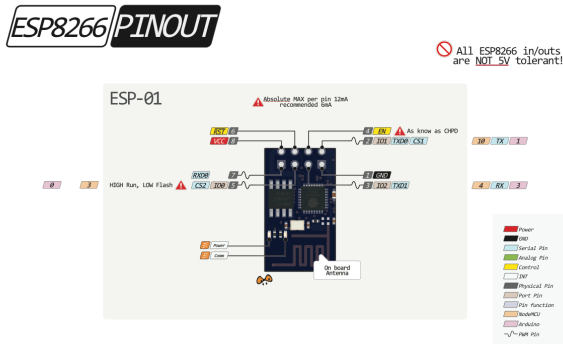
<https://www.arduino.cc/en/Main/ArduinoBoardUno>

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atmega328p

ESP-01

Pinout



Flashing

1. Connect VCC to 3.3 V and GND to ground.
2. Connect GPIO0 to GND.
3. Connect EN/CHPH to 3.3 V.
4. Turn on the power.
5. Upload the software to Flash using esptool.

Boot from flash

1. Connect VCC to 3.3 V and GND to ground.
2. Connect GPIO0 to 3.3 V.
3. Connect EN/CHPH to 3.3 V.
4. Turn on the power.

Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- File system.
- *Debug shell.*

Drivers

Supported drivers for this board.

- *adc* — *Analog to digital conversion*

- *analog_input_pin* — Analog input pin
- *ds18b20* — One-wire temperature sensor
- *eeprom_soft* — Software EEPROM
- *esp_wifi* — Espressif WiFi
- *exti* — External interrupts
- *flash* — Flash memory
- *i2c* — I2C
- *i2c_soft* — Software I2C
- *led_7seg_ht16k33* — LED 7-Segment HT16K33
- *owi* — One-Wire Interface
- *pin* — Digital pins
- *pwm_soft* — Software pulse width modulation
- *random* — Random numbers.
- *sht3xd* — SHT3x-D Humidity and Temperature Sensor
- *spi* — Serial Peripheral Interface
- *uart* — Universal Asynchronous Receiver/Transmitter
- *uart_soft* — Software Universal Asynchronous Receiver/Transmitter

Library Reference

Read more about board specific functionality in the [ESP-01](#) module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The [minimal-configuration](#) application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The [default-configuration](#) application is built with the default configuration, including a lot more functionality. See the list of [Default system features](#) above for a summary.

Application	Flash	RAM
minimal-configuration	265820	34064
default-configuration	312160	47196

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	0
Continued on next page	

Table 1.6 – continued from previous page

Name	Value
CONFIG_ASSERT	0
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	1
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	1
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1

Continued on next page

Table 1.6 – continued from previous page

Name	Value
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	1
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	1
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1

Continued on next page

Table 1.6 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	1
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	1
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	1
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	1
CONFIG_MODULE_INIT_RANDOM	1
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	1
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	1
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	1
CONFIG_RANDOM	1
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256

Continued on next page

Table 1.6 – continued from previous page

Name	Value
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	1
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	1
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	76800
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	1
CONFIG_START_FILESYSTEM_ADDRESS	0x0006b000
CONFIG_START_FILESYSTEM_SIZE	0x10000
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	1536
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	1536
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	1
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	768

Continued on next page

Table 1.6 – continued from previous page

Name	Value
CONFIG_THRD_MONITOR_STACK_SIZE	768
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	1
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

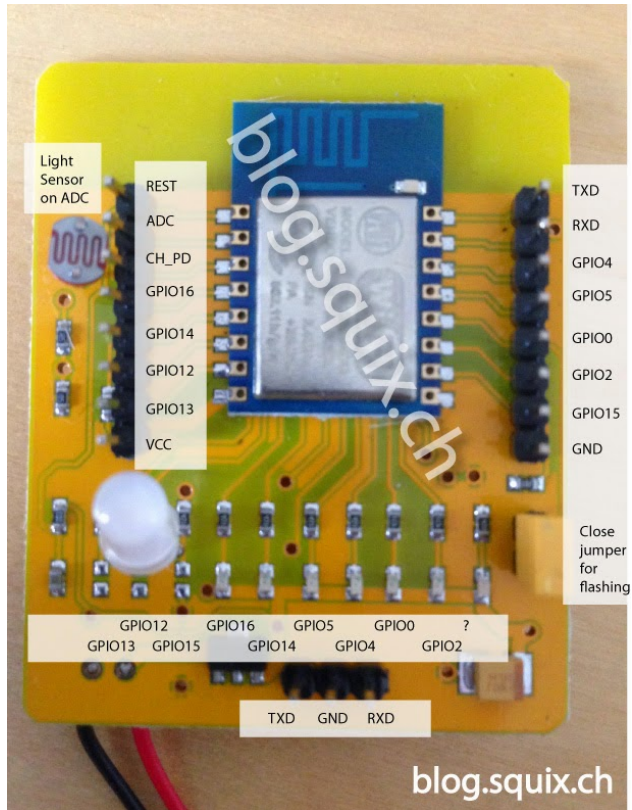
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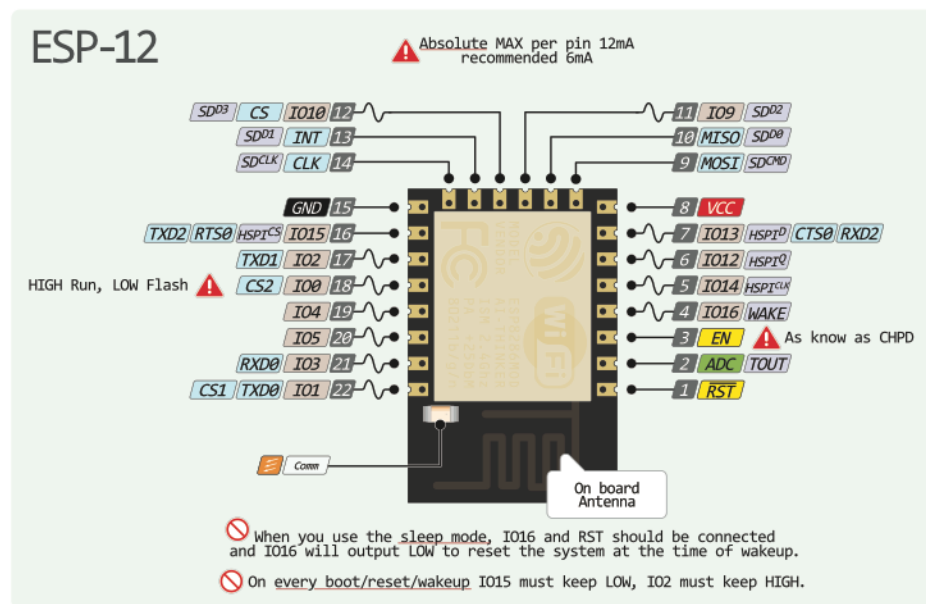
esp8266

ESP-12E Development Board

Pinout



ESP-12 pinout



Flashing

1. Connect 3.3 V to VCC and ground to GND.
2. Attach the flash jumper (to the right in the picture).
3. Turn on the power.
4. Upload the software to Flash using esptool.
5. The application starts automatically when the download is completed.

Hardware

- 3.3 V power supply and logical level voltage.
- Boot message at 76800 baud on a virgin board. Blue, red and RGB LEDs turned on.
- 4 MB Flash.

How to determine the Flash size:

```
$ python esptool.py --port /dev/ttyUSB0 flash_id
Connecting...
head: 0 ;total: 0
erase size : 0
Manufacturer: e0
Device: 4016
```

Device 4016 gives a Flash of size $2^{(16 - 1)} / 8 = 4096 \text{ kB} = 4 \text{ MB}$.

Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- File system.
- *Debug shell.*

Drivers

Supported drivers for this board.

- *adc — Analog to digital conversion*
- *analog_input_pin — Analog input pin*
- *ds18b20 — One-wire temperature sensor*
- *eeeprom_soft — Software EEPROM*
- *esp_wifi — Espressif WiFi*
- *exti — External interrupts*
- *flash — Flash memory*
- *i2c — I2C*

- *i2c_soft* — *Software I2C*
- *led_7seg_ht16k33* — *LED 7-Segment HT16K33*
- *owi* — *One-Wire Interface*
- *pin* — *Digital pins*
- *pwm_soft* — *Software pulse width modulation*
- *random* — *Random numbers.*
- *sht3xd* — *SHT3x-D Humidity and Temperature Sensor*
- *spi* — *Serial Peripheral Interface*
- *uart* — *Universal Asynchronous Receiver/Transmitter*
- *uart_soft* — *Software Universal Asynchronous Receiver/Transmitter*

Library Reference

Read more about board specific functionality in the *ESP-12E Development Board* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The *minimal-configuration* application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The *default-configuration* application is built with the default configuration, including a lot more functionality. See the list of *Default system features* above for a summary.

Application	Flash	RAM
minimal-configuration	265820	34064
default-configuration	312276	47216

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	0
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	1

Continued on next page

Table 1.7 – continued from previous page

Name	Value
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	1
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	1
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1

Continued on next page

Table 1.7 – continued from previous page

Name	Value
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	1
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	1
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	1
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	1
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1

Continued on next page

Table 1.7 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_PING	1
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	1
CONFIG_MODULE_INIT_RANDOM	1
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	1
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	1
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	1
CONFIG_RANDOM	1
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	1
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1

Continued on next page

Table 1.7 – continued from previous page

Name	Value
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	1
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	76800
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNECTION	1
CONFIG_START_FILESYSTEM	1
CONFIG_START_FILESYSTEM_ADDRESS	0x00300000
CONFIG_START_FILESYSTEM_SIZE	0xFB000
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	1536
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	1536
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	1
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	768
CONFIG_THRD_MONITOR_STACK_SIZE	768
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	1
CONFIG_USB	0

Continued on next page

Table 1.7 – continued from previous page

Name	Value
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

<http://espressif.com>

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ESP32-DevKitC

Pinout

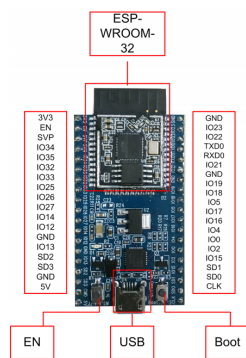


Figure 1-1. ESP32-DevKitC Layout

Default pin mapping

Here is a list of additional pin mappings not part of the picture above.

Device function	GPIO
LED	16
UART 0 TX	1
UART 0 RX	3
UART 1 TX	19
UART 1 RX	23
UART 2 TX	18
UART 2 RX	5
CAN TX	16
CAN RX	17

Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- File system.
- *Debug shell.*

Drivers

Supported drivers for this board.

- *adc — Analog to digital conversion*
- *analog_input_pin — Analog input pin*
- *can — Controller Area Network*
- *dac — Digital to analog conversion*
- *ds18b20 — One-wire temperature sensor*
- *eeeprom_soft — Software EEPROM*
- *esp_wifi — Espressif WiFi*
- *flash — Flash memory*
- *i2c — I2C*
- *i2c_soft — Software I2C*
- *owi — One-Wire Interface*
- *pin — Digital pins*
- *random — Random numbers.*
- *spi — Serial Peripheral Interface*
- *uart — Universal Asynchronous Receiver/Transmitter*
- *ws2812 — NeoPixels*

Library Reference

Read more about board specific functionality in the [ESP32-DevKitC](#) module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The [minimal-configuration](#) application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The [default-configuration](#) application is built with the default configuration, including a lot more functionality. See the list of [Default system features](#) above for a summary.

Application	Flash	RAM
minimal-configuration	91416	8644
default-configuration	355640	83428

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	1
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	1
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	1
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	1
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	0
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
Continued on next page	

Table 1.8 – continued from previous page

Name	Value
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	1
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1

Continued on next page

Table 1.8 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_CAN	1
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	1
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	1
CONFIG_MODULE_INIT_EXTI	0
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	1
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	1
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	1
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	0
CONFIG_MODULE_INIT_RANDOM	1
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	1
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	1
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	0
CONFIG_MODULE_INIT_UPGRADE	1
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040

Continued on next page

Table 1.8 – continued from previous page

Name	Value
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	0
CONFIG_RANDOM	1
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	1
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	115200
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	512
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNENTION	1
CONFIG_START_FILESYSTEM	1
CONFIG_START_FILESYSTEM_ADDRESS	0x00300000
CONFIG_START_FILESYSTEM_SIZE	0x20000
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	4096
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	4096
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100

Continued on next page

Table 1.8 – continued from previous page

Name	Value
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	8192
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	1024
CONFIG_THRD_MONITOR_STACK_SIZE	768
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	0
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

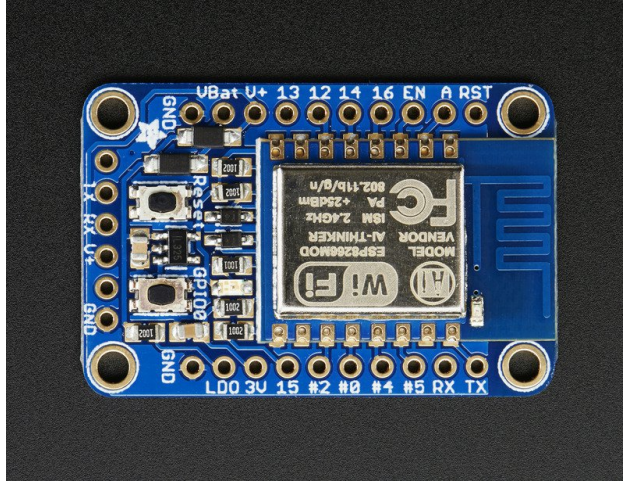
<https://espressif.com/en/products/hardware/esp32-devkitc/overview>

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esp32

Adafruit HUZZAH ESP8266 breakout

Pinout



Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- *File system.*
- *Debug shell.*

Drivers

Supported drivers for this board.

- *adc — Analog to digital conversion*
- *analog_input_pin — Analog input pin*
- *ds18b20 — One-wire temperature sensor*
- *eeprom_soft — Software EEPROM*
- *esp_wifi — Espressif WiFi*
- *exti — External interrupts*
- *flash — Flash memory*
- *i2c — I2C*
- *i2c_soft — Software I2C*
- *led_7seg_ht16k33 — LED 7-Segment HT16K33*
- *owi — One-Wire Interface*
- *pin — Digital pins*
- *pwm_soft — Software pulse width modulation*
- *random — Random numbers.*

- *sht3xd* — *SHT3x-D Humidity and Temperature Sensor*
- *spi* — *Serial Peripheral Interface*
- *uart* — *Universal Asynchronous Receiver/Transmitter*
- *uart_soft* — *Software Universal Asynchronous Receiver/Transmitter*

Library Reference

Read more about board specific functionality in the *Adafruit HUZZAH ESP8266 breakout* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The *minimal-configuration* application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The *default-configuration* application is built with the default configuration, including a lot more functionality. See the list of *Default system features* above for a summary.

Application	Flash	RAM
minimal-configuration	265820	34064
default-configuration	311452	46672

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	0
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_ETH_ROWS_MAX	80
CONFIG_ETH_HEAP_SIZE	32768
CONFIG_ETH_ROWS_MAX	24
CONFIG_ESP_WIFI	1

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Table 1.9 – continued from previous page

Name	Value
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1

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Table 1.9 – continued from previous page

Name	Value
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	1
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	1
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	1
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	1
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	1
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	1
CONFIG_MODULE_INIT_RANDOM	1
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	1

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Table 1.9 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	1
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	1
CONFIG_RANDOM	1
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	1
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	1
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	76800
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0

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Table 1.9 – continued from previous page

Name	Value
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	1
CONFIG_START_FILESYSTEM_ADDRESS	0
CONFIG_START_FILESYSTEM_SIZE	65536
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	1536
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	1536
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	1
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	768
CONFIG_THRD_MONITOR_STACK_SIZE	768
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	1
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

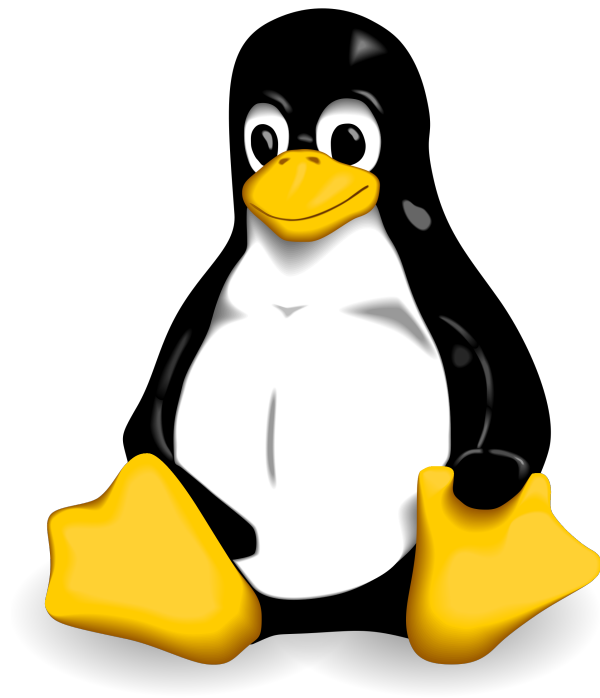
<https://www.adafruit.com/product/2471>

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esp8266

Linux

Pinout



Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- *File system.*
- *Debug shell.*

Drivers

Supported drivers for this board.

- *adc — Analog to digital conversion*
- *analog_input_pin — Analog input pin*
- *analog_output_pin — Analog output pin*
- *can — Controller Area Network*

- *dac* — Digital to analog conversion
- *ds18b20* — One-wire temperature sensor
- *eeeprom_soft* — Software EEPROM
- *exti* — External interrupts
- *flash* — Flash memory
- *i2c* — I2C
- *i2c_soft* — Software I2C
- *owi* — One-Wire Interface
- *pin* — Digital pins
- *pwm* — Pulse width modulation
- *pwm_soft* — Software pulse width modulation
- *random* — Random numbers.
- *sd* — Secure Digital memory
- *spi* — Serial Peripheral Interface
- *uart* — Universal Asynchronous Receiver/Transmitter

Library Reference

Read more about board specific functionality in the [Linux](#) module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The [minimal-configuration](#) application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The [default-configuration](#) application is built with the default configuration, including a lot more functionality. See the list of [Default system features](#) above for a summary.

Application	Flash	RAM
minimal-configuration	145132	320056
default-configuration	385403	474608

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	1
CONFIG_ASSERT	1
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	1

Continued on next page

Table 1.10 – continued from previous page

Name	Value
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	1
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	0
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1

Continued on next page

Table 1.10 – continued from previous page

Name	Value
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	1
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	1
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	1
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	1
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	0
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	1

Continued on next page

Table 1.10 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	1
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	1
CONFIG_MODULE_INIT_PWM	1
CONFIG_MODULE_INIT_PWM_SOFT	1
CONFIG_MODULE_INIT_RANDOM	1
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	1
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	1
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	1
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	0
CONFIG_MODULE_INIT_UPGRADE	1
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0
CONFIG_MONITOR_THREAD	1
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	1
CONFIG_PWM_SOFT	1
CONFIG_RANDOM	1
CONFIG_SD	1
CONFIG_SETTINGS_AREA_SIZE	1028
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768

Continued on next page

Table 1.10 – continued from previous page

Name	Value
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	1
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	38400
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	512
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	1
CONFIG_START_FILESYSTEM_ADDRESS	0
CONFIG_START_FILESYSTEM_SIZE	65536
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	768
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	840
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	1024
CONFIG_THRD_MONITOR_STACK_SIZE	1024
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0

Continued on next page

Table 1.10 – continued from previous page

Name	Value
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	0
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

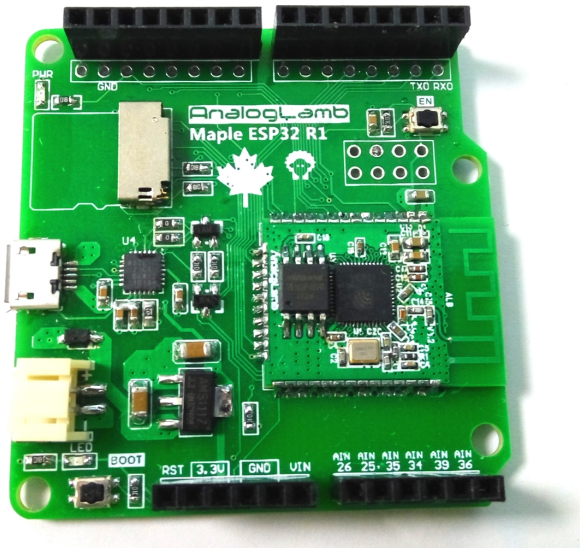
<http://www.kernel.org>

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linux

Maple-ESP32

Pinout



Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- File system.
- *Debug shell.*

Drivers

Supported drivers for this board.

- *adc* — Analog to digital conversion
- *analog_input_pin* — Analog input pin
- *can* — Controller Area Network
- *dac* — Digital to analog conversion
- *ds18b20* — One-wire temperature sensor
- *eeprom_soft* — Software EEPROM
- *esp_wifi* — Espressif WiFi
- *flash* — Flash memory
- *i2c* — I2C
- *i2c_soft* — Software I2C
- *owi* — One-Wire Interface
- *pin* — Digital pins
- *random* — Random numbers.
- *spi* — Serial Peripheral Interface
- *uart* — Universal Asynchronous Receiver/Transmitter
- *ws2812* — NeoPixels

Library Reference

Read more about board specific functionality in the *Maple-ESP32* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The *minimal-configuration* application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The *default-configuration* application is built with the default configuration, including a lot more functionality. See the list of *Default system features* above for a summary.

Application	Flash	RAM
minimal-configuration	91416	8644
default-configuration	355640	83428

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	1
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	1
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	1
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	1
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	0
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1

Continued on next page

Table 1.11 – continued from previous page

Name	Value
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	1
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	1
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	1

Continued on next page

Table 1.11 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	1
CONFIG_MODULE_INIT_EXTI	0
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	1
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	1
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	1
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	0
CONFIG_MODULE_INIT_RANDOM	1
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	1
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	1
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	0
CONFIG_MODULE_INIT_UPGRADE	1
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0

Continued on next page

Table 1.11 – continued from previous page

Name	Value
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	0
CONFIG_RANDOM	1
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	1
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	115200
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	512
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	1
CONFIG_START_FILESYSTEM_ADDRESS	0x00300000
CONFIG_START_FILESYSTEM_SIZE	0x20000
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	4096
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	4096
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0

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Table 1.11 – continued from previous page

Name	Value
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	8192
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	1024
CONFIG_THRD_MONITOR_STACK_SIZE	768
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	0
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

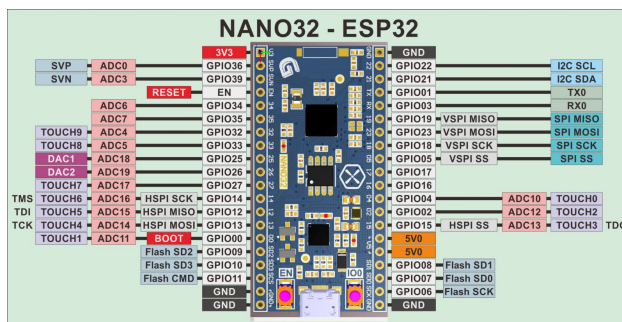
<http://www.analoglamb.com/product/maple-esp32/>

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esp32

Nano32

Pinout



Default pin mapping

Here is a list of additional pin mappings not part of the picture above.

Device function	GPIO
UART 0 TX	1
UART 0 RX	3
UART 1 TX	19
UART 1 RX	23
UART 2 TX	18
UART 2 RX	5
CAN TX	16
CAN RX	17

Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- File system.
- *Debug shell.*

Drivers

Supported drivers for this board.

- *adc — Analog to digital conversion*
- *analog_input_pin — Analog input pin*
- *can — Controller Area Network*
- *dac — Digital to analog conversion*
- *ds18b20 — One-wire temperature sensor*
- *eeprom_soft — Software EEPROM*
- *esp_wifi — Espressif WiFi*
- *flash — Flash memory*
- *i2c — I2C*
- *i2c_soft — Software I2C*
- *owi — One-Wire Interface*
- *pin — Digital pins*
- *random — Random numbers.*
- *spi — Serial Peripheral Interface*
- *uart — Universal Asynchronous Receiver/Transmitter*
- *ws2812 — NeoPixels*

Library Reference

Read more about board specific functionality in the *Nano32* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The [minimal-configuration](#) application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The [default-configuration](#) application is built with the default configuration, including a lot more functionality. See the list of [Default system features](#) above for a summary.

Application	Flash	RAM
minimal-configuration	91416	8644
default-configuration	355632	83428

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	1
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	1
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	1
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	1
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	0
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
Continued on next page	

Table 1.12 – continued from previous page

Name	Value
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	1

Continued on next page

Table 1.12 – continued from previous page

Name	Value
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	1
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	1
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	1
CONFIG_MODULE_INIT_EXTI	0
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	1
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	1
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	1
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	0
CONFIG_MODULE_INIT_RANDOM	1
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	1
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	1
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	0
CONFIG_MODULE_INIT_UPGRADE	1
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0

Continued on next page

Table 1.12 – continued from previous page

Name	Value
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	0
CONFIG_RANDOM	1
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	1
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	115200
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	512
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	1
CONFIG_START_FILESYSTEM_ADDRESS	0x00300000
CONFIG_START_FILESYSTEM_SIZE	0x20000
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1

Continued on next page

Table 1.12 – continued from previous page

Name	Value
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	4096
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	4096
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	8192
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	1024
CONFIG_THRD_MONITOR_STACK_SIZE	768
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	0
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

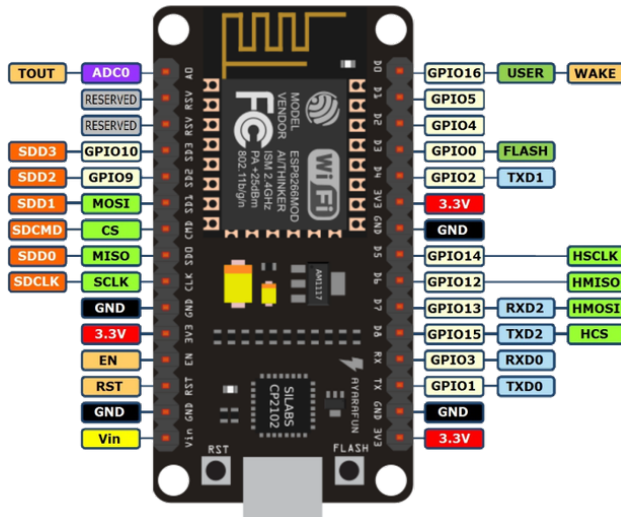
<http://esp32.de>

Mcu

esp32

NodeMCU

Pinout



Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- File system.
- *Debug shell.*

Drivers

Supported drivers for this board.

- *adc* — Analog to digital conversion
- *analog_input_pin* — Analog input pin
- *ds18b20* — One-wire temperature sensor
- *eeeprom_soft* — Software EEPROM
- *esp_wifi* — Espressif WiFi
- *exti* — External interrupts
- *flash* — Flash memory
- *i2c* — I2C
- *i2c_soft* — Software I2C
- *led_7seg_ht16k33* — LED 7-Segment HT16K33
- *owi* — One-Wire Interface
- *pin* — Digital pins
- *pwm_soft* — Software pulse width modulation

- *random* — Random numbers.
- *sht3xd* — SHT3x-D Humidity and Temperature Sensor
- *spi* — Serial Peripheral Interface
- *uart* — Universal Asynchronous Receiver/Transmitter
- *uart_soft* — Software Universal Asynchronous Receiver/Transmitter

Library Reference

Read more about board specific functionality in the *NodeMCU* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The *minimal-configuration* application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The *default-configuration* application is built with the default configuration, including a lot more functionality. See the list of *Default system features* above for a summary.

Application	Flash	RAM
minimal-configuration	265820	34064
default-configuration	312316	47196

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	0
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
Continued on next page	

Table 1.13 – continued from previous page

Name	Value
CONFIG_ESP_WIFI	1
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	1
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1

Continued on next page

Table 1.13 – continued from previous page

Name	Value
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	1
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	1
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	1
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	1
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	1
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	1
CONFIG_MODULE_INIT_RANDOM	1
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1

Continued on next page

Table 1.13 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_SOCKET	1
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	1
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	1
CONFIG_RANDOM	1
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	1
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	1
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	76800
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32

Continued on next page

Table 1.13 – continued from previous page

Name	Value
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	1
CONFIG_START_FILESYSTEM_ADDRESS	0x00300000
CONFIG_START_FILESYSTEM_SIZE	0xFB000
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	1536
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	1536
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	1
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	768
CONFIG_THRD_MONITOR_STACK_SIZE	768
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	1
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

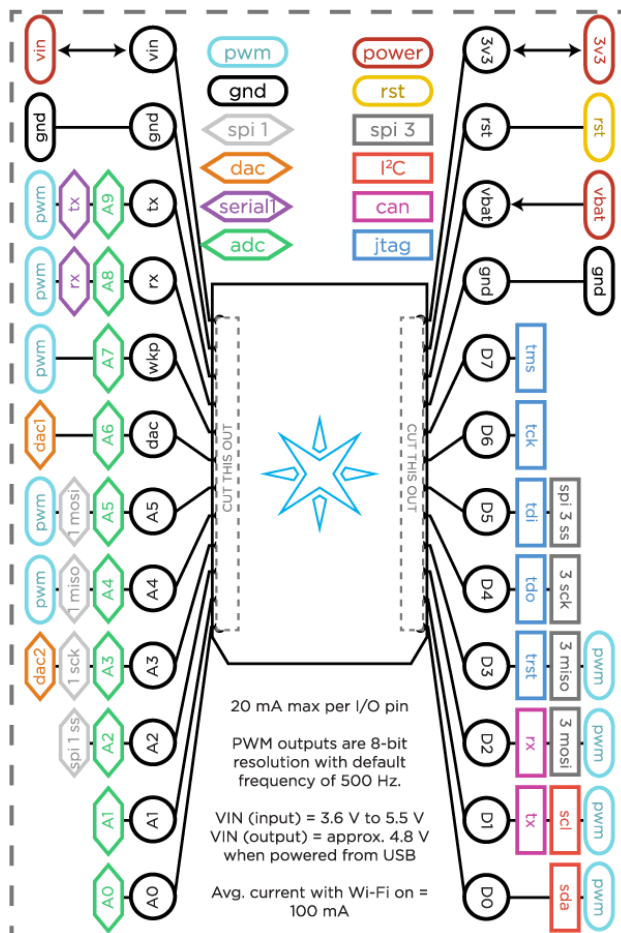
<http://www.nodemcu.com>

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esp8266

Particle IO Photon

Pinout



Detailed pinout

Right side pins

USB	Pin	Exposed Functions				STM32 Pin	PØ Pin #	PØ Pin Name	
P H O T O N	3V3	3V3							
	RST	RST					E8	26	MICRO_RST_N
	VBAT	VBAT					A9	28	VBAT
	GND	GND							
	D7	JTAG_TMS					PA13	44	MICRO_JTAG_TMS
	D6	JTAG_TCK					PA14	40	MICRO_JTAG_TCK
	D5	JTAG_TDI	SPI3_SS			I2S3_WS	PA15	43	MICRO_JTAG_TDI
	D4	JTAG_TDO	SPI3_SCK			I2S3_SCK	PB3	41	MICRO_JTAG_TDO
	D3	JTAG_TRST	SPI3_MISO		TIM3_CH1		PB4	42	MICRO_JTAG_TRSTN
	D2		SPI3_MOSI	CAN2_RX	TIM3_CH2	I2S3_SD	PB5	3	MICRO_GPIO_5
	D1	SCL		CAN2_TX	TIM4_CH1		PB6	5	MICRO_GPIO_3
	D0	SDA				TIM4_CH2	PB7	4	MICRO_GPIO_4

Left side pins

Pin	USB	Exposed Functions				STM32 Pin	PØ Pin #	PØ Pin Name
VIN	P H O T O N	VIN						
GND		GND						
TX			USART1_TX	TIM1_CH2		PA9	39	MICRO_UART_TX
RX			USART1_RX	TIM1_CH3		PA10	38	MICRO_UART_RX
WKP		ADC0		TIM5_CH1		PA0	27	MICRO_WKUP
DAC		ADC4			DAC1	PA4	22	MICRO_SPI_SSN
A5		ADC7	SPI1_MOSI	TIM3_CH2		PA7	23	MICRO_SPI_MOSI
A4		ADC6	SPI1_MISO	TIM3_CH1		PA6	25	MICRO_SPI_MISO
A3		ADC5	SPI1_SCK		DAC2	PA5	24	MICRO_SPI_SCK
A2		ADC12	SPI1_SS			PC2	2	MICRO_GPIO_6
A1		ADC13				PC3	1	MICRO_GPIO_7
A0		ADC15				PC5	54	MICRO_GPIO_8

User I/O

	User I/O	Photon Pin #	Exposed Functions		STM32 Pin	PØ Pin #	PØ Pin Name
P H O T O N	RGB LED - RED	27		TIM2_CH2	PA1	8	MICRO_GPIO_0
	RGB LED - GREEN	28		TIM2_CH3	PA2	7	MICRO_GPIO_1
	RGB LED - BLUE	29		TIM2_CH4	PA3	6	MICRO_GPIO_2
	Setup Button	26		TIM3_CH2 I2S3_MCK	PC7	53	MICRO_GPIO_9
	Reset Button	23			E8	26	MICRO_RST_N
	USB Data+	31			PB15	51	MICRO_USB_HS_DP
	USB Data-	30			PB14	52	MICRO_USB_HS_DM
	SMPS Enable	25					
	Peripheral Key	ADC	SPI	PWM/Servo/Tone			
		JTAG	SPI1	I2S DAC			
		I2C/Wire	Serial1	CAN			

Prerequisites

Install the dfu-utility.

```
git clone git://git.code.sf.net/p/dfu-util/dfu-util
cd dfu-util
sudo apt-get build-dep dfu-util
./autogen.sh
./configure
make
sudo make install
cd ..

# Give users access to the device.
sudo cp simba/environment/udev/49-photon.rules /etc/udev/rules.d
```

Flashing

The Photon must enter DFU mode before software can be uploaded to it. It's recommended to use the manual method to verify that software can be successfully uploaded to the board, and then start using the automatic method to reduce the manual work for each software upload.

Automatic (recommended)

- Connect DTR on the serial adapter to the RST pin on the Photon.
- Connect RTS on the serial adapter to the SETUP pad on the bottom side of the Photon. This requires soldering a cable to the SETUP pad.

Upload the software with `make BOARD=photon upload`.

Manual

To enter DFU Mode:

1. Hold down the RESET and SETUP buttons.
2. Release only the RESET button, while holding down the SETUP button.
3. Wait for the LED to start flashing yellow (it will flash magenta first).
4. Release the SETUP button.

NOTE: Do **not** connect DTR and/or RTS using manual upload. They must only be connected using the automatic method.

Upload the software with `make BOARD=photon upload`.

Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- *Debug shell.*

Drivers

Supported drivers for this board.

- *eeeprom_soft — Software EEPROM*
- *flash — Flash memory*
- *i2c — I2C*
- *i2c_soft — Software I2C*
- *pin — Digital pins*
- *uart — Universal Asynchronous Receiver/Transmitter*

Library Reference

Read more about board specific functionality in the *Particle IO Photon* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The *minimal-configuration* application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The *default-configuration* application is built with the default configuration, including a lot more functionality. See the list of *Default system features* above for a summary.

Application	Flash	RAM
minimal-configuration	2668	1672
default-configuration	63848	5998

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	0
CONFIG_ANALOG_INPUT_PIN	0
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	1
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	0
CONFIG_DS3231	0
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	0
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	0
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1

Continued on next page

Table 1.14 – continued from previous page

Name	Value
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	0
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	0
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0

Continued on next page

Table 1.14 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_DS18B20	0
CONFIG_MODULE_INIT_DS3231	0
CONFIG_MODULE_INIT_ESP_WIFI	0
CONFIG_MODULE_INIT_EXTI	0
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	0
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	0
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	0
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	0
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	0
CONFIG_MODULE_INIT_RANDOM	0
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	0
CONFIG_MODULE_INIT_SPI	0
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	0
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0
CONFIG_MONITOR_THREAD	1
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	1
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	0
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0

Continued on next page

Table 1.14 – continued from previous page

Name	Value
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	0
CONFIG_RANDOM	0
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	0
CONFIG_SPIFFS	0
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	38400
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	0
CONFIG_START_FILESYSTEM_ADDRESS	0
CONFIG_START_FILESYSTEM_SIZE	65536
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	768
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	840
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0

Continued on next page

Table 1.14 – continued from previous page

Name	Value
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	384
CONFIG_THRD_MONITOR_STACK_SIZE	512
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	0
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

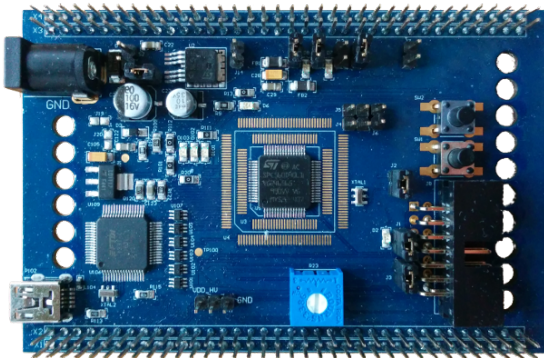
<https://docs.particle.io/datasheets/photon-datasheet/>

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stm32f205rg

SPC56D Discovery

Pinout



Pin functions

These are the default pin functions in Simba.

List	Index	Pin	Function
X1	12	PB0	CAN TX
X2	9	PB1	CAN RX
X1	10	PB2	UART0 TX
X2	10	PB3	UART0 RX
X4	6	PC2	LED (D8)

Toolchain

Download [S32 Design Studio for Power v1.1](#) for Linux and install it.

Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- *Debug shell.*

Drivers

Supported drivers for this board.

- *can — Controller Area Network*
- *eeeprom_soft — Software EEPROM*
- *flash — Flash memory*
- *i2c — I2C*
- *i2c_soft — Software I2C*
- *pin — Digital pins*
- *uart — Universal Asynchronous Receiver/Transmitter*
- *watchdog — Hardware watchdog*

Library Reference

Read more about board specific functionality in the [SPC56D Discovery](#) module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The [minimal-configuration](#) application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.

- The `default-configuration` application is built with the default configuration, including a lot more functionality. See the list of *Default system features* above for a summary.

Application	Flash	RAM
minimal-configuration	13636	952
default-configuration	75308	5954

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	0
CONFIG_ANALOG_INPUT_PIN	0
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	1
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	1
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	0
CONFIG_DS3231	0
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_ETHMACS_COLUMNS_MAX	80
CONFIG_ETHMACS_HEAP_SIZE	32768
CONFIG_ETHMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	0
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	0
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	0
CONFIG_FS_CMD_FS_COUNTERS_LIST	0
CONFIG_FS_CMD_FS_COUNTERS_RESET	0
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	0
CONFIG_FS_CMD_FS_FORMAT	0
CONFIG_FS_CMD_FS_LIST	0
CONFIG_FS_CMD_FS_PARAMETERS_LIST	0
CONFIG_FS_CMD_FS_READ	0

Continued on next page

Table 1.15 – continued from previous page

Name	Value
CONFIG_FS_CMD_FS_REMOVE	0
CONFIG_FS_CMD_FS_WRITE	0
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	0

Continued on next page

Table 1.15 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	0
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	1
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	0
CONFIG_MODULE_INIT_DS3231	0
CONFIG_MODULE_INIT_ESP_WIFI	0
CONFIG_MODULE_INIT_EXTI	0
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	0
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	0
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	0
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	0
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	0
CONFIG_MODULE_INIT_RANDOM	0
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	0
CONFIG_MODULE_INIT_SPI	0
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	0
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	1
CONFIG_MONITOR_THREAD	1
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	1
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384

Continued on next page

Table 1.15 – continued from previous page

Name	Value
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	1
CONFIG_NVM_SIZE	2040
CONFIG_OWI	0
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	0
CONFIG_RANDOM	0
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	1028
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	0
CONFIG_SPIFFS	0
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	115200
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	0
CONFIG_START_FILESYSTEM_ADDRESS	0
CONFIG_START_FILESYSTEM_SIZE	65536
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	1536
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	840
CONFIG_STD_OUTPUT_BUFFER_MAX	16

Continued on next page

Table 1.15 – continued from previous page

Name	Value
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	256
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	156
CONFIG_THRD_MONITOR_STACK_SIZE	768
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	0
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	1

Homepage

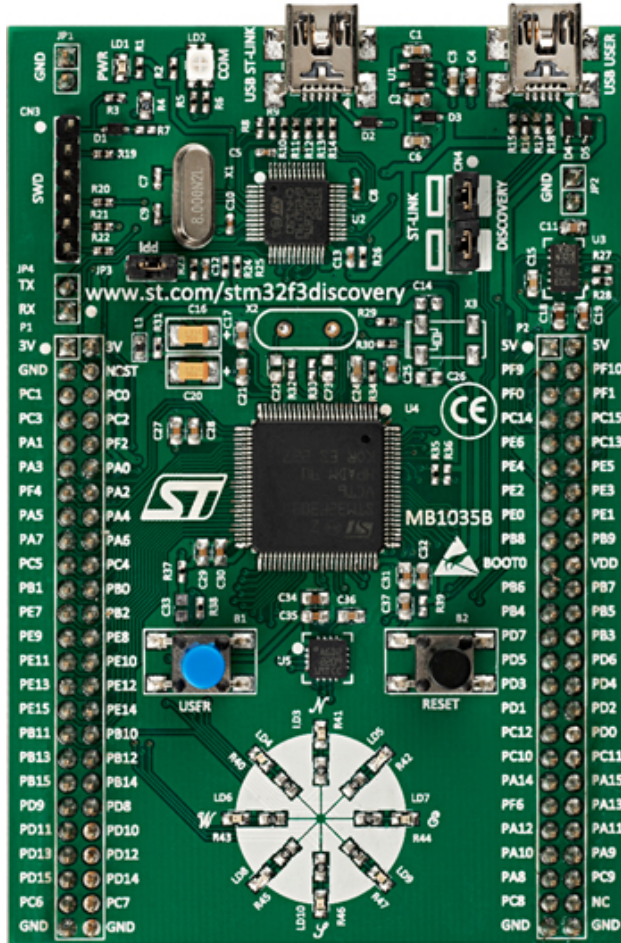
<http://www.st.com/en/evaluation-tools/spc56d-discovery.html>

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spc56d4011

STM32F3DISCOVERY

Pinout



Pin functions

These are the default pin functions in Simba.

Function	Pin
UART0 TX	PA9
UART0 RX	PA10
UART1 TX	PA2
UART1 RX	PA3
UART2 TX	PB10
UART2 RX	PB11
SPI0 SCK	PA5
SPI0 MISO	PA6
SPI0 MOSI	PA7
SPI1 SCK	PA13
SPI1 MISO	PA14
SPI1 MOSI	PA15
SPI2 SCK	PC10
SPI2 MISO	PC11
SPI2 MOSI	PC12
I2C0 SCL	PB8
I2C0 SDA	PB9
I2C1 SCL	PF0
I2C1 SDA	PF1
CAN TX	PD1
CAN RX	PD0

Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- *Debug shell.*

Drivers

Supported drivers for this board.

- *eeeprom_soft — Software EEPROM*
- *flash — Flash memory*
- *i2c — I2C*
- *i2c_soft — Software I2C*
- *pin — Digital pins*
- *uart — Universal Asynchronous Receiver/Transmitter*

Library Reference

Read more about board specific functionality in the *STM32F3DISCOVERY* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The [minimal-configuration](#) application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The [default-configuration](#) application is built with the default configuration, including a lot more functionality. See the list of [Default system features](#) above for a summary.

Application	Flash	RAM
minimal-configuration	2816	1672
default-configuration	62976	5502

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	0
CONFIG_ANALOG_INPUT_PIN	0
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	1
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	0
CONFIG_DS3231	0
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	0
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	0
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
Continued on next page	

Table 1.16 – continued from previous page

Name	Value
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0

Continued on next page

Table 1.16 – continued from previous page

Name	Value
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	0
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	0
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	0
CONFIG_MODULE_INIT_DS3231	0
CONFIG_MODULE_INIT_ESP_WIFI	0
CONFIG_MODULE_INIT_EXTI	0
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	0
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	0
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	0
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	0
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	0
CONFIG_MODULE_INIT_RANDOM	0
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	0
CONFIG_MODULE_INIT_SPI	0
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	0
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0

Continued on next page

Table 1.16 – continued from previous page

Name	Value
CONFIG_MONITOR_THREAD	1
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	1
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	0
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	0
CONFIG_RANDOM	0
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	0
CONFIG_SPIFFS	0
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	38400
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNETION	1
CONFIG_START_FILESYSTEM	0
CONFIG_START_FILESYSTEM_ADDRESS	0
CONFIG_START_FILESYSTEM_SIZE	65536
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1

Continued on next page

Table 1.16 – continued from previous page

Name	Value
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	768
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	840
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	384
CONFIG_THRD_MONITOR_STACK_SIZE	512
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	0
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

http://www.st.com/content/st_com/en/products/evaluation-tools/product-evaluation-tools/mcu-eval-tools/stm32-mcu-eval-tools/stm32-mcu-discovery-kits/stm32f3discovery.html

Mcu

stm32f303vc

STM32VLDISCOVERY

Pinout



st-link

```
sudo apt install libusb-1.0-0-dev
git clone https://github.com/eerimoq/stlink
./autogen.sh
./configure
make
sudo cp etc/udev/rules.d/49* /etc/udev/rules.d
udevadm control --reload-rules
udevadm trigger
```

```
modprobe -r usb-storage && modprobe usb-storage quirks=483:3744:i

st-util -l
arm-none-eabi-gdb app.out
$ target extended-remote localhost:4242
```

Plug in the board in the PC.

Pin functions

These are the default pin functions in Simba.

Function	Pin
UART0 TX	PA9
UART0 RX	PA10
UART1 TX	PA2
UART1 RX	PA3
UART2 TX	PC10
UART2 RX	PC11
SPI0 SCK	PA5
SPI0 MISO	PA6
SPI0 MOSI	PA7
I2C0 SCL	PB8
I2C0 SDA	PB9

Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- *Debug shell.*

Drivers

Supported drivers for this board.

- *eeeprom_soft — Software EEPROM*
- *flash — Flash memory*
- *i2c — I2C*
- *i2c_soft — Software I2C*
- *pin — Digital pins*
- *uart — Universal Asynchronous Receiver/Transmitter*

Library Reference

Read more about board specific functionality in the *STM32VLDISCOVERY* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The [minimal-configuration](#) application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The [default-configuration](#) application is built with the default configuration, including a lot more functionality. See the list of [Default system features](#) above for a summary.

Application	Flash	RAM
minimal-configuration	2816	1672
default-configuration	64256	6006

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	0
CONFIG_ANALOG_INPUT_PIN	0
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	1
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	0
CONFIG_DS3231	0
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	0
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	0
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
Continued on next page	

Table 1.17 – continued from previous page

Name	Value
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0

Continued on next page

Table 1.17 – continued from previous page

Name	Value
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	0
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	0
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	0
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	0
CONFIG_MODULE_INIT_DS3231	0
CONFIG_MODULE_INIT_ESP_WIFI	0
CONFIG_MODULE_INIT_EXTI	0
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	0
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	0
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	0
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	0
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	0
CONFIG_MODULE_INIT_RANDOM	0
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	0
CONFIG_MODULE_INIT_SPI	0
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	0
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0

Continued on next page

Table 1.17 – continued from previous page

Name	Value
CONFIG_MONITOR_THREAD	1
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	1
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	0
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	0
CONFIG_RANDOM	0
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	0
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	0
CONFIG_SPIFFS	0
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	38400
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNECTION	1
CONFIG_START_FILESYSTEM	0
CONFIG_START_FILESYSTEM_ADDRESS	0
CONFIG_START_FILESYSTEM_SIZE	65536
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1

Continued on next page

Table 1.17 – continued from previous page

Name	Value
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	768
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	840
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	0
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	384
CONFIG_THRD_MONITOR_STACK_SIZE	512
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	0
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

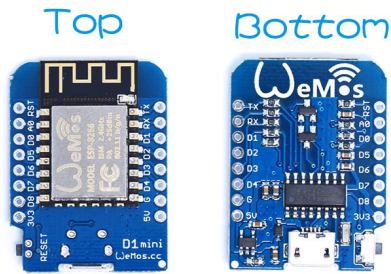
http://www.st.com/content/st_com/en/products/evaluation-tools/product-evaluation-tools/mcu-eval-tools/stm32-mcu-eval-tools/stm32-mcu-discovery-kits/stm32vldiscovery.html?sc=internet/evalboard/product/250863.jsp

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stm32f100rb

WEMOS D1 mini

Pinout



Default system features

The default configuration includes those major features. They are all initialized by `sys_start()` at the startup of the application.

- *Console.*
- File system.
- *Debug shell.*

Drivers

Supported drivers for this board.

- *adc — Analog to digital conversion*
- *analog_input_pin — Analog input pin*
- *ds18b20 — One-wire temperature sensor*
- *eeeprom_soft — Software EEPROM*
- *esp_wifi — Espressif WiFi*
- *exti — External interrupts*
- *flash — Flash memory*
- *i2c — I2C*
- *i2c_soft — Software I2C*
- *led_7seg_ht16k33 — LED 7-Segment HT16K33*
- *owi — One-Wire Interface*
- *pin — Digital pins*
- *pwm_soft — Software pulse width modulation*
- *random — Random numbers.*
- *sht3xd — SHT3x-D Humidity and Temperature Sensor*
- *spi — Serial Peripheral Interface*
- *uart — Universal Asynchronous Receiver/Transmitter*

- *uart_soft* — *Software Universal Asynchronous Receiver/Transmitter*

Library Reference

Read more about board specific functionality in the *WEMOS D1 mini* module documentation in the Library Reference.

Memory usage

Below is the memory usage of two applications:

- The *minimal-configuration* application is configured to only include the bare minimum of functionality for the low level kernel to run. That is, the thread scheduler and system tick.
- The *default-configuration* application is built with the default configuration, including a lot more functionality. See the list of *Default system features* above for a summary.

Application	Flash	RAM
minimal-configuration	265820	34064
default-configuration	311488	46700

Default configuration

Default Standard Library configuration.

Name	Value
CONFIG_ADC	1
CONFIG_ANALOG_INPUT_PIN	1
CONFIG_ANALOG_OUTPUT_PIN	0
CONFIG_ASSERT	0
CONFIG_ASSERT_FORCE_FATAL	1
CONFIG_CAN	0
CONFIG_CAN_FRAME_TIMESTAMP	1
CONFIG_CHIPID	0
CONFIG_CRC_TABLE_LOOKUP	1
CONFIG_DAC	0
CONFIG_DEBUG	1
CONFIG_DS18B20	1
CONFIG_DS3231	1
CONFIG_EEPROM_SOFT_CRC	CONFIG_EEPROM_SOFT_CRC_32
CONFIG_EEPROM_SOFT_CRC_32	0
CONFIG_EEPROM_SOFT_CRC_CCITT	1
CONFIG_EEPROM_SOFT_SEMAPHORE	1
CONFIG_EMACS_COLUMNS_MAX	80
CONFIG_EMACS_HEAP_SIZE	32768
CONFIG_EMACS_ROWS_MAX	24
CONFIG_ESP_WIFI	1
CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ	16000000
CONFIG_EXTI	1
CONFIG_FAT16	1
CONFIG_FATAL_ASSERT	1
CONFIG_FILESYSTEM_GENERIC	1

Continued on next page

Table 1.18 – continued from previous page

Name	Value
CONFIG_FLASH	1
CONFIG_FLASH_DEVICE_SEMAPHORE	1
CONFIG_FLOAT	1
CONFIG_FS_CMD_DS18B20_LIST	1
CONFIG_FS_CMD_ESP_WIFI_STATUS	0
CONFIG_FS_CMD_FS_APPEND	1
CONFIG_FS_CMD_FS_COUNTERS_LIST	1
CONFIG_FS_CMD_FS_COUNTERS_RESET	1
CONFIG_FS_CMD_FS_FILESYSTEMS_LIST	1
CONFIG_FS_CMD_FS_FORMAT	1
CONFIG_FS_CMD_FS_LIST	1
CONFIG_FS_CMD_FS_PARAMETERS_LIST	1
CONFIG_FS_CMD_FS_READ	1
CONFIG_FS_CMD_FS_REMOVE	1
CONFIG_FS_CMD_FS_WRITE	1
CONFIG_FS_CMD_I2C_READ	1
CONFIG_FS_CMD_I2C_WRITE	1
CONFIG_FS_CMD_LOG_LIST	1
CONFIG_FS_CMD_LOG_PRINT	1
CONFIG_FS_CMD_LOG_SET_LOG_MASK	1
CONFIG_FS_CMD_NETWORK_INTERFACE_LIST	1
CONFIG_FS_CMD_NVM_READ	1
CONFIG_FS_CMD_NVM_WRITE	1
CONFIG_FS_CMD_PING_PING	1
CONFIG_FS_CMD_PIN_READ	1
CONFIG_FS_CMD_PIN_SET_MODE	1
CONFIG_FS_CMD_PIN_WRITE	1
CONFIG_FS_CMD_SERVICE_LIST	1
CONFIG_FS_CMD_SERVICE_START	1
CONFIG_FS_CMD_SERVICE_STOP	1
CONFIG_FS_CMD_SETTINGS_LIST	1
CONFIG_FS_CMD_SETTINGS_READ	1
CONFIG_FS_CMD_SETTINGS_RESET	1
CONFIG_FS_CMD_SETTINGS_WRITE	1
CONFIG_FS_CMD_SYS_BACKTRACE	1
CONFIG_FS_CMD_SYS_CONFIG	1
CONFIG_FS_CMD_SYS_INFO	1
CONFIG_FS_CMD_SYS_PANIC	1
CONFIG_FS_CMD_SYS_REBOOT	1
CONFIG_FS_CMD_SYS_RESET_CAUSE	1
CONFIG_FS_CMD_SYS_UPTIME	1
CONFIG_FS_CMD_THRD_LIST	1
CONFIG_FS_CMD_THRD_SET_LOG_MASK	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE	1
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID	1
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER	1
CONFIG_FS_CMD_USB_DEVICE_LIST	1
CONFIG_FS_CMD_USB_HOST_LIST	1

Continued on next page

Table 1.18 – continued from previous page

Name	Value
CONFIG_FS_PATH_MAX	64
CONFIG_HARNESS_EXPECT_BUFFER_SIZE	512
CONFIG_HARNESS_HEAP_MAX	2048
CONFIG_HARNESS MOCK_VERBOSE	1
CONFIG_HARNESS_SLEEP_MS	300
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE	128
CONFIG_HTTP_SERVER_SSL	0
CONFIG_I2C	1
CONFIG_I2C_SOFT	1
CONFIG_LED_7SEG_HT16K33	1
CONFIG_LINUX_SOCKET_DEVICE	0
CONFIG_MCP2515	0
CONFIG_MODULE_INIT_ADC	1
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN	1
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN	0
CONFIG_MODULE_INIT_BUS	1
CONFIG_MODULE_INIT_CAN	0
CONFIG_MODULE_INIT_CHAN	1
CONFIG_MODULE_INIT_CHIPID	0
CONFIG_MODULE_INIT_DAC	0
CONFIG_MODULE_INIT_DS18B20	1
CONFIG_MODULE_INIT_DS3231	1
CONFIG_MODULE_INIT_ESP_WIFI	1
CONFIG_MODULE_INIT_EXTI	1
CONFIG_MODULE_INIT_FLASH	1
CONFIG_MODULE_INIT_FS	1
CONFIG_MODULE_INIT_I2C	1
CONFIG_MODULE_INIT_I2C_SOFT	1
CONFIG_MODULE_INIT_INET	1
CONFIG_MODULE_INIT_LOG	1
CONFIG_MODULE_INIT_MCP2515	0
CONFIG_MODULE_INIT_NETWORK_INTERFACE	1
CONFIG_MODULE_INIT_NRF24L01	0
CONFIG_MODULE_INIT_OWI	1
CONFIG_MODULE_INIT_PIN	1
CONFIG_MODULE_INIT_PING	1
CONFIG_MODULE_INIT_PWM	0
CONFIG_MODULE_INIT_PWM_SOFT	1
CONFIG_MODULE_INIT_RANDOM	1
CONFIG_MODULE_INIT_RWLOCK	1
CONFIG_MODULE_INIT_SD	0
CONFIG_MODULE_INIT_SEM	1
CONFIG_MODULE_INIT_SETTINGS	1
CONFIG_MODULE_INIT_SOCKET	1
CONFIG_MODULE_INIT_SPI	1
CONFIG_MODULE_INIT_SSL	0
CONFIG_MODULE_INIT_STD	1
CONFIG_MODULE_INIT_THRD	1
CONFIG_MODULE_INIT_TIMER	1

Continued on next page

Table 1.18 – continued from previous page

Name	Value
CONFIG_MODULE_INIT_UART	1
CONFIG_MODULE_INIT_UART_SOFT	1
CONFIG_MODULE_INIT_UPGRADE	0
CONFIG_MODULE_INIT_USB	0
CONFIG_MODULE_INIT_USB_DEVICE	0
CONFIG_MODULE_INIT_USB_HOST	0
CONFIG_MODULE_INIT_WATCHDOG	0
CONFIG_MONITOR_THREAD	0
CONFIG_MONITOR_THREAD_PERIOD_US	2000000
CONFIG_NRF24L01	0
CONFIG_NVM_EEPROM_SOFT	0
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE	16384
CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE	(CONFIG_NVM_SIZE + 8)
CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX	0
CONFIG_NVM_SIZE	2040
CONFIG_OWI	1
CONFIG_PANIC_ASSERT	1
CONFIG_PIN	1
CONFIG_PREEMPTIVE_SCHEDULER	0
CONFIG_PROFILE_STACK	1
CONFIG_PWM	0
CONFIG_PWM_SOFT	1
CONFIG_RANDOM	1
CONFIG_SD	0
CONFIG_SETTINGS_AREA_SIZE	256
CONFIG_SETTINGS_BLOB	1
CONFIG_SHELL_COMMAND_MAX	64
CONFIG_SHELL_HISTORY_SIZE	768
CONFIG_SHELL_MINIMAL	0
CONFIG_SHELL_PROMPT	“\$ “
CONFIG_SHT3XD	1
CONFIG_SOAM_EMBEDDED_DATABASE	0
CONFIG_SOCKET_RAW	1
CONFIG_SOFTWARE_I2C	1
CONFIG_SPC5_BOOT_ENTRY_RCHW	1
CONFIG_SPC5_RAM_CLEAR_ALL	1
CONFIG_SPI	1
CONFIG_SPIFFS	1
CONFIG_START_CONSOLE	CONFIG_START_CONSOLE_UART
CONFIG_START_CONSOLE_DEVICE_INDEX	0
CONFIG_START_CONSOLE_UART_BAUDRATE	76800
CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE	32
CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE	0
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_IN	2
CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OUT	3
CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNECTION	1
CONFIG_START_FILESYSTEM	1
CONFIG_START_FILESYSTEM_ADDRESS	0x00300000

Continued on next page

Table 1.18 – continued from previous page

Name	Value
CONFIG_START_FILESYSTEM_SIZE	0xFB000
CONFIG_START_NETWORK	0
CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECT_TIMEOUT	30
CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD	MyWiFiPassword
CONFIG_START_NETWORK_INTERFACE_WIFI_SSID	MyWiFiSSID
CONFIG_START_NVM	1
CONFIG_START_SHELL	1
CONFIG_START_SHELL_PRIO	30
CONFIG_START_SHELL_STACK_SIZE	1536
CONFIG_START_SOAM	0
CONFIG_START_SOAM_PRIO	30
CONFIG_START_SOAM_STACK_SIZE	1536
CONFIG_STD_OUTPUT_BUFFER_MAX	16
CONFIG_SYSTEM_INTERRUPTS	1
CONFIG_SYSTEM_INTERRUPT_STACK_SIZE	0
CONFIG_SYSTEM_TICK_FREQUENCY	100
CONFIG_SYSTEM_TICK_SOFTWARE	1
CONFIG_SYS_CONFIG_STRING	1
CONFIG_SYS_LOG_MASK	LOG_UPTO(INFO)
CONFIG_SYS_PANIC_KICK_WATCHDOG	0
CONFIG_SYS_RESET_CAUSE	1
CONFIG_SYS_SIMBA_MAIN_STACK_MAX	4096
CONFIG_THRD_CPU_USAGE	1
CONFIG_THRD_DEFAULT_LOG_MASK	LOG_UPTO(INFO)
CONFIG_THRD_ENV	1
CONFIG_THRD_IDLE_STACK_SIZE	768
CONFIG_THRD_MONITOR_STACK_SIZE	768
CONFIG_THRD_SCHEDULED	1
CONFIG_THRD_STACK_HEAP	0
CONFIG_THRD_STACK_HEAP_SIZE	0
CONFIG_THRD_TERMINATE	1
CONFIG_TIME_UNIX_TIME_TO_DATE	1
CONFIG_UART	1
CONFIG_UART_SOFT	1
CONFIG_USB	0
CONFIG_USB_DEVICE	0
CONFIG_USB_DEVICE_PID	0x8037
CONFIG_USB_DEVICE_VID	0x2341
CONFIG_USB_HOST	0
CONFIG_WATCHDOG	0

Homepage

https://wiki.wemos.cc/products:d1:d1_mini

Mcu

esp8266

Examples

Below is a list of simple examples that are useful to understand the basics of *Simba*.

There are a lot more [examples](#) and [unit tests](#) on Github that shows how to use most of the *Simba* modules.

Analog Read

About

Read the value of an analog pin periodically once every second and print the read value to standard output.

Source code

```
/**
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 *
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 *
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 * CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
 * SOFTWARE.
 *
 * This file is part of the Simba project.
 */

#include "simba.h"

int main()
{
    int value;
    struct analog_input_pin_t pin;

    sys_start();
    analog_input_pin_module_init();

    /* Initialize the analog input pin. */
}
```

```
if (analog_input_pin_init(&pin, &pin_a0_dev) != 0) {
    std_printf(FSTR("Failed to initialize the analog input pin.\r\n"));
    return (-1);
}

while (1) {
    /* Read the analog pin value and print it. */
    value = analog_input_pin_read(&pin);
    std_printf(FSTR("value = %d\r\n"), value);

    /* Wait 100 ms. */
    thrd_sleep_ms(100);
}

return (0);
}
```

The source code can also be found on Github in the [examples/analog_read](#) folder.

Build and run

Build and run the application.

```
$ cd examples/analog_read
$ make -s BOARD=<board> run
value = 234
value = 249
value = 230
```

Analog Write

About

Write analog values to an analog output pin to form a sawtooth wave. Connect a LED to the analog output pin and watch the brightness of the LED change.

Source code

```
/**
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 * of the Software, and to permit persons to whom the Software is
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 *
 */
```



```

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* SOFTWARE.
*
* This file is part of the Simba project.
*/

#include "simba.h"

int main()
{
    int value;
    struct analog_output_pin_t pin;

    sys_start();
    analog_output_pin_module_init();

    /* Initialize the analog output pin. */
    analog_output_pin_init(&pin, &pin_d10_dev);

    value = 0;

    while (1) {
        /* Write a sawtooth wave to the analog output pin. */
        analog_output_pin_write(&pin, value);
        value += 5;
        value %= 1024;

        /* Wait ten milliseconds. */
        thrd_sleep_ms(10);
    }

    return (0);
}

```

The source code can also be found on Github in the [examples/analog_write](#) folder.

Build and run

Build and upload the application.

```

$ cd examples/analog_write
$ make -s BOARD=<board> upload

```

Blink

About

Turn a LED on and off periodically once a second. This example illustrates how to use digital pins and sleep a thread.

Source code

```
/**
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 *
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 * SOFTWARE.
 *
 * This file is part of the Simba project.
 */

#include "simba.h"

int main()
{
    struct pin_driver_t led;

    /* Start the system. */
    sys_start();

    /* Initialize the LED pin as output and set its value to 1. */
    pin_init(&led, &pin_led_dev, PIN_OUTPUT);
    pin_write(&led, 1);

    while (1) {
        /* Wait half a second. */
        thrd_sleep_ms(500);

        /* Toggle the LED on/off. */
        pin_toggle(&led);
    }
}
```

```
    return (0);
}
```

The source code can also be found on Github in the [examples/blink](#) folder.

Build and run

Build and upload the application.

```
$ cd examples/blink
$ make -s BOARD=<board> upload
```

DS18B20

About

Read and print the temperature measured with one or more DS18B20 sensors.

Source code

```
/**
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 *
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 * CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
 * SOFTWARE.
 *
 * This file is part of the Simba project.
 */

#include "simba.h"

int main()
```

```
{
    struct owi_driver_t owi;
    struct ds18b20_driver_t ds;
    struct owi_device_t devices[4];
    char temperature[16], *temperature_p;
    int number_of_sensors;
    int i;

    /* Initialization. */
    sys_start();
    ds18b20_module_init();
    owi_init(&owi, &pin_d7_dev, devices, membersof(devices));
    ds18b20_init(&ds, &owi);
    time_busy_wait_us(50000);

    /* Search for devices on the OWI bus. */
    number_of_sensors = owi_search(&owi);
    std_printf(FSTR("Number of sensors: %d\r\n"), number_of_sensors);

    while (1) {
        /* Take a new temperature sample. */
        ds18b20_convert(&ds);

        for (i = 0; i < owi.len; i++) {
            if (devices[i].id[0] != DS18B20_FAMILY_CODE) {
                continue;
            }

            temperature_p = ds18b20_get_temperature_str(&ds,
                                                         devices[i].id,
                                                         temperature);

            if (temperature_p == NULL) {
                temperature_p = "failed to get";
            }

            std_printf(FSTR("Device id: %02x %02x %02x %02x %02x %02x %02x %02x,"
                            " Temperature: %s\r\n"),
                      (unsigned int)devices[i].id[0],
                      (unsigned int)devices[i].id[1],
                      (unsigned int)devices[i].id[2],
                      (unsigned int)devices[i].id[3],
                      (unsigned int)devices[i].id[4],
                      (unsigned int)devices[i].id[5],
                      (unsigned int)devices[i].id[6],
                      (unsigned int)devices[i].id[7],
                      temperature_p);
        }
    }

    return (0);
}
```

The source code can also be found on Github in the [examples/ds18b20](#) folder.

Build and run

Build and run the application.

```
$ cd examples/ds18b20
$ make -s BOARD=<board> run
Number of sensors: 2
Device id: 28 9c 1d 5d 05 00 00 32, Temperature: 22.6250
Device id: 28 95 32 5d 05 00 00 33, Temperature: 22.6875
```

Filesystem

About

Create the file `counter.txt` and write 0 to it. Everytime the application is restarted the counter is incremented by one.

Source code

```
/**
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 *
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 * ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN
 * CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
 * SOFTWARE.
 *
 * This file is part of the Simba project.
 */

#include "simba.h"

#if !defined(BOARD_ARDUINO_DUE) && !defined(ARCH_ESP) && !defined(ARCH_ESP32)
# error "This example can only be built for Arduino Due, ESP and ESP32."
#endif
```

```
/**
 * Increment the counter in 'counter.txt'.
 */
static int increment_counter(void)
{
    char buf[32];
    struct fs_file_t file;
    long counter;
    size_t size;

    std_printf(FSTR("Incrementing the counter in 'counter.txt'.\r\n"));

    if (fs_open(&file, "counter.txt", FS_RDWR) != 0) {
        /* Create the file if missing. */
        if (fs_open(&file,
                    "counter.txt",
                    FS_CREAT | FS_TRUNC | FS_RDWR) != 0) {
            return (-1);
        }

        if (fs_write(&file, "0", 2) != 2) {
            return (-2);
        }

        if (fs_seek(&file, 0, FS_SEEK_SET) != 0) {
            return (-3);
        }
    }

    if (fs_read(&file, buf, 16) <= 0) {
        return (-4);
    }

    if (std_strtol(buf, &counter) == NULL) {
        return (-5);
    }

    /* Increment the counter. */
    counter++;
    std_sprintf(buf, FSTR("%lu"), counter);
    size = strlen(buf) + 1;

    if (fs_seek(&file, 0, FS_SEEK_SET) != 0) {
        return (-6);
    }

    if (fs_write(&file, buf, size) != size) {
        return (-7);
    }

    if (fs_close(&file) != 0) {
        return (-8);
    }

    std_printf(FSTR("Counter incremented to %lu\r\n"), counter);

    return (0);
}
```

```

int main()
{
    int res;

    sys_start();
    std_printf(sys_get_info());

    /* Increment the counter. */
    res = increment_counter();

    if (res != 0) {
        std_printf(FSTR("Failed to increment the counter with error %d.\r\n"),
                    res);
    }

    /* The shell thread is started in sys_start() so just suspend this
       thread. */
    thrd_suspend(NULL);

    return (0);
}

```

The source code can also be found on Github in the [examples/filesystem](#) folder.

Build and run

Build and run the application.

```

$ cd examples/filesystem
$ make -s BOARD=arduino_due upload

```

The output in the terminal emulator:

```

Incrementing the counter in 'counter.txt'.
Counter incremented to 1.
<manually reset the board>
Incrementing the counter in 'counter.txt'.
Counter incremented to 2.
<manually reset the board>
Incrementing the counter in 'counter.txt'.
Counter incremented to 3.

```

Hello World

About

This application prints “Hello world!” to standard output.

Source code

```

/**
 * @section License

```

```
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* CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
* SOFTWARE.
*
* This file is part of the Simba project.
*/

#include "simba.h"

int main()
{
    /* Start the system. */
    sys_start();

    std_printf(FSTR("Hello world!\r\n"));

    return (0);
}
```

The source code can also be found on [Github](#) in the `examples/hello_world` folder.

Build and run

Build and run the application.

```
$ cd examples/hello_world
$ make -s BOARD=<board> run
...
Hello world!
$
```

HTTP Client

About

Conenct to a remote host perform a HTTP GET action to fetch the root page '/' from the remote host.

Define `CONFIG_START_NETWORK_INTERFACE_WIFI_SSID` and `CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD` in `config.h` to the SSID and password of your WiFi, otherwise the board will fail to connect to the WiFi network. Alternatively, the defines can be given as defines on the make command line as seen in the example below.

Source code

```
/**
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 *
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 *
 * This file is part of the Simba project.
 */

#include "simba.h"

/* The ip address of the host to connect to. */
#define REMOTE_HOST_IP 216.58.211.142

int main()
{
    struct socket_t socket;
    char http_request[] =
        "GET / HTTP/1.1\r\n"
        "Host: " STRINGIFY(REMOTE_HOST_IP) "\r\n"
        "\r\n";
    char http_response[64];
    char remote_host_ip[] = STRINGIFY(REMOTE_HOST_IP);
    struct inet_addr_t remote_host_address;

    /* Start the system. Brings up the configured network interfaces
```

```

    and starts the TCP/IP-stack. */
sys_start();

/* Open the tcp socket. */
socket_open_tcp(&socket);

std_printf(FSTR("Connecting to '%s'.\r\n"), remote_host_ip);

if (inet_aton(remote_host_ip, &remote_host_address.ip) != 0) {
    std_printf(FSTR("Bad ip address '%s'.\r\n"), remote_host_ip);
    return (-1);
}

remote_host_address.port = 80;

if (socket_connect(&socket, &remote_host_address) != 0) {
    std_printf(FSTR("Failed to connect to '%s'.\r\n"), remote_host_ip);
    return (-1);
}

/* Send the HTTP request... */
if (socket_write(&socket,
                http_request,
                strlen(http_request)) != strlen(http_request)) {
    std_printf(FSTR("Failed to send the HTTP request.\r\n"));
    return (-1);
}

/* ...and receive the first 64 bytes of the response. */
if (socket_read(&socket,
                http_response,
                sizeof(http_response)) != sizeof(http_response)) {
    std_printf(FSTR("Failed to receive the response.\r\n"));
}

std_printf(FSTR("First 64 bytes of the response:\r\n"
                "%s"),
            http_response);

/* Close the socket. */
socket_close(&socket);

return (0);
}

```

The source code can also be found on Github in the [examples/http_client](#) folder.

Build and run

Build and run the application. It must be built for ESP12E or ESP01 since those are the only boards with a network connection (WiFi).

```

$ cd examples/http_client
$ make -s BOARD=esp12e CDEFS_EXTRA="CONFIG_START_NETWORK_INTERFACE_WIFI_SSID=Qvist_
↪CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD=FooBar" run
...
Connecting to WiFi with SSID 'Qvist'.

```

```

Connected to WiFi with SSID 'Qvist'. Got IP address '192.168.1.103'.
Connecting to '216.58.211.142'.
First 64 bytes of the response:
HTTP/1.1 301 Moved Permanently
Location: http://www.google.com/GET / HTTP/1.1
Host: 216.58.211.142
...
$

```

Ping

About

Ping a remote host periodically once every second.

Source code

```

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 *
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 * SOFTWARE.
 *
 * This file is part of the Simba project.
 */

#include "simba.h"

/* The ip address of the host to ping. */
#define REMOTE_HOST_IP 216.58.211.142

int main()
{

```

```
int res, attempt;
char remote_host_ip[] = STRINGIFY(REMOTE_HOST_IP);
struct inet_ip_addr_t remote_host_ip_address;
struct time_t round_trip_time, timeout;

sys_start();

if (inet_aton(remote_host_ip, &remote_host_ip_address) != 0) {
    std_printf(FSTR("Bad ip address '%s'.\r\n"), remote_host_ip);
    return (-1);
}

timeout.seconds = 3;
timeout.nanoseconds = 0;
attempt = 1;

/* Ping the remote host once every second. */
while (1) {
    res = ping_host_by_ip_address(&remote_host_ip_address,
                                &timeout,
                                &round_trip_time);

    if (res == 0) {
        std_printf(FSTR("Successfully pinged '%s' (%d).\r\n"),
                    remote_host_ip,
                    attempt);
    } else {
        std_printf(FSTR("Failed to ping '%s' (%d).\r\n"),
                    remote_host_ip,
                    attempt);
    }

    attempt++;
    thrd_sleep(1);
}

return (0);
}
```

The source code can also be found on Github in the [examples/ping](#) folder.

Build and run

Build and run the application.

```
$ cd examples/ping
$ make -s BOARD=<board> run
Successfully pinged '192.168.1.100' in 20 ms (#1).
Successfully pinged '192.168.1.100' in 20 ms (#2).
Successfully pinged '192.168.1.100' in 20 ms (#3).
```

Queue

About

Use a queue to communicate between two threads.

Source code

```
/**
 * @section License
 *
 * The MIT License (MIT)
 *
 * Copyright (c) 2014-2017, Erik Moqvist
 *
 * Permission is hereby granted, free of charge, to any person
 * obtaining a copy of this software and associated documentation
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 * restriction, including without limitation the rights to use, copy,
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 * ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN
 * CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
 * SOFTWARE.
 *
 * This file is part of the Simba project.
 */

#include "simba.h"

static struct queue_t queue;

static THRD_STACK(writer_stack, 256);

static void *writer_main(void *arg_p)
{
    int value;

    /* Write to the queue. */
    value = 1;
    queue_write(&queue, &value, sizeof(value));

    return (NULL);
}

int main()
{
    int value;
```

```
sys_start();
queue_init(&queue, NULL, 0);
thrd_spawn(writer_main, NULL, 0, writer_stack, sizeof(writer_stack));

/* Read from the queue. */
queue_read(&queue, &value, sizeof(value));

std_printf(FSTR("read value = %d\r\n"), value);

return (0);
}
```

The source code can also be found on Github in the [examples/queue](#) folder.

Build and run

Build and upload the application.

```
$ cd examples/queue
$ make -s BOARD=<board> run
read value = 1
```

Shell

About

Use the serial port to monitor and control the application.

Source code

```
/**
 * @section License
 *
 * The MIT License (MIT)
 *
 * Copyright (c) 2014-2017, Erik Moqvist
 *
 * Permission is hereby granted, free of charge, to any person
 * obtaining a copy of this software and associated documentation
 * files (the "Software"), to deal in the Software without
 * restriction, including without limitation the rights to use, copy,
 * modify, merge, publish, distribute, sublicense, and/or sell copies
 * of the Software, and to permit persons to whom the Software is
 * furnished to do so, subject to the following conditions:
 *
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 * MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND
 * NONINFRINGEMENT. IN NO EVENT SHALL THE AUTHORS OR COPYRIGHT HOLDERS
 * BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN
```

```

* ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN
* CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
* SOFTWARE.
*
* This file is part of the Simba project.
*/

#include "simba.h"

/* Hello world command. */
static struct fs_command_t cmd_hello_world;

static struct shell_t shell;

/**
 * The shell command callback for "/hello_world".
 */
static int cmd_hello_world_cb(int argc,
                              const char *argv[],
                              void *out_p,
                              void *in_p,
                              void *arg_p,
                              void *call_arg_p)
{
    /* Write "Hello World!" to the output channel. */
    std_fprintf(out_p, OSTR("Hello World!\r\n"));

    return (0);
}

int main()
{
    /* Start the system. */
    sys_start();

    std_printf(sys_get_info());

    /* Register the hello world command. */
    fs_command_init(&cmd_hello_world,
                   CSTR("/hello_world"),
                   cmd_hello_world_cb,
                   NULL);
    fs_command_register(&cmd_hello_world);

    /* Start the shell. */
    shell_init(&shell,
              sys_get_stdin(),
              sys_get_stdout(),
              NULL,
              NULL,
              NULL,
              NULL);
    shell_main(&shell);

    return (0);
}

```

The source code can also be found on Github in the [examples/shell](#) folder.

Build and run

Build and run the application.

```
$ cd examples/shell
$ make -s BOARD=<board> upload
```

Communicate with the board using a serial terminal emulator, for example *TeraTerm*.

Type `hello_world` in the terminal emulator and press Enter. `Hello World!` is printed.

Press Tab to print a list of all registered commands and try them if you want to.

```
$ hello_world
Hello World!
$ <tab>
drivers/
filesystems/
hello_world
help
history
kernel/
logout
oam/
$ kernel/thrd/list
      NAME      STATE  PRIO   CPU  MAX-STACK-USAGE  LOGMASK
      shell     current  0    0%      358/  5575      0x0f
      idle      ready   127   0%       57/   156      0x0f
$
```

Timer

About

Start a periodic timer that writes an event to the main thread. The main thread reads the event and prints “timeout” to the standard output.

Source code

```
/**
 * @section License
 *
 * The MIT License (MIT)
 *
 * Copyright (c) 2014-2017, Erik Moqvist
 *
 * Permission is hereby granted, free of charge, to any person
 * obtaining a copy of this software and associated documentation
 * files (the "Software"), to deal in the Software without
 * restriction, including without limitation the rights to use, copy,
 * modify, merge, publish, distribute, sublicense, and/or sell copies
 * of the Software, and to permit persons to whom the Software is
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 *
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```



```

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* BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN
* ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN
* CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
* SOFTWARE.
*
* This file is part of the Simba project.
*/

#include "simba.h"

#define TIMEOUT_EVENT    0x1

static struct event_t event;
static struct timer_t timer;

static void timer_cb(void *arg_p)
{
    uint32_t mask;

    mask = TIMEOUT_EVENT;
    event_write_isr(&event, &mask, sizeof(mask));
}

int main()
{
    uint32_t mask;
    struct time_t timeout;

    sys_start();
    event_init(&event);

    /* Initialize and start a periodic timer. */
    timeout.seconds = 1;
    timeout.nanoseconds = 0;
    timer_init(&timer, &timeout, timer_cb, NULL, TIMER_PERIODIC);
    timer_start(&timer);

    while (1) {
        mask = TIMEOUT_EVENT;
        event_read(&event, &mask, sizeof(mask));

        std_printf(FSTR("timeout\xr\n"));
    }

    return (0);
}

```

The source code can also be found on Github in the [examples/timer](#) folder.

Build and run

Build and upload the application.

```
$ cd examples/timer
$ make -s BOARD=<board> run
timeout
timeout
timeout
```

Library Reference

Simba's standard library is very extensive, offering a wide range of facilities as indicated by the long table of contents listed below. The library contains modules used by many developers in their everyday programming.

Besides the generated documentation, the source code of the interfaces and their implementations are available on [Github](#).

kernel

The kernel package is the heart in *Simba*. It implements the thread scheduler.

The kernel package on [Github](#).

assert — Assertions

Source code: [src/kernel/assert.h](#)

Defines

FATAL (n) (-n)

IS_FATAL (n) (n < 0)

Check if an error code is fatal (negative error code).

ASSERT (cond, ...) ASSERTNR(cond, EASSERT, FATAL(EASSERT), __VA_ARGS__)

Assert given condition and print an error message on assertion failure. Call the system on fatal callback with error code EASSERT on fatal error, otherwise return NULL.

ASSERTN (cond, n, ...) ASSERTNR(cond, n, FATAL(n), __VA_ARGS__)

Assert given condition and print an error message on assertion failure. Call the system on fatal callback with given error code n on fatal error, otherwise return the error code negated.

ASSERTRV (cond, ...) ASSERTNRV(cond, EASSERT, __VA_ARGS__)

Assert given condition and print an error message on assertion failure. Call the system on fatal callback with error code EASSERT on fatal error, otherwise return NULL.

ASSERTRN (cond, ...) ASSERTNR(cond, EASSERT, NULL, __VA_ARGS__)

Assert given condition and print an error message on assertion failure. Call the system on fatal callback with error code EASSERT on fatal error, otherwise return NULL.

ASSERTNR (cond, n, ...)

Assert given condition and print an error message. Call the system on fatal callback with given error code `n` on fatal error, otherwise return given error code `res`.

ASSERTNRV (cond, n, ...)

Assert given condition and print an error message on assertion failure. Call the system on fatal callback with given error code `n` on fatal error, otherwise return.

ASSERTNRN (cond, n, ...) **ASSERTNR**(cond, n, NULL, __VA_ARGS__)

Assert given condition and print an error message on assertion failure. Call the system on fatal callback with given error code `n` on fatal error, otherwise return NULL.

FATAL_ASSERTN (cond, n, ...)

Assert given condition and print an error message on assertion failure, then call the system on fatal callback with given error code `n`.

This assertion is not affected by `CONFIG_ASSERT`, but instead `CONFIG_FATAL_ASSERT`.

FATAL_ASSERT (cond, ...) **FATAL_ASSERTN**(cond, EASSERT, __VA_ARGS__)

Assert given condition and print an error message on assertion failure, then call the system on fatal callback with error code `EASSERT`.

This assertion is not affected by `CONFIG_ASSERT`, but instead `CONFIG_FATAL_ASSERT`.

PANIC_ASSERTN (cond, n, ...)

Assert given condition and call `sys_panic()` with given error code `n` on assertion failure.

This assertion is not affected by `CONFIG_ASSERT`, but instead `CONFIG_PANIC_ASSERT`.

PANIC_ASSERT (cond, ...) **PANIC_ASSERTN**(cond, EASSERT, __VA_ARGS__)

Assert given condition and call `sys_panic()` with error code `EASSERT`.

This assertion is not affected by `CONFIG_ASSERT`, but instead `CONFIG_PANIC_ASSERT`.

errno — Error numbers

Source code: <src/kernel/errno.h>

Defines**EPERM** 1**ENOENT** 2

No such file or directory.

ESRCH 3

No such process.

EINTR 4

Interrupted system call.

EIO 5

I/O error.

ENXIO 6

No such device or address.

E2BIG 7

Argument list too long.

ENOEXEC 8
Exec format error.

EBADF 9
Bad file number.

ECHILD 10
No child processes.

EAGAIN 11
Try again.

ENOMEM 12
Out of memory.

EACCES 13
Permission denied.

EFAULT 14
Bad address.

ENOTBLK 15
Block device required.

EBUSY 16
Device or resource busy.

EEXIST 17
File exists.

EXDEV 18
Cross-device link.

ENODEV 19
No such device.

ENOTDIR 20
Not a directory.

EISDIR 21
Is a directory.

EINVAL 22
Invalid argument.

ENFILE 23
File table overflow.

EMFILE 24
Too many open files.

ENOTTY 25
Not a typewriter.

ETXTBSY 26
Text file busy.

EFBIG 27
File too large.

ENOSPC 28
No space left on device.

ESPIPE 29
Illegal seek.

EROFS 30
Read-only file system.

EMLINK 31
Too many links.

EPIPE 32
Broken pipe.

EDOM 33
Math argument out of domain of func.

ERANGE 34
Math result not representable.

EDEADLK 35
Resource deadlock would occur.

ENAMETOOLONG 36
File name too long.

ENOLCK 37
No record locks available.

ENOSYS 38
Function not implemented.

ENOTEMPTY 39
Directory not empty.

ELOOP 40
Too many symbolic links encountered.

EWouldBlock EAGAIN
Operation would block.

ENOMSG 42
No message of desired type.

EIDRM 43
Identifier removed.

ECHRNG 44
Channel number out of range.

EL2NSYNC 45
Level 2 not synchronized.

EL3HLT 46
Level 3 halted.

EL3RST 47
Level 3 reset.

ELNRNG 48
Link number out of range.

EUNATCH 49
Protocol driver not attached.

ENOC SI 50
No CSI structure available.

EL2HLT 51
Level 2 halted.

EBAD E 52
Invalid exchange.

EBADR 53
Invalid request descriptor.

EXFULL 54
Exchange full.

ENOANO 55
No anode.

EBADRQC 56
Invalid request code.

EBADSLT 57
Invalid slot.

EDEADLOCK EDEADLK
Deadlock.

EBFONT 59
Bad font file format.

ENOSTR 60
Device not a stream.

ENODATA 61
No data available.

ETIME 62
Timer expired.

ENOSR 63
Out of streams resources.

ENONET 64
Machine is not on the network.

ENOPKG 65
Package not installed.

EREMOTE 66
Object is remote.

ENOLINK 67
Link has been severed.

EADV 68
Advertise error.

ESRMNT 69
Srmount error.

ECOMM 70
Communication error on send.

EPROTO 71	Protocol error.
EMULTIHOP 72	Multihop attempted.
EDOTDOT 73	RFS specific error.
EBADMSG 74	Not a data message.
EOVERFLOW 75	Value too large for defined data type.
ENOTUNIQ 76	Name not unique on network.
EBADFD 77	File descriptor in bad state.
EREMCHG 78	Remote address changed.
ELIBACC 79	Can not access a needed shared library.
ELIBBAD 80	Accessing a corrupted shared library.
ELIBSCN 81	.lib section in a.out corrupted.
ELIBMAX 82	Attempting to link in too many shared libraries.
ELIBEXEC 83	Cannot exec a shared library directly.
EILSEQ 84	Illegal byte sequence.
ERESTART 85	Interrupted system call should be restarted.
ESTRPIPE 86	Streams pipe error.
EUSERS 87	Too many users.
ENOTSOCK 88	Socket operation on non-socket.
EDESTADDRREQ 89	Destination address required.
EMSGSIZE 90	Message too long.
EPROTOTYPE 91	Protocol wrong type for socket.

ENOPROTOOPT 92
Protocol not available.

EPROTONOSUPBOARD 93
Protocol not supported.

ESOCKTNOSUPBOARD 94
Socket type not supported.

EOPNOTSUPP 95
Operation not supported on transport endpoint.

EPFNOSUPBOARD 96
Protocol family not supported.

EAFNOSUPBOARD 97
Address family not supported by protocol.

EADDRINUSE 98
Address already in use.

EADDRNOTAVAIL 99
Cannot assign requested address.

ENETDOWN 100
Network is down.

ENETUNREACH 101
Network is unreachable.

ENETRESET 102
Network dropped connection because of reset.

ECONNABORTED 103
Software caused connection abort.

ECONNRESET 104
Connection reset by peer.

ENOBUFS 105
No buffer space available.

EISCONN 106
Transport endpoint is already connected.

ENOTCONN 107
Transport endpoint is not connected.

ESHUTDOWN 108
Cannot send after transport endpoint shutdown.

ETOOMANYREFS 109
Too many references: cannot splice.

ETIMEDOUT 110
Connection timed out.

ECONNREFUSED 111
Connection refused.

EHOSTDOWN 112
Host is down.

EHOSTUNREACH 113
No route to host.

EALREADY 114
Operation already in progress.

EINPROGRESS 115
Operation now in progress.

ESTALE 116
Stale NFS file handle.

EUCLEAN 117
Structure needs cleaning.

ENOTNAM 118
Not a XENIX named type file.

ENAVAIL 119
No XENIX sems available.

EISNAM 120
Is a named type file.

EREMOTEIO 121
Remote I/O error.

EDQUOT 122
Quota exceeded.

ENOMEDIUM 123
No medium found.

EMEDIUMTYPE 124
Wrong medium type.

ECANCELED 125
Operation Canceled.

ENOKEY 126
Required key not available.

EKEYEXPIRED 127
Key has expired.

EKEYREVOKED 128
Key has been revoked.

EKEYREJECTED 129
Key was rejected by service.

ESTACK 1000
Stack corrupt.

EBTASSERT 1001
Test assertion.

EASSERT 1002
Assertion.

ENOCOMMAND 1003
Command not found.

sys — System

System level functionality and definitions.

Source code: [src/kernel/sys.h](#), [src/kernel/sys.c](#)

Test code: [tst/kernel/sys/main.c](#)

Test coverage: [src/kernel/sys.c](#)

Defines

VERSION_STR `STRINGIFY(VERSION)`

SYS_TICK_MAX `((sys_tick_t)-1)`

Typedefs

`typedef uint32_t sys_tick_t`

`typedef uint32_t cpu_usage_t`

`typedef void(* sys_on_fatal_fn_t) (int error) __attribute__((noreturn))`

Enums

`enum sys_reset_cause_t`

System reset causes.

Values:

`sys_reset_cause_unknown_t = 0`

`sys_reset_cause_power_on_t`

`sys_reset_cause_watchdog_timeout_t`

`sys_reset_cause_software_t`

`sys_reset_cause_external_t`

`sys_reset_cause_jtag_t`

`sys_reset_cause_max_t`

Functions

`static sys_tick_t t2st (const struct time_t *time_p)`

Conversion from the time struct to system ticks.

`static void st2t (sys_tick_t tick, struct time_t *time_p)`

Conversion from system ticks to the time struct.

int **sys_module_init** (void)

Initialize the sys module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **sys_start** (void)

Start the system and convert this context to the main thread.

This function initializes a bunch of enabled features in the simba platform. Many low level features (scheduling, timers, ...) are always enabled, but higher level features are only enabled if configured.

This function **must** be the first function call in main().

Return zero(0) or negative error code.

void **sys_stop** (int *error*)

Stop the system.

Return Never returns.

Parameters

- *error*: Error code.

void **sys_panic** (const char **message_p*)

System panic. Write given message, a backtrace and other port specific debug information to the console and then reboot the system.

This function may be called from interrupt context and with the system lock taken.

Return Never returns.

Parameters

- *message_p*: Panic message to write to the console.

void **sys_reboot** (void)

Reboot the system. Also known as a soft reset.

Return Never returns.

int **sys_backtrace** (void ***buf_p*, size_t *size*)

Store the backtrace in given buffer.

Return Backtrace depth.

Parameters

- *buf_p*: Buffer to store the backtrace in.
- *size*: Size of the buffer.

enum *sys_reset_cause_t* **sys_reset_cause** (void)

Get the system reset cause.

Return The reset cause.

int **sys_uptime** (struct *time_t* *uptime_p)
Get the system uptime.

Return zero(0) or negative error code.

Parameters

- uptime_p: System uptime.

int **sys_uptime_isr** (struct *time_t* *uptime_p)
Get the system uptime from interrupt context or with the system lock taken.

Return zero(0) or negative error code.

Parameters

- uptime_p: System uptime.

void **sys_set_on_fatal_callback** (sys_on_fatal_fn_t callback)
Set the on-fatal-callback function to given callback.

The on-fatal-callback is called when a fatal error occurs. The default on-fatal-callback is `sys_stop()`.

Return void

Parameters

- callback: Callback called when a fatal error occurs.

void **sys_set_stdin** (void *chan_p)
Set the standard input channel.

Return void.

Parameters

- chan_p: New standard input channel.

void ***sys_get_stdin** (void)
Get the standard input channel.

Return Standard input channel.

void **sys_set_stdout** (void *chan_p)
Set the standard output channel.

Return void.

Parameters

- chan_p: New standard output channel.

void ***sys_get_stdout** (void)
Get the standard output channel.

Return Standard output channel.

void **sys_lock** (void)
Take the system lock. Turns off interrupts.

Return void.

void **sys_unlock** (void)

Release the system lock. Turn on interrupts.

Return void.

void **sys_lock_isr** (void)

Take the system lock from isr. In many ports this has no effect.

Return void.

void **sys_unlock_isr** (void)

Release the system lock from isr. In many ports this function has no effect.

Return void.

far_string_t **sys_get_info** (void)

Get a pointer to the application information string.

The buffer contains various information about the application; for example the application name and the build date.

Return The pointer to the application information string.

far_string_t **sys_get_config** (void)

Get a pointer to the application configuration string.

The buffer contains a string of all configuration variables and their values.

Return The pointer to the application configuration string.

cpu_usage_t **sys_interrupt_cpu_usage_get** (void)

Get the current interrupt cpu usage counter.

Return cpu usage, 0-100.

void **sys_interrupt_cpu_usage_reset** (void)

Reset the interrupt cpu usage counter.

Variables

const char ***sys_reset_cause_string_map**[sys_reset_cause_max_t]

System reset cause strings map.

struct *sys_t* **sys**

struct **sys_t**

Public Members

```
sys_on_fatal_fn_t on_fatal_callback
void *stdin_p
void *stdout_p
uint32_t start
uint32_t time
struct sys_t::@71 sys_t::interrupt
```

thrd — Threads

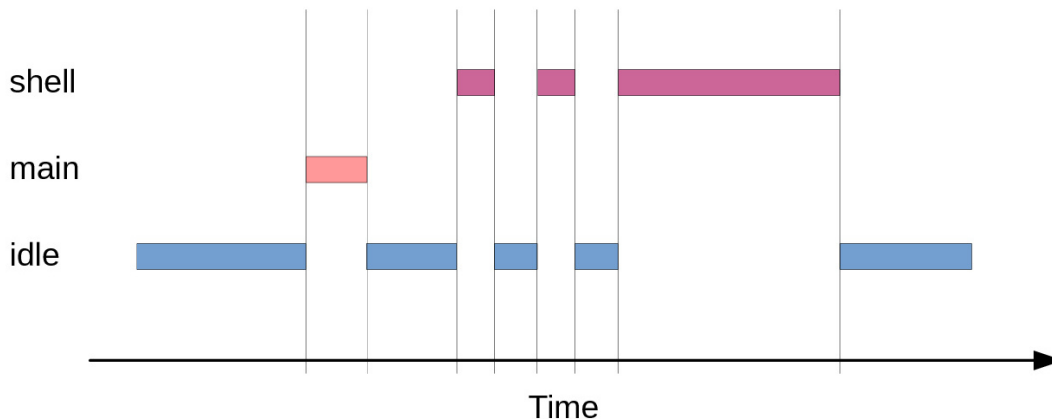
A thread is the basic execution entity in the OS. A pre-emptive or cooperative scheduler controls the execution of threads.

Scheduler

The single core scheduler is configured as cooperative or preemptive at compile time. The cooperative scheduler is implemented for all boards, but the preemptive scheduler is only implemented for a few boards.

There are two threads that are always present; the main thread and the idle thread. The main thread is the root thread in the system, created in the `main()` function by calling `sys_start()`. The idle thread is running when no other thread is ready to run. It simply waits for an interrupt to occur and then reschedules to run other ready threads.

The diagram below is an example of how three threads; `shell`, `main` and `idle` are scheduled over time.



As it is a single core scheduler only one thread is running at a time. In the beginning the system is idle and the `idle` thread is running. After a while the `main` and `shell` threads have some work to do, and since they have higher priority than the `idle` thread they are scheduled. At the end the `idle` thread is running again.

Debug file system commands

Four debug file system commands are available, all located in the directory `kernel/thrd/`.

Command	Description
<code>list</code>	Print a list of all threads.
<code>set_log_mask <thread name> <mask></code>	Set the log mask of thread <thread name> to mask.
<code>monitor/set_period_ms <ms></code>	Set the monitor thread sampling period to <ms> milliseconds.
<code>monitor/set_print <state></code>	Enable(1)/disable(0) monitor statistics to be printed periodically.

Example output from the shell:

\$ <code>kenel/thrd/list</code>						
	NAME	STATE	PRIO	CPU	SCHEDULED	LOGMASK
	main	current	0	0%	1	0x0f
		ready	127	0%	0	0x0f
		ready	-80	0%	0	0x0f

Source code: [src/kernel/thrd.h](#), [src/kernel/thrd.c](#)

Test code: [tst/kernel/thrd/main.c](#)

Test coverage: [src/kernel/thrd.c](#)

Defines

THRD_STACK (name, size) **THRD_PORT_STACK**(name, size)

THRD_CONTEXT_STORE_ISR **THRD_PORT_CONTEXT_STORE_ISR**

Push all callee-save registers not part of the context struct. The preemptive scheduler requires this macro before the `thrd_yield_isr()` function is called from interrupt context.

THRD_CONTEXT_LOAD_ISR **THRD_PORT_CONTEXT_LOAD_ISR**

Pop all callee-save registers not part of the context struct. The preemptive scheduler requires this macro after the `thrd_yield_isr()` function is called from interrupt context.

THRD_RESCHEDULE_ISR `do { \ THRD_CONTEXT_STORE_ISR; \ thrd_yield_isr(); \ THRD_CONTEXT_LOAD_ISR; \ } while (0)`
Reschedule from isr. Used by preemptive systems to interrupt low priority threads in favour of high priority threads.

Functions

`int` **thrd_module_init** (void)

Initialize the thread module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code

struct *thrd_t* ***thrd_spawn** (void *(*main)) void *

, void **arg_p*, int *prio*, void **stack_p*, size_t *stack_size* Spawn a thread with given main (entry) function and argument. The thread is initialized and added to the ready queue in the scheduler for execution when prioritized.

Return Thread id, or NULL on error.

Parameters

- `main`: Thread main (entry) function. This function normally contains an infinite loop waiting for events to occur.
- `arg_p`: Main function argument. Passed as `arg_p` to the main function.
- `prio`: Thread scheduling priority. [-127..127], where -127 is the highest priority and 127 is the lowest.
- `stack_p`: Stack pointer. The pointer to a stack created with the macro `THRD_STACK()`.
- `stack_size`: The stack size in number of bytes.

int **thrd_suspend** (const struct *time_t* **timeout_p*)

Suspend current thread and wait to be resumed or a timeout occurs (if given).

Return zero(0), -ETIMEDOUT on timeout or other negative error code.

Parameters

- `timeout_p`: Time to wait to be resumed before a timeout occurs and the function returns.

int **thrd_resume** (struct *thrd_t* **thrd_p*, int *err*)

Resume given thread. If resumed thread is not yet suspended it will not be suspended on next suspend call to `thrd_suspend()` or `thrd_suspend_isr()`.

Return zero(0) or negative error code.

Parameters

- `thrd_p`: Thread id to resume.
- `err`: Error code to be returned by `thrd_suspend()` or `thrd_suspend_isr()`.

int **thrd_yield** (void)

Put the currently executing thread on the ready list and reschedule.

This function is often called periodically from low priority work heavy threads to give higher priority threads the chance to execute.

Return zero(0) or negative error code.

int **thrd_join** (struct *thrd_t* **thrd_p*)

Wait for given thread to terminate.

Return zero(0) or negative error code.

Parameters

- `thrd_p`: Thread to wait for.

int **thrd_sleep** (float *seconds*)

Pauses the current thread for given number of seconds.

Return zero(0) or negative error code.

Parameters

- `seconds`: Seconds to sleep.

int **thrd_sleep_ms** (int *ms*)

Pauses the current thread for given number of milliseconds.

Return zero(0) or negative error code.

Parameters

- *ms*: Milliseconds to sleep.

int **thrd_sleep_us** (long *us*)

Pauses the current thread for given number of microseconds.

Return zero(0) or negative error code.

Parameters

- *us*: Microseconds to sleep.

struct *thrd_t* ***thrd_self** (void)

Get current thread's id.

Return Thread id.

int **thrd_set_name** (const char **name_p*)

Set the name of the current thread.

Return zero(0) or negative error code.

Parameters

- *name_p*: New thread name.

const char ***thrd_get_name** (void)

Get the name of the current thread.

Return Current thread name.

struct *thrd_t* ***thrd_get_by_name** (const char **name_p*)

Get the pointer to given thread.

Return Thread pointer or NULL if the thread was not found.

int **thrd_set_log_mask** (struct *thrd_t* **thrd_p*, int *mask*)

Set the log mask of given thread.

Return Old log mask.

Parameters

- *thrd_p*: Thread to set the log mask of.
- *mask*: Log mask. See the log module for available levels.

int **thrd_get_log_mask** (void)

Get the log mask of the current thread.

Return Log mask of current thread.

int **thrd_set_prio** (struct *thrd_t* **thrd_p*, int *prio*)

Set the priority of given thread.

Return zero(0) or negative error code.

Parameters

- *thrd_p*: Thread to set the priority for.
- *prio*: Priority.

int **thrd_get_prio** (void)

Get the priority of the current thread.

Return Priority of current thread.

int **thrd_init_global_env** (struct *thrd_environment_variable_t* **variables_p*, int *length*)

Initialize the global environment variables storage. These variables are shared among all threads.

Return zero(0) or negative error code.

Parameters

- *variables_p*: Variables array.
- *length*: Length of the variables array.

int **thrd_set_global_env** (const char **name_p*, const char **value_p*)

Set the value of given environment variable. The pointers to given name and value are stored in the current global environment array.

Return zero(0) or negative error code.

Parameters

- *name_p*: Name of the environment variable to set.
- *value_p*: Value of the environment variable. Set to NULL to remove the variable.

const char ***thrd_get_global_env** (const char **name_p*)

Get the value of given environment variable in the global environment array.

Return Value of given environment variable or NULL if it is not found.

Parameters

- *name_p*: Name of the environment variable to get.

int **thrd_init_env** (struct *thrd_environment_variable_t* **variables_p*, int *length*)

Initialize the current threads' environment variables storage.

Return zero(0) or negative error code.

Parameters

- *variables_p*: Variables are to be used by this thread.
- *length*: Length of the variables array.

int **thrd_set_env** (const char *name_p, const char *value_p)

Set the value of given environment variable. The pointers to given name and value are stored in the current threads' environment array.

Return zero(0) or negative error code.

Parameters

- name_p: Name of the environment variable to set.
- value_p: Value of the environment variable. Set to NULL to remove the variable.

const char ***thrd_get_env** (const char *name_p)

Get the value of given environment variable. If given variable is not found in the current threads' environment array, the global environment array is searched.

Return Value of given environment variable or NULL if it is not found.

Parameters

- name_p: Name of the environment variable to get.

int **thrd_suspend_isr** (const struct *time_t* *timeout_p)

Suspend current thread with the system lock taken (see `sys_lock()`) and wait to be resumed or a timeout occurs (if given).

Return zero(0), -ETIMEDOUT on timeout or other negative error code.

Parameters

- timeout_p: Time to wait to be resumed before a timeout occurs and the function returns.

int **thrd_resume_isr** (struct *thrd_t* *thrd_p, int err)

Resume given thread from isr or with the system lock taken (see `sys_lock()`). If resumed thread is not yet suspended it will not be suspended on next suspend call to `thrd_suspend()` or `thrd_suspend_isr()`.

Return zero(0) or negative error code.

Parameters

- thrd_p: Thread id to resume.
- err: Error code to be returned by `thrd_suspend()` or `thrd_suspend_isr()`.

int **thrd_yield_isr** (void)

Yield current thread from isr (preemptive scheduler only) or with the system lock taken.

Return zero(0) or negative error code.

void ***thrd_stack_alloc** (size_t size)

Allocate a thread stack of given size.

Return The pointer to allocated thread stack, or NULL on error.

int **thrd_stack_free** (void *stack_p)

Free given thread stack.

Return zero(0) or negative error code.

const void ***thrd_get_bottom_of_stack** (struct *thrd_t* *thrd_p)

Get the pointer to given threads' bottom of stack.

Return The pointer to given threads' bottom of stack, or NULL on error.

const void ***thrd_get_top_of_stack** (struct *thrd_t* *thrd_p)

Get the pointer to given threads' top of stack.

Return The pointer to given threads' top of stack, or NULL on error.

int **thrd_prio_list_init** (struct *thrd_prio_list_t* *self_p)

Initialize given prio list.

void **thrd_prio_list_push_isr** (struct *thrd_prio_list_t* *self_p, struct *thrd_prio_list_elem_t* *elem_p)

Push given element on given priority list. The priority list is a linked list with the highest priority thread first. The pushed element is added *after* any already pushed elements with the same thread priority.

Return void.

Parameters

- self_p: Priority list to push on.
- elem_p: Element to push.

struct *thrd_prio_list_elem_t* ***thrd_prio_list_pop_isr** (struct *thrd_prio_list_t* *self_p)

Pop the highest priority element from given priority list.

Return Popped element or NULL if the list was empty.

Parameters

- self_p: Priority list to pop from.

int **thrd_prio_list_remove_isr** (struct *thrd_prio_list_t* *self_p, struct *thrd_prio_list_elem_t* *elem_p)

Remove given element from given priority list.

Return zero(0) or negative error code.

Parameters

- self_p: Priority list to remove given element from.
- elem_p: Element to remove.

struct **thrd_environment_variable_t**
#include <thrd.h> A thread environment variable.

Public Members

const char ***name_p**

const char ***value_p**

struct **thrd_environment_t**

Public Members

```

struct thrd_environment_variable_t *variables_p
size_t number_of_variables
size_t max_number_of_variables

```

```

struct thrd_t

```

Public Members

```

struct thrd_prio_list_elem_t elem
struct thrd_t::@72  thrd_t::scheduler
struct thrd_port_t port
int prio
int state
int err
int log_mask
struct timer_t *timer_p
const char *name_p
struct thrd_t *next_p
struct thrd_t::@73  thrd_t::statistics
size_t stack_size

```

time — System time

Source code: [src/kernel/time.h](#), [src/kernel/time.c](#)

Test code: [tst/kernel/time/main.c](#)

Test coverage: [src/kernel/time.c](#)

Functions

```

int time_get (struct time_t *now_p)

```

Get current time in seconds and nanoseconds. The resolution of the time is implementation specific and may vary a lot between different architectures.

Return zero(0) or negative error code.

Parameters

- now_p: Read current time.

```

int time_set (struct time_t *new_p)

```

Set current time in seconds and nanoseconds.

Return zero(0) or negative error code.

Parameters

- `new_p`: New current time.

int **time_add** (struct *time_t* *`res_p`, struct *time_t* *`left_p`, struct *time_t* *`right_p`)

Add given times.

Return zero(0) or negative error code.

Parameters

- `res_p`: The result of the adding `left_p` to `right_p`.
- `left_p`: First operand.
- `right_p`: Second operand.

int **time_subtract** (struct *time_t* *`res_p`, struct *time_t* *`left_p`, struct *time_t* *`right_p`)

Subtract given times.

Return zero(0) or negative error code.

Parameters

- `res_p`: The result of the subtrantcing `left_p` from `right_p`.
- `left_p`: The operand to subtract from.
- `right_p`: The operand to subtract.

void **time_busy_wait_us** (long *useconds*)

Busy wait for given number of microseconds.

NOTE: The maximum allowed time to sleep is target specific.

Return void

Parameters

- `useconds`: Microseconds to busy wait.

int **time_unix_time_to_date** (struct *date_t* *`date_p`, struct *time_t* *`time_p`)

Convert given unix time to a date.

Return zero(0) or negative error code.

Parameters

- `date_p`: Converted time.
- `time_p`: Unix time to convert.

struct **time_t**

#include <time.h>

Public Members

`int32_t seconds`
Number of seconds.

`int32_t nanoseconds`
Number of nanoseconds.

`struct date_t`
#include <time.h> A date in year, month, date, day, hour, minute and seconds.

Public Members

`int second`
Second [0..59].

`int minute`
Minute [0..59].

`int hour`
Hour [0..23].

`int day`
Weekday [1..7], where 1 is Monday and 7 is Sunday.

`int date`
Day in month [1..31]

`int month`
Month [1..12] where 1 is January and 12 is December.

`int year`
Year [1970..].

timer — Timers

Timers are started with a timeout, and when the time is up the timer expires and the timer callback function is called from interrupt context.

The timeout resolution is the system tick period. Timeouts are always rounded up to the closest system tick. That is, a timer can never expire early, but may expire slightly late.

An application requiring timers with higher precision than the system tick must use the hardware timers.

Source code: [src/kernel/timer.h](#), [src/kernel/timer.c](#)

Test code: [tst/kernel/timer/main.c](#)

Test coverage: [src/kernel/timer.c](#)

Defines

`TIMER_PERIODIC` 0x1

Typedefs

typedef void (***timer_callback_t**) (void *arg_p)
Time callback prototype.

Functions

int timer_module_init (void)
Initialize the timer module. This function must be called before calling any other function in this module.
The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int timer_init (struct *timer_t* *self_p, const struct *time_t* *timeout_p, *timer_callback_t* callback, void *arg_p, int flags)
Initialize given timer object with given timeout and expiry callback. The timer resolution directly depends on the system tick frequency and is rounded up to the closest possible value. This applies to both single shot and periodic timers.

Return zero(0) or negative error code.

Parameters

- self_p: Timer object to initialize with given parameters.
- timeout_p: The timer timeout value.
- callback: Function called when the timer expires. Called from interrupt context.
- arg_p: Function callback argument. Passed to the callback when the timer expires.
- flags: Set `TIMER_PERIODIC` for periodic timer.

int timer_start (struct *timer_t* *self_p)
Start given initialized timer object.

Return zero(0) or negative error code.

Parameters

- self_p: Timer object to start.

int timer_start_isr (struct *timer_t* *self_p)
See `timer_start()` for a description.

This function may only be called from an isr or with the system lock taken (see `sys_lock()`).

int timer_stop (struct *timer_t* *self_p)
Stop given timer object. This has no effect on a timer that already expired or was never started.

Return true(1) if the timer was stopped, false(0) if the timer already expired or was never started, and otherwise negative error code.

Parameters

- self_p: Timer object to stop.

int **timer_stop_isr** (struct *timer_t* *self_p)
 See `timer_stop()` for description.

This function may only be called from an isr or with the system lock taken (see `sys_lock()`).

struct timer_t

Public Members

struct *timer_t* *next_p
sys_tick_t delta
sys_tick_t timeout
 int flags
timer_callback_t callback
 void *arg_p

types — Common types

Source code: [src/kernel/types.h](#)

Defines

UNUSED (v) (void)(v)

STRINGIFY (x) STRINGIFY2(x)
 Create a string of an identifier using the pre-processor.

STRINGIFY2 (x) #x
 Used internally by `STRINGIFY()`.

TOKENPASTE (x, y) TOKENPASTE2(x, y)
 Concatenate two tokens.

TOKENPASTE2 (x, y) x ## y
 Used internally by `TOKENPASTE()`.

UNIQUE (x) TOKENPASTE(x, TOKENPASTE(__, __LINE__))
 Create a unique token.

PRINT_FILE_LINE std_printf(OSTR(“%s:%d:\r\n”), __FILE__, __LINE__);
 Debug print of file and line.

STD_PRINTF_DEBUG (...)

membersof (a) ((ssize_t)(sizeof(a) / sizeof((a)[0])))
 Get the number of elements in an array.

As an example, the code below outputs number of members in `foo = 10`.

```
int foo[10];

std_printf(FSTR("number of members in foo = %d\\r\\n"),
           membersof(foo));
```

```
container_of (ptr, type, member) ({ \ const typeof( ((type *)0)->member ) *__mptr = (ptr); \ (type *)(  
    (char *)__mptr - offsetof(type,member) );})
```

```
DIV_CEIL (n, d) (((n) + (d) - 1) / d)  
Integer division that rounds the result up.
```

```
DIV_ROUND (n, d) (((n) + (d / 2)) / d)  
Integer division that rounds the result to the closest integer.
```

```
MIN (a, b) (((a) < (b)) ? (a) : (b))  
Get the minimum value of the two.
```

```
MAX (a, b) (((a) > (b)) ? (a) : (b))  
Get the maximum value of the two.
```

```
BIT (pos) (1 << (pos))
```

```
BITFIELD_SET (name, value) (((value) << name ## _POS) & name ## _MASK)
```

```
BITFIELD_GET (name, value) (((value) & name ## _MASK) >> name ## _POS)
```

```
OSTR (string) FSTR(string)
```

```
CSTR (string) FSTR(string)
```

Typedefs

```
typedef uint8_t u8_t
```

```
typedef int8_t s8_t
```

```
typedef uint16_t u16_t
```

```
typedef int16_t s16_t
```

```
typedef uint32_t u32_t
```

```
typedef int32_t s32_t
```

```
struct thrd_prio_list_elem_t
```

Public Members

```
struct thrd_prio_list_elem_t *next_p
```

```
struct thrd_t *thrd_p
```

```
struct thrd_prio_list_t
```

Public Members

```
struct thrd_prio_list_elem_t *head_p
```

sync

Thread synchronization refers to the idea that multiple threads are to join up or handshake at a certain point, in order to reach an agreement or commit to a certain sequence of action.

The sync package on [Github](#).

int **bus_listener_init** (struct *bus_listener_t* *self_p, int id, void *chan_p)

Initialize given listener to receive messages with given id, after the listener is attached to the bus. A listener can only receive messages of a single id, though, the same channel may be used in multiple listeners with different ids (if the channel supports it).

Return zero(0) or negative error code.

Parameters

- self_p: Listener to initialize.
- id: Message id to receive.
- chan_p: Channel to receive messages on.

int **bus_attach** (struct *bus_t* *self_p, struct *bus_listener_t* *listener_p)

Attach given listener to given bus. Messages written to the bus will be written to all listeners initialized with the written message id.

Return zero(0) or negative error code.

Parameters

- self_p: Bus to attach the listener to.
- listener_p: Listener to attach to the bus.

int **bus_detach** (struct *bus_t* *self_p, struct *bus_listener_t* *listener_p)

Detach given listener from given bus. A detached listener will not receive any messages from the bus.

Return zero(0) or negative error code.

Parameters

- self_p: Bus to detach listener from.
- listener_p: Listener to detach from the bus.

int **bus_write** (struct *bus_t* *self_p, int id, const void *buf_p, size_t size)

Write given message to given bus. All attached listeners to given bus will receive the message.

Return Number of listeners that received the message, or negative error code.

Parameters

- self_p: Bus to write the message to.
- id: Message identity.
- buf_p: Buffer to write to the bus. All listeners with given message id will receive this data.
- size: Number of bytes to write.

struct **bus_t**

#include <bus.h>

Public Members

```
struct rwlock_t rwlock
```

```
struct binary_tree_t listeners
```

```
struct bus_listener_t
```

Public Members

```
struct binary_tree_node_t base
```

```
int id
```

```
void *chan_p
```

```
struct bus_listener_t *next_p
```

chan — Abstract channel communication

Threads often communicate over channels. The producer thread or isr writes data to a channel and the consumer reads it. There may be multiple producers writing to a single channel, but only one consumer is allowed.

In the first example, `thread 0` and `thread 1` communicate over a channel. `thread 0` writes data to the channel and `thread 1` reads the written data.

```
+-----+
| thread 0 | channel 0 | thread 1 |
|          +-----+          |
| producer |          | consumer |
+-----+          +-----+
```

In the second example, `isr 0` and `thread 2` communicate over a channel. `isr 0` writes data to the channel and `thread 2` reads the written data.

```
+-----+
| isr 0   | channel 1 | thread 2 |
|         +-----+          |
| producer |          | consumer |
+-----+          +-----+
```

Source code: [src/sync/chan.h](#), [src/sync/chan.c](#)

Test coverage: [src/sync/chan.c](#)

Defines

```
CHAN_CONTROL_LOG_BEGIN 1
```

```
CHAN_CONTROL_LOG_END 2
```

End of a log entry.

```
CHAN_CONTROL_PRINTF_BEGIN 3
```

Beginning of printf output.

CHAN_CONTROL_PRINTF_END 4

End of printf output.

Typedefs

typedef ssize_t (***chan_read_fn_t**) (void *self_p, void *buf_p, size_t size)

Channel read function callback type.

Return Number of read bytes or negative error code.

Parameters

- **self_p**: Channel to read from.
- **buf_p**: Buffer to read into.
- **size**: Number of bytes to read.

typedef ssize_t (***chan_write_fn_t**) (void *self_p, const void *buf_p, size_t size)

Channel write function callback type.

Return Number of written bytes or negative error code.

Parameters

- **self_p**: Channel to write to.
- **buf_p**: Buffer to write.
- **size**: Number of bytes to write.

typedef int (***chan_control_fn_t**) (void *self_p, int operation)

Channel control function callback type.

Return Operation specific.

Parameters

- **self_p**: Channel to read from.
- **operation**: Control operation.

typedef int (***chan_write_filter_fn_t**) (void *self_p, const void *buf_p, size_t size)

Channel write filter function callback type.

Return true(1) if the buffer shall be written to the channel, otherwise false(0).

Parameters

- **self_p**: Channel to write to.
- **buf_p**: Buffer to write.
- **size**: Number of bytes in buffer.

typedef size_t (***chan_size_fn_t**) (void *self_p)

Channel size function callback type.

Return Number of bytes available.

Parameters

- `self_p`: Channel to get the size of.

Functions

int **chan_module_init** (void)

Initialize the channel module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **chan_init** (struct *chan_t* *`self_p`, *chan_read_fn_t* `read`, *chan_write_fn_t* `write`, *chan_size_fn_t* `size`)

Initialize given channel with given callbacks. A channel must be initialized before it can be used.

Return zero(0) or negative error code.

Parameters

- `self_p`: Channel to initialize.
- `read`: Read function callback. This function must implement the channel read functionality, and will be called when the user reads data from the channel.
- `write`: Write function callback. This function must implement the channel write functionality, and will be called when the user writes data to the channel.
- `size`: Size function callback. This function must return the size of the channel. It should return zero(0) if there is no data available in the channel, and otherwise a positive integer.

int **chan_set_write_isr_cb** (struct *chan_t* *`self_p`, *chan_write_fn_t* `write_isr_cb`)

Set the write isr function callback.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `filter`: Write isr function to set.

int **chan_set_write_filter_cb** (struct *chan_t* *`self_p`, *chan_write_filter_fn_t* `write_filter_cb`)

Set the write filter callback function. The write filter function is called when data is written to the channel, and its return value determines if the data shall be written to the underlying channel implementation, or discarded.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `write_filter_cb`: filter Write filter function to set.

int **chan_set_write_filter_isr_cb** (struct *chan_t* *`self_p`, *chan_write_filter_fn_t* `write_filter_isr_cb`)

Set the write isr filter callback function. The write filter function is called when data is written to the channel, and its return value determines is the data shall be written to the underlying channel implementation, or discarded.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `write_filter_isr_cb`: filter Write filter function to set.

int **chan_set_control_cb** (struct *chan_t* **self_p*, *chan_control_fn_t* *control_cb*)
Set control function callback.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `control`: Control function to set.

ssize_t **chan_read** (void **self_p*, void **buf_p*, size_t *size*)

Read data from given channel. The behaviour of this function depends on the channel implementation. Often, the calling thread will be blocked until all data has been read or an error occurs.

Return Number of read bytes or negative error code.

Parameters

- `self_p`: Channel to read from.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to read.

ssize_t **chan_write** (void **self_p*, const void **buf_p*, size_t *size*)

Write data to given channel. The behaviour of this function depends on the channel implementation. Some channel implementations blocks until the receiver has read the data, and some returns immediately.

Return Number of written bytes or negative error code.

Parameters

- `self_p`: Channel to write to.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

size_t **chan_size** (void **self_p*)

Get the number of bytes available to read from given channel.

Return Number of bytes available.

Parameters

- `self_p`: Channel to get the size of.

int **chan_control** (void **self_p*, int *operation*)

Control given channel.

Return Operation specific.

ssize_t **chan_write_isr** (void **self_p*, const void **buf_p*, size_t *size*)

Write data to given channel from interrupt context or with the system lock taken. The behaviour of this function depends on the channel implementation. Some channel implementations blocks until the receiver has read the data, and some returns immediately.

Return Number of written bytes or negative error code.

Parameters

- `self_p`: Channel to write to.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

int **chan_is_polled_isr** (struct *chan_t* **self_p*)

Check if a channel is polled. May only be called from isr or with the system lock taken (see `sys_lock()`).

Return true(1) or false(0).

Parameters

- `self_p`: Channel to check.

int **chan_list_init** (struct *chan_list_t* **list_p*, void **workspace_p*, size_t *size*)

Initialize an empty list of channels. A list is used to wait for data on multiple channel at the same time. When there is data on at least one channel, the poll function returns and the application can read from the channel with data.

Return zero(0) or negative error code.

Parameters

- `list_p`: List to initialize.
- `workspace_p`: Workspace for internal use.
- `size`: Size of the workspace in bytes.

int **chan_list_destroy** (struct *chan_list_t* **list_p*)

Destroy an initialized list of channels.

Return zero(0) or negative error code.

Parameters

- `list_p`: List to destroy.

int **chan_list_add** (struct *chan_list_t* **list_p*, void **chan_p*)

Add given channel to list of channels.

Return zero(0) or negative error code.

Parameters

- `list_p`: List of channels.
- `chan_p`: Channel to add.

int **chan_list_remove** (struct *chan_list_t* **list_p*, void **chan_p*)

Remove given channel from list of channels.

Return zero(0) or negative error code.

Parameters

- `list_p`: List of channels.

- `chan_p`: Channel to remove.

void ***chan_list_poll** (struct *chan_list_t* **list_p*, const struct *time_t* **timeout_p*)

Poll given list of channels for events. Blocks until at least one of the channels in the list has data ready to be read or an timeout occurs.

Return Channel with data or NULL on timeout.

Parameters

- `list_p`: List of channels to poll.
- `timeout_p`: Time to wait for data on any channel before a timeout occurs. Set to NULL to wait forever.

void ***chan_poll** (void **chan_p*, const struct *time_t* **timeout_p*)

Poll given channel for events. Blocks until the channel has data ready to be read or an timeout occurs.

Return The channel or NULL on timeout.

Parameters

- `chan_p`: Channel to poll.
- `timeout_p`: Time to wait for data on the channel before a timeout occurs. Set to NULL to wait forever.

void ***chan_null** (void)

Get a reference to the null channel. This channel will ignore all written data but return that it was successfully written.

Return The null channel.

ssize_t **chan_read_null** (void **self_p*, void **buf_p*, size_t *size*)

Null channel read function callback. Pass to `chan_init()` if no read function callback is needed for the channel.

Return Always returns -1.

ssize_t **chan_write_null** (void **self_p*, const void **buf_p*, size_t *size*)

Null channel write function callback. Pass to `chan_init()` if no write function callback is needed for the channel.

Return Always returns `size`.

size_t **chan_size_null** (void **self_p*)

Null channel size function callback. Pass to `chan_init()` if no size function callback is needed for the channel.

Return Always returns zero(0).

int **chan_control_null** (void **self_p*, int *operation*)

Null channel control function callback. Will silently ignore the control request.

Return Always returns zero(0).

struct **chan_list_t**

Public Members

```
struct chan_t **chans_pp
```

```
size_t max
```

```
size_t len
```

```
int flags
```

```
struct chan_t
```

```
#include <chan.h> Channel datastructure.
```

Public Members

```
chan_read_fn_t read
```

```
chan_write_fn_t write
```

```
chan_size_fn_t size
```

```
chan_control_fn_t control
```

```
chan_write_filter_fn_t write_filter_cb
```

```
chan_write_fn_t write_isr
```

```
chan_write_filter_fn_t write_filter_isr_cb
```

```
struct thrd_t *reader_p
```

```
struct chan_list_t *list_p
```

event — Event channel

An event channel consists of a 32 bits bitmap, where each bit corresponds to an event state. If the bit is set, the event is active. Since an event only has two states, active and inactive, signalling the same event multiple times will just result in the event to be active. There is no internal counter of how “active” an event is, it’s simply active or inactive.

Source code: [src/sync/event.h](#), [src/sync/event.c](#)

Test code: [tst/sync/event/main.c](#)

Test coverage: [src/sync/event.c](#)

Functions

```
int event_init (struct event_t *self_p)
```

```
Initialize given event channel.
```

Return zero(0) or negative error code

Parameters

- *self_p*: Event channel to initialize.

`ssize_t event_read(struct event_t *self_p, void *buf_p, size_t size)`

Wait for an event to occur in given event mask. This function blocks until at least one of the events in the event mask has been set. When the function returns, given event mask has been overwritten with the events that actually occurred.

Return sizeof(mask) or negative error code.

Parameters

- `self_p`: Event channel object.
- `buf_p`: The mask of events to wait for. When the function returns the mask contains the events that have occurred.
- `size`: Size to read (always sizeof(mask)).

`ssize_t event_write(struct event_t *self_p, const void *buf_p, size_t size)`

Write given event(s) to given event channel.

Return sizeof(mask) or negative error code.

Parameters

- `self_p`: Event channel object.
- `buf_p`: The mask of events to write.
- `size`: Must always be sizeof(mask).

`ssize_t event_write_isr(struct event_t *self_p, const void *buf_p, size_t size)`

Write given events to the event channel from isr or with the system lock taken (see `sys_lock()`).

Return sizeof(mask) or negative error code.

Parameters

- `self_p`: Event channel object.
- `buf_p`: The mask of events to write.
- `size`: Must always be sizeof(mask).

`ssize_t event_size(struct event_t *self_p)`

Checks if there are events active on the event channel.

Return one(1) is at least one event is active, otherwise zero(0).

Parameters

- `self_p`: Event channel object.

`struct event_t`

`#include <event.h>`

Public Members

`struct chan_t base`

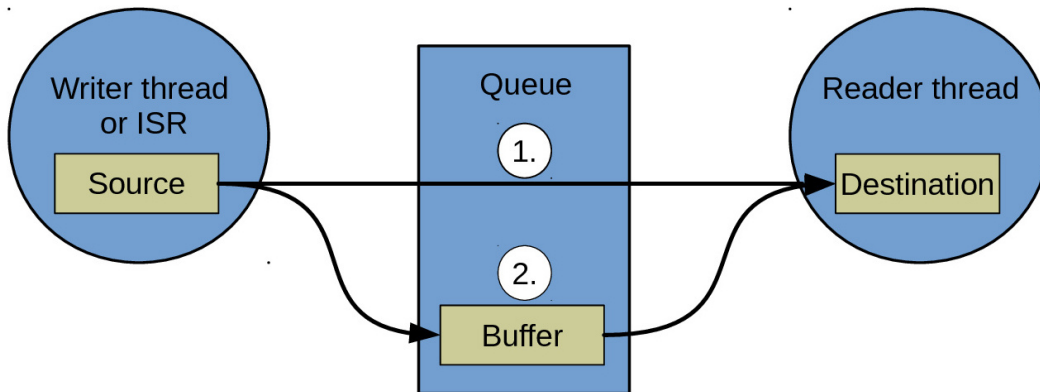
`uint32_t mask`

`uint32_t reader_mask`

queue — Queue channel

The most common channel is the queue. It can be either synchronous or semi-asynchronous. In the synchronous version the writing thread will block until all written data has been read by the reader. In the semi-asynchronous version the writer writes to a buffer within the queue, and only blocks all data does not fit in the buffer. The buffer size is selected by the application when initializing the queue.

The diagram below shows how two threads communicates using a queue. The writer thread writes from its source buffer to the queue. The reader thread reads from the queue to its destination buffer.



The data is either copied directly from the source to the destination buffer (1. in the figure), or via the internal queue buffer (2. in the figure).

1. The reader thread is waiting for data. The writer writes from its source buffer directly to the readers' destination buffer.
2. The reader thread is *not* waiting for data. The writer writes from its source buffer into the queue buffer. Later, the reader reads data from the queue buffer to its destination buffer.

Source code: [src/sync/queue.h](#), [src/sync/queue.c](#)

Test code: [tst/sync/queue/main.c](#)

Test coverage: [src/sync/queue.c](#)

Example code: [examples/queue/main.c](#)

Defines

```
QUEUE_INIT_DECL(_name, _buf, _size) struct queue_t _name = { \
    .base = { \
        .read = (chan_read_fn_t)queue_read, \
        .write = (chan_write_fn_t)queue_write, \
        .size = (chan_size_fn_t)queue_size, \
        .control = chan_control_null, \
        .reader_p = NULL, \
        .list_p = NULL \
    }, \
    .writers = { \
        .head_p = NULL, \
    }, \
    .writer_p = NULL, \
    .buffer = { \
        .begin_p = _buf, \
        .read_p = _buf, \
        .write_p = _buf, \
        .end_p = &_buf[_size], \
        .size = _size \
    }, \
    .state = QUEUE_STATE_INITIALIZED, \
    .reader = { \
        .buf_p = NULL, \
        .size = 0, \
        .left = 0 \
    } \
}
```

Enums

enum **queue_state_t**

Values:

QUEUE_STATE_INITIALIZED = 0

Queue initialized state.

QUEUE_STATE_RUNNING

Queue running state.

QUEUE_STATE_STOPPED

Queue stopped state.

Functions

int **queue_init** (struct *queue_t* *self_p, void *buf_p, size_t size)

Initialize given queue.

Return zero(0) or negative error code

Parameters

- self_p: Queue to initialize.
- buf_p: Buffer.
- size: Size of buffer.

int **queue_start** (struct *queue_t* *self_p)

Start given queue. It is not required to start a queue unless it has been stopped.

Return zero(0) or negative error code.

Parameters

- self_p: Queue to start.

int **queue_stop** (struct *queue_t* *self_p)

Stop given queue. Any ongoing read and write operations will return with the currently read/written number of bytes. Any read and write operations on a stopped queue will return zero(0).

Return true(1) if a thread was resumed, false(0) if no thread was resumed, or negative error code.

Parameters

- self_p: Queue to stop.

int **queue_stop_isr** (struct *queue_t* *self_p)

Same as queue_stop() but from isr or with the system lock taken (see sys_lock()).

ssize_t **queue_read** (struct *queue_t* *self_p, void *buf_p, size_t size)

Read from given queue. Blocks until size bytes has been read.

Return Number of read bytes or negative error code.

Parameters

- self_p: Queue to read from.

- `buf_p`: Buffer to read to.
- `size`: Size to read.

`ssize_t queue_write (struct queue_t *self_p, const void *buf_p, size_t size)`

Write bytes to given queue. Blocks until size bytes has been written.

Return Number of written bytes or negative error code.

Parameters

- `self_p`: Queue to write to.
- `buf_p`: Buffer to write from.
- `size`: Number of bytes to write.

`ssize_t queue_write_isr (struct queue_t *self_p, const void *buf_p, size_t size)`

Write bytes to given queue from isr or with the system lock taken (see `sys_lock()`). May write less than size bytes.

Return Number of written bytes or negative error code.

Parameters

- `self_p`: Queue to write to.
- `buf_p`: Buffer to write from.
- `size`: Number of bytes to write.

`ssize_t queue_size (struct queue_t *self_p)`

Get the number of bytes currently stored in the queue. May return less bytes than number of bytes stored in the channel.

Return Number of bytes in queue.

Parameters

- `self_p`: Queue.

`ssize_t queue_unused_size (struct queue_t *self_p)`

Get the number of unused bytes in the queue.

Return Number of bytes unused in the queue.

Parameters

- `self_p`: Queue.

`ssize_t queue_unused_size_isr (struct queue_t *self_p)`

Get the number of unused bytes in the queue from isr or with the system lock taken (see `sys_lock()`).

Return Number of bytes unused in the queue.

Parameters

- `self_p`: Queue.

`struct queue_buffer_t`

Public Members

char ***begin_p**

char ***read_p**

char ***write_p**

char ***end_p**

size_t **size**

struct queue_writer_elem_t

Public Members

struct *thrd_prio_list_elem_t* **base**

void ***buf_p**

size_t **size**

size_t **left**

struct queue_t

Public Members

struct *chan_t* **base**

struct *thrd_prio_list_t* **writers**

struct *queue_writer_elem_t* ***writer_p**

char ***buf_p**

size_t **size**

size_t **left**

struct *queue_t::@103* **queue_t::reader**

struct *queue_buffer_t* **buffer**

queue_state_t **state**

rwlock — Reader-writer lock

An RW lock allows concurrent access for read-only operations, while write operations require exclusive access. This means that multiple threads can read the data in parallel but an exclusive lock is needed for writing or modifying data. When a writer is writing the data, all other writers or readers will be blocked until the writer is finished writing. A common use might be to control access to a data structure in memory that cannot be updated atomically and is invalid (and should not be read by another thread) until the update is complete.

Source code: [src/sync/rwlock.h](#), [src/sync/rwlock.c](#)

Test code: [tst/sync/rwlock/main.c](#)

Test coverage: [src/sync/rwlock.c](#)

Functions

int **rwlock_module_init** (void)

Initialize the reader-writer lock module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code

int **rwlock_init** (struct *rwlock_t* *self_p)

Initialize given reader-writer lock object.

Return zero(0) or negative error code.

Parameters

- self_p: Reader-writer lock to initialize.

int **rwlock_reader_take** (struct *rwlock_t* *self_p)

Take given reader-writer lock. Multiple threads can have the reader lock at the same time.

Return zero(0) or negative error code.

Parameters

- self_p: Reader-writer lock to take.

int **rwlock_reader_give** (struct *rwlock_t* *self_p)

Give given reader-writer lock.

Return zero(0) or negative error code.

Parameters

- self_p: Reader-writer lock give.

int **rwlock_reader_give_isr** (struct *rwlock_t* *self_p)

Give given reader-writer lock from isr or with the system lock taken.

Return zero(0) or negative error code.

Parameters

- self_p: Reader-writer lock to give.

int **rwlock_writer_take** (struct *rwlock_t* *self_p)

Take given reader-writer lock as a writer. Only one thread can have the lock at a time, including both readers and writers.

Return zero(0) or negative error code.

Parameters

- self_p: Reader-writer lock to take.

int **rwlock_writer_give** (struct *rwlock_t* **self_p*)

Give given reader-writer lock.

Return zero(0) or negative error code.

Parameters

- *self_p*: Reader-writer lock to give.

int **rwlock_writer_give_isr** (struct *rwlock_t* **self_p*)

Give given reader-writer lock from isr or with the system lock taken.

Return zero(0) or negative error code.

Parameters

- *self_p*: Reader-writer lock to give.

struct **rwlock_t**

#include <rwlock.h>

Public Members

int **number_of_readers**

int **number_of_writers**

volatile struct *rwlock_elem_t* ***readers_p**

volatile struct *rwlock_elem_t* ***writers_p**

sem — Counting semaphores

The semaphore is a synchronization primitive used to protect a shared resource. A semaphore counts the number of resources taken, and suspends threads when the maximum number of resources are taken. When a resource becomes available, a suspended thread is resumed.

A semaphore initialized with *count_max* one(1) is called a binary semaphore. A binary semaphore can only be taken by one thread at a time and can be used to signal that an event has occurred. That is, *sem_give()* may be called multiple times and the semaphore resource count will remain at zero(0) until *sem_take()* is called.

Source code: [src/sync/sem.h](#), [src/sync/sem.c](#)

Test code: [tst/sync/sem/main.c](#)

Test coverage: [src/sync/sem.c](#)

Defines

SEM_INIT_DECL (name, _count, _count_max) struct *sem_t* name = { .count = _count, \ .count_max = _count_max, \ .head_p = NULL }

Functions

int **sem_module_init** (void)

Initialize the semaphore module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code

int **sem_init** (struct *sem_t* *self_p, int count, int count_max)

Initialize given semaphore object. Maximum count is the number of resources that can be taken at any given moment.

Return zero(0) or negative error code.

Parameters

- self_p: Semaphore to initialize.
- count: Initial taken resource count. Set the initial count to the same value as count_max to initialize the semaphore with all resources taken.
- count_max: Maximum number of resources that can be taken at any given moment.

int **sem_take** (struct *sem_t* *self_p, struct *time_t* *timeout_p)

Take given semaphore. If the semaphore count is zero the calling thread will be suspended until count is incremented by `sem_give()`.

Return zero(0) or negative error code.

Parameters

- self_p: Semaphore to take.
- timeout_p: Timeout.

int **sem_give** (struct *sem_t* *self_p, int count)

Give given count to given semaphore. Any suspended thread waiting for this semaphore, in `sem_take()`, is resumed. This continues until the semaphore count becomes zero or there are no threads in the suspended list.

Giving a count greater than the currently taken count is allowed and results in all resources available. This is especially useful for binary semaphores where `sem_give()` is often called more often than `sem_take()`.

Return zero(0) or negative error code.

Parameters

- self_p: Semaphore to give count to.
- count: Count to give.

int **sem_give_isr** (struct *sem_t* *self_p, int count)

Give given count to given semaphore from isr or with the system lock taken.

Return zero(0) or negative error code.

Parameters

- self_p: Semaphore to give count to.
- count: Count to give.

struct sem_t

Public Members

int **count**

Number of used resources.

int **count_max**

Maximum number of resources.

struct *thrd_prio_list_t* **waiters**

Wait list.

drivers

The drivers package on [Github](#).

Modules:

adc — Analog to digital conversion

Source code: [src/drivers/adc.h](#), [src/drivers/adc.c](#)

Test code: [tst/drivers/adc/main.c](#)

Defines

ADC_REFERENCE_VCC **ADC_PORT_REFERENCE_VCC**

Functions

int **adc_module_init** (void)

Initialize the ADC driver module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **adc_init** (**struct** *adc_driver_t* **self_p*, **struct** *adc_device_t* **dev_p*, **struct** *pin_device_t* **pin_dev_p*, int *reference*, long *sampling_rate*)

Initialize given driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- *self_p*: Driver object to be initialized.
- *dev_p*: ADC device to use.
- *pin_dev_p*: Pin device to use.
- *reference*: Voltage reference. Only **ADC_REFERENCE_VCC** is supported.

- `sampling_rate`: Sampling rate in Hz. The lowest allowed value is one and the highest value depends on the architecture. The sampling rate is not used in single sample conversions, ie. calls to `adc_async_convert()` and `adc_convert()` with length one; or calls to `adc_convert_isr()`.

int **adc_async_convert** (struct adc_driver_t *self_p, uint16_t *samples_p, size_t length)

Start an asynchronous conversion of analog signal to digital samples. Call `adc_async_wait()` to wait for the conversion to complete.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `samples_p`: Converted samples.
- `length`: Length of samples array.

int **adc_async_wait** (struct adc_driver_t *self_p)

Wait for an asynchronous conversion to complete.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.

int **adc_convert** (struct adc_driver_t *self_p, uint16_t *samples_p, size_t length)

Start a synchronous conversion of an analog signal to digital samples. This is equivalent to `adc_async_convert() + adc_async_wait()`, but in a single function call.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `samples_p`: Converted samples.
- `length`: Length of samples array.

int **adc_convert_isr** (struct adc_driver_t *self_p, uint16_t *sample_p)

Start a synchronous conversion of analog signal to digital samples from isr or with the system lock taken. This function will poll the ADC hardware until the sample has been converted.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `sample_p`: Converted sample.

int **adc_is_valid_device** (struct adc_device_t *dev_p)

Check if given ADC device is valid.

Return true(1) if the pin device is valid, otherwise false(0).

Parameters

- `dev_p`: ADC device to validate.

Variables

`struct adc_device_t adc_device[ADC_DEVICE_MAX]`

`analog_input_pin` — Analog input pin

Source code: `src/drivers/analog_input_pin.h`, `src/drivers/analog_input_pin.c`

Test code: `tst/drivers/analog_input_pin/main.c`

Functions

`int analog_input_pin_module_init (void)`

Initialize the analog input pin module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

`int analog_input_pin_init (struct analog_input_pin_t *self_p, struct pin_device_t *dev_p)`

Initialize given driver object with given device and mode.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to be initialized.
- `dev_p`: Device to use.

`int analog_input_pin_read (struct analog_input_pin_t *self_p)`

Read the current value of given pin.

Return Analog pin value, otherwise negative error code.

Parameters

- `self_p`: Driver object.

`int analog_input_pin_read_isr (struct analog_input_pin_t *self_p)`

Read the current value of given pin from an isr or with the system lock taken.

Return Analog pin value, otherwise negative error code.

Parameters

- `self_p`: Driver object.

`struct analog_input_pin_t`
`#include <analog_input_pin.h>`

Public Members

`struct adc_driver_t adc`

`analog_output_pin` — Analog output pin

Source code: `src/drivers/analog_output_pin.h`, `src/drivers/analog_output_pin.c`

Test code: `tst/drivers/analog_output_pin/main.c`

Functions

`int analog_output_pin_module_init (void)`

Initialize the analog output pin module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

`int analog_output_pin_init (struct analog_output_pin_t *self_p, struct pin_device_t *dev_p)`

Initialize given driver object with given device and mode.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to be initialized.
- `dev_p`: Device to use.

`int analog_output_pin_write (struct analog_output_pin_t *self_p, int value)`

Write given value to the analog pin.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `value`: The value to write to the pin. A number in the range 0 to 1023, where 0 is lowest output and 1023 is highest output.

`int analog_output_pin_read (struct analog_output_pin_t *self_p)`

Read the value that is currently written to given analog output pin.

Return Value in the range 0 to 1023, or negative error code.

Parameters

- `self_p`: Driver object.

`struct analog_output_pin_t`
`#include <analog_output_pin.h>`

Public Members

`struct pwm_driver_t` **pwm**

can — Controller Area Network

A Controller Area Network (CAN bus) is a vehicle bus standard designed to allow microcontrollers and devices to communicate with each other in applications without a host computer. It is a message-based protocol, designed originally for multiplex electrical wiring within automobiles, but is also used in many other contexts.

Below is a short example of how to use this module. The error handling is left out for readability.

```
struct can_frame_t can_rx_buf[8];
struct can_frame_t frame;

/* Initialize and start the CAN controller. */
can_init(&can,
        &can_device[0],
        CAN_SPEED_500KBPS,
        can_rx_buf,
        sizeof(can_rx_buf)) == 0);
can_start(&can);

/* Read a frame from the bus. */
can_read(&can, &frame, sizeof(frame));

/* Stop the CAN controller. */
can_stop(&can);
```

Source code: [src/drivers/can.h](#), [src/drivers/can.c](#)

Test code: [tst/drivers/can/main.c](#)

Defines

CAN_SPEED_1000KBPS **CAN_PORT_SPEED_1000KBPS**

CAN_SPEED_500KBPS **CAN_PORT_SPEED_500KBPS**

CAN_SPEED_250KBPS **CAN_PORT_SPEED_250KBPS**

Functions

int **can_module_init** (void)

Initialize CAN module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **can_init** (**struct** can_driver_t **self_p*, **struct** can_device_t **dev_p*, uint32_t *speed*, void **rxbuf_p*, size_t *size*)

Initialize given driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to initialize.
- `dev_p`: CAN device to use.
- `speed`: Can bus speed. One of the defines with the prefix `CAN_SPEED_`.
- `rxbuf_p`: CAN frame reception buffer.
- `size`: Size of the reception buffer in bytes.

int **can_start** (**struct** can_driver_t **self_p*)

Starts the CAN device using configuration in given driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.

int **can_stop** (**struct** can_driver_t **self_p*)

Stops the CAN device referenced by given driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.

ssize_t **can_read** (**struct** can_driver_t **self_p*, **struct** can_frame_t **frame_p*, size_t *size*)

Read one or more CAN frames from the CAN bus. Blocks until the frame(s) are received.

Return Number of bytes read or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `frame_p`: Array of read frames.
- `size`: Size of frames buffer in bytes. Must be a multiple of `sizeof(struct can_frame_t)`.

ssize_t **can_write** (**struct** can_driver_t **self_p*, **const struct** can_frame_t **frame_p*, size_t *size*)

Write one or more CAN frames to the CAN bus. Blocks until the frame(s) have been transmitted.

Return Number of bytes written or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `frame_p`: Array of frames to write.
- `size`: Size of frames buffer in bytes. Must be a multiple of `sizeof(struct can_frame_t)`.

Variables

struct can_device_t **can_device**[CAN_DEVICE_MAX]

struct can_frame_t

Public Members

uint32_t **id**

uint8_t **extended_frame**

uint8_t **rtr**

uint8_t **size**

struct can_frame_t::@0 **can_frame_t**::@1

uint8_t **u8**[8]

uint32_t **u32**[2]

union can_frame_t::@2 **can_frame_t**::data

chipid — Chip identity

Source code: [src/drivers/chipid.h](#), [src/drivers/chipid.c](#)

Test code: [tst/drivers/chipid/main.c](#)

Functions

int **chipid_read** (struct chipid_t **id_p*)

dac — Digital to analog conversion

Source code: [src/drivers/dac.h](#), [src/drivers/dac.c](#)

Test code: [tst/drivers/dac/main.c](#)

Functions

int **dac_module_init** (void)

Initialize DAC driver module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **dac_init** (struct dac_driver_t **self_p*, struct dac_device_t **dev_p*, struct pin_device_t **pin0_dev_p*, struct pin_device_t **pin1_dev_p*, int *sampling_rate*)

Initialize given driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to be initialized.
- `dev_p`: Device to use.
- `pin0_dev_p`: Pin used for mono or first stereo channel.
- `pin1_dev_p`: Second stereo pin.
- `sampling_rate`: Sampling rate in Hz.

int **`dac_async_convert`** (**`struct dac_driver_t`** **self_p*, void **samples_p*, size_t *length*)

Start an asynchronous conversion of samples to an analog signal.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `samples`: Samples to convert to an analog signal.
- `length`: Length of samples array.

int **`dac_async_wait`** (**`struct dac_driver_t`** **self_p*)

Wait for ongoing asynchronous conversion to finish.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.

int **`dac_convert`** (**`struct dac_driver_t`** **self_p*, void **samples_p*, size_t *length*)

Start synchronous conversion of samples to an analog signal.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `samples`: Converted samples.
- `length`: Length of samples array.

Variables

`struct dac_device_t` **`dac_device`**[DAC_DEVICE_MAX]

ds18b20 — One-wire temperature sensor

Source code: [src/drivers/ds18b20.h](#), [src/drivers/ds18b20.c](#)

Test code: [tst/drivers/ds18b20/main.c](#)

Defines

DS18B20_FAMILY_CODE 0x28

Functions

int **ds18b20_module_init** (void)

Initialize the DS18B20 driver module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **ds18b20_init** (struct *ds18b20_driver_t* *self_p, struct *owi_driver_t* *owi_p)

Initialize given driver object. The driver object will communicate with all DS18B20 devices on given OWI bus.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.
- owi_p: One-Wire (OWI) driver.

int **ds18b20_convert** (struct *ds18b20_driver_t* *self_p)

Start temperature conversion on all sensors.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.

int **ds18b20_get_temperature** (struct *ds18b20_driver_t* *self_p, const uint8_t *id_p, int *temp_p)

Get the temperature for given device identity.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.
- id_p: Device identity.
- temp_p: Measured temperature in Q4.4 to Q8.4 depending on resolution.

char ***ds18b20_get_temperature_str** (struct *ds18b20_driver_t* *self_p, const uint8_t *id_p, char *temp_p)

Get temperature for given device identity formatted as a string.

Return temp_p on success, NULL otherwise.

Parameters

- self_p: Driver object to be initialized.
- id_p: Device identity.
- temp_p: Measured formatted temperature.

```
struct ds18b20_driver_t
```

Public Members

```
struct owi_driver_t *owi_p
struct ds18b20_driver_t *next_p
```

ds3231 — RTC clock

Source code: [src/drivers/ds3231.h](#), [src/drivers/ds3231.c](#)

Test code: [tst/drivers/ds3231/main.c](#)

Functions

int **ds3231_init** (struct *ds3231_driver_t* *self_p, struct *i2c_driver_t* *i2c_p)
Initialize given driver object.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.
- i2c_p: I2C driver to use.

int **ds3231_set_date** (struct *ds3231_driver_t* *self_p, struct *date_t* *date_p)
Set date in the DS3231 device.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.
- date_p: Date to set in the device.

int **ds3231_get_date** (struct *ds3231_driver_t* *self_p, struct *date_t* *date_p)
Get date from the DS3231 device.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.
- date_p: Date read from the device.

```
struct ds3231_driver_t
#include <ds3231.h>
```

Public Members

```
struct i2c_driver_t *i2c_p
```

eeeprom_soft — Software EEPROM

Source code: [src/drivers/eeeprom_soft.h](#), [src/drivers/eeeprom_soft.c](#)

Test code: [tst/drivers/eeeprom_soft/main.c](#)

Functions

int **eeeprom_soft_module_init** (void)

Initialize software EEPROM module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **eeeprom_soft_init** (struct *eeeprom_soft_driver_t* *self_p, struct flash_driver_t *flash_p, const struct *eeeprom_soft_block_t* *blocks_p, int number_of_blocks, size_t chunk_size)

Initialize given driver object.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to initialize.
- flash_p: Flash driver.
- blocks_p: Flash memory blocks to use.
- number_of_blocks: Number of blocks.
- chunk_size: Chunk size in bytes. This is the size of the EEPROM. Eight bytes of the chunk will be used to store metadata, so only `chunk_size - 8` bytes are available to the user.

int **eeeprom_soft_mount** (struct *eeeprom_soft_driver_t* *self_p)

Mount given software EEPROM.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to mount.

int **eeeprom_soft_format** (struct *eeeprom_soft_driver_t* *self_p)

Format given software EEPROM.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to format.

`ssize_t eeprom_soft_read(struct eeprom_soft_driver_t *self_p, void *dst_p, uintptr_t src, size_t size)`
 Read into given buffer from given address.

Return Number of bytes read or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `dst_p`: Buffer to read into.
- `src`: Software EEPROM address to read from. Addressing starts at zero(0).
- `size`: Number of bytes to read.

`ssize_t eeprom_soft_write(struct eeprom_soft_driver_t *self_p, uintptr_t dst, const void *src_p, size_t size)`
 Write given buffer to given address.

Return Number of bytes written or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `dst`: Software EEPROM address to write to. Addressing starts at zero(0).
- `src_p`: Buffer to write.
- `size`: Number of bytes to write.

`struct eeprom_soft_block_t`
#include <eeprom_soft.h>

Public Members

`uintptr_t address`

`size_t size`

`struct eeprom_soft_driver_t`

Public Members

`struct flash_driver_t *flash_p`

`const struct eeprom_soft_block_t *blocks_p`

`int number_of_blocks`

`size_t chunk_size`

`size_t eeprom_size`

`const struct eeprom_soft_block_t *block_p`

`uintptr_t chunk_address`

`uint16_t revision`

`struct eeprom_soft_driver_t::@3 eeprom_soft_driver_t::current`

esp_wifi — Espressif WiFi

This module is a wrapper for the Espressif WiFi interface.

Configure the WiFi as a Station and an Access Point at the same time. The application tries to connect to a Wifi with SSID *ssid* and will accept connections to the SSID *Simba*.

```
esp_wifi_set_op_mode(esp_wifi_op_mode_station_softap_t);
esp_wifi_softap_init("Simba", NULL);
esp_wifi_station_init("ssid", "password", NULL, NULL);
```

Configure the WiFi as an Access Point. The application will accept connections to the SSID *Simba*.

```
esp_wifi_set_op_mode(esp_wifi_op_mode_softap_t);
esp_wifi_softap_init("Simba", NULL);
```

Configure the WiFi as a Station. The application tries to connect to a Wifi with SSID *ssid*.

```
esp_wifi_set_op_mode(esp_wifi_op_mode_station_t);
esp_wifi_station_init("ssid", "password", NULL, NULL);
```

Configure the WiFi as a Station specifying the MAC address of the access point. The application tries to connect to a Wifi with a MAC of *c8:d7:19:0f:04:66* and SSID *ssid*.

```
esp_wifi_set_op_mode(esp_wifi_op_mode_station_t);
esp_wifi_station_init("ssid",
                     "password",
                     (uint8_t[]){0xc8, 0xd7, 0x19, 0x0f, 0x04, 0x66},
                     NULL);
```

Submodules:

esp_wifi_softap — Espressif WiFi SoftAP

This module is a wrapper for the Espressif WiFi SoftAP interface.

Source code: [src/drivers/esp_wifi/softap.h](#), [src/drivers/esp_wifi/softap.c](#)

Test code: [tst/drivers/esp_wifi/softap/main.c](#)

Functions

int **esp_wifi_softap_init** (const char *ssid_p, const char *password_p)
Initialize the WiFi SoftAP interface.

Return zero(0) or negative error code.

Parameters

- ssid_p: SSID of the SoftAP.
- password_p: Password of SoftAP.

int **esp_wifi_softap_set_ip_info** (const struct *inet_if_ip_info_t* *info_p)
Set the ip address, netmask and gateway of the WiFi SoftAP.

Return zero(0) or negative error code.

int **esp_wifi_softap_get_ip_info** (struct *inet_if_ip_info_t* *info_p)
Get the SoftAP ip address, netmask and gateway.

Return zero(0) or negative error code.

Parameters

- info_p: Read ip information.

int **esp_wifi_softap_get_number_of_connected_stations** (void)
Get the number of stations connected to the SoftAP.

Return Number of conencted stations.

int **esp_wifi_softap_get_station_info** (struct *esp_wifi_softap_station_info_t* *info_p, int length)
Get the information of stations connected to the SoftAP, including MAC and IP addresses.

Return Number of valid station information entries or negative error code.

Parameters

- info_p: An array to write the station information to.
- length: Length of the info array.

int **esp_wifi_softap_dhcp_server_start** (void)
Enable the SoftAP DHCP server.

Return zero(0) or negative error code.

int **esp_wifi_softap_dhcp_server_stop** (void)
Disable the SoftAP DHCP server. The DHCP server is enabled by default.

Return zero(0) or negative error code.

enum *esp_wifi_dhcp_status_t* **esp_wifi_softap_dhcp_server_status** (void)
Get the SoftAP DHCP server status.

Return DHCP server status.

struct **esp_wifi_softap_station_info_t**
#include <softap.h>

Public Members

uint8_t **bssid**[6]

struct *inet_ip_addr_t* **ip_address**

esp_wifi_station — Espressif WiFi Station

This module is a wrapper for the Espressif WiFi station interface.

Source code: `src/drivers/esp_wifi/station.h`, `src/drivers/esp_wifi/station.c`

Test code: `tst/drivers/esp_wifi/station/main.c`

Enums

`enum esp_wifi_station_status_t`

Values:

```
esp_wifi_station_status_idle_t = 0
esp_wifi_station_status_connecting_t
esp_wifi_station_status_auth_failure_t
esp_wifi_station_status_no_ap_found_t
esp_wifi_station_status_connect_fail_t
esp_wifi_station_status_got_ip_t
esp_wifi_station_status_connected_t
```

Functions

`int esp_wifi_station_init (const char *ssid_p, const char *password_p, const uint8_t *bssid_p, const struct inet_if_ip_info_t *info_p)`

Initialize the WiFi station.

Return zero(0) or negative error code.

Parameters

- `ssid_p`: WiFi SSID to connect to.
- `password_p`: WiFi password.
- `bssid_p`: WiFi station MAC (BSSID) or NULL to ignore.
- `info_p`: Static ip configuration or NULL to use DHCP.

`int esp_wifi_station_connect (void)`

Connect the WiFi station to the Access Point (AP).

Return zero(0) or negative error code.

`int esp_wifi_station_disconnect (void)`

Disconnect the WiFi station from the AP.

Return zero(0) or negative error code.

int **esp_wifi_station_set_ip_info** (const struct *inet_if_ip_info_t* *info_p)
Set the ip address, netmask and gateway of the WiFi station.

Return zero(0) or negative error code.

int **esp_wifi_station_get_ip_info** (struct *inet_if_ip_info_t* *info_p)
Get the station ip address, netmask and gateway.

Return zero(0) or negative error code.

int **esp_wifi_station_set_reconnect_policy** (int policy)
Set whether the station will reconnect to the AP after disconnection. It will do so by default.

Return zero(0) or negative error code.

Parameters

- policy: If it's true, it will enable reconnection; if it's false, it will disable reconnection.

int **esp_wifi_station_get_reconnect_policy** (void)
Check whether the station will reconnect to the AP after disconnection.

Return true(1) or false(0).

enum *esp_wifi_station_status_t* **esp_wifi_station_get_status** (void)
Get the connection status of the WiFi station.

Return The connection status.

int **esp_wifi_station_dhcp_client_start** (void)
Enable the station DHCP client.

Return zero(0) or negative error code.

int **esp_wifi_station_dhcp_client_stop** (void)
Disable the station DHCP client.

Return zero(0) or negative error code.

enum *esp_wifi_dhcp_status_t* **esp_wifi_station_dhcp_client_status** (void)
Get the station DHCP client status.

Return Station DHCP client status.

const char ***esp_wifi_station_status_as_string** (enum *esp_wifi_station_status_t* status)
Convert given status code to a string.

Return Status code as a string.

Source code: [src/drivers/esp_wifi.h](#), [src/drivers/esp_wifi.c](#)

Test code: [tst/drivers/esp_wifi/main.c](#)

Enums

enum `esp_wifi_op_mode_t`

Values:

`esp_wifi_op_mode_null_t` = 0

`esp_wifi_op_mode_station_t`

`esp_wifi_op_mode_softap_t`

`esp_wifi_op_mode_station_softap_t`

`esp_wifi_op_mode_max_t`

enum `esp_wifi_phy_mode_t`

Physical WiFi mode.

Values:

`esp_wifi_phy_mode_11b_t` = 1

`esp_wifi_phy_mode_11g_t`

`esp_wifi_phy_mode_11n_t`

enum `esp_wifi_dhcp_status_t`

DHCP status.

Values:

`esp_wifi_dhcp_status_stopped_t` = 0

`esp_wifi_dhcp_status_running_t`

Functions

int `esp_wifi_module_init` (void)

Initialize the Espressif WiFi module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int `esp_wifi_set_op_mode` (enum *esp_wifi_op_mode_t* mode)

Set the WiFi operating mode to None, Station, SoftAP or Station + SoftAP. The default mode is SoftAP.

Return zero(0) or negative error code.

Parameters

- mode: Operating mode to set.

enum *esp_wifi_op_mode_t* `esp_wifi_get_op_mode` (void)

Get the current WiFi operating mode. The operating mode can be None, Station, SoftAP, or Station + SoftAP.

Return Current operating mode.

int **esp_wifi_set_phy_mode** (enum *esp_wifi_phy_mode_t* mode)
Set the WiFi physical mode (802.11b/g/n).

The SoftAP only supports b/g.

Return zero(0) or negative error code.

Parameters

- mode: Physical mode.

enum *esp_wifi_phy_mode_t* **esp_wifi_get_phy_mode** (void)
Get the physical mode (802.11b/g/n).

Return WiFi physical mode.

void **esp_wifi_print** (void *chout_p)
Print information about the WiFi.

exti — External interrupts

Source code: [src/drivers/exti.h](#), [src/drivers/exti.c](#)

Test code: [tst/drivers/exti/main.c](#)

Defines

EXTI_TRIGGER_BOTH_EDGES EXTI_PORT_TRIGGER_BOTH_EDGES
Trigger an interrupt on both rising and falling edges.

EXTI_TRIGGER_FALLING_EDGE EXTI_PORT_TRIGGER_FALLING_EDGE
Trigger an interrupt on falling edges.

EXTI_TRIGGER_RISING_EDGE EXTI_PORT_TRIGGER_RISING_EDGE
Trigger an interrupt on both rising edges.

Functions

int **exti_module_init** (void)
Initialize the external interrupt (EXTI) module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **exti_init** (struct exti_driver_t *self_p, struct exti_device_t *dev_p, int trigger, void (*on_interrupt) void *arg_p, void *arg_p)
Initialize given driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to be initialized.
- `dev_p`: Device to use.
- `trigger`: One of `EXTI_TRIGGER_BOTH_EDGES`, `EXTI_TRIGGER_FALLING_EDGE` or `EXTI_TRIGGER_RISING_EDGE`.
- `on_interrupt`: Function callback called when an interrupt occurs.
- `arg_p`: Function callback argument.

int **exti_start** (**struct** exti_driver_t **self_p*)
Starts the EXTI device using given driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.

int **exti_stop** (**struct** exti_driver_t **self_p*)
Stops the EXTI device referenced by given driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.

int **exti_clear** (**struct** exti_driver_t **self_p*)
Clear the interrupt flag.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.

Variables

struct exti_device_t **exti_device**[EXTI_DEVICE_MAX]

flash — Flash memory

Source code: [src/drivers/flash.h](#), [src/drivers/flash.c](#)

Test code: [tst/drivers/flash/main.c](#)

Functions

int **flash_module_init** (void)
Initialize the flash module. This function must be called before calling any other function in this module.
The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **flash_init** (struct flash_driver_t *self_p, struct flash_device_t *dev_p)
Initialize given driver object.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to initialize.
- dev_p: Device to use.

ssize_t **flash_read** (struct flash_driver_t *self_p, void *dst_p, uintptr_t src, size_t size)
Read data from given flash memory.

Return Number of read bytes or negative error code.

Parameters

- self_p: Initialized driver object.
- dst_p: Buffer to read into.
- src: Address in flash memory to read from.
- size: Number of bytes to receive.

ssize_t **flash_write** (struct flash_driver_t *self_p, uintptr_t dst, const void *src_p, size_t size)
Write data to given flash memory.

Return Number of written bytes or negative error code.

Parameters

- self_p: Initialized driver object.
- dst: Address in flash memory to write to.
- src_p: Buffer to write.
- size: Number of bytes to write.

int **flash_erase** (struct flash_driver_t *self_p, uintptr_t addr, size_t size)
Erase all sectors part of given memory range.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.
- dst: Address in flash memory to erase from.
- size: Number of bytes to erase.

Variables

struct flash_device_t **flash_device**[FLASH_DEVICE_MAX]

i2c — I2C

I2C is a data transfer bus. Normally one master and one or more slaves are connected to the bus. The master addresses one slave at a time to transfer data between the devices.

The master is normally fairly easy to implement since it controls the bus clock and no race conditions can occur. The slave, on the other hand, can be implemented in various ways depending on the application requirements. In this implementation the slave will always send an acknowledgement when addressed by the master, and lock the bus by pulling SCL low until it is ready for the transmission.

This driver is for systems with hardware I2C support. For systems without hardware I2C support the *i2c_soft* — *Software I2C* driver can be used.

Source code: `src/drivers/i2c.h`, `src/drivers/i2c.c`

Test code: `tst/drivers/i2c/master/main.c`

Defines

I2C_BAUDRATE_3_2MBPS I2C_PORT_BAUDRATE_3_2MBPS

I2C_BAUDRATE_1MBPS I2C_PORT_BAUDRATE_1MBPS

I2C_BAUDRATE_400KBPS I2C_PORT_BAUDRATE_400KBPS

I2C_BAUDRATE_100KBPS I2C_PORT_BAUDRATE_100KBPS

Functions

int i2c_module_init ()

Initialize the i2c module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int i2c_init (struct i2c_driver_t *self_p, struct i2c_device_t *dev_p, int baudrate, int address)

Initialize given driver object. The same driver object is used for both master and slave modes. Use `i2c_start ()` to start the device as a master, and `i2c_slave_start ()` to start it as a slave.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to initialize.
- `dev_p`: I2C device to use.
- `baudrates`: Bus baudrate when in master mode. Unused in slave mode.
- `address`: Slave address when in slave mode. Unused in master mode.

int i2c_start (struct i2c_driver_t *self_p)

Start given driver object in master mode. Enables data reception and transmission, but does not start any transmission. Use `i2c_read ()` and `i2c_write ()` to exchange data with the peer.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to initialize.

int **i2c_stop** (struct i2c_driver_t **self_p*)

Stop given driver object. Disables data reception and transmission in master mode.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to initialize.

ssize_t **i2c_read** (struct i2c_driver_t **self_p*, int *address*, void **buf_p*, size_t *size*)

Read given number of bytes into given buffer from given slave.

Return Number of bytes read or negative error code.

Parameters

- `self_p`: Driver object.
- `address`: Slave address to read from.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to read.

ssize_t **i2c_write** (struct i2c_driver_t **self_p*, int *address*, const void **buf_p*, size_t *size*)

Write given number of bytes from given buffer to given slave.

Return Number of bytes written or negative error code.

Parameters

- `self_p`: Driver object.
- `address`: Slave address to write to.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

int **i2c_scan** (struct i2c_driver_t **self_p*, int *address*)

Scan the i2c bus for a slave with given address.

Return true(1) if a slave responded to given address, otherwise false(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `address`: Address of the slave to scan for.

int **i2c_slave_start** (struct i2c_driver_t **self_p*)

Start given driver object in slave mode. Enables data reception and transmission, but does not start any transmission. Data transfers are started by calling the `i2c_slave_read()` and `i2c_slave_write()`.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to initialize.

`int i2c_slave_stop (struct i2c_driver_t *self_p)`

Stop given driver object. Disables data reception and transmission in slave mode.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to initialize.

`ssize_t i2c_slave_read (struct i2c_driver_t *self_p, void *buf_p, size_t size)`

Read into given buffer from the next master that addresses this slave.

Return Number of bytes read or negative error code.

Parameters

- `self_p`: Driver object.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to read.

`ssize_t i2c_slave_write (struct i2c_driver_t *self_p, const void *buf_p, size_t size)`

Write given buffer to the next master that addresses this slave.

Return Number of bytes written or negative error code.

Parameters

- `self_p`: Driver object.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

Variables

`struct i2c_device_t i2c_device[I2C_DEVICE_MAX]`

i2c_soft — Software I2C

I2C is a data transfer bus. Normally one master and one or more slaves are connected to the bus. The master addresses one slave at a time to transfer data between the devices.

This driver implements I2C in software for MCUs without I2C hardware support. For systems with hardware I2C support, the *i2c — I2C* driver will probably be preferable.

Source code: [src/drivers/i2c_soft.h](#), [src/drivers/i2c_soft.c](#)

Test code: [tst/drivers/i2c/master_soft/main.c](#)

Functions

int **i2c_soft_module_init** (void)

Initialize the i2c soft module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **i2c_soft_init** (struct *i2c_soft_driver_t* *self_p, struct pin_device_t *scl_dev_p, struct pin_device_t *sda_dev_p, long baudrate, long max_clock_stretching_us, long clock_stretching_sleep_us)

Initialize given driver object.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to initialize.
- scl_dev_p: The I2C clock pin (SCL).
- sda_dev_p: The I2C data pin (SDA).
- baudrate: Bus baudrate.
- max_clock_stretching_us: Maximum number of microseconds to wait for the clock stretching to end.
- clock_stretching_sleep_us: SCL poll interval in number of microseconds waiting for clock stretching to end.

int **i2c_soft_start** (struct *i2c_soft_driver_t* *self_p)

Start given driver object. Enables data reception and transmission, but does not start any transmission. Data transfers are started by calling the `i2c_soft_read()` and `i2c_soft_write()`.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to initialize.

int **i2c_soft_stop** (struct *i2c_soft_driver_t* *self_p)

Stop given driver object. Disables data reception and transmission.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to initialize.

ssize_t **i2c_soft_read** (struct *i2c_soft_driver_t* *self_p, int address, void *buf_p, size_t size)

Read given number of bytes into given buffer from given slave.

Return Number of bytes read or negative error code.

Parameters

- self_p: Driver object.
- address: Slave address to read from.

- `buf_p`: Buffer to read into.
- `size`: Number of bytes to read.

`ssize_t i2c_soft_write (struct i2c_soft_driver_t *self_p, int address, const void *buf_p, size_t size)`
Write given number of bytes from given buffer to given slave.

Return Number of bytes written or negative error code.

Parameters

- `self_p`: Driver object.
- `address`: Slave address to write to.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

`int i2c_soft_scan (struct i2c_soft_driver_t *self_p, int address)`
Scan the i2c bus for a slave with given address.

Return true(1) if a slave responded to given address, otherwise false(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `address`: Address of the slave to scan for.

`struct i2c_soft_driver_t`
`#include <i2c_soft.h>`

Public Members

`struct pin_device_t *scl_p`
`struct pin_device_t *sda_p`
`long baudrate`
`long baudrate_us`
`long max_clock_stretching_us`
`long clock_stretching_sleep_us`

led_7seg_ht16k33 — LED 7-Segment HT16K33

This is a driver for ‘**Adafruit 0.56” 4-Digit 7-Segment Display w/I2C Backpack**’ or compatible devices which uses the Holtek HT16K33 chip.

At this time the driver only supports using the *i2c_soft* — *Software I2C* driver to communicate with the HT16K33, not the *i2c* — *I2C* driver.

Source code: `src/drivers/led_7seg_ht16k33.h`, `src/drivers/led_7seg_ht16k33.c`

Defines

LED_7SEG_HT16K33_BRIGHTNESS_MIN 0
Minimum brightness.

LED_7SEG_HT16K33_BRIGHTNESS_MAX 0xf
Maximum brightness.

LED_7SEG_HT16K33_DEFAULT_I2C_ADDR 0x70
Default I2C address for HT16K33.

Functions

int **led_7seg_ht16k33_module_init** (void)
Initialize the driver module. This function must be called before calling any other function in this module.
The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **led_7seg_ht16k33_init** (struct *led_7seg_ht16k33_driver_t* *self_p, struct *i2c_soft_driver_t* *i2c_p,
int i2c_addr)
Initialize driver object. The driver object will be used for a single display.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialize.
- i2c_p: The I2C driver pointer.
- i2c_addr: The address of the HT16K33 controller. Probably LED_7SEG_HT16K33_DEFAULT_I2C_ADDR.

int **led_7seg_ht16k33_start** (struct *led_7seg_ht16k33_driver_t* *self_p)
Start driver.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.

int **led_7seg_ht16k33_display** (struct *led_7seg_ht16k33_driver_t* *self_p)
Send content of display buffer to the display.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.

int **led_7seg_ht16k33_clear** (struct *led_7seg_ht16k33_driver_t* *self_p)
Clear content of display buffer.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.

int **led_7seg_ht16k33_brightness** (struct *led_7seg_ht16k33_driver_t* **self_p*, int *brightness*)
Set display brightness.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `brightness`: Brightness from LED_7SEG_HT16K33_BRIGHTNESS_MIN to LED_7SEG_HT16K33_BRIGHTNESS_MAX.

int **led_7seg_ht16k33_set_num** (struct *led_7seg_ht16k33_driver_t* **self_p*, int *num*, int *base*)
Set a number in the display buffer.

Number cannot be more than 4 digits AKA $\text{base}^4 - 1$.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `num`: Number to set.
- `base`: Base of *num*.

int **led_7seg_ht16k33_show_colon** (struct *led_7seg_ht16k33_driver_t* **self_p*, int *show_colon*)
Set show/hide of colon in the display buffer.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `show_colon`: If true light colon, otherwise turn off.

int **led_7seg_ht16k33_show_dot** (struct *led_7seg_ht16k33_driver_t* **self_p*, int *position*, int *show_colon*)
Set show/hide of dot in the display buffer.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `position`: The position to light colon or not. Range: 0 to 3.
- `show_dot`: If true light dot, otherwise turn off.

struct **led_7seg_ht16k33_driver_t**
#include <led_7seg_ht16k33.h>

Public Members

```

struct i2c_soft_driver_t *i2c_p
int i2c_addr
uint8_t buf[5]

```

mcp2515 — CAN BUS chipset

Source code: `src/drivers/mcp2515.h`, `src/drivers/mcp2515.c`

Test code: `tst/drivers/mcp2515/main.c`

Defines

```

MCP2515_SPEED_1000KBPS 1000
MCP2515_SPEED_500KBPS 500
MCP2515_MODE_NORMAL 0x00
MCP2515_MODE_LOOPBACK 0x40

```

Functions

int **mcp2515_init** (**struct** *mcp2515_driver_t* **self_p*, **struct** *spi_device_t* **spi_p*, **struct** *pin_device_t* **cs_p*, **struct** *exti_device_t* **exti_p*, void **chin_p*, int *mode*, int *speed*)
 Initialize given driver object.

Return zero(0) or negative error code.

Parameters

- *self_p*: Driver object to initialize.
- *spi_p*: SPI driver to use.
- *cs_p*: SPI chip select pin.
- *exti_p*: External interrupt tp use.
- *chin_p*: Frames received from the hardware are written to this channel.
- *mode*: Device mode.
- *speed*: CAN bus speed in kbps.

int **mcp2515_start** (**struct** *mcp2515_driver_t* **self_p*)
 Starts the CAN device using given driver object.

Return zero(0) or negative error code.

Parameters

- *self_p*: Initialized driver object.

int **mcp2515_stop** (struct *mcp2515_driver_t* **self_p*)
Stops the CAN device referenced by driver object.

Return zero(0) or negative error code.

Parameters

- *self_p*: Initialized driver object.

ssize_t **mcp2515_read** (struct *mcp2515_driver_t* **self_p*, struct *mcp2515_frame_t* **frame_p*)
Read a CAN frame.

Return zero(0) or negative error code.

Parameters

- *self_p*: Initialized driver object.
- *frame_p*: Read frame.

ssize_t **mcp2515_write** (struct *mcp2515_driver_t* **self_p*, const struct *mcp2515_frame_t* **frame_p*)
Write a CAN frame.

Return zero(0) or negative error code.

Parameters

- *self_p*: Initialized driver object.
- *frame_p*: Frame to write.

struct **mcp2515_frame_t**

Public Members

uint32_t **id**

int **size**

int **rtr**

uint32_t **timestamp**

uint8_t **data**[8]

struct **mcp2515_driver_t**

Public Functions

mcp2515_driver_t::THR_STACK(stack, 1024)

Public Members

struct spi_driver_t **spi**

struct exti_driver_t **exti**

int **mode**


```

int speed
struct chan_t chout
struct chan_t *chin_p
struct sem_t isr_sem
struct sem_t tx_sem

```

nrf24l01 — Wireless communication

Source code: [src/drivers/nrf24l01.h](#), [src/drivers/nrf24l01.c](#)

Functions

int **nrf24l01_module_init** (void)

Initialize NRF24L01 module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **nrf24l01_init** (struct *nrf24l01_driver_t* *self_p, struct spi_device_t *spi_p, struct pin_device_t *cs_p, struct pin_device_t *ce_p, struct exti_device_t *exti_p, uint32_t address)

Initialize given driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.
- spi_p: SPI device.
- cs_p: Chip select pin device.
- ce_p: CE pin device.
- exti_p: External interrupt flagdevice.
- address: 4 MSB:s of RX pipes. LSB is set to 0 through 5 for the 6 pipes.

int **nrf24l01_start** (struct *nrf24l01_driver_t* *self_p)

Starts the NRF24L01 device using given driver object.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.

int **nrf24l01_stop** (struct *nrf24l01_driver_t* *self_p)

Stops the NRF24L01 device referenced by driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.

`ssize_t nrf24l01_read(struct nrf24l01_driver_t *self_p, void *buf_p, size_t size)`
Read data from the NRF24L01 device.

Return Number of received bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to read (must be 32).

`ssize_t nrf24l01_write(struct nrf24l01_driver_t *self_p, uint32_t address, uint8_t pipe, const void *buf_p, size_t size)`
Write data to the NRF24L01 device.

Return number of sent bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `address`: 4 MSB:s of TX address.
- `pipe`: LSB of TX address.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write (must be 32).

`struct nrf24l01_driver_t`
`#include <nrf24l01.h>`

Public Members

`struct spi_driver_t spi`
`struct exti_driver_t exti`
`struct pin_driver_t ce`
`struct queue_t irqchan`
`struct queue_t chin`
`struct thrd_t *thrd_p`
`uint32_t address`
`char irqbuf[8]`
`char chinbuf[32]`
`char stack[256]`

owi — One-Wire Interface

Source code: `src/drivers/owi.h`, `src/drivers/owi.c`

Test code: `tst/drivers/owi/main.c`

Defines

OWI_SEARCH_ROM 0xf0

OWI_READ_ROM 0x33

OWI_MATCH_ROM 0x55

OWI_SKIP_ROM 0xcc

OWI_ALARM_SEARCH 0xec

Functions

int **owi_init** (**struct** *owi_driver_t* **self_p*, **struct** pin_device_t **dev_p*, **struct** *owi_device_t* **devices_p*,
 size_t *nmemb*)
Initialize driver object.

Return zero(0) or negative error code.

Parameters

- *self_p*: Driver object to be initialized.
- *dev_p*: Pin device to use.
- *devices_p*: Storage for devices found when searching.
- *nmemb*: Number of members in devices.

int **owi_reset** (**struct** *owi_driver_t* **self_p*)
Send reset on one wire bus.

Return true(1) if one or more devices are connected to the bus, false(0) if no devices were found, otherwise negative error code.

Parameters

- *self_p*: Driver object.

int **owi_search** (**struct** *owi_driver_t* **self_p*)
Search for devices on given one wire bus. The device id of all found devices are stored in the devices array passed to `owi_init()`.

Return Number of devices found or negative error code.

Parameters

- *self_p*: Driver object.

ssize_t **owi_read** (**struct** *owi_driver_t* **self_p*, void **buf_p*, size_t *size*)
Read into buffer from one wire bus.

Return Number of bits read or negative error code.

Parameters

- `self_p`: Driver object.
- `buf_p`: Buffer to read into.
- `size`: Number of bits to read.

`ssize_t owi_write (struct owi_driver_t *self_p, const void *buf_p, size_t size)`
Write buffer to given one wire bus.

Return Number of bits written or negative error code.

Parameters

- `self_p`: Driver object.
- `buf_p`: Buffer to write.
- `size`: Number of bits to write.

`struct owi_device_t`

Public Members

`uint8_t id[8]`

`struct owi_driver_t`

Public Members

`struct pin_driver_t pin`

`struct owi_device_t *devices_p`

`size_t nmemb`

`size_t len`

pin — Digital pins

Debug file system commands

Three debug file system commands are available, all located in the directory `drivers/pin/`. These commands directly access the pin device registers, without using the pin driver object.

Command	Description
<code>set_mode <pin> <mode></code>	Set the mode of the pin <pin> to <mode>, where <mode> is one of output and input.
<code>read <pin></code>	Read current input or output value of the pin <pin>. high or low is printed.
<code>write <pin> <value></code>	Write the value <value> to pin <pin>, where <value> is one of high and low.

Example output from the shell:

```
$ drivers/pin/set_mode d2 output
$ drivers/pin/read d2
low
$ drivers/pin/write d2 high
$ drivers/pin/read d2
high
$ drivers/pin/set_mode d3 input
$ drivers/pin/read d3
low
```

Source code: [src/drivers/pin.h](#), [src/drivers/pin.c](#)

Test code: [tst/drivers/pin/main.c](#)

Defines

PIN_OUTPUT 0

PIN_INPUT 1

Configure the pin as an input pin.

Functions

int **pin_module_init** (void)

Initialize the pin module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **pin_init** (struct pin_driver_t *self_p, struct pin_device_t *dev_p, int mode)

Initialize given driver object with given device and mode.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.
- dev_p: Device to use.
- mode: Pin mode. One of PIN_INPUT or PIN_OUTPUT.

int **pin_write** (struct pin_driver_t *self_p, int value)

Write given value to given pin.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.
- value: 1 for high and 0 for low output.

int **pin_read** (struct pin_driver_t *self_p)

Read the current value of given pin.

Return 1 for high and 0 for low input, otherwise negative error code.

Parameters

- self_p: Driver object.

int **pin_toggle** (struct pin_driver_t *self_p)

Toggle the pin output value (high/low).

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.

int **pin_set_mode** (struct pin_driver_t *self_p, int mode)

Set the pin mode of given pin.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.
- mode: New pin mode.

static int **pin_device_set_mode** (const struct pin_device_t *dev_p, int mode)

Pin device mode to set. One of PIN_INPUT or PIN_OUTPUT.

Return zero(0) or negative error code.

Parameters

- self_p: Pin device.
- mode: New pin mode.

static int **pin_device_read** (const struct pin_device_t *dev_p)

Read the value of given pin device.

Return 1 for high and 0 for low input, otherwise negative error code.

Parameters

- self_p: Pin device.

static int **pin_device_write_high** (const struct pin_device_t *dev_p)

Write high to given pin device.

Return zero(0) or negative error code.

Parameters

- self_p: Pin device.

static int **pin_device_write_low** (const struct pin_device_t *dev_p)

Write low to given pin device.

Return zero(0) or negative error code.

Parameters

- `self_p`: Pin device.

int **pin_is_valid_device** (**struct** pin_device_t **dev_p*)

Check if given pin device is valid.

Return true(1) if the pin device is valid, otherwise false(0).

Parameters

- `dev_p`: Pin device to validate.

Variables

struct pin_device_t **pin_device**[PIN_DEVICE_MAX]

pwm — Pulse width modulation

Source code: [src/drivers/pwm.h](#), [src/drivers/pwm.c](#)

Functions

int **pwm_module_init** (void)

Initialize the pwm module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **pwm_init** (**struct** pwm_driver_t **self_p*, **struct** pwm_device_t **dev_p*, long *frequency*, long *duty_cycle*)

Initialize given PWM driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to be initialized.
- `dev_p`: PWM device to use.
- `frequency`: Frequency.
- `duty_cycle`: Duty cycle.

int **pwm_start** (**struct** pwm_driver_t **self_p*)

Start given PWM driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to start.

int **pwm_stop** (struct pwm_driver_t *self_p)
Stop given PWM driver object.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to stop.

int **pwm_set_frequency** (struct pwm_driver_t *self_p, long value)
Set the frequency of the PWM signal.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.
- value: Frequency. Use `pwm_frequency()` to convert a frequency in Hertz to a value expected by this function.

long **pwm_get_frequency** (struct pwm_driver_t *self_p)
Get current frequency.

Return Current frequency.

Parameters

- self_p: Driver object.

int **pwm_set_duty_cycle** (struct pwm_driver_t *self_p, long value)
Set the duty cycle of the signal.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.
- value: Duty cycle. Use `pwm_duty_cycle()` to convert a duty cycle percentage to a value expected by this function.

long **pwm_get_duty_cycle** (struct pwm_driver_t *self_p)
Get current duty cycle.

Return Current duty cycle.

Parameters

- self_p: Driver object.

long **pwm_frequency** (int hertz)
Convert a duty cycle percentage to a value for `pwm_set_frequency()`.

Return Frequency.

Parameters

- hertz: Frequency in Hertz.

int **pwm_frequency_as_hertz** (long *value*)

Convert a frequency value returned by `pwm_get_frequency()` to Hertz.

Return Frequency in Hertz.

Parameters

- *value*: Frequency.

long **pwm_duty_cycle** (int *percentage*)

Convert a duty cycle percentage to a value for `pwm_set_duty_cycle()`.

Return Duty cycle.

Parameters

- *percentage*: Duty cycle percentage.

int **pwm_duty_cycle_as_percent** (long *value*)

Convert a duty cycle value returned by `pwm_get_duty_cycle()` to a percentage.

Return Duty cycle percentage.

Parameters

- *value*: Duty cycle.

struct pwm_device_t ***pwm_pin_to_device** (struct pin_device_t **pin_p*)

Get the PWM device for given pin.

Return PWM device, or NULL on error.

Parameters

- *pin_p*: The pin device to get the PWM device for.

Variables

struct pwm_device_t **pwm_device**[PWM_DEVICE_MAX]

pwm_soft — Software pulse width modulation

This module implements software PWM on all digital pins. In general, software PWM outputs an inaccurate, low frequency signal. Keep that in mind designing your application.

If an accurate and/or high frequency PWM signal is required, a *hardware PWM* should be used instead.

Here is a short example of how to use this module. A software PWM driver is initialized for digital pin 3 (D3). A software PWM signal with duty cycle 10% is outputted on D3 after the calling `pwm_soft_start()`.

```
struct pwm_soft_driver_t pwm_soft;

pwm_soft_module_init(500);
pwm_soft_init(&pwm_soft, &pin_d3_dev, pwm_soft_duty_cycle(10));
pwm_soft_start(&pwm_soft);
```

Change the duty cycle to 85% by calling `pwm_soft_set_duty_cycle()`.

```
pwm_soft_set_duty_cycle(&pwm_soft, pwm_soft_duty_cycle(85));
```

Stop outputting the software PWM signal to D3 by calling *pwm_soft_stop()*.

```
pwm_soft_stop(&pwm_soft);
```

Source code: [src/drivers/pwm_soft.h](#), [src/drivers/pwm_soft.c](#)

Test code: [tst/drivers/pwm_soft/main.c](#)

Functions

int **pwm_soft_module_init** (long *frequency*)

Initialize the software PWM module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

Parameters

- *frequency*: PWM module frequency in Hertz. All software PWM:s will run at this frequency. The frequency can later be changed by calling *pwm_soft_set_frequency()*.

int **pwm_soft_set_frequency** (long *value*)

Set the frequency. The frequency is the same for all software PWM:s. All software PWM:s must be stopped before calling this function, otherwise a negative error code will be returned.

Return zero(0) or negative error code.

Parameters

- *value*: Frequency to set in Hertz. All software PWM:s will run at this frequency.

long **pwm_soft_get_frequency** (void)

Get current frequency.

Return Current frequency in Hertz.

int **pwm_soft_init** (*struct pwm_soft_driver_t* **self_p*, *struct pin_device_t* **pin_dev_p*, long *duty_cycle*)

Initialize given software PWM driver object.

Return zero(0) or negative error code.

Parameters

- *self_p*: Driver object to be initialized.
- *pin_dev_p*: Pin device to use.
- *duty_cycle*: Initial duty cycle.

int **pwm_soft_start** (*struct pwm_soft_driver_t* **self_p*)

Start outputting the PWM signal on the pin given to *pwm_soft_init()*.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to start.

int **pwm_soft_stop** (struct *pwm_soft_driver_t* **self_p*)

Stop outputting the PWM signal on the pin given to `pwm_soft_init()`.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to stop.

int **pwm_soft_set_duty_cycle** (struct *pwm_soft_driver_t* **self_p*, long *value*)

Set the duty cycle. Calls `pwm_soft_stop()` and `pwm_soft_start()` to restart outputting the PWM signal with the new duty cycle.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `value`: Duty cycle. Use `pwm_soft_duty_cycle()` to convert a duty cycle percentage to a value expected by this function.

unsigned int **pwm_soft_get_duty_cycle** (struct *pwm_soft_driver_t* **self_p*)

Get current duty cycle. Use `pwm_soft_duty_cycle_as_percent()` to convert a duty cycle to a percentage.

Return Current duty cycle.

Parameters

- `self_p`: Driver object.

long **pwm_soft_duty_cycle** (int *percentage*)

Convert a duty cycle percentage to a value for `pwm_soft_init()` and `pwm_soft_set_duty_cycle()`.

Return Duty cycle.

Parameters

- `percentage`: Duty cycle percentage.

int **pwm_soft_duty_cycle_as_percent** (long *value*)

Convert a duty cycle value for `pwm_soft_init()` and `pwm_soft_set_duty_cycle()` to a percentage.

Return Duty cycle percentage.

Parameters

- `value`: Duty cycle.

struct **pwm_soft_driver_t**

#include <pwm_soft.h>

Public Members

```
struct pin_device_t *pin_dev_p
long frequency
long duty_cycle
unsigned int delta
struct thrd_t *thrd_p
struct pwm_soft_driver_t *next_p
```

random — Random numbers.

Source code: [src/drivers/random.h](#), [src/drivers/random.c](#)

Test code: [tst/drivers/random/main.c](#)

Functions

```
int random_module_init (void)
uint32_t random_read (void)
    Read a random number from the hardware.

    Return Read random number.
```

sd — Secure Digital memory

Source code: [src/drivers/sd.h](#), [src/drivers/sd.c](#)

Test code: [tst/drivers/sd/main.c](#)

Defines

```
SD_ERR_NORESPONSE_WAIT_FOR_DATA_START_BLOCK 5001
SD_ERR_GO_IDLE_STATE 5002
SD_ERR_CRC_ON_OFF 5003
SD_ERR_SEND_IF_COND 5004
SD_ERR_CHECK_PATTERN 5005
SD_ERR_SD_SEND_OP_COND 5006
SD_ERR_READ_OCR 5007
SD_ERR_READ_COMMAND 5008
SD_ERR_READ_DATA_START_BLOCK 5009
```

SD_ERR_READ_WRONG_DATA_CRC 5010

SD_ERR_WRITE_BLOCK 5011

SD_ERR_WRITE_BLOCK_TOKEN_DATA_RES_ACCEPTED 5012

SD_ERR_WRITE_BLOCK_WAIT_NOT_BUSY 5013

SD_ERR_WRITE_BLOCK_SEND_STATUS 5014

SD_BLOCK_SIZE 512

SD_CCC (csd_p) (((uint16_t)(csd_p)->ccc_high << 4) \ | ((uint16_t)(csd_p)->ccc_low << 0))

SD_C_SIZE (csd_p) (((uint16_t)(csd_p)->c_size_high << 10) \ | ((uint16_t)(csd_p)->c_size_mid << 2) \ | ((uint16_t)(csd_p)->c_size_low << 0))

SD_C_SIZE_MULT (csd_p) (((csd_p)->c_size_mult_high << 1) \ | ((csd_p)->c_size_mult_low << 0))

SD_SECTOR_SIZE (csd_p) (((csd_p)->sector_size_high << 1) \ | ((csd_p)->sector_size_low << 0))

SD_WRITE_BL_LEN (csd_p) (((csd_p)->write_bl_len_high << 2) \ | ((csd_p)->write_bl_len_low << 0))

SD_CSD_STRUCTURE_V1 0

SD_CSD_STRUCTURE_V2 1

Functions

int **sd_init** (struct *sd_driver_t* *self_p, struct spi_driver_t *spi_p)

Initialize given driver object.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to initialize.

int **sd_start** (struct *sd_driver_t* *self_p)

Start given SD card driver. This resets the SD card and performs the initialization sequence.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.

int **sd_stop** (struct *sd_driver_t* *self_p)

Stop given SD card driver.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.

ssize_t **sd_read_cid** (struct *sd_driver_t* *self_p, struct *sd_cid_t* *cid_p)

Read card CID register. The CID contains card identification information such as Manufacturer ID, Product name, Product serial number and Manufacturing date.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `cid`: pointer to cid data store.

`ssize_t sd_read_csd(struct sd_driver_t *self_p, union sd_csd_t *csd_p)`

Read card CSD register. The CSD contains that provides information regarding access to the card's contents.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `csd`: pointer to csd data store.

`ssize_t sd_read_block(struct sd_driver_t *self_p, void *dst_p, uint32_t src_block)`

Read given block from SD card.

Return Number of read bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `buf_p`: Buffer to read into.
- `src_block`: Block to read from.

`ssize_t sd_write_block(struct sd_driver_t *self_p, uint32_t dst_block, const void *src_p)`

Write data to the SD card.

Return Number of written bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `dst_block`: Block to write to.
- `src_p`: Buffer to write.

Variables

`struct sd_csd_v2_t PACKED`

`struct sd_cid_t`

Public Members

`uint8_t mid`

`char oid[2]`

`char pnm[5]`

`uint8_t prv`

`uint32_t psn`

`uint16_t mdt`

```
uint8_t crc  
struct sd_csd_v1_t
```

Public Members

```
uint8_t reserved1  
uint8_t csd_structure  
uint8_t taac  
uint8_t nsac  
uint8_t tran_speed  
uint8_t ccc_high  
uint8_t read_bl_len  
uint8_t ccc_low  
uint8_t c_size_high  
uint8_t reserved2  
uint8_t dsr_imp  
uint8_t read_blk_misalign  
uint8_t write_blk_misalign  
uint8_t read_bl_partial  
uint8_t c_size_mid  
uint8_t vdd_r_curr_max  
uint8_t vdd_r_curr_min  
uint8_t c_size_low  
uint8_t c_size_mult_high  
uint8_t vdd_w_curr_max  
uint8_t vdd_w_curr_min  
uint8_t sector_size_high  
uint8_t erase_blk_en  
uint8_t c_size_mult_low  
uint8_t wp_grp_size  
uint8_t sector_size_low  
uint8_t write_bl_len_high  
uint8_t r2w_factor  
uint8_t reserved3  
uint8_t wp_grp_enable  
uint8_t reserved4  
uint8_t write_bl_partial
```

```
uint8_t write_bl_len_low
uint8_t reserved5
uint8_t file_format
uint8_t tmp_write_protect
uint8_t perm_write_protect
uint8_t copy
uint8_t file_format_grp
uint8_t crc
struct sd_csd_v2_t
```

Public Members

```
uint8_t reserved1
uint8_t csd_structure
uint8_t taac
uint8_t nsac
uint8_t tran_speed
uint8_t ccc_high
uint8_t read_bl_len
uint8_t ccc_low
uint8_t reserved2
uint8_t dsr_imp
uint8_t read_blk_misalign
uint8_t write_blk_misalign
uint8_t read_bl_partial
uint8_t c_size_high
uint8_t reserved3
uint8_t c_size_mid
uint8_t c_size_low
uint8_t sector_size_high
uint8_t erase_blk_en
uint8_t reserved4
uint8_t wp_grp_size
uint8_t sector_size_low
uint8_t write_bl_len_high
uint8_t r2w_factor
uint8_t reserved5
```



```

uint8_t wp_grp_enable
uint8_t reserved6
uint8_t write_bl_partial
uint8_t write_bl_len_low
uint8_t reserved7
uint8_t file_format
uint8_t tmp_write_protect
uint8_t perm_write_protect
uint8_t copy
uint8_t file_format_grp
uint8_t crc
union sd_csd_t

```

Public Members

```

struct sd_csd_v1_t v1
struct sd_csd_v2_t v2
struct sd_driver_t

```

Public Members

```

struct spi_driver_t *spi_p
int type

```

sht3xd — SHT3x-D Humidity and Temperature Sensor



The [Sensirion SHT3x-D](#) is a series of digital of Humidity and Temperature Sensors. This driver supports the SHT30-D, SHT31-D, and SHT35-D using an I2C interface. The analog SHT3x-A, such as SHT30-A and SHT31-A are not supported.

The SHT3x-D sensors supports I2C speed of up to 1MHz.

Current limitations of this driver:

- Only supports using the *i2c_soft* — *Software I2C* driver to communicate with the SHT3x sensor, not the *i2c* — *I2C* driver.

- Only supports basic functionality and high repeatability mode.
- Does not perform check CRC of sensor result.

Datasheet: [Datasheet SHT3x-DIS](#)

Source code: [src/drivers/sht3xd.h](#), [src/drivers/sht3xd.c](#)

Defines

SHT3X_DIS_I2C_ADDR_A 0x44

SHT3x-DIS default I2C address.

SHT3X_DIS_I2C_ADDR_B 0x45

SHT3x-DIS alternate I2C address.

MEASUREMENT_DURATION_HIGH_MS 15

Max measurement time for high repeatability.

Functions

int **sht3xd_module_init** (void)

Initialize the driver module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **sht3xd_init** (struct *sht3xd_driver_t* *self_p, struct *i2c_soft_driver_t* *i2c_p, int i2c_addr)

Initialize driver object. The driver object will be used for a single sensor.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialize.
- i2c_p: The I2C driver pointer.
- i2c_addr: The address of the SHT3x-D. Probably SHT3X_DIS_I2C_ADDR_A.

int **sht3xd_start** (struct *sht3xd_driver_t* *self_p)

Start the driver.

This verify the sensor is present.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.

int **sht3xd_get_temp_humid** (struct *sht3xd_driver_t* *self_p, float *temp_p, float *humid_p)

Get measurements and return it from the SHD3x-DIS chip.

This is a “high level” function which will block for the time it takes the sensor to perform the measurement.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `temp_p`: Temperature in Celsius, or NULL.
- `humid_p`: Relative Humidity, or NULL.

int **sht3xd_get_serial** (struct *sht3xd_driver_t* **self_p*, uint32_t **serial_p*)
Get the serial number from the SHD3x-D.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object.
- `serial_p`: Serial number of the SHT3x-D sensor.

```
struct sht3xd_driver_t
#include <sht3xd.h>
```

Public Members

```
struct i2c_soft_driver_t *i2c_p
int i2c_addr
uint32_t serial
```

spi — Serial Peripheral Interface

Source code: [src/drivers/spi.h](#), [src/drivers/spi.c](#)

Defines

```
SPI_MODE_SLAVE 0
SPI_MODE_MASTER 1
SPI_SPEED_8MBPS SPI_PORT_SPEED_8MBPS
SPI_SPEED_4MBPS SPI_PORT_SPEED_4MBPS
SPI_SPEED_2MBPS SPI_PORT_SPEED_2MBPS
SPI_SPEED_1MBPS SPI_PORT_SPEED_1MBPS
SPI_SPEED_500KBPS SPI_PORT_SPEED_500KBPS
SPI_SPEED_250KBPS SPI_PORT_SPEED_250KBPS
SPI_SPEED_125KBPS SPI_PORT_SPEED_125KBPS
```

Functions

int **spi_module_init** (void)

Initialize SPI module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **spi_init** (struct spi_driver_t *self_p, struct spi_device_t *dev_p, struct pin_device_t *ss_pin_p, int mode, int speed, int polarity, int phase)

Initialize driver object.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to initialize.
- dev_p: Device to use.
- ss_pin_p: Slave select pin device.
- mode: Master or slave mode.
- speed: Speed in kbps.
- polarity: Set to 0 or 1.
- phase: Set to 0 or 1.

int **spi_start** (struct spi_driver_t *self_p)

Start given SPI driver. Configures the SPI hardware.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.

int **spi_stop** (struct spi_driver_t *self_p)

Stop given SPI driver. Deconfigures the SPI hardware if given driver currently owns the bus.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.

int **spi_take_bus** (struct spi_driver_t *self_p)

In multi master application the driver must take ownership of the SPI bus before performing data transfers. Will re-configure the SPI hardware if configured by another driver.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.

int **spi_give_bus** (struct spi_driver_t *self_p)

In multi master application the driver must give ownership of the SPI bus to let other masters take it.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.

int **spi_select** (**struct** spi_driver_t **self_p*)
Select the slave by asserting the slave select pin.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.

int **spi_deselect** (**struct** spi_driver_t **self_p*)
Deselect the slave by de-asserting the slave select pin.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.

ssize_t **spi_transfer** (**struct** spi_driver_t **self_p*, void **rxbuf_p*, **const** void **txbuf_p*, size_t *size*)
Simultaneous read/write operation over the SPI bus.

Return Number of transferred bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `rxbuf_p`: Buffer to read into.
- `txbuf_p`: Buffer to write.
- `size`: Number of bytes to transfer.

ssize_t **spi_read** (**struct** spi_driver_t **self_p*, void **buf_p*, size_t *size*)
Read data from the SPI bus.

Return Number of read bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to receive.

ssize_t **spi_write** (**struct** spi_driver_t **self_p*, **const** void **buf_p*, size_t *size*)
Write data to the SPI bus.

Return Number of written bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `buf_p`: Buffer to write.

- `size`: Number of bytes to write.

`ssize_t spi_get (struct spi_driver_t *self_p, uint8_t *data_p)`
Get one byte of data from the SPI bus.

Return Number of read bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `data_p`: Read data.

`ssize_t spi_put (struct spi_driver_t *self_p, uint8_t data)`
Put one byte of data to the SPI bus.

Return Number of written bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `data`: data to write.

Variables

`struct spi_device_t spi_device[SPI_DEVICE_MAX]`

uart — Universal Asynchronous Receiver/Transmitter

Source code: [src/drivers/uart.h](#), [src/drivers/uart.c](#)

Test code: [tst/drivers/uart/main.c](#)

Defines

`uart_read (self_p, buf_p, size) queue_read(&(self_p->chin, buf_p, size)`
Read data from the UART.

Return Number of received bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to receive.

`uart_write (self_p, buf_p, size) (self_p->chout.write(&(self_p->chout, buf_p, size)`
Write data to the UART.

Return Number of written bytes or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

Typedefs

```
typedef int (*uart_rx_filter_cb_t) (char c)
```

Functions

```
int uart_module_init (void)
```

Initialize UART module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

```
int uart_init (struct uart_driver_t *self_p, struct uart_device_t *dev_p, long baudrate, void *rxbuf_p,
               size_t size)
```

Initialize driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to be initialized.
- `dev_p`: Device to use.
- `baudrate`: Baudrate.
- `rxbuf_p`: Reception buffer.
- `size`: Reception buffer size.

```
int uart_set_rx_filter_cb (struct uart_driver_t *self_p, uart_rx_filter_cb_t rx_filter_cb)
```

Set the reception filter callback function.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `rx_filter_cb`: Callback to set.

```
int uart_start (struct uart_driver_t *self_p)
```

Starts the UART device using given driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.

```
int uart_stop (struct uart_driver_t *self_p)
```

Stops the UART device referenced by driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.

int **uart_device_start** (**struct** uart_device_t **dev_p*, long *baudrate*)

Starts the UART device using given configuration. The UART device group of functions does not use interrupts, but instead polls the hardware for events. The driver and device functions may not be used for the same UART device.

Return zero(0) or negative error code.

Parameters

- `dev_p`: UART device to start.
- `baudrate`: Baudrate.

int **uart_device_stop** (**struct** uart_device_t **dev_p*)

Stops given UART device.

Return zero(0) or negative error code.

Parameters

- `dev_p`: UART device to stop.

ssize_t **uart_device_read** (**struct** uart_device_t **dev_p*, void **buf_p*, size_t *size*)

Read data from the UART. This function does not wait for interrupts, but instead busy-waits for data by polling UART registers.

Return Number of received bytes or negative error code.

Parameters

- `dev_p`: UART device to read from.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to receive.

ssize_t **uart_device_write** (**struct** uart_device_t **dev_p*, **const** void **buf_p*, size_t *size*)

Write data to the UART. This function does not wait for interrupts, but instead busy-waits for data by polling UART registers.

Return Number of written bytes or negative error code.

Parameters

- `dev_p`: UART device to write to.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

Variables

struct uart_device_t **uart_device**[UART_DEVICE_MAX]

uart_soft — Software Universal Asynchronous Receiver/Transmitter

Source code: `src/drivers/uart_soft.h`, `src/drivers/uart_soft.c`

Defines

uart_soft_read(self_p, buf_p, size) `queue_read(&(self_p)->chin, buf_p, size)`
 Read data from the UART.

Return Number of received bytes or negative error code.

Parameters

- self_p: Initialized driver object.
- buf_p: Buffer to read into.
- size: Number of bytes to receive.

uart_soft_write(self_p, buf_p, size) `(self_p)->chout.write(&(self_p)->chout, buf_p, size)`
 Write data to the UART.

Return number of sent bytes or negative error code.

Parameters

- self_p: Initialized driver object.
- buf_p: Buffer to write.
- size: Number of bytes to write.

Functions

int uart_soft_init(**struct** *uart_soft_driver_t* *self_p, **struct** pin_device_t *tx_dev_p, **struct** pin_device_t *rx_dev_p, **struct** exti_device_t *rx_exti_dev_p, int baudrate, void *rxbuf_p, size_t size)
 Initialize driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.
- tx_dev_p: TX pin device.
- rx_dev_p: RX pin device.
- rx_exti_dev_p: RX pin external interrupt device.
- baudrate: Baudrate.
- rxbuf_p: Reception buffer.
- size: Reception buffer size.

struct uart_soft_driver_t
#include <uart_soft.h>

Public Members

```
struct pin_driver_t tx_pin
struct pin_driver_t rx_pin
struct exti_driver_t rx_exti
struct chan_t chout
struct queue_t chin
int sample_time
int baudrate
```

usb — Universal Serial Bus

Source code: [src/drivers/usb.h](#), [src/drivers/usb.c](#)

Defines

```
REQUEST_TYPE_DATA_MASK (0x80)
REQUEST_TYPE_DATA_DIRECTION_HOST_TO_DEVICE (0x00)
REQUEST_TYPE_DATA_DIRECTION_DEVICE_TO_HOST (0x80)
REQUEST_TYPE_TYPE_MASK (0x60)
REQUEST_TYPE_TYPE_STANDARD (0x00)
REQUEST_TYPE_TYPE_CLASS (0x20)
REQUEST_TYPE_TYPE_VENDOR (0x40)
REQUEST_TYPE_RECIPIENT_MASK (0x0f)
REQUEST_TYPE_RECIPIENT_DEVICE (0x00)
REQUEST_TYPE_RECIPIENT_INTERFACE (0x01)
REQUEST_TYPE_RECIPIENT_ENDPOINT (0x02)
REQUEST_TYPE_RECIPIENT_OTHER (0x03)
REQUEST_GET_STATUS 0
REQUEST_SET_ADDRESS 5
REQUEST_GET_DESCRIPTOR 6
REQUEST_SET_CONFIGURATION 9
DESCRIPTOR_TYPE_DEVICE 1
DESCRIPTOR_TYPE_CONFIGURATION 2
DESCRIPTOR_TYPE_STRING 3
DESCRIPTOR_TYPE_INTERFACE 4
DESCRIPTOR_TYPE_ENDPOINT 5
```

```

DESCRIPTOR_TYPE_INTERFACE_ASSOCIATION 11
DESCRIPTOR_TYPE_RPIPE 34
DESCRIPTOR_TYPE_CDC 36
USB_CLASS_USE_INTERFACE 0x00 /* Device. */
USB_CLASS_AUDIO 0x01 /* Interface. */
USB_CLASS_CDC_CONTROL 0x02 /* Both. */
USB_CLASS_HID 0x03 /* Interface. */
USB_CLASS_PHYSICAL 0x05 /* Interface. */
USB_CLASS_IMAGE 0x06 /* Interface. */
USB_CLASS_PRINTER 0x07 /* Interface. */
USB_CLASS_MASS_STORAGE 0x08 /* Interface. */
USB_CLASS_HUB 0x09 /* Device. */
USB_CLASS_CDC_DATA 0x0a /* Interface. */
USB_CLASS_SMART_CARD 0x0b /* Interface. */
USB_CLASS_CONTENT_SECURITY 0x0d /* Interface. */
USB_CLASS_VIDEO 0x0e /* Interface. */
USB_CLASS_PERSONAL_HEALTHCARE 0x0f /* Interface. */
USB_CLASS_AUDIO_VIDEO_DEVICES 0x10 /* Interface. */
USB_CLASS_BILLBOARD_DEVICE_CLASS 0x11 /* Device. */
USB_CLASS_DIAGNOSTIC_DEVICE 0xdc /* Both. */
USB_CLASS_WIRELESS_CONTROLLER 0xe0 /* Interface. */
USB_CLASS_MISCELLANEOUS 0xef /* Both. */
USB_CLASS_APPLICATION_SPECIFIC 0xfe /* Interface. */
USB_CLASS_VENDOR_SPECIFIC 0xff /* Both. */
ENDPOINT_ENDPOINT_ADDRESS_DIRECTION (address) (((address) >> 7) & 0x1)
ENDPOINT_ENDPOINT_ADDRESS_NUMBER (address) (((address) >> 0) & 0xf)
ENDPOINT_ATTRIBUTES_USAGE_TYPE (attributes) (((attributes) >> 4) & 0x3)
ENDPOINT_ATTRIBUTES_SYNCHRONISATION_TYPE (attributes) (((attributes) >> 2) & 0x3)
ENDPOINT_ATTRIBUTES_TRANSFER_TYPE (attributes) (((attributes) >> 0) & 0x3)
ENDPOINT_ATTRIBUTES_TRANSFER_TYPE_CONTROL 0
ENDPOINT_ATTRIBUTES_TRANSFER_TYPE_ISOCHRONOUS 1
ENDPOINT_ATTRIBUTES_TRANSFER_TYPE_BULK 2
ENDPOINT_ATTRIBUTES_TRANSFER_TYPE_INTERRUPT 3
CONFIGURATION_ATTRIBUTES_BUS_POWERED 0x80
USB_CDC_LINE_CODING 0x20
USB_CDC_CONTROL_LINE_STATE 0x22

```

```
USB_CDC_SEND_BREAK 0x23
USB_MESSAGE_TYPE_ADD 0
USB_MESSAGE_TYPE_REMOVE 1
```

Functions

int **usb_format_descriptors** (void **out_p*, uint8_t **buf_p*, size_t *size*)
Format the descriptors and write them to given channel.

Return zero(0) or negative error code.

Parameters

- *out_p*: Output channel.
- *buf_p*: Pointer to the descriptors to format.
- *size*: Number of bytes in the descriptors buffer.

struct *usb_descriptor_configuration_t* ***usb_desc_get_configuration** (uint8_t **desc_p*, size_t *size*,
int *configuration*)

Get the configuration descriptor for given configuration index.

Return Configuration or NULL on failure.

Parameters

- *buf_p*: Pointer to the descriptors.
- *size*: Number of bytes in the descriptors buffer.
- *configuration*: Configuration to find.

struct *usb_descriptor_interface_t* ***usb_desc_get_interface** (uint8_t **desc_p*, size_t *size*, int *configuration*,
int *interface*)

Get the interface descriptor for given configuration and interface index.

Return Interface or NULL on failure.

Parameters

- *buf_p*: Pointer to the descriptors.
- *size*: Number of bytes in the descriptors buffer.
- *configuration*: Configuration to find.
- *interface*: Interface to find.

struct *usb_descriptor_endpoint_t* ***usb_desc_get_endpoint** (uint8_t **desc_p*, size_t *size*, int *configuration*,
int *interface*, int *endpoint*)

Get the endpoint descriptor for given configuration, interface and endpoint index.

Return Endpoint or NULL on failure.

Parameters

- *buf_p*: Pointer to the descriptors.
- *size*: Number of bytes in the descriptors buffer.

- `configuration`: Configuration to find.
- `interface`: Interface to find.
- `endpoint`: Endpoint to find.

int **usb_desc_get_class** (uint8_t **buf_p*, size_t *size*, int *configuration*, int *interface*)

Get the interface class.

Return

Parameters

- `buf_p`: Pointer to the descriptors.
- `size`: Number of bytes in the descriptors buffer.
- `configuration`: Configuration to find.
- `interface`: Interface to find.

Variables

struct usb_device_t **usb_device**[USB_DEVICE_MAX]

struct usb_setup_t

Public Members

uint8_t **request_type**

uint8_t **request**

uint16_t **feature_selector**

uint16_t **zero_interface_endpoint**

struct usb_setup_t::@20::@21 **usb_setup_t::clear_feature**

uint16_t **zero0**

uint16_t **zero1**

struct usb_setup_t::@20::@22 **usb_setup_t::get_configuration**

uint8_t **descriptor_index**

uint8_t **descriptor_type**

uint16_t **language_id**

struct usb_setup_t::@20::@23 **usb_setup_t::get_descriptor**

uint16_t **device_address**

uint16_t **zero**

struct usb_setup_t::@20::@24 **usb_setup_t::set_address**

uint16_t **configuration_value**

struct usb_setup_t::@20::@25 **usb_setup_t::set_configuration**

uint16_t **value**

```
uint16_t index
struct usb_setup_t::@20::@26  usb_setup_t::base
union usb_setup_t::@20  usb_setup_t::u
uint16_t length
struct usb_descriptor_header_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
struct usb_descriptor_device_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
uint16_t bcd_usb
uint8_t device_class
uint8_t device_subclass
uint8_t device_protocol
uint8_t max_packet_size_0
uint16_t id_vendor
uint16_t id_product
uint16_t bcd_device
uint8_t manufacturer
uint8_t product
uint8_t serial_number
uint8_t num_configurations
struct usb_descriptor_configuration_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
uint16_t total_length
uint8_t num_interfaces
uint8_t configuration_value
uint8_t configuration
```

```
uint8_t configuration_attributes
uint8_t max_power
struct usb_descriptor_interface_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
uint8_t interface_number
uint8_t alternate_setting
uint8_t num_endpoints
uint8_t interface_class
uint8_t interface_subclass
uint8_t interface_protocol
uint8_t interface
struct usb_descriptor_endpoint_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
uint8_t endpoint_address
uint8_t attributes
uint16_t max_packet_size
uint8_t interval
struct usb_descriptor_string_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
uint8_t string[256]
struct usb_descriptor_interface_association_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
uint8_t first_interface
```

```
uint8_t interface_count
uint8_t function_class
uint8_t function_subclass
uint8_t function_protocol
uint8_t function
```

```
struct usb_descriptor_cdc_header_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
uint8_t sub_type
uint16_t bcd
```

```
struct usb_descriptor_cdc_acm_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
uint8_t sub_type
uint8_t capabilities
```

```
struct usb_descriptor_cdc_union_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
uint8_t sub_type
uint8_t master_interface
uint8_t slave_interface
```

```
struct usb_descriptor_cdc_call_management_t
```

Public Members

```
uint8_t length
uint8_t descriptor_type
uint8_t sub_type
uint8_t capabilities
uint8_t data_interface
```


union usb_descriptor_t

Public Members

struct *usb_descriptor_header_t* **header**
struct *usb_descriptor_device_t* **device**
struct *usb_descriptor_configuration_t* **configuration**
struct *usb_descriptor_interface_t* **interface**
struct *usb_descriptor_endpoint_t* **endpoint**
struct *usb_descriptor_string_t* **string**

struct usb_cdc_line_info_t

Public Members

uint32_t **dte_rate**
uint8_t **char_format**
uint8_t **parity_type**
uint8_t **data_bits**

struct usb_message_header_t

Public Members

int **type**

struct usb_message_add_t

Public Members

struct *usb_message_header_t* **header**
int **device**

union usb_message_t

Public Members

struct *usb_message_header_t* **header**
struct *usb_message_add_t* **add**

usb_device — Universal Serial Bus - Device

A USB device is powered and enumerated by a USB host.

The implementation of this module aims to be simple, but yet flexible. It's possible to change the USB configuration descriptors at runtime by stopping the current driver, initialize a new driver and start the new driver. For simple devices only a single configuration is normally needed.

Using the USB device module is fairly easy. First write the USB descriptors, then initialize the class drivers, then initialize the USB device driver and then start it.

See the test code below for an example usage.

Class driver modules:

usb_device_class_cdc — CDC ACM (serial port over USB)

USB CDC (Communications Device Class) ACM (Abstract Control Model) is a vendor-independent publicly documented protocol that can be used for emulating serial ports over USB.

More information on [Wikipedia](#).

Source code: [src/drivers/usb/device/class/cdc.h](#), [src/drivers/usb/device/class/cdc.c](#)

Test code: [tst/drivers/usb_device/main.c](#)

Defines

usb_device_class_cdc_read (self_p, buf_p, size) queue_read(&(self_p)->chin, buf_p, size)

Read data from the CDC driver.

Return Number of bytes read or negative error code.

Parameters

- self_p: Initialized driver object.
- buf_p: Buffer to read into.
- size: Number of bytes to read.

usb_device_class_cdc_write (self_p, buf_p, size) (self_p)->chout.write(&(self_p)->chout, buf_p, size)

Write data to the CDC driver.

Return Number of bytes written or negative error code.

Parameters

- self_p: Initialized driver object.
- buf_p: Buffer to write.
- size: Number of bytes to write.

Functions

int **usb_device_class_cdc_module_init** (void)

Initialize the CDC module.

Return zero(0) or negative error code.

int **usb_device_class_cdc_init** (struct *usb_device_class_cdc_driver_t* *self_p, int control_interface,
int endpoint_in, int endpoint_out, void *rxbuf_p, size_t size)

Initialize driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.
- rxbuf_p: Reception buffer.
- size: Reception buffer size.

int **usb_device_class_cdc_input_isr** (struct *usb_device_class_cdc_driver_t* *self_p)

Called by the USB device driver periodically to let the CDC driver read received data from the hardware.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.

int **usb_device_class_cdc_is_connected** (struct *usb_device_class_cdc_driver_t* *self_p)

Check if the CDC is connected to the remote endpoint.

Return true(1) if connected, false(0) if disconnected, otherwise negative error code.

Parameters

- self_p: Initialized driver object.

struct **usb_device_class_cdc_driver_t**

#include <cdc.h>

Public Members

struct usb_device_driver_base_t **base**

struct usb_device_driver_t ***drv_p**

int **control_interface**

int **endpoint_in**

int **endpoint_out**

int **line_state**

struct *usb_cdc_line_info_t* **line_info**

struct *chan_t* **chout**

struct *queue_t* **chin**

Source code: `src/drivers/usb_device.h`, `src/drivers/usb_device.c`

Test code: `tst/drivers/usb_device/main.c`

Functions

`int usb_device_module_init (void)`

`int usb_device_init(struct usb_device_driver_t * self_p, struct usb_device_t * dev_p, s`
Initialize the USB device driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to be initialized.
- `dev_p`: USB device to use.
- `drivers_pp`: An array of initialized drivers.
- `drivers_max`: Length of the drivers array.
- `descriptors_pp`: A NULL terminated array of USB descriptors.

`int usb_device_start (struct usb_device_driver_t *self_p)`
Start the USB device device using given driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.

`int usb_device_stop (struct usb_device_driver_t *self_p)`
Stop the USB device device referenced by driver object.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver object.

`ssize_t usb_device_write (struct usb_device_driver_t *self_p, int endpoint, const void *buf_p, size_t`
size
Write data to given endpoint.

Return Number of bytes written or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `endpoint`: Endpoint to write to.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

`ssize_t usb_device_read_isr (struct usb_device_driver_t *self_p, int endpoint, void *buf_p, size_t size)`
Read data from given endpoint from an isr or with the system lock taken.

Return Number of bytes read or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `endpoint`: Endpoint to read data from.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to read.

`ssize_t usb_device_write_isr (struct usb_device_driver_t *self_p, int endpoint, const void *buf_p, size_t size)`
Write data to given endpoint from an isr or with the system lock taken.

Return Number of bytes written or negative error code.

Parameters

- `self_p`: Initialized driver object.
- `endpoint`: Endpoint to write to.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

usb_host — Universal Serial Bus - Host

A USB host powers the bus and enumerates connected USB devices.

Class driver modules:

usb_host_class_hid — Human Interface Device (HID)

In computing, the USB human interface device class (USB HID class) is a part of the USB specification for computer peripherals: it specifies a device class (a type of computer hardware) for human interface devices such as keyboards, mice, game controllers and alphanumeric display devices.

More information on [Wikipedia](#).

Source code: [src/drivers/usb/host/class/hid.h](#), [src/drivers/usb/host/class/hid.c](#)

Defines

```
USB_CLASS_HID_SUBCLASS_NONE 0
USB_CLASS_HID_SUBCLASS_BOOT_INTERFACE 1
USB_CLASS_HID_PROTOCOL_NONE 0
USB_CLASS_HID_PROTOCOL_KEYBOARD 1
USB_CLASS_HID_PROTOCOL_MOUSE 2
```

Functions

int **usb_host_class_hid_init** (struct *usb_host_class_hid_driver_t* *self_p, struct usb_host_driver_t *usb_p, struct *usb_host_class_hid_device_t* *devices_p, size_t length)
Initialize driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.
- usb_p: USB driver to use.
- devices_p: Array of devices. One entry in this array is allocated for each HID device that is connected to the host.
- length: Length of the devices array.

int **usb_host_class_hid_start** (struct *usb_host_class_hid_driver_t* *self_p)
Starts the HID driver.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object to start.

int **usb_host_class_hid_stop** (struct *usb_host_class_hid_driver_t* *self_p)
Stops the HID driver.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized to stop.

```
struct usb_host_class_hid_device_t
```

Public Members

```
uint8_t buf[1]
```

```
struct usb_host_class_hid_driver_t
```

Public Members

```

struct usb_host_driver_t *usb_p
struct usb_host_class_hid_device_t *devices_p
size_t length
size_t size

struct usb_host_class_hid_driver_t::@18  usb_host_class_hid_driver_t::report
struct usb_host_device_driver_t device_driver

```

usb_host_class_mass_storage — Mass Storage

The USB mass storage device class (also known as USB MSC or UMS) is a set of computing communications protocols defined by the USB Implementers Forum that makes a USB device accessible to a host computing device and enables file transfers between the host and the USB device. To a host, the USB device acts as an external hard drive; the protocol set interfaces with a number of storage devices.

More information on [Wikipedia](#).

Source code: `src/drivers/usb/host/class/mass_storage.h`, `src/drivers/usb/host/class/mass_storage.c`

Functions

```

int usb_host_class_mass_storage_init (struct usb_host_class_mass_storage_driver_t
                                         *self_p, struct usb_host_driver_t *usb_p, struct
                                         usb_host_class_mass_storage_device_t *devices_p,
                                         size_t length)

int usb_host_class_mass_storage_start (struct usb_host_class_mass_storage_driver_t *self_p)

int usb_host_class_mass_storage_stop (struct usb_host_class_mass_storage_driver_t *self_p)

ssize_t usb_host_class_mass_storage_device_read (struct usb_host_device_t *device_p, void
                                                  *buf_p, size_t address, size_t size)

struct usb_host_class_mass_storage_device_t
#include <mass_storage.h>

```

Public Members

```

uint8_t buf[1]

struct usb_host_class_mass_storage_driver_t

```

Public Members

```
struct usb_host_driver_t *usb_p
struct usb_host_class_mass_storage_device_t *devices_p
size_t length
size_t size
struct usb_host_class_mass_storage_driver_t::@19 usb_host_class_mass_storage_driver_t
struct usb_host_device_driver_t device_driver
```

Source code: [src/drivers/usb_host.h](#), [src/drivers/usb_host.c](#)

Defines

```
USB_HOST_DEVICE_STATE_NONE 0
USB_HOST_DEVICE_STATE_ATTACHED 1
USB_PIPE_TYPE_CONTROL 0
USB_PIPE_TYPE_INTERRUPT 1
USB_PIPE_TYPE_ISOCHRONOUS 2
USB_PIPE_TYPE_BULK 3
```

Functions

int **usb_host_module_init** (void)

Initialize the USB host module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **usb_host_init** (struct usb_host_driver_t *self_p, struct usb_device_t *dev_p, struct *usb_host_device_t* *devices_p, size_t length)

Initialize the USB host driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.
- dev_p: USB device to use.
- devices_p: An array of devices. One entry in this array is allocated for each USB device that is connected to the host.
- length: Length of the devices array.

int **usb_host_start** (struct usb_host_driver_t *self_p)
 Start the USB host device using given driver object.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.

int **usb_host_stop** (struct usb_host_driver_t *self_p)
 Stop the USB host device referenced by driver object.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.

int **usb_host_driver_add** (struct usb_host_driver_t *self_p, struct usb_host_device_driver_t *driver_p,
 void *arg_p)
 Add given class/vendor driver to the USB host driver.

When a USB device is plugged in, its class and vendor information is read by the host. Those values are used to find the device driver for this particular device. If there is no driver, the device cannot be configured and will not work.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.
- driver_p: USB device driver to add.

int **usb_host_driver_remove** (struct usb_host_driver_t *self_p, struct usb_host_device_driver_t
 *driver_p)
 Remove given class/vendor driver from the USB host driver.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized driver object.
- driver_p: USB device driver to remove.

struct usb_host_device_t ***usb_host_device_open** (struct usb_host_driver_t *self_p, int device)
 Open given device in given driver. Open a device before reading and writing data to it with usb_host_device_read() or usb_host_device_write().

Return Opened device or NULL on failure.

Parameters

- self_p: Initialized driver.
- device: Device to open.

int **usb_host_device_close** (struct usb_host_driver_t *self_p, int device)
 Close given device in given driver.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized driver.
- `device`: Device to close.

`ssize_t usb_host_device_read(struct usb_host_device_t *device_p, int endpoint, void *buf_p, size_t size)`
Read data from given endpoint for given device.

Return Number of bytes read or negative error code.

Parameters

- `device_p`: Device to read from.
- `endpoint`: Endpoint to read data from.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to read.

`ssize_t usb_host_device_write(struct usb_host_device_t *device_p, int endpoint, const void *buf_p, size_t size)`
Write data to given endpoint for given device.

Return Number of bytes written or negative error code.

Parameters

- `device_p`: Device to write to.
- `endpoint`: Endpoint to write to.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

`ssize_t usb_host_device_control_transfer(struct usb_host_device_t *device_p, struct usb_setup_t *setup_p, void *buf_p, size_t size)`
Perform a control transfer on endpoint zero(0).

A control transfer can have up to three stages. First the setup stage, then an optional data stage, and at last a status stage.

Return Number of bytes read/written or negative error code.

Parameters

- `device_p`: Device to write to.
- `setup_p`: Setup packet to write.
- `buf_p`: Buffer to read/write. May be NULL if no data shall be transferred.
- `size`: Number of bytes to read/write.

`int usb_host_device_set_configuration(struct usb_host_device_t *device_p, uint8_t configuration)`
Set configuration for given device.

Return zero(0) or negative error code.

Parameters

- `device_p`: Device to use.
- `configuration`: Configuration to set.

struct `usb_host_device_t`

#include <usb_host.h> An USB device as seen by the host.

Public Members

```
int id
int state
int address
int vid
int pid
char *description_p
size_t max_packet_size
uint8_t configuration
struct usb_descriptor_device_t *dev_p
struct usb_descriptor_configuration_t *conf_p
struct usb_host_device_t::@27::@29 usb_host_device_t::descriptor
struct usb_host_device_t::@27 usb_host_device_t::current
struct usb_host_driver_t *self_p
struct usb_pipe_t *pipes[32]
size_t size
uint8_t buf[128]
struct usb_host_device_t::@28 usb_host_device_t::descriptors
```

struct `usb_host_device_driver_t`

#include <usb_host.h> Used to find a device driver.

Public Members

```
int (*supports)(struct usb_host_device_t *)
int (*enumerate)(struct usb_host_device_t *)
struct usb_host_device_driver_t *next_p
```

watchdog — Hardware watchdog

Source code: [src/drivers/watchdog.h](#), [src/drivers/watchdog.c](#)

Typedefs

```
typedef void (*watchdog_isr_fn_t) (void)
```

Functions

```
int watchdog_module_init (void)
```

Initialize the watchdog driver module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

```
int watchdog_start_ms (int timeout, watchdog_isr_fn_t on_interrupt)
```

Start the watchdog with given timeout. Use `watchdog_kick()` to periodically restart the timer.

Return zero(0) or negative error code.

Parameters

- `timeout`: Watchdog timeout in milliseconds.
- `on_interrupt`: Function callback called when a watchdog interrupt occurs. Not all MCU:s supports this feature.

```
int watchdog_stop (void)
```

Stop the watchdog.

Return zero(0) or negative error code.

```
int watchdog_kick (void)
```

Kick the watchdog. Restarts the watchdog timer with its original timeout given to `watchdog_start_ms()`. The board will be reset if this function is not called before the watchdog timer expires.

Return zero(0) or negative error code.

ws2812 — NeoPixels

Source code: [src/drivers/ws2812.h](#), [src/drivers/ws2812.c](#)

Defines

```
WS2812_PIN_DEVICES_MAX 8
```

Functions

int **ws2812_module_init** (void)

Initialize the WS2812 driver module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **ws2812_init** (struct *ws2812_driver_t* *self_p, struct pin_device_t **pin_devices_pp, int number_of_pin_devices)

Initialize given driver object from given configuration.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object to be initialized.
- pin_devices_pp: An array of pin device(s) to use. The maximum length of the array is defined as WS2812_PIN_DEVICES_MAX.
- number_of_pin_devices: Number of pin devices in the pin devices array.

int **ws2812_write** (struct *ws2812_driver_t* *self_p, const uint8_t *colors_p, int number_of_pixles)

Write given RGB colors to the NeoPixels.

CAUTION: Interrupts are disabled during the write to meet the strict timing requirements on the pulse train. It takes ~30 us to write to one pixel, that is, interrupts are disabled for ~30 * number_of_pixles us. Long pixel chains may cause the rest of the system to misbehave.

Return zero(0) or negative error code.

Parameters

- self_p: Driver object.
- colors_p: An array of GRB colors to write to the NeoPixels. All pin devices green component first, then all red, and last all blue, repeated for all NeoPixels. For example, when a single pin device is configured the array is G0, R0, B0, G1, R1, B1, ...
- number_of_pixles: Number of GRB colors per pin device in colors_p.

struct **ws2812_driver_t**

Public Members

struct pin_device_t **pins_pp

int number_of_pins

uint32_t mask

filesystems

File systems and file system like frameworks.

The filesystems package on [Github](#).

fat16 — FAT16 filesystem

File Allocation Table (FAT) is a computer file system architecture and a family of industry-standard file systems utilizing it. The FAT file system is a legacy file system which is simple and robust. It offers good performance even in light-weight implementations, but cannot deliver the same performance, reliability and scalability as some modern file systems. It is, however, supported for compatibility reasons by nearly all currently developed operating systems for personal computers and many mobile devices and embedded systems, and thus is a well-suited format for data exchange between computers and devices of almost any type and age from 1981 up to the present.

Example

Here is the pseudo-code for mounting a file system, performing file operations and unmounting the file system.

All function arguments are omitted in this example.

```
/* Mount the file system. This is normally done once when the
   application starts. */
fat16_init();
fat16_mount();

/* Perform file operations. */
fat16_file_open();
fat16_file_read();
fat16_file_close();

fat16_file_open();
fat16_file_write();
fat16_file_close();

/* Unmount the file system when it is no long needed. Normally when
   the application stops. */
fat16_unmount();
```

Source code: [src/filesystems/fat16.h](#), [src/filesystems/fat16.c](#)

Test code: [tst/filesystems/fat16/main.c](#)

Test coverage: [src/filesystems/fat16.c](#)

Example code: [examples/fat16/main.c](#)

Defines

FAT16_SEEK_SET 0

FAT16_SEEK_CUR 1

The offset is relative to the current position indicator.

FAT16_SEEK_END 2

The offset is relative to the end of the file.

FAT16_EOF -1

End of file indicator.

O_READ 0x01

Open for reading.

O_RDONLY O_READ

Same as O_READ.

O_WRITE 0x02

Open for write.

O_WRONLY O_WRITE

Same as O_WRITE.

O_RDWR (O_READ | O_WRITE)

Open for reading and writing.

O_APPEND 0x04

The file position indicator shall be set to the end of the file prior to each write.

O_SYNC 0x08

Synchronous writes.

O_CREAT 0x10

Create the file if non-existent.

O_EXCL 0x20

If O_CREAT and O_EXCL are set, file open shall fail if the file exists.

O_TRUNC 0x40

Truncate the file to zero length.

DIR_ATTR_READ_ONLY 0x01

File is read-only.

DIR_ATTR_HIDDEN 0x02

File should hidden in directory listings.

DIR_ATTR_SYSTEM 0x04

Entry is for a system file.

DIR_ATTR_VOLUME_ID 0x08

Directory entry contains the volume label.

DIR_ATTR_DIRECTORY 0x10

Entry is for a directory.

DIR_ATTR_ARCHIVE 0x20

Old DOS archive bit for backup support.

Typedefs

```
typedef ssize_t (*fat16_read_t) (void *arg_p, void *dst_p, uint32_t src_block)
```

Block read function callback.

```
typedef ssize_t (*fat16_write_t) (void *arg_p, uint32_t dst_block, const void *src_p)
```

Block write function callback.

typedef uint16_t fat_t
A FAT entry.

Functions

int **fat16_init** (**struct fat16_t** *self_p, **fat16_read_t** read, **fat16_write_t** write, void *arg_p, unsigned int partition)
Initialize a FAT16 volume.

Return zero(0) or negative error code.

Parameters

- self_p: FAT16 object to initialize.
- read: Callback function used to read blocks of data.
- write: Callback function used to write blocks of data.
- arg_p: Argument passed as the first argumtn to read() and write().
- partition: Partition to be used. Legal values for a partition are 1-4 to use the corresponding partition on a device formatted with a MBR, Master Boot Record, or zero if the device is formatted as a super floppy with the FAT boot sector in block zero.

int **fat16_mount** (**struct fat16_t** *self_p)
Mount given FAT16 volume.

Return zero(0) or negative error code.

Parameters

- self_p: FAT16 object.

int **fat16_unmount** (**struct fat16_t** *self_p)
Unmount given FAT16 volume.

Return zero(0) or negative error code.

Parameters

- self_p: FAT16 object.

int **fat16_format** (**struct fat16_t** *self_p)
Create an empty FAT16 file system on the device.

Parameters

- self_p: FAT16 object.

int **fat16_print** (**struct fat16_t** *self_p, void *chan_p)
Print volume information to given channel.

Return zero(0) or negative error code.

Parameters

- self_p: FAT16 object.
- chan_p: Output channel.

int **fat16_file_open** (struct *fat16_t* **self_p*, struct *fat16_file_t* **file_p*, const char **path_p*, int *oflag*)

Open a file by file path and mode flags.

Return zero(0) or negative error code.

Parameters

- *self_p*: FAT16 object.
- *file_p*: File object to be initialized.
- *path_p*: A valid 8.3 DOS name for a file path.
- *oflag*: mode of file open (create, read, write, etc).

int **fat16_file_close** (struct *fat16_file_t* **file_p*)

Close a file and force cached data and directory information to be written to the media.

Return zero(0) or negative error code.

Parameters

- *file_p*: File object.

ssize_t **fat16_file_read** (struct *fat16_file_t* **file_p*, void **buf_p*, size_t *size*)

Read data to given buffer with given size from the file.

Return Number of bytes read or EOF(-1).

Parameters

- *file_p*: File object.
- *buf_p*: Buffer to read into.
- *size*: number of bytes to read.

ssize_t **fat16_file_write** (struct *fat16_file_t* **file_p*, const void **buf_p*, size_t *size*)

Write data from buffer with given size to the file.

Return Number of bytes written or EOF(-1).

Parameters

- *file_p*: File object.
- *buf_p*: Buffer to write.
- *size*: number of bytes to write.

int **fat16_file_seek** (struct *fat16_file_t* **file_p*, int *pos*, int *whence*)

Sets the file's read/write position relative to mode.

Return zero(0) or negative error code.

Parameters

- *file_p*: File object.
- *pos*: New position in bytes from given mode.
- *whence*: Absolute, relative or from end.

`ssize_t fat16_file_tell (struct fat16_file_t *file_p)`

Return current position in the file.

Return Current position or negative error code.

Parameters

- `file_p`: File object.

`int fat16_file_truncate (struct fat16_file_t *file_p, size_t size)`

Truncate given file to a size of precisely `size` bytes.

If the file previously was larger than this size, the extra data is lost. If the file previously was shorter, it is extended, and the extended part reads as null bytes (`'\0'`).

Return zero(0) or negative error code.

Parameters

- `file_p`: File object.
- `size`: New size of the file in bytes.

`ssize_t fat16_file_size (struct fat16_file_t *file_p)`

Return number of bytes in the file.

Return File size in bytes or negative error code.

Parameters

- `file_p`: File object.

`int fat16_file_sync (struct fat16_file_t *file_p)`

Causes all modified data and directory fields to be written to the storage device.

Return zero(0) or negative error code.

Parameters

- `file_p`: File object.

`int fat16_dir_open (struct fat16_t *self_p, struct fat16_dir_t *dir_p, const char *path_p, int oflag)`

Open a directory by directory path and mode flags.

Return zero(0) or negative error code.

Parameters

- `self_p`: FAT16 object.
- `dir_p`: Directory object to be initialized.
- `path_p`: A valid 8.3 DOS name for a directory path.
- `oflag`: mode of the directory to open (create, read, etc).

`int fat16_dir_close (struct fat16_dir_t *dir_p)`

Close given directory.

Return zero(0) or negative error code.

Parameters

- `dir_p`: Directory object.

int **fat16_dir_read** (struct *fat16_dir_t* **dir_p*, struct *fat16_dir_entry_t* **entry_p*)

Read the next file or directory within the opened directory.

Return true(1) if an entry was read or false(0) if no entry could be read, otherwise negative error code.

Parameters

- `dir_p`: Directory object.
- `entry_p`: Read entry.

int **fat16_stat** (struct *fat16_t* **self_p*, const char **path_p*, struct *fat16_stat_t* **stat_p*)

Gets file status by path.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `path_p`: The path of the file to stat.
- `stat_p`: The stat struct to populate.

Variables

struct *dir_t* **PACKED**

union **fat16_time_t**

#include <fat16.h> FAT Time Format. A FAT directory entry time stamp is a 16-bit field that has a granularity of 2 seconds. Here is the format (bit 0 is the LSB of the 16-bit word, bit 15 is the MSB of the 16-bit word).

Bits 0-4: 2-second count, valid value range 0-29 inclusive (0-58 seconds). Bits 5-10: Minutes, valid value range 0-59 inclusive. Bits 11-15: Hours, valid value range 0-23 inclusive.

The valid time range is from Midnight 00:00:00 to 23:59:58.

Public Members

uint16_t **as_uint16**

uint16_t **seconds**

uint16_t **minutes**

uint16_t **hours**

struct **fat16_time_t::@30** **fat16_time_t::bits**

union **fat16_date_t**

#include <fat16.h> FAT date representation support Date Format. A FAT directory entry date stamp is a 16-bit field that is basically a date relative to the MS-DOS epoch of 01/01/1980. Here is the format (bit 0 is the LSB of the 16-bit word, bit 15 is the MSB of the 16-bit word):

Bits 0-4: Day of month, valid value range 1-31 inclusive. Bits 5-8: Month of year, 1 = January, valid value range 1-12 inclusive. Bits 9-15: Count of years from 1980, valid value range 0-127 inclusive (1980-2107).

Public Members

uint16_t **as_uint16**

uint16_t **day**

uint16_t **month**

uint16_t **year**

struct fat16_date_t::@31 fat16_date_t::bits

struct part_t

#include <fat16.h> MBR partition table entry. A partition table entry for a MBR formatted storage device. The MBR partition table has four entries.

Public Members

uint8_t **boot**

Boot Indicator. Indicates whether the volume is the active partition. Legal values include: 0x00. Do not use for booting. 0x80 Active partition.

uint8_t **begin_head**

Head part of Cylinder-head-sector address of the first block in the partition. Legal values are 0-255. Only used in old PC BIOS.

unsigned **begin_sector**

Sector part of Cylinder-head-sector address of the first block in the partition. Legal values are 1-63. Only used in old PC BIOS.

unsigned **begin_cylinder_high**

High bits cylinder for first block in partition.

uint8_t **begin_cylinder_low**

Combine beginCylinderLow with beginCylinderHigh. Legal values are 0-1023. Only used in old PC BIOS.

uint8_t **type**

Partition type. See defines that begin with PART_TYPE_ for some Microsoft partition types.

uint8_t **end_head**

head part of cylinder-head-sector address of the last sector in the partition. Legal values are 0-255. Only used in old PC BIOS.

unsigned **end_sector**

Sector part of cylinder-head-sector address of the last sector in the partition. Legal values are 1-63. Only used in old PC BIOS.

unsigned **end_cylinder_high**

High bits of end cylinder

uint8_t **end_cylinder_low**

Combine endCylinderLow with endCylinderHigh. Legal values are 0-1023. Only used in old PC BIOS.

uint32_t **first_sector**

Logical block address of the first block in the partition.

uint32_t **total_sectors**

Length of the partition, in blocks.

struct bpb_t

#include <fat16.h> BIOS parameter block; The BIOS parameter block describes the physical layout of a FAT volume.

Public Members**uint16_t bytes_per_sector**

Count of bytes per sector. This value may take on only the following values: 512, 1024, 2048 or 4096

uint8_t sectors_per_cluster

Number of sectors per allocation unit. This value must be a power of 2 that is greater than 0. The legal values are 1, 2, 4, 8, 16, 32, 64, and 128.

uint16_t reserved_sector_count

Number of sectors before the first FAT. This value must not be zero.

uint8_t fat_count

The count of FAT data structures on the volume. This field should always contain the value 2 for any FAT volume of any type.

uint16_t root_dir_entry_count

For FAT12 and FAT16 volumes, this field contains the count of 32-byte directory entries in the root directory. For FAT32 volumes, this field must be set to 0. For FAT12 and FAT16 volumes, this value should always specify a count that when multiplied by 32 results in a multiple of bytesPerSector. FAT16 volumes should use the value 512.

uint16_t total_sectors_small

This field is the old 16-bit total count of sectors on the volume. This count includes the count of all sectors in all four regions of the volume. This field can be 0; if it is 0, then totalSectors32 must be non-zero. For FAT32 volumes, this field must be 0. For FAT12 and FAT16 volumes, this field contains the sector count, and totalSectors32 is 0 if the total sector count fits (is less than 0x10000).

uint8_t media_type

This dates back to the old MS-DOS 1.x media determination and is no longer usually used for anything. 0xf8 is the standard value for fixed (non-removable) media. For removable media, 0xf0 is frequently used. Legal values are 0xf0 or 0xf8-0xff.

uint16_t sectors_per_fat

Count of sectors occupied by one FAT on FAT12/FAT16 volumes. On FAT32 volumes this field must be 0, and sectorsPerFat32 contains the FAT size count.

uint16_t sectors_per_track

Sectors per track for interrupt 0x13. Not used otherwise.

uint16_t head_count

Number of heads for interrupt 0x13. Not used otherwise.

uint32_t hiddden_sectors

Count of hidden sectors preceding the partition that contains this FAT volume. This field is generally only relevant for media visible on interrupt 0x13.

uint32_t total_sectors_large

This field is the new 32-bit total count of sectors on the volume. This count includes the count of all sectors in all four regions of the volume. This field can be 0; if it is 0, then totalSectors16 must be non-zero.

struct fbs_t

#include <fat16.h> Boot sector for a FAT16 or FAT32 volume.

Public Members

uint8_t **jmp_to_boot_code**[3]

X86 jmp to boot program

char **oem_name**[8]

Informational only - don't depend on it

struct *bpb_t* **bpb**

BIOS Parameter Block

uint8_t **drive_number**

For int0x13 use value 0x80 for hard drive

uint8_t **reserved1**

Used by Windows NT - should be zero for FAT

uint8_t **boot_signature**

0x29 if next three fields are valid

uint32_t **volume_serial_number**

Usually generated by combining date and time

char **volume_label**[11]

Should match volume label in root dir

char **file_system_type**[8]

Informational only - don't depend on it

uint8_t **boot_code**[448]

X86 boot code

uint16_t **boot_sector_sig**

Must be 0x55AA

struct **mbr_t**

#include <fat16.h> Master Boot Record. The first block of a storage device that is formatted with a MBR.

Public Members

uint8_t **codeArea**[440]

Code Area for master boot program.

uint32_t **diskSignature**

Optional WindowsNT disk signature. May contain more boot code.

uint16_t **usuallyZero**

Usually zero but may be more boot code.

struct *part_t* **part**[4]

Partition tables.

uint16_t **mbr_sig**

First MBR signature byte. Must be 0x55

struct **dir_t**

#include <fat16.h> FAT short directory entry. Short means short 8.3 name, not the entry size.

Public Members

`uint8_t name[11]`

Short 8.3 name. The first eight bytes contain the file name with blank fill. The last three bytes contain the file extension with blank fill.

`uint8_t attributes`

Entry attributes. The upper two bits of the attribute byte are reserved and should always be set to 0 when a file is created and never modified or looked at after that. See defines that begin with `DIR_ATT_`.

`uint8_t reserved1`

Reserved for use by Windows NT. Set value to 0 when a file is created and never modify or look at it after that.

`uint8_t creation_time_tenths`

The granularity of the seconds part of `creationTime` is 2 seconds so this field is a count of tenths of a second and its valid value range is 0-199 inclusive. (WHG note - seems to be hundredths)

`uint16_t creation_time`

Time file was created.

`uint16_t creation_date`

Date file was created.

`uint16_t last_access_date`

Last access date. Note that there is no last access time, only a date. This is the date of last read or write. In the case of a write, this should be set to the same date as `lastWriteDate`.

`uint16_t first_cluster_high`

High word of this entry's first cluster number (always 0 for a FAT12 or FAT16 volume).

`uint16_t last_write_time`

Time of last write. File creation is considered a write.

`uint16_t last_write_date`

Date of last write. File creation is considered a write.

`uint16_t first_cluster_low`

Low word of this entry's first cluster number.

`uint32_t file_size`

32-bit unsigned holding this file's size in bytes.

`union fat16_cache16_t`

Public Members

`uint8_t data[512]`

fat_t `fat[256]`

`struct dir_t dir[16]`

`struct mbr_t mbr`

`struct fbs_t fbs`

`struct fat16_cache_t`

Public Members

```
uint32_t block_number
uint8_t dirty
uint32_t mirror_block
union fat16_cache16_t buffer
```

```
struct fat16_t
```

Public Members

```
fat16_read_t read
fat16_write_t write
void *arg_p
unsigned int partition
uint8_t fat_count
uint8_t blocks_per_cluster
uint16_t root_dir_entry_count
fat_t blocks_per_fat
fat_t cluster_count
uint32_t volume_start_block
uint32_t fat_start_block
uint32_t root_dir_start_block
uint32_t data_start_block
struct fat16_cache_t cache
```

```
struct fat16_file_t
```

Public Members

```
struct fat16_t *fat16_p
uint8_t flags
int16_t dir_entry_block
int16_t dir_entry_index
fat_t first_cluster
size_t file_size
fat_t cur_cluster
size_t cur_position
```

```
struct fat16_dir_t
```


Public Members

```
int16_t root_index
struct fat16_file_t file
struct fat16_dir_entry_t
```

Public Members

```
char name[256]
int is_dir
size_t size
struct date_t latest_mod_date
struct fat16_stat_t
```

Public Members

```
size_t size
int is_dir
```

fs — Debug file system

The debug file system is not really a file system, but rather a file system like tree of commands, counters, parameters, and “real” file systems.

- A command is a file path mapped to a function callback. The callback is invoked when its path is passed to the `fs_call()` function. Commands are registered into the debug file system by a call to `fs_command_register()`.
- A counter is a file path mapped to a 64 bit value. The value can be incremented and read by the application. Counters are registered into the debug file system by a call to `fs_counter_register()`.
- A parameter is file path mapped to a value stored in ram that can be easily read and modified by the user from a shell. Parameters are registered into the debug file system by a call to `fs_parameter_register()`.
- A “real” file system is a file path, or mount point, mapped to a file system instance. The debug file system has a file access interface. The purpose of this interface is to have a common file access interface, independent of the underlying file systems interface. File systems are registered into the debug file system by a call to `fs_filesystem_register()`.

Debug file system commands

The debug file system module itself registers seven commands, all located in the directory `filesystems/fs/`.

Command	Description
filesystems/list	Print a list of all registered file systems.
list [<folder>]	Print a list of all files and folders in given folder.
read <file>	Read from given file.
write <file> <data>	Create and write to a file. Overwrites existing files.
append <file> <data>	Append data to an existing file.
counters/list	Print a list of all registered counters.
counters/reset	Reset all counters to zero.
parameters/list	Print a list of all registered parameters.

Example output from the shell:

```
$ filesystems/fs/filesystems/list
MOUNT-POINT      MEDIUM  TYPE      AVAILABLE  SIZE  USAGE
/tmp              ram      fat16      54K        64K   14%
/home/erik        sd       fat16      1.9G       2G    5%
/etc              flash    spiffs     124K       128K   3%
$ filesystems/fs/write tmp/foo.txt "Hello "
$ filesystems/fs/append tmp/foo.txt world!
$ filesystems/fs/read tmp/foo.txt
Hello world!
$ filesystems/fs/list tmp
xxxx-xx-xx xx-xx      12 foo.txt
$ filesystems/fs/counters/list
NAME                                     VALUE
/your/counter          0000000000000034
/my/counter            0000000000000002
$ filesystems/fs/counters/reset
$ filesystems/fs/counters/list
NAME                                     VALUE
/your/counter          0000000000000000
/my/counter            0000000000000000
$ filesystems/fs/parameters/list
NAME                                     VALUE
/foo/bar                -2
```

Source code: [src/filesystems/fs.h](#), [src/filesystems/fs.c](#)

Test code: [tst/filesystems/fs/main.c](#)

Test coverage: [src/filesystems/fs.c](#)

Defines

FS_SEEK_SET 0

FS_SEEK_CUR 1

The offset is relative to the current position indicator.

FS_SEEK_END 2

The offset is relative to the end of the file.

FS_READ 0x01

Open for reading.

FS_WRITE 0x02

Open for write.

FS_RDWR (FS_READ | FS_WRITE)

Open for reading and writing.

FS_APPEND 0x04

The file position indicator shall be set to the end of the file prior to each write.

FS_SYNC 0x08

Synchronous writes.

FS_CREAT 0x10

Create the file if non-existent.

FS_EXCL 0x20

If FS_CREAT and FS_EXCL are set, file open shall fail if the file exists.

FS_TRUNC 0x40

Truncate the file to zero length.

FS_TYPE_FILE 1

FS_TYPE_DIR 2

FS_TYPE_HARD_LINK 3

FS_TYPE_SOFT_LINK 4

Typedefs

```
typedef int (*fs_callback_t)(int argc, const char *argv[], void *out_p, void *in_p, void *arg_p, void
                             *call_arg_p)
```

Command callback prototype.

Return zero(0) or negative error code.

Parameters

- `argc`: Number of arguments in `argv`.
- `argv`: An array of arguments.
- `out_p`: Output channel.
- `in_p`: Input channel.
- `arg_p`: Argument passed to the init function of given command.
- `call_arg_p`: Argument passed to the `fs_call` function.

```
typedef int (*fs_parameter_set_callback_t)(void *value_p, const char *src_p)
```

Parameter setter callback prototype.

Return zero(0) or negative error code.

Parameters

- `value_p`: Buffer the new value should be written to.
- `src_p`: Value to set as a string.

```
typedef int (*fs_parameter_print_callback_t) (void *chout_p, void *value_p)
```

Parameter printer callback prototype.

Return zero(0) or negative error code.

Parameters

- `chout_p`: Channel to write the formatted value to.
- `value_p`: Value to format and print to the output channel.

Enums

```
enum fs_type_t
```

Values:

```
fs_type_fat16_t = 0
```

```
fs_type_spiffs_t
```

```
fs_type_generic_t
```

Functions

```
int fs_module_init (void)
```

Initialize the file system module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

```
int fs_call (char *command_p, void *chin_p, void *chout_p, void *arg_p)
```

Call given file system command with given input and output channels. Quote an argument if it contains spaces, otherwise it is parsed as multiple arguments. Any quotation mark in an argument string must be escaped with a backslash (\), otherwise it is interpreted as a string quotation mask.

Return zero(0) or negative error code.

Parameters

- `command_p`: Command string to call. The command string will be modified by this function, so don't use it after this function returns.
- `chin_p`: Input channel.
- `chout_p`: Output channel.
- `arg_p`: User argument passed to the command callback function as `call_arg_p`.

```
int fs_open (struct fs_file_t *self_p, const char *path_p, int flags)
```

Open a file by file path and mode flags. File operations are permitted after the file has been opened.

The path can be either absolute or relative. It's an absolute path if it starts with a forward slash /, and relative otherwise. Relative paths are relative to the current working directory, given by the thread environment variable CWD.

Return zero(0) or negative error code.

Parameters

- `self_p`: File object to be initialized.
- `path_p`: Path of the file to open. The path can be absolute or relative.
- `flags`: Mode of file open. A combination of `FS_READ`, `FS_RDONLY`, `FS_WRITE`, `FS_WRONLY`, `FS_RDWR`, `FS_APPEND`, `FS_SYNC`, `FS_CREAT`, `FS_EXCL` and `FS_TRUNC`.

int **fs_close** (struct *fs_file_t* **self_p*)

Close given file. No file operations are permitted on a closed file.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized file object.

ssize_t **fs_read** (struct *fs_file_t* **self_p*, void **dst_p*, size_t *size*)

Read from given file into given buffer.

Return Number of bytes read or negative error code.

Parameters

- `self_p`: Initialized file object.
- `dst_p`: Buffer to read data into.
- `size`: Number of bytes to read.

ssize_t **fs_read_line** (struct *fs_file_t* **self_p*, void **dst_p*, size_t *size*)

Read one line from given file into given buffer. The function reads one character at a time from given file until the destination buffer is full, a newline `\n` is found or end of file is reached.

Return If a line was found the number of bytes read not including the null-termination is returned. If the destination buffer becomes full before a newline character, the destination buffer size is returned. Otherwise a negative error code is returned.

Parameters

- `self_p`: Initialized file object.
- `dst_p`: Buffer to read data into. Should fit the whole line and null-termination.
- `size`: Size of the destination buffer.

ssize_t **fs_write** (struct *fs_file_t* **self_p*, const void **src_p*, size_t *size*)

Write from given buffer into given file.

Return Number of bytes written or negative error code.

Parameters

- `self_p`: Initialized file object.
- `dst_p`: Buffer to write.
- `size`: Number of bytes to write.

int **fs_seek** (struct *fs_file_t* **self_p*, int *offset*, int *whence*)

Sets the file's read/write position relative to whence.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized file object.
- `offset`: New position in bytes from given whence.
- `whence`: Absolute (`FS_SEEK_SET`), relative (`FS_SEEK_CUR`) or from end (`FS_SEEK_END`).

`ssize_t fs_tell (struct fs_file_t *self_p)`

Return current position in the file.

Return Current position or negative error code.

Parameters

- `self_p`: Initialized file object.

`int fs_dir_open (struct fs_dir_t *dir_p, const char *path_p, int oflag)`

Open a directory by directory path and mode flags.

Return zero(0) or negative error code.

Parameters

- `dir_p`: Directory object to be initialized.
- `path_p`: A valid path name for a directory path.
- `oflag`: mode of the directory to open (create, read, etc).

`int fs_dir_close (struct fs_dir_t *dir_p)`

Close given directory.

Return zero(0) or negative error code.

Parameters

- `dir_p`: Directory object.

`int fs_dir_read (struct fs_dir_t *dir_p, struct fs_dir_entry_t *entry_p)`

Read the next file or directory within the opened directory.

Return true(1) if an entry was read or false(0) if no entry could be read, otherwise negative error code.

Parameters

- `dir_p`: Directory object.
- `entry_p`: Read entry.

`int fs_remove (const char *path_p)`

Remove file by given path.

Return zero(0) or negative error code.

Parameters

- `path_p`: The path of the file to remove.

`int fs_stat (const char *path_p, struct fs_stat_t *stat_p)`

Gets file status by path.

Return zero(0) or negative error code.

Parameters

- `path_p`: The path of the file to stat.
- `stat_p`: The stat struct to populate.

int **fs_mkdir** (const char **path_p*)
Create a directory with given path.

Return zero(0) or negative error code.

Parameters

- `path_p`: The path of the directory to create.

int **fs_format** (const char **path_p*)
Format file system at given path.

Return zero(0) or negative error code.

Parameters

- `path_p`: The path to the root of the file system to format. All data in the file system will be deleted.

int **fs_ls** (const char **path_p*, const char **filter_p*, void **chout_p*)
List files and folders in given path. Optionally with given filter. The list is written to the output channel.

Return zero(0) or negative error code.

Parameters

- `path_p`: Directory to list.
- `filter_p`: Filter out files and folders.
- `chout_p`: Output chan.

int **fs_list** (const char **path_p*, const char **filter_p*, void **chout_p*)
List files (callbacks) and directories in given path. Optionally with given filter. The list is written to the output channel.

Return zero(0) or negative error code.

Parameters

- `path_p`: Directory to list.
- `filter_p`: Filter out files and folders.
- `chout_p`: Output chan.

int **fs_auto_complete** (char **path_p*)
Auto-complete given path.

Return >=1 if completion happened. Number of autocompleted characters added to the path. 0 if no completion happend, or negative error code.

Parameters

- `path_p`: Absolute or relative path to auto-complete.

void **fs_split** (char **buf_p*, char ***path_pp*, char ***cmd_pp*)
Split buffer into path and command inplace.

Return zero(0) or negative error code.

Parameters

- *buf_p*: Buffer to split.
- *path_pp*: Path or NULL if no path was found.
- *cmd_pp*: Command or empty string.

void **fs_merge** (char **path_p*, char **cmd_p*)
Merge path and command previously split using `fs_split()`.

Return zero(0) or negative error code.

Parameters

- *path_p*: Path from split.
- *cmd_p*: Command from split.

int **fs_filesystem_init_generic** (struct *fs_filesystem_t* **self_p*, const char **name_p*, struct *fs_filesystem_operations_t* **ops_p*)
Initialize given generic file system.

Return zero(0) or negative error code.

Parameters

- *self_p*: File system to initialize.
- *name_p*: Path to register.
- *ops_p*: File system function callbacks.

int **fs_filesystem_register** (struct *fs_filesystem_t* **self_p*)
Register given file system. Use the functions `fs_open()`, `fs_read()`, `fs_write()`, `fs_close()`, `fs_seek()`, `fs_tell()` and `fs_read_line()` to access files in a registered file system.

Return zero(0) or negative error code.

Parameters

- *self_p*: File system to register.

int **fs_filesystem_deregister** (struct *fs_filesystem_t* **self_p*)
Deregister given file system.

Return zero(0) or negative error code.

Parameters

- *self_p*: File system to deregister.

int **fs_command_init** (struct *fs_command_t* * *self_p*, const FAR char * *path_p*, *fs_callback_t*)
Initialize given command.

Return zero(0) or negative error code.

Parameters

- `self_p`: Command to initialize.
- `path_p`: Path to register.
- `callback`: Command callback function.
- `arg_p`: Callback argument.

int **fs_command_register** (struct *fs_command_t* **command_p*)
 Register given command. Registered commands are called by the function `fs_call()`.

Return zero(0) or negative error code.

Parameters

- `command_p`: Command to register.

int **fs_command_deregister** (struct *fs_command_t* **command_p*)
 Deregister given command.

Return zero(0) or negative error code.

Parameters

- `command_p`: Command to deregister.

int **fs_counter_init** (struct *fs_counter_t* * *self_p*, const FAR char * *path_p*, uint64_t *value*)
 Initialize given counter.

Return zero(0) or negative error code.

Parameters

- `self_p`: Counter to initialize.
- `path_p`: Path to register.
- `value`: Initial value of the counter.

int **fs_counter_increment** (struct *fs_counter_t* **self_p*, uint64_t *value*)
 Increment given counter.

Return zero(0) or negative error code.

Parameters

- `self_p`: Command to initialize.
- `value`: Increment value.

int **fs_counter_register** (struct *fs_counter_t* **counter_p*)
 Register given counter.

Return zero(0) or negative error code.

Parameters

- `counter_p`: Counter to register.

int **fs_counter_deregister** (struct *fs_counter_t* **counter_p*)
 Deregister given counter.

Return zero(0) or negative error code.

Parameters

- `counter_p`: Counter to deregister.

int `fs_parameter_init(struct fs_parameter_t * self_p, const FAR char * path_p, fs_parameter_t * value_p)`
Initialize given parameter.

Return zero(0) or negative error code.

Parameters

- `self_p`: Parameter to initialize.
- `path_p`: Path to register.
- `set_cb`: Callback function set set the parameter value.
- `print_cb`: Callback function set print the parameter value.
- `value_p`: Value storage area.

int `fs_parameter_register(struct fs_parameter_t *parameter_p)`
Register given parameter.

Return zero(0) or negative error code.

Parameters

- `parameter_p`: Parameter to register.

int `fs_parameter_deregister(struct fs_parameter_t *parameter_p)`
Deregister given parameter.

Return zero(0) or negative error code.

Parameters

- `parameter_p`: Parameter to deregister.

int `fs_parameter_int_set(void *value_p, const char *src_p)`
Integer parameter setter function callback

Return zero(0) or negative error code.

Parameters

- `value_p`: Buffer the new value should be written to.
- `src_p`: Value to set as a string.

int `fs_parameter_int_print(void *chout_p, void *value_p)`
Integer parameter printer function callback

Return zero(0) or negative error code.

Parameters

- `chout_p`: Channel to write the formatted value to.
- `value_p`: Value to format and print to the output channel.

```
struct fs_filesystem_t
```

Public Members

```
const char *name_p
fs_type_t type
struct fs_filesystem_operations_t *ops_p
struct fs_filesystem_t::@32::@34 fs_filesystem_t::generic
union fs_filesystem_t::@32 fs_filesystem_t::fs
union fs_filesystem_t::@33 fs_filesystem_t::config
struct fs_filesystem_t *next_p
```

```
struct fs_file_t
```

Public Members

```
struct fs_filesystem_t *filesystem_p
union fs_file_t::@35 fs_file_t::u
```

```
struct fs_stat_t
#include <fs.h> Path stats.
```

Public Members

```
uint32_t size
uint8_t type
```

```
struct fs_command_t
```

Public Members

```
const FAR char* fs_command_t::path_p
fs_callback_t callback
void *arg_p
struct fs_command_t *next_p
```

```
struct fs_counter_t
```

Public Members

```
struct fs_command_t command
long long unsigned int fs_counter_t::value
struct fs_counter_t *next_p
```

```
struct fs_parameter_t
```

Public Members

```
struct fs_command_t command
fs_parameter_set_callback_t set_cb
fs_parameter_print_callback_t print_cb
void *value_p
struct fs_parameter_t *next_p
struct fs_dir_t
```

Public Members

```
struct fs_filesystem_t *filesystem_p
union fs_dir_t::@36 fs_dir_t::u
struct fs_dir_entry_t
```

Public Members

```
char name[256]
int type
size_t size
struct date_t latest_mod_date
struct fs_filesystem_operations_t
```

Public Members

```
int (*file_open) (struct fs_filesystem_t *filesystem_p, struct fs_file_t *self_p, const char *path_p, int
                  flags)
int (*file_close) (struct fs_file_t *self_p)
ssize_t (*file_read) (struct fs_file_t *self_p, void *dst_p, size_t size)
ssize_t (*file_write) (struct fs_file_t *self_p, const void *src_p, size_t size)
int (*file_seek) (struct fs_file_t *self_p, int offset, int whence)
ssize_t (*file_tell) (struct fs_file_t *self_p)
```

spiffs — SPI Flash File System

The source code of this module is based on <https://github.com/pellepl/spiffs>.

About

Spiffs is a file system intended for SPI NOR flash devices on embedded targets.

Spiffs is designed with following characteristics in mind:

- Small (embedded) targets, sparse RAM without heap.
 - Only big areas of data (blocks) can be erased.
 - An erase will reset all bits in block to ones.
 - Writing pulls one to zeroes.
 - Zeroes can only be pulled to ones by erase.
 - Wear leveling.
-

Source code: [src/filesystems/spiffs.h](#), [src/filesystems/spiffs.c](#)

Test code: [tst/filesystems/spiffs/main.c](#)

Defines

```
SPIFFS_OK 0
SPIFFS_ERR_NOT_MOUNTED -10000
SPIFFS_ERR_FULL -10001
SPIFFS_ERR_NOT_FOUND -10002
SPIFFS_ERR_END_OF_OBJECT -10003
SPIFFS_ERR_DELETED -10004
SPIFFS_ERR_NOT_FINALIZED -10005
SPIFFS_ERR_NOT_INDEX -10006
SPIFFS_ERR_OUT_OF_FILE_DESCS -10007
SPIFFS_ERR_FILE_CLOSED -10008
SPIFFS_ERR_FILE_DELETED -10009
SPIFFS_ERR_BAD_DESCRIPTOR -10010
SPIFFS_ERR_IS_INDEX -10011
SPIFFS_ERR_IS_FREE -10012
SPIFFS_ERR_INDEX_SPAN_MISMATCH -10013
SPIFFS_ERR_DATA_SPAN_MISMATCH -10014
SPIFFS_ERR_INDEX_REF_FREE -10015
SPIFFS_ERR_INDEX_REF_LU -10016
SPIFFS_ERR_INDEX_REF_INVALID -10017
SPIFFS_ERR_INDEX_FREE -10018
```

SPIFFS_ERR_INDEX_LU -10019

SPIFFS_ERR_INDEX_INVALID -10020

SPIFFS_ERR_NOT_WRITABLE -10021

SPIFFS_ERR_NOT_READABLE -10022

SPIFFS_ERR_CONFLICTING_NAME -10023

SPIFFS_ERR_NOT_CONFIGURED -10024

SPIFFS_ERR_NOT_A_FS -10025

SPIFFS_ERR_MOUNTED -10026

SPIFFS_ERR_ERASE_FAIL -10027

SPIFFS_ERR_MAGIC_NOT_POSSIBLE -10028

SPIFFS_ERR_NO_DELETED_BLOCKS -10029

SPIFFS_ERR_FILE_EXISTS -10030

SPIFFS_ERR_NOT_A_FILE -10031

SPIFFS_ERR_RO_NOT_IMPL -10032

SPIFFS_ERR_RO_ABORTED_OPERATION -10033

SPIFFS_ERR_PROBE_TOO_FEW_BLOCKS -10034

SPIFFS_ERR_PROBE_NOT_A_FS -10035

SPIFFS_ERR_NAME_TOO_LONG -10036

SPIFFS_ERR_INTERNAL -10050

SPIFFS_ERR_TEST -10100

SPIFFS_DBG (...) print(__VA_ARGS__)

SPIFFS_GC_DBG (...) printf(__VA_ARGS__)

SPIFFS_CACHE_DBG (...) printf(__VA_ARGS__)

SPIFFS_CHECK_DBG (...) printf(__VA_ARGS__)

SPIFFS_APPEND 0x04
Any write to the filehandle is appended to end of the file.

SPIFFS_O_APPEND SPIFFS_APPEND

SPIFFS_TRUNC 0x40
If the opened file exists, it will be truncated to zero length before opened.

SPIFFS_O_TRUNC SPIFFS_TRUNC

SPIFFS_CREAT 0x10
If the opened file does not exist, it will be created before opened.

SPIFFS_O_CREAT SPIFFS_CREAT

SPIFFS_RDONLY 0x01
The opened file may only be read.

SPIFFS_O_RDONLY SPIFFS_RDONLY

SPIFFS_WRONLY 0x02
The opened file may only be written.

SPIFFS_O_WRONLY SPIFFS_WRONLY

SPIFFS_RDWR (SPIFFS_RDONLY | SPIFFS_WRONLY)

The opened file may be both read and written.

SPIFFS_O_RDWR SPIFFS_RDWR

SPIFFS_DIRECT 0x08

Any writes to the filehandle will never be cached but flushed directly.

SPIFFS_O_DIRECT SPIFFS_DIRECT

SPIFFS_EXCL 0x20

If SPIFFS_O_CREAT and SPIFFS_O_EXCL are set, SPIFFS_open() shall fail if the file exists.

SPIFFS_O_EXCL SPIFFS_EXCL

SPIFFS_SEEK_SET (0)

SPIFFS_SEEK_CUR (1)

SPIFFS_SEEK_END (2)

SPIFFS_TYPE_FILE (1)

SPIFFS_TYPE_DIR (2)

SPIFFS_TYPE_HARD_LINK (3)

SPIFFS_TYPE_SOFT_LINK (4)

SPIFFS_LOCK (fs)

SPIFFS_UNLOCK (fs)

Typedefs

typedef int16_t **spiffs_file_t**

Spiffs file descriptor index type. must be signed.

typedef uint16_t **spiffs_flags_t**

Spiffs file descriptor flags.

typedef uint16_t **spiffs_mode_t**

Spiffs file mode.

typedef uint8_t **spiffs_obj_type_t**

Object type.

typedef int32_t (***spiffs_read_cb_t**) (uint32_t addr, uint32_t size, uint8_t *dst_p)

Spi read call function type.

typedef int32_t (***spiffs_write_cb_t**) (uint32_t addr, uint32_t size, uint8_t *src_p)

Spi write call function type.

typedef int32_t (***spiffs_erase_cb_t**) (uint32_t addr, uint32_t size)

Spi erase call function type.

typedef void (***spiffs_check_callback_t**) (enum *spiffs_check_type_t* type, enum *spiffs_check_report_t* report, uint32_t arg1, uint32_t arg2)

File system check callback function.

```
typedef void (*spiffs_file_callback_t)(struct spiffs_t *fs_p, enum spiffs_fileop_type_t op,  
                                     spiffs_obj_id_t obj_id, spiffs_page_ix_t pix)
```

File system listener callback function.

```
typedef spiffs_block_ix_t spiffs_block_ix  
typedef spiffs_page_ix_t spiffs_page_ix  
typedef spiffs_obj_id_t spiffs_obj_id  
typedef spiffs_span_ix_t spiffs_span_ix  
typedef struct spiffs_t spiffs  
typedef spiffs_file_t spiffs_file  
typedef spiffs_flags_t spiffs_flags  
typedef spiffs_obj_type_t spiffs_obj_type  
typedef spiffs_mode_t spiffs_mode  
typedef enum spiffs_fileop_type_t spiffs_fileop_type  
typedef struct spiffs_config_t spiffs_config  
typedef spiffs_check_callback_t spiffs_check_callback  
typedef struct spiffs_dirent_t spiffs_dirent  
typedef struct spiffs_dir_t spiffs_DIR  
typedef spiffs_file_callback_t spiffs_file_callback
```

Enums

```
enum spiffs_check_type_t  
File system check callback report operation.
```

Values:

```
SPIFFS_CHECK_LOOKUP = 0  
SPIFFS_CHECK_INDEX  
SPIFFS_CHECK_PAGE
```

```
enum spiffs_check_report_t  
File system check callback report type.
```

Values:

```
SPIFFS_CHECK_PROGRESS = 0  
SPIFFS_CHECK_ERROR  
SPIFFS_CHECK_FIX_INDEX  
SPIFFS_CHECK_FIX_LOOKUP  
SPIFFS_CHECK_DELETE_ORPHANED_INDEX  
SPIFFS_CHECK_DELETE_PAGE  
SPIFFS_CHECK_DELETE_BAD_FILE
```


enum spiiffs_fileop_type_t

File system listener callback operation.

Values:

SPIFFS_CB_CREATED = 0

The file has been created.

SPIFFS_CB_UPDATED

The file has been updated or moved to another page.

SPIFFS_CB_DELETED

The file has been deleted.

Functions

int32_t spiiffs_mount (**struct** *spiiffs_t* *self_p, **struct** *spiiffs_config_t* *config_p, uint8_t *work_p, uint8_t *fd_space_p, uint32_t fd_space_size, void *cache_p, uint32_t cache_size, *spiiffs_check_callback_t* check_cb)

Initializes the file system dynamic parameters and mounts the filesystem. If SPIFFS_USE_MAGIC is enabled the mounting may fail with SPIFFS_ERR_NOT_A_FS if the flash does not contain a recognizable file system. In this case, SPIFFS_format must be called prior to remounting.

Return zero(0) or negative error code.

Parameters

- self_p: The file system struct.
- config_p: The physical and logical configuration of the file system.
- work_p: A memory work buffer comprising 2*config->log_page_size bytes used throughout all file system operations
- fd_space_p: Memory for file descriptors.
- fd_space_size: Memory size of file descriptors.
- cache_p: Memory for cache, may be NULL.
- cache_size: Memory size of cache.
- check_cb: Callback function for reporting during consistency checks.

void spiiffs_unmount (**struct** *spiiffs_t* *self_p)

Unmounts the file system. All file handles will be flushed of any cached writes and closed.

Return void.

Parameters

- self_p: The file system struct.

int32_t spiiffs_creat (**struct** *spiiffs_t* *self_p, **const** char *path_p, *spiiffs_mode_t* mode)

Creates a new file.

Return zero(0) or negative error code.

Parameters

- self_p: The file system struct.

- `path_p`: The path of the new file.
- `mode`: Ignored, for posix compliance.

spiffs_file_t **spiffs_open** (**struct** *spiffs_t* **self_p*, **const** **char** **path_p*, *spiffs_flags_t* *flags*, *spiffs_mode_t* *mode*)

Opens/creates a file.

Parameters

- `self_p`: The file system struct.
- `path_p`: The path of the new file.
- `flags`: The flags for the open command, can be combinations of SPIFFS_O_APPEND, SPIFFS_O_TRUNC, SPIFFS_O_CREAT, SPIFFS_O_RDONLY, SPIFFS_O_WRONLY, SPIFFS_O_RDWR, SPIFFS_O_DIRECT, SPIFFS_O_EXCL.
- `mode`: Ignored, for posix compliance.

spiffs_file_t **spiffs_open_by_dirent** (**struct** *spiffs_t* **self_p*, **struct** *spiffs_dirent_t* **ent_p*, *spiffs_flags_t* *flags*, *spiffs_mode_t* *mode*)

Opens a file by given dir entry.

Optimization purposes, when traversing a file system with SPIFFS_readdir a normal SPIFFS_open would need to traverse the filesystem again to find the file, whilst SPIFFS_open_by_dirent already knows where the file resides.

Parameters

- `self_p`: The file system struct.
- `e_p`: The dir entry to the file.
- `flags`: The flags for the open command, can be combinations of SPIFFS_APPEND, SPIFFS_TRUNC, SPIFFS_CREAT, SPIFFS_RD_ONLY, SPIFFS_WR_ONLY, SPIFFS_RDWR, SPIFFS_DIRECT. SPIFFS_CREAT will have no effect in this case.
- `mode`: Ignored, for posix compliance.

spiffs_file_t **spiffs_open_by_page** (**struct** *spiffs_t* **self_p*, *spiffs_page_ix_t* *page_ix*, *spiffs_flags_t* *flags*, *spiffs_mode_t* *mode*)

Opens a file by given page index.

Optimization purposes, opens a file by directly pointing to the page index in the spi flash. If the page index does not point to a file header SPIFFS_ERR_NOT_A_FILE is returned.

Parameters

- `self_p`: The file system struct.
- `page_ix`: The page index.
- `flags`: The flags for the open command, can be combinations of SPIFFS_APPEND, SPIFFS_TRUNC, SPIFFS_CREAT, SPIFFS_RD_ONLY, SPIFFS_WR_ONLY, SPIFFS_RDWR, SPIFFS_DIRECT. SPIFFS_CREAT will have no effect in this case.
- `mode`: Ignored, for posix compliance.

int32_t **spiffs_read** (**struct** *spiffs_t* **self_p*, *spiffs_file_t* *fh*, **void** **buf_p*, **int32_t** *len*)

Reads from given filehandle.

Return Number of bytes read or negative error code.

Parameters

- `self_p`: The file system struct.
- `fh`: The filehandle.
- `buf_p`: Where to put read data.
- `len`: How much to read.

`int32_t spiffs_write (struct spiffs_t *self_p, spiffs_file_t fh, void *buf_p, int32_t len)`
Writes to given filehandle.

Return Number of bytes written, or negative error code.

Parameters

- `self_p`: The file system struct.
- `fh`: The filehandle.
- `buf_p`: The data to write.
- `len`: How much to write.

`int32_t spiffs_lseek (struct spiffs_t *self_p, spiffs_file_t fh, int32_t offs, int whence)`
Moves the read/write file offset. Resulting offset is returned or negative if error.

`lseek(fs, fd, 0, SPIFFS_SEEK_CUR)` will thus return current offset.

If `SPIFFS_SEEK_CUR`, the file offset shall be set to its current location plus offset.

Parameters

- `self_p`: The file system struct.
- `fh`: The filehandle.
- `offs`: How much/where to move the offset.
- `whence`: If `SPIFFS_SEEK_SET`, the file offset shall be set to offset bytes.

If `SPIFFS_SEEK_END`, the file offset shall be set to the size of the file plus offse, which should be negative.

Return zero(0) or negative error code.

`int32_t spiffs_remove (struct spiffs_t *self_p, const char *path_p)`
Removes a file by path.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `path_p`: The path of the file to remove.

`int32_t spiffs_fremove (struct spiffs_t *self_p, spiffs_file_t fh)`
Removes a file by filehandle.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `fh`: The filehandle of the file to remove.

`int32_t spiffs_stat (struct spiffs_t *self_p, const char *path_p, struct spiffs_stat_t *stat_p)`
Gets file status by path.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `path_p`: The path of the file to stat.
- `stat_p`: The stat struct to populate.

`int32_t spiffs_fstat (struct spiffs_t *self_p, spiffs_file_t fh, struct spiffs_stat_t *stat_p)`
Gets file status by filehandle.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `fh`: The filehandle of the file to stat.
- `stat_p`: The stat struct to populate.

`int32_t spiffs_fflush (struct spiffs_t *self_p, spiffs_file_t fh)`
Flushes all pending write operations from cache for given file.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `fh`: The filehandle of the file to flush.

`int32_t spiffs_close (struct spiffs_t *self_p, spiffs_file_t fh)`
Closes a filehandle. If there are pending write operations, these are finalized before closing.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `fh`: The filehandle of the file to close.

`int32_t spiffs_rename (struct spiffs_t *self_p, const char *old_path_p, const char *new_path_p)`
Renames a file.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `old_path_p`: Path of file to rename.

- `new_path_p`: New path of file.

`int32_t spiffs_errno (struct spiffs_t *self_p)`
Returns last error of last file operation.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.

`void spiffs_clearerr (struct spiffs_t *self_p)`
Clears last error.

Return void.

Parameters

- `self_p`: The file system struct.

`struct spiffs_dir_t *spiffs_opendir (struct spiffs_t *self_p, const char *name_p, struct spiffs_dir_t *dir_p)`

Opens a directory stream corresponding to the given name. The stream is positioned at the first entry in the directory. On hydrogen builds the name argument is ignored as hydrogen builds always correspond to a flat file structure - no directories.

Parameters

- `self_p`: The file system struct.
- `name_p`: The name of the directory.
- `dir_p`: Pointer the directory stream to be populated.

`int32_t spiffs_closedir (struct spiffs_dir_t *dir_p)`
Closes a directory stream

Return zero(0) or negative error code.

Parameters

- `dir_p`: The directory stream to close.

`struct spiffs_dirent_t *spiffs_readdir (struct spiffs_dir_t *dir_p, struct spiffs_dirent_t *ent_p)`
Reads a directory into given spifs_dirent struct.

Return NULL if error or end of stream, else given dirent is returned.

Parameters

- `dir_p`: Pointer to the directory stream.
- `ent_p`: The dirent struct to be populated.

`int32_t spiffs_check (struct spiffs_t *self_p)`
Runs a consistency check on given filesystem.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.

`int32_t spiffs_info (struct spiffs_t *self_p, uint32_t *total_p, uint32_t *used_p)`

Returns number of total bytes available and number of used bytes. This is an estimation, and depends on if there are many files with little data or few files with much data.

NB: If used number of bytes exceeds total bytes, a SPIFFS_check should run. This indicates a power loss in midst of things. In worst case (repeated powerlosses in mending or gc) you might have to delete some files.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `total_p`: Total number of bytes in filesystem.
- `used_p`: Used number of bytes in filesystem.

`int32_t spiffs_format (struct spiffs_t *self_p)`

Formats the entire file system. All data will be lost. The filesystem must not be mounted when calling this.

NB: formatting is awkward. Due to backwards compatibility, SPIFFS_mount MUST be called prior to formatting in order to configure the filesystem. If SPIFFS_mount succeeds, SPIFFS_unmount must be called before calling SPIFFS_format. If SPIFFS_mount fails, SPIFFS_format can be called directly without calling SPIFFS_unmount first.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.

`uint8_t spiffs_mounted (struct spiffs_t *self_p)`

Returns nonzero if spiffs is mounted, or zero if unmounted.

Parameters

- `self_p`: The file system struct.

`int32_t spiffs_gc_quick (struct spiffs_t *self_p, uint16_t max_free_pages)`

Tries to find a block where most or all pages are deleted, and erase that block if found. Does not care for wear levelling. Will not move pages around.

If parameter `max_free_pages` are set to 0, only blocks with only deleted pages will be selected.

NB: the garbage collector is automatically called when spiffs needs free pages. The reason for this function is to give possibility to do background tidying when user knows the system is idle.

Use with care.

Setting `max_free_pages` to anything larger than zero will eventually wear flash more as a block containing free pages can be erased.

Will set `err_no` to SPIFFS_OK if a block was found and erased, SPIFFS_ERR_NO_DELETED_BLOCK if no matching block was found, or other error.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.

- `max_free_pages`: maximum number allowed free pages in block.

`int32_t spiffs_gc (struct spiffs_t *self_p, uint32_t size)`

Will try to make room for given amount of bytes in the filesystem by moving pages and erasing blocks. If it is physically impossible, `err_no` will be set to `SPIFFS_ERR_FULL`. If there already is this amount (or more) of free space, `SPIFFS_gc` will silently return. It is recommended to call `SPIFFS_info` before invoking this method in order to determine what amount of bytes to give.

NB: the garbage collector is automatically called when `spiffs` needs free pages. The reason for this function is to give possibility to do background tidying when user knows the system is idle.

Use with care.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `size`: Amount of bytes that should be freed.

`int32_t spiffs_eof (struct spiffs_t *self_p, spiffs_file_t fh)`

Check if EOF reached.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `fh`: The filehandle of the file to check.

`int32_t spiffs_tell (struct spiffs_t *self_p, spiffs_file_t fh)`

Get position in file.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `fh`: The filehandle of the file to check.

`int32_t spiffs_set_file_callback_func (struct spiffs_t *self_p, spiffs_file_callback_t cb_func)`

Registers a callback function that keeps track on operations on file headers. Do note, that this callback is called from within internal `spiffs` mechanisms. Any operations on the actual file system being callbacked from in this callback will mess things up for sure - do not do this. This can be used to track where files are and move around during garbage collection, which in turn can be used to build location tables in ram. Used in conjunction with `SPIFFS_open_by_page` this may improve performance when opening a lot of files. Must be invoked after mount.

Return zero(0) or negative error code.

Parameters

- `self_p`: The file system struct.
- `cb_func`: The callback on file operations.

`struct spiffs_config_t`

`#include <spiffs.h>` Spiiffs spi configuration struct.

Public Members

spiffs_read_cb_t **hal_read_f**

Physical read function.

spiffs_write_cb_t **hal_write_f**

Physical write function.

spiffs_erase_cb_t **hal_erase_f**

Physical erase function.

uint32_t **phys_size**

Physical size of the spi flash.

uint32_t **phys_addr**

Physical offset in spi flash used for spiffs, must be on block boundary.

uint32_t **phys_erase_block**

Physical size when erasing a block.

uint32_t **log_block_size**

Logical size of a block, must be on physical block size boundary and must never be less than a physical block.

uint32_t **log_page_size**

Logical size of a page, must be at least `log_block_size / 1`.

struct spiffs_t

Public Members

struct spiffs_config_t **cfg**

File system configuration.

uint32_t **block_count**

Number of logical blocks.

spiffs_block_ix_t **free_cursor_block_ix**

Cursor for free blocks, block index.

int **free_cursor_obj_lu_entry**

Cursor for free blocks, entry index.

spiffs_block_ix_t **cursor_block_ix**

Cursor when searching, block index.

int **cursor_obj_lu_entry**

Cursor when searching, entry index.

uint8_t ***lu_work**

Primary work buffer, size of a logical page.

uint8_t ***work**

Secondary work buffer, size of a logical page.

uint8_t ***fd_space**

File descriptor memory area.

uint32_t **fd_count**

Available file descriptors.


```

int32_t err_code
    Last error.

uint32_t free_blocks
    Current number of free blocks.

uint32_t stats_p_allocated
    Current number of busy pages.

uint32_t stats_p_deleted
    Current number of deleted pages.

uint8_t cleaning
    Flag indicating that garbage collector is cleaning.

spiffs_obj_id_t max_erase_count
    Max erase count amongst all blocks.

spiffs_check_callback_t check_cb_f
    Check callback function.

spiffs_file_callback_t file_cb_f
    File callback function.

uint8_t mounted
    Mounted flag.

void *user_data
    User data.

uint32_t config_magic
    Config magic.

struct spiffs_stat_t
    #include <spiffs.h> Spiffs file status struct.

```

Public Members

```

spiffs_obj_id_t obj_id

uint32_t size

spiffs_obj_type_t type

spiffs_page_ix_t pix

uint8_t name[SPIFFS_OBJ_NAME_LEN]

struct spiffs_dirent_t

```

Public Members

```

spiffs_obj_id_t obj_id

uint8_t name[SPIFFS_OBJ_NAME_LEN]

spiffs_obj_type_t type

uint32_t size

spiffs_page_ix_t pix

struct spiffs_dir_t

```

Public Members

```
struct spiffs_t *fs
spiffs_block_ix_t block
int entry
```

inet

The inet package on [Github](#).

Modules:

http_server — HTTP server

A HTTP server serves HTTP client requests, typically from a web browser.

A HTTP server can be wrapped in SSL, a security layer, to create a HTTPS server.

Source code: [src/inet/http_server.h](#), [src/inet/http_server.c](#)

Test code: [tst/inet/http_server/main.c](#)

Test coverage: [src/inet/http_server.c](#)

Example code: [examples/http_server/main.c](#), [examples/https_server/main.c](#)

Typedefs

```
typedef int (*http_server_route_callback_t) (struct http_server_connection_t *connection_p,
                                             struct http_server_request_t *request_p)
```

Enums

```
enum http_server_request_action_t
```

Values:

```
http_server_request_action_get_t = 0
http_server_request_action_post_t = 1
```

```
enum http_server_content_type_t
```

Content type.

Values:

```
http_server_content_type_text_plain_t = 0
http_server_content_type_text_html_t = 1
```

```
enum http_server_response_code_t
```

Response codes.

Values:

```

http_server_response_code_200_ok_t = 200
http_server_response_code_400_bad_request_t = 400
http_server_response_code_401_unauthorized_t = 401
http_server_response_code_404_not_found_t = 404
enum http_server_connection_state_t
    Connection state.

    Values:

    http_server_connection_state_free_t = 0
    http_server_connection_state_allocated_t

```

Functions

```

int http_server_init (struct http_server_t *self_p, struct http_server_listener_t *listener_p, struct
    http_server_connection_t *connections_p, const char *root_path_p, const struct
    http_server_route_t *routes_p, http_server_route_callback_t on_no_route)

```

Initialize given http server with given root path and maximum number of clients.

Return zero(0) or negative error code.

Parameters

- `self_p`: Http server to initialize.
- `listener_p`: Listener.
- `connections_p`: A NULL terminated list of connections.
- `root_path_p`: Working directory for the connection threads.
- `routes_p`: An array of routes.
- `on_no_route`: Callback called for all requests without a matching route in `route_p`.

```

int http_server_wrap_ssl (struct http_server_t *self_p, struct ssl_context_t *context_p)

```

Wrap given HTTP server in SSL, to make it secure.

This function must be called after `http_server_init()` and before `http_server_start()`.

Return zero(0) or negative error code.

Parameters

- `self_p`: Http server to wrap in SSL.
- `context_p`: SSL context to wrap the server in.

```

int http_server_start (struct http_server_t *self_p)

```

Start given HTTP server.

Spawn the threads and start listening for connections.

Return zero(0) or negative error code.

Parameters

- `self_p`: Http server.

```
int http_server_stop (struct http_server_t *self_p)
```

Stop given HTTP server.

Closes the listener and all open connections, and then kills the threads.

Return zero(0) or negative error code.

Parameters

- `self_p`: Http server.

```
int http_server_response_write (struct http_server_connection_t *connection_p, struct  
                                http_server_request_t *request_p, struct http_server_response_t  
                                *response_p)
```

Write given HTTP response to given connected client. This function should only be called from the route callbacks to respond to given request.

Return zero(0) or negative error code.

Parameters

- `connection_p`: Current connection.
- `request_p`: Current request.
- `response_p`: Current response. If `buf_p` in the response to NULL this function will only write the HTTP header, including the size, to the socket. After this function returns write the payload by calling `socket_write()`.

```
struct http_server_request_t
```

#include <http_server.h> HTTP request.

Public Members

http_server_request_action_t **action**

char **path**[64]

int **present**

char **value**[20]

struct http_server_request_t::@38::@39 http_server_request_t::sec_websocket_key

struct http_server_request_t::@38::@40 http_server_request_t::content_type

long **value**

struct http_server_request_t::@38::@41 http_server_request_t::content_length

struct http_server_request_t::@38::@42 http_server_request_t::authorization

struct http_server_request_t::@38::@43 http_server_request_t::expect

struct http_server_request_t::@38 http_server_request_t::headers

```
struct http_server_response_t
```

#include <http_server.h> HTTP response.

Public Members

```

int type
http_server_response_code_t code
const char *buf_p
size_t size
struct http_server_response_t::@44 http_server_response_t::content
struct http_server_listener_t

```

Public Members

```

const char *address_p
int port
const char *name_p
void *buf_p
size_t size
struct http_server_listener_t::@45::@46 http_server_listener_t::stack
struct thrd_t *id_p
struct http_server_listener_t::@45 http_server_listener_t::thrd
struct socket_t socket
struct http_server_connection_t

```

Public Members

```

http_server_connection_state_t state
const char *name_p
void *buf_p
size_t size
struct http_server_connection_t::@47::@48 http_server_connection_t::stack
struct thrd_t *id_p
struct http_server_connection_t::@47 http_server_connection_t::thrd
struct http_server_t *self_p
struct socket_t socket
void *chan_p
struct event_t events
struct http_server_route_t
    #include <http_server.h> Call given callback for given path.

```

Public Members

```
const char *path_p
http_server_route_callback_t callback
```

```
struct http_server_t
```

Public Members

```
const char *root_path_p
const struct http_server_route_t *routes_p
http_server_route_callback_t on_no_route
struct http_server_listener_t *listener_p
struct http_server_connection_t *connections_p
struct ssl_context_t *ssl_context_p
struct event_t events
```

http_websocket_client — HTTP websocket client

Source code: [src/inet/http_websocket_client.h](#), [src/inet/http_websocket_client.c](#)

Test code: [tst/inet/http_websocket_client/main.c](#)

Test coverage: [src/inet/http_websocket_client.c](#)

Functions

```
int http_websocket_client_init (struct http_websocket_client_t *self_p, const char *server_p, int
                                port, const char *path_p)
```

Initialize given http.

Return zero(0) or negative error code.

Parameters

- self_p: Http to initialize.
- server_p: Server hostname to connect to.
- port: Port to connect to.
- path_p: Path.

```
int http_websocket_client_connect (struct http_websocket_client_t *self_p)
```

Connect given http to the server.

Return zero(0) or negative error code.

Parameters

- self_p: Http to connect.

```
int http_websocket_client_disconnect (struct http_websocket_client_t *self_p)
```

Disconnect given http from the server.

Return zero(0) or negative error code.

Parameters

- `self_p`: Http to connect.

```
ssize_t http_websocket_client_read (struct http_websocket_client_t *self_p, void *buf_p, size_t  
size)
```

Read from given http.

Return Number of bytes read or negative error code.

Parameters

- `self_p`: Http to read from.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to read..

```
ssize_t http_websocket_client_write (struct http_websocket_client_t *self_p, int type, const void  
*buf_p, uint32_t size)
```

Write given data to given http.

Return Number of bytes written or negative error code.

Parameters

- `self_p`: Http to write to.
- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

```
struct http_websocket_client_t  
#include <http_websocket_client.h>
```

Public Members

```
struct socket_t socket
```

```
const char *host_p
```

```
int port
```

```
struct http_websocket_client_t::@49 http_websocket_client_t::server
```

```
size_t left
```

```
struct http_websocket_client_t::@50 http_websocket_client_t::frame
```

```
const char *path_p
```

http_websocket_server — HTTP websocket server

Source code: `src/inet/http_websocket_server.h`, `src/inet/http_websocket_server.c`

Test code: `tst/inet/http_websocket_server/main.c`

Test coverage: `src/inet/http_websocket_server.c`

Functions

int **http_websocket_server_init** (**struct** *http_websocket_server_t* *self_p, **struct** *socket_t* *socket_p)
Initialize given websocket server. The server uses the http module interface to communicate with the client.

Return zero(0) or negative error code.

Parameters

- self_p: Http to initialize.
- socket_p: Connected socket.

int **http_websocket_server_handshake** (**struct** *http_websocket_server_t* *self_p, **struct** *http_server_request_t* *request_p)
Read the handshake request from the client and send the handshake response.

Return zero(0) or negative error code.

Parameters

- self_p: Websocket server.
- request_p: Read handshake request.

ssize_t **http_websocket_server_read** (**struct** *http_websocket_server_t* *self_p, int *type_p, void *buf_p, size_t size)
Read a message from given websocket.

Return Number of bytes read or negative error code.

Parameters

- self_p: Websocket to read from.
- type_p: Read message type.
- buf_p: Buffer to read into.
- size: Number of bytes to read. Longer messages will be truncated and the leftover data dropped.

ssize_t **http_websocket_server_write** (**struct** *http_websocket_server_t* *self_p, int type, **const** void *buf_p, uint32_t size)
Write given message to given websocket.

Return Number of bytes written or negative error code.

Parameters

- self_p: Websocket to write to.
- type: One of HTTP_TYPE_TEXT and HTTP_TYPE_BINARY.

- `buf_p`: Buffer to write.
- `size`: Number of bytes to write.

```
struct http_websocket_server_t
#include <http_websocket_server.h>
```

Public Members

```
struct socket_t *socket_p
```

inet — Internet utilities

Source code: [src/inet/inet.h](#), [src/inet/inet.c](#)

Test code: [tst/inet/inet/inet.c](#)

Test coverage: [src/inet/inet.c](#)

Functions

```
int inet_module_init (void)
```

Initialize the inet module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

```
int inet_aton (const char *src_p, struct inet_ip_addr_t *dst_p)
```

Convert the Internet host address `src_p` from the IPv4 numbers-and-dots notation into binary form (in network byte order) and stores it in the structure that `dst_p` points to.

The address supplied in `src_p` can have one of the following forms:

- a.b.c.d Each of the four numeric parts specifies a byte of the address; the bytes are assigned in left-to-right order to produce the binary address.

Return zero(0) or negative error code.

Parameters

- `src_p`: Address a.b.c.d to convert into a number.
- `dst_p`: Converted address.

```
char *inet_ntoa (const struct inet_ip_addr_t *src_p, char *dst_p)
```

Convert the Internet host `src_p` from the IPv4 binary form (in network byte order) to numbers-and-dots notation and stores it in the structure that `dst_p` points to.

Return Converted address pointer or NULL on failure.

Parameters

- `src_p`: Address to convert into a string.

- `dst_p`: Converted address as a string.

`uint16_t inet_checksum (void *buf_p, size_t size)`
Calculate the internet checksum of given buffer.

Return Calculated checksum.

Parameters

- `buf_p`: Buffer to calculate the checksum of.
- `size`: Size of the buffer.

`struct inet_ip_addr_t`
#include <inet.h>

Public Members

`uint32_t number`
IPv4 address.

`struct inet_addr_t`

Public Members

`struct inet_ip_addr_t ip`
IPv4 address.

`uint16_t port`
Port.

`struct inet_if_ip_info_t`
#include <inet.h> Interface IP information.

Public Members

`struct inet_ip_addr_t address`

`struct inet_ip_addr_t netmask`

`struct inet_ip_addr_t gateway`

isotp — ISO-TP

Source code: `src/inet/isotp.h`, `src/inet/isotp.c`

Test code: `tst/inet/isotp/main.c`

Defines

`ISOTP_FLAGS_NO_FLOW_CONTROL` (1 << 0)

Functions

int **isotp_init** (struct *isotp_t* *self_p, uint8_t *message_p, size_t size, int flags)

Initialize given ISO-TP object. An object can *either* be used to transmit or receive an ISO-TP message. Once `isotp_input()` or `isotp_output()` returns a positive value the message transmission is completed.

An object can only be used to transmit one message. Initialize a new object to transmit another message.

Return zero(0) or negative error code.

Parameters

- `self_p`: Driver object to initialize.
- `message_p`: ISO-TP message to transmit, or a reception buffer for an incoming message.
- `size`: Size of the message buffer in bytes.
- `flags`: Configuration flags.

ssize_t **isotp_input** (struct *isotp_t* *self_p, const uint8_t *buf_p, size_t size)

Input a CAN frame into given ISO-TP object. Always call `isotp_output()` after this function returns zero(0) to check if there are frames to transmit.

For an ISO-TP object that transmits a message this function always returns zero(0) or negative error code.

Return Once a complete ISO-TP message has been received the size of the message is returned. Meanwhile, zero(0) is returned if the frame was expected. A negative error code is returned if the frame was unexpected or invalid.

Parameters

- `self_p`: Initialized ISO-TP object.
- `buf_p`: Input data.
- `size`: Data buffer length in bytes.

ssize_t **isotp_output** (struct *isotp_t* *self_p, uint8_t *buf_p, size_t *size_p)

Check if there is data to be transmitted. The caller must transmit all frames this function creates.

For an ISO-TP object that receives a message this function always returns zero(0) or negative error code.

Return Once a complete ISO-TP message has been transmitted the size of the message is returned. Meanwhile, zero(0) or negative error code is returned.

Parameters

- `self_p`: Initialized ISO-TP object.
- `buf_p`: Output data to be transmitted to the peer. The size of this buffer must be at least eight bytes.
- `size_p`: Number of bytes to be transmitted.

struct **isotp_t**

Public Members

uint8_t ***message_p**

size_t **size**

int **state**

```
int flags
size_t offset
int next_index
struct isotp_t::@51 isotp_t::message
```

mqtt_client — MQTT client

MQTT is a publish-subscribe-based lightweight messaging protocol.

Note: This driver only implements the MQTT protocol, not the transport layer (normally TCP). That has to be set up using channels.

The driver works by running the processing code in a thread which communicate with the MQTT broker on one side using channels, and the application on the other side using queues.

This means the application has to set up appropriate channels, which is already ready to communicate with the MQTT server, e.g. using TCP, and the thread running the MQTT client.

Basic example of initializing MQTT over TCP (error checking left out for brevity).

```
static size_t on_publish(struct mqtt_client_t *client_p,
                        const char *topic_p,
                        void *chin_p,
                        size_t size)
{
    uint8_t buf[32];

    chan_read(chin_p, buf, size);
    buf[size] = '\0';
    std_printf(OSTR("on_publish: %s\r\n"), &buf[0]);

    return (0);
}
```

```
struct inet_addr_t remote_host_address;

inet_aton("127.0.0.1", &remote_host_address.ip);
remote_host_address.port = 1883;
socket_open_tcp(&server_sock);
socket_connect(&server_sock, &remote_host_address);

mqtt_client_init(&client,
                "mqtt_client",
                NULL,
                &server_sock,
                &server_sock,
                on_publish,
                NULL);

thrd_spawn(mqtt_client_main,
           &client,
           0,
           stack,
           sizeof(stack));
```

```
mqtt_client_connect(&client);
```

Source code: [src/inet/mqtt_client.h](#), [src/inet/mqtt_client.c](#)

Test code: [tst/inet/mqtt_client/main.c](#)

Test coverage: [src/inet/mqtt_client.c](#)

Example code: [examples/mqtt_client/main.c](#)

Typedefs

typedef size_t (***mqtt_on_publish_t**)(**struct** *mqtt_client_t* *client_p, **const** char *topic_p, void *chin_p, size_t size)

Prototype of the on-publish callback function.

Return Number of bytes read from the input channel.

Parameters

- `client_p`: The client.
- `topic_p`: The received topic.
- `chin_p`: The channel to read the value from.
- `size`: Number of bytes of the value to read from `chin_p`.

typedef int (***mqtt_on_error_t**)(**struct** *mqtt_client_t* *client_p, int error)

Prototype of the on-error callback function.

Return zero(0) or negative error code.

Parameters

- `client_p`: The client.
- `error`: The number of error that occurred.

Enums

enum **mqtt_client_state_t**

Values:

mqtt_client_state_disconnected_t

mqtt_client_state_connected_t

mqtt_client_state_connecting_t

enum **mqtt_qos_t**

Quality of Service.

Values:

mqtt_qos_0_t = 0

mqtt_qos_1_t = 1

```
mqtt_qos_2_t = 2
```

Functions

```
int mqtt_client_init (struct mqtt_client_t *self_p, const char *name_p, struct log_object_t  
                    *log_object_p, void *chout_p, void *chin_p, mqtt_on_publish_t on_publish,  
                    mqtt_on_error_t on_error)
```

Initialize given MQTT client.

Return zero(0) or negative error code.

Parameters

- self_p: MQTT client.
- name_p: Name of the thread.
- log_object_p: Log object.
- chout_p: Output channel for client to server packets.
- chin_p: Input channel for server to client packets.
- on_publish: On-publish callback function. Called when the server publishes a message.
- on_error: On-error callback function. Called when an error occurs. If NULL, a default handler is used.

```
void *mqtt_client_main (void *arg_p)
```

MQTT client thread.

Return Never returns.

Parameters

- arg_p: MQTT client.

```
int mqtt_client_connect (struct mqtt_client_t *self_p)
```

Establish a connection to the server.

Return zero(0) or negative error code.

Parameters

- self_p: MQTT client.

```
int mqtt_client_disconnect (struct mqtt_client_t *self_p)
```

Disconnect from the server.

Return zero(0) or negative error code.

Parameters

- self_p: MQTT client.

```
int mqtt_client_ping (struct mqtt_client_t *self_p)
```

Send a ping request to the server (broker) and wait for the ping response.

Return zero(0) or negative error code.

Parameters

- `self_p`: MQTT client.

int `mqtt_client_publish` (struct `mqtt_client_t` *`self_p`, struct `mqtt_application_message_t` *`message_p`)

Publish given topic.

Return zero(0) or negative error code.

Parameters

- `self_p`: MQTT client.
- `topic_p`: Topic.
- `payload_p`: Payload to publish. May be NULL.
- `payload_size`: Number of bytes in the payload.

int `mqtt_client_subscribe` (struct `mqtt_client_t` *`self_p`, struct `mqtt_application_message_t` *`message_p`)

Subscribe to given message.

Return zero(0) or negative error code.

Parameters

- `self_p`: MQTT client.
- `message_p`: The message to subscribe to. The payload part of the message is not used. The topic may use wildcards, given that the server supports it.

int `mqtt_client_unsubscribe` (struct `mqtt_client_t` *`self_p`, struct `mqtt_application_message_t` *`message_p`)

Unsubscribe from given message.

Return zero(0) or negative error code.

Parameters

- `self_p`: MQTT client.
- `message_p`: The message to unsubscribe from. Only the topic in the message is used.

struct `mqtt_client_t`
#include <mqtt_client.h> MQTT client.

Public Members

```
const char *name_p
struct log_object_t *log_object_p
int state
int type
void *data_p
struct mqtt_client_t::@52 mqtt_client_t::message
void *out_p
```

```
void *in_p
struct mqtt_client_t::@53  mqtt_client_t::transport
struct queue_t out
struct queue_t in
struct mqtt_client_t::@54  mqtt_client_t::control
mqtt_on_publish_t on_publish
mqtt_on_error_t on_error
struct mqtt_application_message_t
#include <mqtt_client.h> MQTT application message.
```

Public Members

```
const char *buf_p
size_t size
struct mqtt_application_message_t::@55  mqtt_application_message_t::topic
const void *buf_p
struct mqtt_application_message_t::@56  mqtt_application_message_t::payload
mqtt_qos_t qos
```

network_interface — Network interface

The network interface module has a list of all network interfaces and their states.

Network interface modules:

network_interface_slip — Serial Link Internet Protocol

Serial Line Internet Protocol (SLIP) is a link layer internet protocol used to transfer TCP/IP packets over a point-to-point serial line.

It is documented in RFC 1055.

Source code: [src/inet/network_interface/slipo.h](#)

Example code: [examples/inet/slipo/main.c](#)

Defines

NETWORK_INTERFACE_SLIP_FRAME_SIZE_MAX 1500

Enums

enum **network_interface_slip_state_t**

Values:

NETWORK_INTERFACE_SLIP_STATE_NORMAL = 0

NETWORK_INTERFACE_SLIP_STATE_ESCAPE

Functions

int **network_interface_slip_module_init** (void)

Initialize the slip module.

Return zero(0) or negative error code.

int **network_interface_slip_init** (struct *network_interface_slip_t* *self_p, struct *inet_ip_addr_t* *ipaddr_p, struct *inet_ip_addr_t* *netmask_p, struct *inet_ip_addr_t* *gateway_p, void *chout_p)

Initialize given slip network interface with given configuration and output channel.

Return zero(0) or negative error code.

Parameters

- self_p: Slip to initialize.
- ipaddr_p: Network interface IP address.
- netmask_p: Network interface netmask.
- gateway_p: Network interface gateway.
- chout_p: Output channel.

int **network_interface_slip_input** (struct *network_interface_slip_t* *self_p, uint8_t data)

Input a byte into the SLIP IP stack. Normally a user thread reads one byte at a time from the UART and calls this functions with the read byte as argument.

Return Number of bytes written to the input frame or negative error code.

Parameters

- self_p: Slip to initialize.
- data: Byte to input into the stack.

struct **network_interface_slip_t**

Public Members

network_interface_slip_state_t **state**

struct pbuf ***pbuf_p**

uint8_t ***buf_p**

size_t **size**

```
struct network_interface_slip_t::@57 network_interface_slip_t::frame
void *chout_p
struct network_interface_t network_interface
```

network_interface_wifi — WiFi network interface

WiFi network interface driver modules:

network_interface_driver_esp — ESP WiFi network interface driver

Source code: `src/inet/network_interface/driver/esp.h`, `src/inet/network_interface/driver/esp.c`

Test code: `tst/inet/network_interface/wifi_esp/main.c`

Variables

```
struct network_interface_wifi_driver_t network_interface_wifi_driver_esp_station
struct network_interface_wifi_driver_t network_interface_wifi_driver_esp_softap
```

Espressif WiFi SoftAP driver callbacks. To be used as driver in the wifi network interface.

Source code: `src/inet/network_interface/wifi.h`, `src/inet/network_interface/wifi.c`

Test code: `tst/inet/network_interface/wifi_esp/main.c`

Functions

int **network_interface_wifi_module_init** (void)
Initialize the WiFi network interface module.

Return zero(0) or negative error code.

int **network_interface_wifi_init** (struct *network_interface_wifi_t* *self_p, const char *name_p,
struct *network_interface_wifi_driver_t* *driver_p, void *arg_p,
const char *ssid_p, const char *password_p)
Initialize given WiFi network interface with given configuration.

Return zero(0) or negative error code.

Parameters

- self_p: The WiFi network interface to initialize.
- name_p: Name to assign the to interface.
- driver_p: Driver virtualization callbacks to use.

- `arg_p`: Argument passed to the driver callbacks. In case of ESP chips and WiFi station mode - compound literal of `uint8_t[6]` specifying the access point MAC.
- `ssid_p`: Access Point SSID.
- `password_p`: Access Point password.

int **network_interface_wifi_start** (struct *network_interface_wifi_t* *self_p)
Start given WiFi network interface.

Return zero(0) or negative error code.

Parameters

- `self_p`: WiFi network interface to start.

int **network_interface_wifi_stop** (struct *network_interface_wifi_t* *self_p)
Stop given WiFi network interface.

Return zero(0) or negative error code.

Parameters

- `self_p`: WiFi network interface to stop.

int **network_interface_wifi_is_up** (struct *network_interface_wifi_t* *self_p)
Get the connection status of given network interface.

Return true(1) if the network interface is up, false(0) if it is down, and otherwise negative error code.

Parameters

- `self_p`: Network interface to get the connection status of.

int **network_interface_wifi_set_ip_info** (struct *network_interface_wifi_t* *self_p, const struct *inet_if_ip_info_t* *info_p)
Set the ip address, netmask and gateway of given network interface.

Return zero(0) if the interface has valid IP information, otherwise negative error code.

Parameters

- `self_p`: Network interface.
- `info_p`: Interface IP information to set.

int **network_interface_wifi_get_ip_info** (struct *network_interface_wifi_t* *self_p, struct *inet_if_ip_info_t* *info_p)
Get the ip address, netmask and gateway of given network interface.

Return zero(0) if the interface has valid IP information, otherwise negative error code.

Parameters

- `self_p`: Network interface.
- `info_p`: Interface IP information. Only valid if this function returns zero(0).

struct **network_interface_wifi_t**
#include <wifi.h>

Public Members

```
struct network_interface_t network_interface
struct network_interface_wifi_driver_t *driver_p
void *arg_p
const char *ssid_p
const char *password_p
const struct inet_if_ip_info_t *info_p
struct network_interface_wifi_driver_t
#include <wifi.h> Driver virtualization callbacks. See the driver/ subfolder for available drivers.
```

Public Members

```
int (*init)(void *arg_p)
int (*start)(void *arg_p, const char *ssid_p, const char *password_p, const struct inet_if_ip_info_t
               *info_p)
int (*stop)(void *arg_p)
int (*is_up)(void *arg_p)
int (*set_ip_info)(void *arg_p, const struct inet_if_ip_info_t *info_p)
int (*get_ip_info)(void *arg_p, struct inet_if_ip_info_t *info_p)
```

Debug file system commands

One debug file system command is available, located in the directory `inet/network_interface/`.

Command	Description
<code>list</code>	Print a list of all registered network interfaces.

Example output from the shell:

\$ inet/network_interface/list					
NAME	STATE	ADDRESS	TX BYTES	RX BYTES	
esp-wlan-ap	up	192.168.4.1	—	—	
esp-wlan-sta	up	192.168.0.5	—	—	

Source code: `src/inet/network_interface.h`, `src/inet/network_interface.c`

Test coverage: `src/inet/network_interface.c`

Typedefs

```
typedef int (*network_interface_start_t)(struct network_interface_t *netif_p)
typedef int (*network_interface_stop_t)(struct network_interface_t *netif_p)
typedef int (*network_interface_is_up_t)(struct network_interface_t *netif_p)
typedef int (*network_interface_set_ip_info_t)(struct network_interface_t *netif_p, const
                                              struct inet_if_ip_info_t *info_p)
typedef int (*network_interface_get_ip_info_t)(struct network_interface_t *netif_p, struct
                                              inet_if_ip_info_t *info_p)
```

Functions

int **network_interface_module_init** (void)

Initialize the network interface module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **network_interface_add** (struct *network_interface_t* *netif_p)

Add given network interface to the global list of network interfaces. Call `network_interface_start()` to enable the interface.

Return zero(0) or negative error code.

Parameters

- `netif_p`: Network interface to register.

int **network_interface_start** (struct *network_interface_t* *netif_p)

Start given network interface. Enables the interface in the IP stack to allow packets to be sent and received. If the interface is a WiFi station interface it will try initiate the connection to its configured access point. Use `network_interface_is_up()` to check if the interface is connected to its access point.

Return zero(0) or negative error code.

Parameters

- `netif_p`: Network interface to start.

int **network_interface_stop** (struct *network_interface_t* *netif_p)

Stop given network interface. Disconnects from any WiFi access points and disables the interface in the IP stack. No packets can be sent or received on this interface after this function is called.

Return zero(0) or negative error code.

Parameters

- `netif_p`: Network interface to stop.

int **network_interface_is_up** (struct *network_interface_t* *netif_p)

Get the connection status of given network interface. Packets can only be sent and received when the interface is up.

Return true(1) if the network interface is up, false(0) if it is down, and otherwise negative error code.

Parameters

- `netif_p`: Network interface to get the connection status of.

struct *network_interface_t* ***network_interface_get_by_name** (**const** char **name_p*)
Search the global list of network interfaces for an interface with given name and return it.

Return Found network interface or NULL if it was not found.

Parameters

- `name_p`: Name of the network interface to find.

int **network_interface_set_ip_info** (**struct** *network_interface_t* **netif_p*, **const** **struct** *inet_if_ip_info_t* **info_p*)
Set the IP information of given network interface.

Return zero(0) or negative error code.

Parameters

- `netif_p`: Network interface to get the IP information of.
- `info_p`: IP information to set.

int **network_interface_get_ip_info** (**struct** *network_interface_t* **netif_p*, **struct** *inet_if_ip_info_t* **info_p*)
Get the IP information of given network interface.

Return zero(0) or negative error code.

Parameters

- `netif_p`: Network interface to get the IP information of.
- `info_p`: Read IP information.

struct *network_interface_t*

Public Members

```
const char *name_p
struct inet_if_ip_info_t info
network_interface_start_t start
network_interface_stop_t stop
network_interface_is_up_t is_up
network_interface_set_ip_info_t set_ip_info
network_interface_get_ip_info_t get_ip_info
void *netif_p
struct network_interface_t *next_p
```

ping — Ping

Debug file system commands

One debug file system command is available, located in the directory `inet/ping/`.

Command	Description
<code>ping <remote host></code>	Ping a remote host by given ip address.

Example output from the shell:

```
$ inet/ping/ping 192.168.1.100
Successfully pinged '192.168.1.100' in 10 ms.
$
```

Source code: `src/inet/ping.h`, `src/inet/ping.c`

Test code: `tst/inet/ping/main.c`

Test coverage: `src/inet/ping.c`

Functions

`int ping_module_init (void)`

`int ping_host_by_ip_address (struct inet_ip_addr_t *address_p, struct time_t *timeout_p, struct time_t *round_trip_time_p)`

Ping host by given ip address. Send an echo request packet to given host and wait for the echo reply packet. No extra payload data is transmitted, only the ICMP header.

Return zero(0) or negative error code.

Parameters

- `address_p`: IP address of the host to ping.
- `timeout_p`: Number of seconds to wait for the echo reply packet.
- `round_trip_time_p`: The time it took from sending the echo request packet to receiving the echo reply packet. Only valid if this functions returns zero(0).

socket — Internet communication

Sockets are used to communicate over IP networks. TCP and UDP are the most common transport protocols.

No more than one thread may read from a socket at any given moment. The same applies when writing to a socket. The reader and writer may be different threads, though. The behaviour is undefined if more threads use the same socket simultaneously. The application will likely crash. Add a semaphore to protect the socket if more threads need access to a socket.

Below is a TCP client example that connects to a server and sends data.

```
uint8_t buf[16];
struct socket_t tcp;
struct inet_addr_t local_addr, remote_addr;

/* Set the local and remote addresses. */
inet_aton("192.168.1.103", &local_addr.ip);
local_addr.port = 6000;
inet_aton("192.168.1.106", &remote_addr.ip);
remote_addr.port = 5000;

/* Initialize the socket and connect to the server. */
socket_open_tcp(&tcp);
socket_bind(&tcp, &local_addr);
socket_connect(&tcp, &remote_addr);

/* Send the data. */
memset(buf, 0, sizeof(buf));
socket_write(&tcp, buf, sizeof(buf));

/* Close the connection. */
socket_close(&tcp);
```

And below is the same scenario for UDP.

```
uint8_t buf[16];
struct socket_t udp;
struct socket_addr_t local_addr, remote_addr;

/* Set the local and remote addresses. */
inet_aton("192.168.1.103", &local_addr.ip);
local_addr.port = 6000;
inet_aton("192.168.1.106", &remote_addr.ip);
remote_addr.port = 5000;

/* Initialize the socket and connect to the server. */
socket_open_udp(&udp);
socket_bind(&udp, &local_addr);
socket_connect(&udp, &remote_addr);

/* Send the data. */
memset(buf, 0, sizeof(buf));
socket_send(&udp, buf, sizeof(buf));

/* Close the connection. */
socket_close(&udp);
```

Source code: `src/inet/socket.h`, `src/inet/socket.c`

Defines

SOCKET_DOMAIN_INET 0

SOCKET_TYPE_STREAM 1
TCP socket type.

SOCKET_TYPE_DGRAM 2

UDP socket type.

SOCKET_TYPE_RAW 3

RAW socket type.

SOCKET_PROTO_ICMP 0

Functions

int **socket_module_init** (void)

Initialize the socket module. This function will start the lwIP TCP/IP stack. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **socket_open_tcp** (struct *socket_t* *self_p)

Initialize given TCP socket.

Return zero(0) or negative error code.

Parameters

- self_p: Socket to initialize.

int **socket_open_udp** (struct *socket_t* *self_p)

Initialize given UDP socket.

Return zero(0) or negative error code.

Parameters

- self_p: Socket to initialize.

int **socket_open_raw** (struct *socket_t* *self_p)

Initialize given RAW socket.

Return zero(0) or negative error code.

Parameters

- self_p: Socket to initialize.

int **socket_open** (struct *socket_t* *self_p, int domain, int type, int protocol)

Initialize given socket.

Return zero(0) or negative error code.

Parameters

- self_p: Socket to initialize.
- domain: Socket domain.
- type: Socket type.
- protocol: Socket protocol.

int **socket_close** (struct *socket_t* *self_p)

Close given socket. No data transfers are allowed on after the socket has been closed.

Return zero(0) or negative error code.

Parameters

- self_p: Socket to close.

int **socket_bind** (struct *socket_t* *self_p, const struct *inet_addr_t* *local_addr_p)

Bind given local address to given socket.

Return zero(0) or negative error code.

Parameters

- self_p: Socket.
- local_addr_p: Local address.

int **socket_listen** (struct *socket_t* *self_p, int backlog)

Listen for connections from remote clients. Only applicable for TCP sockets.

Return zero(0) or negative error code.

Parameters

- self_p: Socket to listen on.
- backlog: Unused.

int **socket_connect** (struct *socket_t* *self_p, const struct *inet_addr_t* *remote_addr_p)

Connect to given remote address. Connecting a UDP socket sets the default remote address for outgoing datagrams. For TCP a three-way handshake with the remote peer is initiated.

Return zero(0) or negative error code.

Parameters

- self_p: Socket.
- remote_addr_p: Remote address.

int **socket_connect_by_hostname** (struct *socket_t* *self_p, const char *hostname_p, uint16_t port)

Connect to the remote device with given hostname.

In computer networking, a hostname (archaically nodename) is a label that is assigned to a device connected to a computer network and that is used to identify the device in various forms of electronic communication, such as the World Wide Web.

Return zero(0) or negative error code.

Parameters

- self_p: Socket.
- hostname_p: The hostname of the remote device to connect to.
- port: Remote device port to connect to.

int **socket_accept** (struct *socket_t* *self_p, struct *socket_t* *accepted_p, struct *inet_addr_t* *remote_addr_p)

Accept a client connect attempt. Only applicable for TCP sockets that are listening for connections.

Return zero(0) or negative error code.

Parameters

- self_p: TCP socket.
- accepted_p: New client socket of the accepted client.
- remote_addr_p: Address of the client.

ssize_t **socket_sendto** (struct *socket_t* *self_p, const void *buf_p, size_t size, int flags, const struct *inet_addr_t* *remote_addr_p)

Write data to given socket. Only used by UDP sockets.

Return Number of sent bytes or negative error code.

Parameters

- self_p: Socket to send data on.
- buf_p: Buffer to send.
- size: Size of buffer to send.
- flags: Unused.
- remote_addr_p: Remote address to send the data to.

ssize_t **socket_recvfrom** (struct *socket_t* *self_p, void *buf_p, size_t size, int flags, struct *inet_addr_t* *remote_addr_p)

Read data from given socket. Only used by UDP sockets.

Return Number of received bytes or negative error code.

Parameters

- self_p: Socket to receive data on.
- buf_p: Buffer to read into.
- size: Size of buffer to read.
- flags: Unused.
- remote_addr_p: Remote address to receive data from.

ssize_t **socket_write** (struct *socket_t* *self_p, const void *buf_p, size_t size)

Write data to given TCP or UDP socket. For UDP sockets, `socket_connect()` must have been called prior to calling this function.

Return Number of written bytes or negative error code.

Parameters

- self_p: Socket.
- buf_p: Buffer to send.
- size: Numer of bytes to send.

ssize_t **socket_read**(struct *socket_t* *self_p, void *buf_p, size_t size)

Read data from given socket.

Return Number of read bytes or negative error code.

Parameters

- self_p: Socket.
- buf_p: Buffer to read into.
- size: Number of bytes to read.

ssize_t **socket_size**(struct *socket_t* *self_p)

Get the number of input bytes currently stored in the socket. May return less bytes than number of bytes stored in the channel.

Return Number of input bytes in the socket.

Parameters

- self_p: Socket.

struct **socket_t**

Public Members

struct *chan_t* base

int type

ssize_t left

struct socket_t::@59::@61::@63 socket_t::common

struct pbuf *pbuf_p

struct *inet_addr_t* remote_addr

int closed

struct socket_t::@59::@61::@64 socket_t::recvfrom

struct tcp_pcb *pcb_p

struct socket_t::@59::@61::@65 socket_t::accept

union socket_t::@59::@61 socket_t::u

int state

void *args_p

struct *thrd_t* *thrd_p

struct socket_t::@59::@62 socket_t::cb

struct socket_t::@59 socket_t::input

struct socket_t::@60::@66 socket_t::cb

struct socket_t::@60 socket_t::output

void *pcb_p

ssl — Secure socket layer

SSL/TLS based on mbedTLS. Server side sockets works, but not client side.

Warning: This module may lead to a false sense of security, as it is implemented by a TLS/SSL novice, me. Use with care!

Simplified server and client side examples to illustrate how to use the module. All error checking is left out to make the example easier to understand. There are links to the full examples further down in this document.

Server side:

```
/* Create the SSL context. */
ssl_context_init(&context, ssl_protocol_tls_v1_0);
ssl_context_load_cert_chain(&context, &certificate[0], &key[0]);

/* Create the TCP listener socket. */
socket_open_tcp(&listener_sock);
socket_bind(&listener_sock, &addr);
socket_listen(&listener_sock, 5);

/* Accept a client.*/
socket_accept(&listener_sock, &sock, &addr);
ssl_socket_open(&ssl_sock,
                &context,
                &sock,
                SSL_SOCKET_SERVER_SIDE,
                NULL);

/* Communicate with the client. */
ssl_socket_read(&ssl_sock, &buf[0], 6);
ssl_socket_write(&ssl_sock, "Goodbye!", 8);
ssl_socket_close(&ssl_sock);
socket_close(&sock);
```

Client side:

```
/* Create the SSL context. */
ssl_context_init(&context, ssl_protocol_tls_v1_0);
ssl_context_load_verify_location(&context, &certificate[0]);

/* Create the TCP socket and connect to the server. */
socket_open_tcp(&sock);
socket_connect(&sock, &addr);
ssl_socket_open(&ssl_sock,
                &context,
                &sock,
                0,
                "foobar.org");

/* Communicate with the client. */
ssl_socket_write(&ssl_sock, "Hello!", 6);
ssl_socket_read(&ssl_sock, &buf[0], 8);
ssl_socket_close(&ssl_sock);
socket_close(&ssl_sock);
```

Source code: `src/inet/ssl.h`, `src/inet/ssl.c`

Test code: `tst/inet/ssl/main.c`,

Test coverage: `src/inet/ssl.c`

Example code: `examples/ssl_client/main.c`, `examples/ssl_server/main.c`

Defines

`SSL_SOCKET_SERVER_SIDE` 0x1

Enums

`enum ssl_protocol_t`

Values:

`ssl_protocol_tls_v1_0`

`enum ssl_verify_mode_t`

Values:

`ssl_verify_mode_cert_none_t = 0`

`ssl_verify_mode_cert_required_t = 2`

Functions

`int ssl_module_init (void)`

Initialize the SSL module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

`int ssl_context_init (struct ssl_context_t *self_p, enum ssl_protocol_t protocol)`

Initialize given SSL context. A SSL context contains settings that lives longer than a socket.

Return zero(0) or negative error code.

Parameters

- `self_p`: SSL context to initialize.
- `protocol`: SSL protocol to use.

`int ssl_context_destroy (struct ssl_context_t *self_p)`

Destroy given SSL context. The context may not be used after it has been destroyed.

Return zero(0) or negative error code.

Parameters

- `self_p`: SSL context to destroy.

int **ssl_context_load_cert_chain**(struct *ssl_context_t* *self_p, const char *cert_p, const char *key_p)

Load given certificate chain into given context.

Return zero(0) or negative error code.

Parameters

- self_p: SSL context.
- cert_p: Certificate to load.
- key_p: Optional key to load. May be NULL.

int **ssl_context_load_verify_location**(struct *ssl_context_t* *self_p, const char *ca_certs_p)

Load a set of “certification authority” (CA) certificates used to validate other peers’ certificates when verify_mode is other than ssl_verify_mode_cert_none_t.

Return zero(0) or negative error code.

Parameters

- self_p: SSL context.
- ca_certs_p: CA certificates.

int **ssl_context_set_verify_mode**(struct *ssl_context_t* *self_p, enum *ssl_verify_mode_t* mode)

Whether to try to verify other peers’ certificates.

Load CA certificates with `ssl_context_load_verify_location()`.

Return zero(0) or negative error code.

Parameters

- self_p: SSL context.
- mode: Mode to set.

int **ssl_socket_open**(struct *ssl_socket_t* *self_p, struct *ssl_context_t* *context_p, void *socket_p, int flags, const char *server_hostname_p)

Initialize given SSL socket with given socket and SSL context. Performs the SSL handshake.

Return zero(0) or negative error code.

Parameters

- self_p: SSL socket to initialize.
- context_p: SSL context to execute in.
- socket_p: Socket to wrap in the SSL socket.
- flags: Give as SSL_SOCKET_SERVER_SIDE for server side sockets. Otherwise 0.
- server_hostname_p: The server hostname used by client side sockets to verify the server. Give as NULL to skip the verification. Must be NULL for server side sockets.

int **ssl_socket_close**(struct *ssl_socket_t* *self_p)

Close given SSL socket.

Return zero(0) or negative error code.

Parameters

- `self_p`: SSL socket to close.

`ssize_t ssl_socket_write(struct ssl_socket_t *self_p, const void *buf_p, size_t size)`
Write data to given SSL socket.

Return Number of written bytes or negative error code.

Parameters

- `self_p`: SSL socket.
- `buf_p`: Buffer to send.
- `size`: Numer of bytes to send.

`ssize_t ssl_socket_read(struct ssl_socket_t *self_p, void *buf_p, size_t size)`
Read data from given SSL socket.

Return Number of read bytes or negative error code.

Parameters

- `self_p`: SSL socket.
- `buf_p`: Buffer to read into.
- `size`: Number of bytes to read.

`ssize_t ssl_socket_size(struct ssl_socket_t *self_p)`
Get the number of input bytes currently stored in the SSL socket.

Return Number of input bytes in the SSL socket.

Parameters

- `self_p`: SSL socket.

`const char *ssl_socket_get_server_hostname(struct ssl_socket_t *self_p)`
Get the hostname of the server.

Return Server hostname or NULL.

Parameters

- `self_p`: SSL socket.

`int ssl_socket_get_cipher(struct ssl_socket_t *self_p, const char **cipher_pp, const char **protocol_pp, int *number_of_secret_bits_p)`
Get the cipher information.

Return zero(0) or negative error code.

Parameters

- `self_p`: SSL socket.
- `cipher_pp`: Connection cipher.
- `protocol_pp`: Connection protocol.
- `number_of_secret_bits_p`: Number of secret bits.

struct ssl_context_t

Public Members

ssl_protocol_t **protocol**

void ***conf_p**

int **server_side**

int **verify_mode**

struct ssl_socket_t

Public Members

struct *chan_t* **base**

void ***ssl_p**

void ***socket_p**

tftp_server — TFTP server

TFTP is a simple file transfer protocol.

Only binary mode is supported.

Source code: [src/inet/tftp_server.h](#), [src/inet/tftp_server.c](#)

Test code: [tst/inet/tftp_server/main.c](#)

Test coverage: [src/inet/tftp_server.c](#)

Example code: [examples/tftp_server/main.c](#)

Functions

int **tftp_server_init** (**struct** *tftp_server_t* **self_p*, **struct** *inet_addr_t* **addr_p*, int *timeout_ms*, **const** char **name_p*, **const** char **root_p*, void **stack_p*, size_t *stack_size*)
 Initialize given TFTP server.

Return zero(0) or negative error code.

Parameters

- *self_p*: TFTP server to initialize.
- *addr_p*: Ip address and port of the server.
- *timeout_ms*: Packet reception timeout.
- *name_p*: Name of the server thread.
- *root_p*: File system root path.

- `stack_p`: Server thread stack.
- `stack_size`: Server thread stack size.

int **tftp_server_start** (struct *tftp_server_t* *self_p)
Start given TFTP server.

Return zero(0) or negative error code.

Parameters

- `self_p`: TFTP server to start.

struct **tftp_server_t**
#include <tftp_server.h>

Public Members

struct *inet_addr_t* **addr**
struct *socket_t* **listener**
int **timeout_ms**
const char ***name_p**
const char ***root_p**
void ***stack_p**
size_t **stack_size**
struct *thrd_t* ***thrd_p**

oam

Operations and maintenance of an application is essential to configure, debug and monitor its operation.

The oam package on [Github](#).

console — System console

The system console is the default communication channel to an application. The console input and output channels are often terminated by a shell to enable the user to control and debug the application.

Configure the console by changing the *configuration variables* called `CONFIG_START_CONSOLE*`.

Source code: [src/oam/console.h](#), [src/oam/console.c](#)

Test coverage: [src/oam/console.c](#)

Functions

int **console_module_init** (void)

int **console_init** (void)

Initialize the console.

Return zero(0) or negative error code.

int **console_start** (void)

Start the console.

Return zero(0) or negative error code.

int **console_stop** (void)

Stop the console.

Return zero(0) or negative error code.

int **console_set_input_channel** (void **chan_p*)

Set the pointer to the input channel.

Return zero(0) or negative error code.

void ***console_get_input_channel** (void)

Get the pointer to the input channel.

Return Input channel or NULL.

void ***console_set_output_channel** (void **chan_p*)

Set the pointer to the output channel.

Return zero(0) or negative error code.

void ***console_get_output_channel** (void)

Get the pointer to the output channel.

Return Output channel or NULL.

nvm — Non-volatile memory

A non-volatile memory is typically used for long-term persistent storage.

This module implements a singleton non-volatile memory, often on top of an EEPROM or software emulated EEPROM.

Source code: [src/oam/nvm.h](#), [src/oam/nvm.c](#)

Test coverage: [src/oam/nvm.c](#)

Functions

int **nvm_module_init** (void)

int **nvm_mount** (void)

Mount the non-volatile memory.

Return zero(0) if the memory was successfully mounted, otherwise negative error code.

int **nvm_format** (void)

Format the non-volatile memory, writing 0xff/erasing to the whole memory. A formatted NVM can always be mounted with `nvm_mount()`.

Return zero(0) or negative error code.

ssize_t **nvm_read** (void **dst_p*, uint32_t *src*, size_t *size*)

Read into given buffer from given NVM address.

Return Number of bytes read or negative error code.

Parameters

- *dst_p*: Buffer to read into.
- *src*: Address in NVM to read from. Addressing starts at zero(0).
- *size*: Number of bytes to read.

ssize_t **nvm_write** (uint32_t *dst*, const void **src_p*, size_t *size*)

Write given buffer to given NVM address.

Return Number of bytes written or negative error code.

Parameters

- *dst*: Address in NVM to write to. Addressing starts at zero(0).
- *src_p*: Buffer to write.
- *size*: Number of bytes to write.

service — Services

A service is as a background task. A service is either running or stopped.

Debug file system commands

Three debug file system commands is available, all located in the directory `oam/service/`.

Command	Description
<code>list</code>	List all registered services.
<code>start <service></code>	Start given service.
<code>stop <service></code>	Stop given service.

Example output from the shell:

```

$ oam/service/list
NAME                STATUS
http_server         running
ftp_server           stopped
network_manager     running
$ oam/service/start ftp_server
$ oam/service/stop http_server
$ oam/service/list
NAME                STATE
http_server         stopped
ftp_server           running
network_manager     running

```

Source code: [src/oam/service.h](#), [src/oam/service.c](#)

Test code: [tst/oam/service/main.c](#)

Test coverage: [src/oam/service.c](#)

Defines

SERVICE_CONTROL_EVENT_START 0x1

SERVICE_CONTROL_EVENT_STOP 0x2
Service stop event.

Typedefs

typedef enum *service_status_t* (***service_get_status_cb_t**) (struct *service_t* *self_p)

Enums

enum service_status_t

Values:

service_status_running_t = 0

service_status_stopped_t = 1

Functions

int service_module_init (void)

Initialize the service module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int service_init (struct *service_t* *self_p, const char *name_p, *service_get_status_cb_t* status_cb)

Initialize a service with given name and status callback.

Return zero(0) or negative error code.

Parameters

- `self_p`: Service to initialize.
- `name_p`: Name of the service.
- `status_callback`: Callback function returning the service status.

int **service_start** (struct *service_t* **self_p*)
Start given service.

The event `SERVICE_CONTROL_EVENT_START` will be written to the control channel of given service and it's up to the service to act on this event. All services should act on all control events.

Return zero(0) or negative error code.

Parameters

- `self_p`: Service to start.

int **service_stop** (struct *service_t* **self_p*)
Stop given service.

The event `SERVICE_CONTROL_EVENT_STOP` will be written to the control channel of given service and it's up to the service to act on this event. All services should act on all control events.

Return zero(0) or negative error code.

Parameters

- `self_p`: Service to stop.

int **service_register** (struct *service_t* **service_p*)
Register given service to the global list of services.

Return zero(0) or negative error code.

Parameters

- `service_p`: Service to register.

int **service_deregister** (struct *service_t* **service_p*)
Deregister given service from the global list of services.

Return zero(0) or negative error code.

Parameters

- `service_p`: Service to deregister.

struct **service_t**
#include <service.h> A service with name and control event channel.

Public Members

const char ***name_p**
struct *event_t* **control**

```
service_get_status_cb_t status_cb
```

```
struct service_t *next_p
```

settings — Persistent application settings

Settings are stored in a non-volatile memory (NVM). In other words, settings are perserved after a board reset or power cycle.

Application settings are defined in an ini-file that is used to generate the c source code. A setting has a type, a size, an address and a default value, all defined in the ini-file.

Supported types are:

- `int32_t` A 32 bits signed integer.
- `string` An ASCII string.
- `blob` A chunk of data.

The size is the number of bytes of the value. For the standard integer types the size must be the value returned by `sizeof()`. For strings it is the length of the string, including null termination.

The address for each setting is defined by the user, starting at address 0 and increasing from there.

The build system variable `SETTINGS_INI` contains the path to the ini-file used by the build system.

Debug file system commands

Four debug file system commands are available, all located in the directory `oam/settings/`.

Command	Description
<code>list</code>	Print a list of the current settings.
<code>reset</code>	Overwrite the current settings values with their default values (the values defined in the ini-file values).
<code>read <name></code>	Read the value of setting <name>.
<code>write <name></code> <code><value></code>	Write <value> to setting <name>.

Example output from the shell:

```
$ oam/settings/list
NAME          TYPE      SIZE  VALUE
version       int32_t    4     1
value_1       int32_t    4    24567
value_2       blob_t     4    cafebabe
value_3       string_t   16    foobar
$ oam/settings/read value_1
24567
$ oam/settings/write value_1 -5
$ oam/settings/read value_1
-5
$ oam/settings/reset
$ oam/settings/list
NAME          TYPE      SIZE  VALUE
version       int32_t    4     1
value_1       int32_t    4    24567
value_2       blob_t     4    cafebabe
value_3       string_t   16    foobar
```

Example

In this example the ini-file has one setting defined, `foo`. The type is `int32_t`, the address is `0x00`, the size is 4 and the default value is `-4`.

```
[values]
foo = -4

[types]
foo = int32_t

[addresses]
foo = 0x00

[sizes]
foo = 4
```

The settings can be read and written with the functions `settings_read()` and `settings_write()`. Give the generated defines `SETTING_FOO_ADDR` and `SETTING_FOO_SIZE` as arguments to those functions.

```
int my_read_write_foo()
{
    int32_t foo;

    /* Read the foo setting. */
    if (settings_read(&foo,
                     SETTING_FOO_ADDR,
                     SETTING_FOO_SIZE) != 0) {
        return (-1);
    }

    foo -= 1;

    /* Write the foo setting. */
    if (settings_write(SETTING_FOO_ADDR,
                      &foo,
                      SETTING_FOO_SIZE) != 0) {
        return (-1);
    }

    return (0);
}
```

Source code: `src/oam/settings.h`, `src/oam/settings.c`

Test code: `tst/oam/settings/main.c`

Test coverage: `src/oam/settings.c`

Defines

`SETTINGS_AREA_CRC_OFFSET` (`CONFIG_SETTINGS_AREA_SIZE - 4`)

Enums

enum `setting_type_t`

Settings types. Each setting must have be one of these types.

Values:

`setting_type_int32_t` = 0

`setting_type_string_t`

`setting_type_blob_t`

Functions

int `settings_module_init` (void)

Initialize the settings module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

ssize_t `settings_read` (void **dst_p*, size_t *src*, size_t *size*)

Read the value of given setting by address.

Return Number of words read or negative error code.

Parameters

- *dst_p*: The read value.
- *src*: Setting source address.
- *size*: Number of words to read.

ssize_t `settings_write` (size_t *dst*, const void **src_p*, size_t *size*)

Write given value to given setting by address.

Return Number of words written or negative error code.

Parameters

- *dst*: Destination setting address.
- *src_p*: Value to write.
- *size*: Number of bytes to write.

ssize_t `settings_read_by_name` (const char **name_p*, void **dst_p*, size_t *size*)

Read the value of given setting by name.

Return Number of words read or negative error code.

Parameters

- *name_p*: Setting name.
- *dst_p*: The read value.
- *size*: Size of the destination buffer.

ssize_t **settings_write_by_name** (const char *name_p, const void *src_p, size_t size)

Write given value to given setting by name.

Return Number of words read or negative error code.

Parameters

- name_p: Setting name.
- src_p: Value to write.
- size: Number of bytes to write.

int **settings_reset** (void)

Overwrite all settings with their default values.

Return zero(0) or negative error code.

struct **setting_t**

Public Members

FAR const char* **setting_t::name_p**

setting_type_t **type**

uint32_t **address**

size_t **size**

shell — Debug shell

The shell is a command line interface where the user can execute various commands to control, debug and monitor its

```
username: erik
password: *****
$
$ kernel/thrd/list
      NAME      PARENT    STATE  PRIO   CPU  LOGMASK
      main              current   0    0%    0x3f
      idle       main      ready   127   0%    0x3f
      monitor    main      ready   -80   0%    0x3f
$ history
1: kernel/thrd/list
2: history
$ logout
```

application. The shell module has a few configuration variables that can be used to tailor the shell to the application requirements. Most noticeably is the configuration variable `CONFIG_SHELL_MINIMAL`. If set to 0 all the shell functionality is built; including tab completion, cursor movement, line editing and command history. If set to 1 only the minimal functionality is built; only including tab completion and line editing at the end of the line.

See [Configuration](#) for a list of all configuration variables.

Source code: [src/oam/shell.h](#), [src/oam/shell.c](#)

Test code: [tst/oam/shell/main.c](#)

Test coverage: [src/oam/shell.c](#)

Example code: [examples/shell/main.c](#)

Functions

int **shell_module_init** (void)

Initialize the shell module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **shell_init** (struct *shell_t* *self_p, void *chin_p, void *chout_p, void *arg_p, const char *name_p, const char *username_p, const char *password_p)

Initialize a shell with given parameters.

Parameters

- chin_p: The shell input channel. The shell waits for commands on this channel.
- chout_p: The shell output channel. The shell writes responses on this channel.
- arg_p: User supplied argument passed to all commands.
- name_p: The shell thread name.
- username_p: Shell login username, or NULL if no username is required to use the shell.
- password_p: Shell login password. This field is unused if username_p is NULL.

void ***shell_main** (void *arg_p)

The shell main function that listens for commands on the input channel and send response on the output channel. All received commands are passed to the debug file system function `fs_call()` for execution.

Here is an example of using the shell to list and execute debug file system commands.

```
$ <tab>
drivers/
kernel/
$ kernel/ <tab>
fs/
sys/
thrd/
$ kernel/thrd/list
      NAME      STATE  PRIO   CPU  LOGMASK
      main      current  0      0%    0x0f
      idle      ready   127    0%    0x0f
      monitor   ready   -80    0%    0x0f
$
```

Return Never returns.

Parameters

- arg_p: Pointer to the shell arguemnt struct struct *shell_t*. See the struct definition for a description of it's content.

struct **shell_history_elem_t**

#include <shell.h>

Public Members

```
struct shell_history_elem_t *next_p
struct shell_history_elem_t *prev_p
char buf[1]
struct shell_line_t
```

Public Members

```
char buf[CONFIG_SHELL_COMMAND_MAX]
int length
int cursor
struct shell_t
```

Public Members

```
void *chin_p
void *chout_p
void *arg_p
const char *name_p
const char *username_p
const char *password_p
struct shell_line_t line
struct shell_line_t prev_line
int carriage_return_received
int newline_received
int authorized
struct shell_history_elem_t *head_p
struct shell_history_elem_t *tail_p
struct shell_history_elem_t *current_p
struct shell_line_t pattern
struct shell_line_t match
int line_valid
struct circular_heap_t heap
uint8_t buf[CONFIG_SHELL_HISTORY_SIZE]
struct shell_t::@99::@100 shell_t::heap
struct shell_t::@99 shell_t::history
```

soam — Simba OAM

Simba Operation And Maintenance (SOAM) is a framed debug protocol with enumerated format strings and file system commands. This both saves memory and makes the communication more reliable.

Two macros are defined; `OSTR()` and `CSTR()`, both required by the SOAM build system. It is considered good practice to always use these macros, even if SOAM is not used.

- The `OSTR()` macro.

An output format string.

```
/* Log object. */
log_object_print(NULL, LOG_INFO, OSTR("Hello %s!\r\n"), "Erik");

/* File system command output. */
static int cmd_foo_cb(...)
{
    std_fprintf(chout_p, OSTR("Foo %d!\r\n"), 1);

    return (0);
}

/* Regular printf. */
std_printf(OSTR("Hello 0x%x!\r\n"), 0xbabe);
```

- The `CSTR()` macro.

A file system command string.

```
fs_command_init(&cmd_foo, CSTR("/foo"), cmd_foo_cb, NULL);
```

Usage

Enable SOAM by adding `SOAM=yes` to the application makefile.

Connect to the board with `soam.py` instead of a serial terminal program. The only required argument is the string database file.

Here is an example usage of the script. *Ctrl-D* is pressed to exit the script.

```
> soam.py --port /dev/arduino --baudrate 115200 \
    build/arduino_due/soam.soamdb
Welcome to the SOAM shell.

Type help or ? to list commands.

$ kernel/sys/info
app:    soam-master built 2017-03-05 21:26 CET by erik.
board:  Arduino Due
mcu:    Atmel SAM3X8E Cortex-M3 @ 84MHz, 96k sram, 512k flash
OK
$ kernel/thrd/list
      NAME      STATE  PRIO   CPU   SCHEDULED  MAX-STACK-USAGE  LOGMASK
      soam      current   30    0%        112        748/ 1542    0x0f
    monitor    suspended -80    0%         22        176/  518    0x0f
      idle      ready   127   99%        594        276/  390    0x0f
      main      suspended   0    0%        305       540/ 88898    0x00
```

```
OK
$ kernel/thrd/set_log_mask foo 0
ERROR (-3)
$ <Ctrl-D>

Bye!
>
```

OK is printed by the shell if the file system command returned `zero(0)`, otherwise `ERROR(error code)` is printed.

Source code: [src/oam/soam.h](#), [src/oam/soam.c](#)

Test code: [tst/oam/soam/main.c](#)

Test coverage: [src/oam/soam.c](#)

Example code: [examples/soam/main.c](#)

Functions

int **soam_module_init** (void)

Initialize the soam module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **soam_init** (struct *soam_t* *self_p, void *buf_p, size_t size, void *chout_p)

Initialize given soam object.

Return zero(0) or negative error code.

Parameters

- self_p: Object to initialize.
- buf_p: Transmission buffer.
- size: Transmission buffer size.
- chout_p: Soam packets are written to this channel.

int **soam_input** (struct *soam_t* *self_p, uint8_t *buf_p, size_t size)

Process given soam packet.

Return zero(0) or negative error code.

Parameters

- self_p: Soam object.
- buf_p: Buffer to input.
- size: Size to input in bytes.

ssize_t **soam_write_begin** (struct *soam_t* *self_p, int type)

Start outputting a soam packet of given type.

Return zero(0) or negative error code.

Parameters

- `self_p`: Soam object.
- `type`: Packet type.

`ssize_t soam_write_chunk (struct soam_t *self_p, const void *buf_p, size_t size)`
Add given chunk of data to current packet.

Return zero(0) or negative error code.

Parameters

- `self_p`: Soam object.
- `buf_p`: Buffer to output.
- `size`: Size to output in bytes.

`ssize_t soam_write_end (struct soam_t *self_p)`
Finalize current packet and transmit it.

Return zero(0) or negative error code.

Parameters

- `self_p`: Soam object.

`ssize_t soam_write (struct soam_t *self_p, int type, const void *buf_p, size_t size)`
Create and transmit a soam packet of given type and data.

Return zero(0) or negative error code.

Parameters

- `self_p`: Soam object.
- `type`: Packet type.
- `buf_p`: Buffer to output.
- `size`: Size to output in bytes.

`void *soam_get_log_input_channel (struct soam_t *self_p)`
Get the log input channel. This channel can be set as output channel of the log module with `log_set_default_handler_output_channel()`.

Return Log input channel.

Parameters

- `self_p`: Soam object.

`void *soam_get_stdout_input_channel (struct soam_t *self_p)`
Get the standard output input channel. This channel can be set as standard output channel of the sys module with `sys_set_stdout()`.

Return Standard output input channel.

Parameters

- `self_p`: Soam object.

```
struct soam_t
#include <soam.h>
```

Public Members

```
int is_printf
uint8_t transaction_id
uint8_t *buf_p
size_t size
ssize_t pos
struct sem_t sem
void *chout_p
uint8_t packet_index
struct soam_t::@101 soam_t::tx
struct chan_t stdout_chan
struct chan_t log_chan
struct chan_t command_chan
```

upgrade — Software upgrade

Upgrade/upload an application over the air (OTA) or using a cable. HTTP, TFTP, Kermit and UDS protocols are supported.

The flash memory is partitioned into two partitions; the bootloader partition and the application partition. The software in the bootloader partition can perform a software upgrade of the application partition by using the erase and write commands.

Warning: The WiFi connection is often lost during the erase operation on ESP32. Troubleshooting ongoing...

Debug file system commands

Five debug file system commands are available, all located in the directory `oam/upgrade/`.

Command	Description
<code>application/enter</code>	Enter the application.
<code>application/erase</code>	Erase the application. May not be called from the application about to be erased.
<code>application/is_valid</code>	Check if there is a valid application in the memory.
<code>kermit/upload</code>	Upload a upgrade binary file using the Kermit file transfer protocol.
<code>bootloader/enter</code>	Enter the bootloader.

Example output from the shell:

```
$ oam/upgrade/application/is_valid
yes
```


HTTP requests

Five HTTP requests are available. Form the URL by prefixing them with `http://<hostname>/oam/upgrade/`, ie. `http://<hostname>/oam/upgrade/application/is_valid`.

Request	Type	Description
<code>application/enter</code>	GET	Enter the appliaction.
<code>application/erase</code>	GET	Erase the appliaction. May not be called from the application about to be erased.
<code>application/is_valid</code>	GET	Check is there is a valid application in the memory.
<code>upload</code>	POST	Upload a upgrade binary file using the Kermit file transfer protocol.
<code>bootloader/enter</code>	GET	Enter the bootloader.

TFTP file transfer

Only upload, aka “put”, in binary mode is supported.

Examples

Here are a few examples of how to upgrade the application using the different supported protocols.

HTTP

Build and upload the bootloader to the board over the serial port.

```
> make -C bootloader -s BOARD=nano32 run
```

Build the test application and use curl to upload it to the Nano32 over HTTP.

```
> make -C application -s BOARD=nano32
> cd application/build/nano32
> curl http://192.168.0.7/oam/upgrade/application/is_valid
no
> curl --header "Content-Type: application/octet-stream" \
  --data-binary @application.ubin \
  http://192.168.0.7/oam/upgrade/upload
> curl http://192.168.0.7/oam/upgrade/application/is_valid
yes
```

Then start it using HTTP.

```
> curl http://192.168.0.7/oam/upgrade/application/enter
Welcome to the test application!
```

TFTP

Build and upload the bootloader to the board over the serial port.

```
> make -C bootloader -s BOARD=nano32 run
```

Build the test application and use tftp to upload it to the Nano32 over TFTP.

```
> make -C application -s BOARD=nano32
> cd application/build/nano32
> tftp 192.168.0.7
tftp> mode binary
tftp> put application.ubin
5460544 bytes
tftp> q
```

Then start it using the serial port.

```
> kermit
C-Kermit>connect
$ oam/upgrade/application/is_valid
yes
$ oam/upgrade/application/enter
Welcome to the test application!
```

Kermit

Build and upload the bootloader to the board over the serial port.

```
> make -s -C bootloader BOARD=arduino_due run
```

Build the test application and use Kermit to upload it to the Arduino Due over the serial port.

```
> make -s -C application BOARD=arduino_due
> cd application/build/arduino_due
> kermit
C-Kermit>connect
$ oam/upgrade/application/is_valid
no
$ oam/upgrade/application/erase
$ oam/upgrade/kermit/upload      # Type '\+c' to return to kermit.
C-Kermit> send application.ubin
```

Then start it using the serial port.

```
C-Kermit> connect
$ oam/upgrade/application/is_valid
yes
$ oam/upgrade/application/enter
Welcome to the test application!
```

Source code: [src/oam/upgrade.h](#), [src/oam/upgrade.c](#), [src/oam/upgrade](#)

Test code: [tst/oam/upgrade/main.c](#), [tst/oam/upgrade/kermit/main.c](#), [tst/oam/upgrade/uds/main.c](#)

Test coverage: [src/oam/upgrade.c](#), [src/oam/upgrade](#)

Example code: [examples/upgrade/bootloader/main.c](#), [examples/upgrade/application/main.c](#)

Functions

int **upgrade_module_init** (void)

int **upgrade_bootloader_enter** (void)

Enter the bootloader. This function does not return if all preconditions for entering the bootloader are met.

Return zero(0) or negative error code.

int **upgrade_bootloader_stay_set** (void)

Stay in the bootloader after next system reboot.

Return zero(0) or negative error code.

int **upgrade_bootloader_stay_clear** (void)

Do not stay in the bootloader after next system reboot.

Return zero(0) or negative error code.

int **upgrade_bootloader_stay_get** (void)

Check if the bootlaoder is forced to enter its main loop instead of calling any valid application.

Return true(1) if the bootloder shall not call the application, otherwise false(0).

int **upgrade_application_enter** (void)

Enter the application. This function does not return if all preconditions for entering the application are met.

Return zero(0) or negative error code.

int **upgrade_application_erase** (void)

Erase the application area.

Return zero(0) or negative error code.

int **upgrade_application_is_valid** (int *quick*)

Returns true(1) if there is a valid application in the application area.

Return true(1) if a valid application exists in the memory region, otherwise false(0).

Parameters

- *quick*: Perform a quick validation. The quick validation is port specific, while the non-quick validation always calculates a checksum of the application and compares it to the expected checksum.

int **upgrade_binary_upload_begin** (void)

Begin an upload transaction of a .ubin file.

Return zero(0) or negative error code.

int **upgrade_binary_upload** (const void **buf_p*, size_t *size*)

Add data to current upload transaction.

Return zero(0) or negative error code.

Parameters

- `buf_p`: Buffer to write.
- `size`: Size of the buffer.

int **upgrade_binary_upload_end** (void)
End current upload transaction.

Return zero(0) or negative error code.

debug

The debug package on [Github](#).

harness — Test harness

In software testing, a test harness or automated test framework is a collection of software and test data configured to test a program unit by running it under varying conditions and monitoring its behavior and outputs. It has two main parts: the test execution engine and the test script repository.

This module implements the test execution engine.

The test scripts are part of the build system.

Stubs

Symbols can be stubbed per C-file using the `STUB()` macro and `STUB` make variable. The `STUB` make variable is a list of source files and the symbols to stub within given file.

For example, stub functions `foo_bar()` and `foo_fie()` in `fum.c` by defining stub functions `STUB(foo_bar)()` and `STUB(foo_fie)()`, and set the make variable `STUB` to `fum.c:foo_bar,foo_fie`.

Prototypes for `foo_bar()` and `foo_fie()` in `foo.h`:

```
int foo_bar();
int foo_fie();
```

`foo_bar()` and `foo_fie()` called in `fum.c`. Both function calls will call the stubbed version on the respective function.

```
int fum_init()
{
    foo_bar();
    foo_fie();
}
```

The stubbed implementations, often defined in the test suite file `main.c`:

```
int STUB(foo_bar)()
{
    return (0);
}

int STUB(foo_fie)()
{
    return (0);
}
```

And last, add the stubbed symbol to the test suite makefile Makefile:

```
STUB = fum.c:foo_bar,foo_fie
```

Example test suite

Below is an example of a test suite using the harness. It has three test cases; `test_passed`, `test_failed` and `test_skipped`.

The test macro `BTASSERT (condition)` should be used to validate conditions.

```
#include "simba.h"

static int test_passed(struct harness_t *harness_p)
{
    /* Return zero(0) when a test case passes. */
    return (0);
}

static int test_failed(struct harness_t *harness_p)
{
    /* Return a negative integer when a test case fails. BTASSERT
       will return -1 when the condition is false. */
    BTASSERT(0);

    return (0);
}

static int test_skipped(struct harness_t *harness_p)
{
    /* Return a positive integer when a test case is skipped. */
    return (1);
}

int main()
{
    /* Test harness and NULL terminated list of test cases.*/
    struct harness_t harness;
    struct harness_testcase_t harness_testcases[] = {
        { test_passed, "test_passed" },
        { test_failed, "test_failed" },
        { test_skipped, "test_skipped" },
        { NULL, NULL }
    };

    sys_start();

    harness_init(&harness);
    harness_run(&harness, harness_testcases);

    return (0);
}
```

The output from the test suite is:

```
app:    test_suite-7.0.0 built 2016-07-25 17:38 CEST by erik.
board:  Linux
```

```

mcu:      Linux

enter: test_passed
exit: test_passed: PASSED

enter: test_failed
exit: test_failed: FAILED

enter: test_skipped
exit: test_skipped: SKIPPED

      NAME      STATE  PRIO   CPU  LOGMASK
      main      current    0    0%    0x0f
              ready   127    0%    0x0f
harness report: total(3), passed(1), failed(1), skipped(1)

```

There are plenty of test suites in the `tst` folder on Github.

Source code: [src/debug/harness.h](#), [src/debug/harness.c](#)

Defines

__ASSERTFMT (fmt, ...) `std_printf(FSTR(fmt "\n"), ##__VA_ARGS__);`

__ASSERTTHEX (actual_str, actual, expected_str, expected, size) `std_printf(FSTR(":: \r\n" \ "Memory buffer
" actual_str "\r\n")); \ std_hexdump(sys_get_stdout(), actual, size); \ std_printf(FSTR("is not
equal to memory buffer " expected_str "\r\n")); \ std_hexdump(sys_get_stdout(), expected,
size);`

BTASSERTRM (cond, cond_str, res, msg) `if (!(cond)) { \ std_printf(FSTR(__FILE__ ":"
STRINGIFY(__LINE__) ": BTASSERT: " \ cond_str " ")); \ msg; \ return (res); \ }`
Assert given condition. Print an error message and return given value `res` on error.

BTASSERTR (cond, cond_str, res, ...) `BTASSERTRM(cond, cond_str, res, __ASSERTFMT(__VA_ARGS__));`
Assert given condition. Print an error message and return given value `res` on error.

BTASSERTN (cond, ...) `BTASSERTR(cond, #cond, NULL, __VA_ARGS__)`
Assert given condition. Print an error message and return given value on error.

BTASSERT (cond, ...) `BTASSERTR(cond, #cond, -1, __VA_ARGS__)`
Assert given condition. Print an error message and return.

BTASSERTI (actual, operator, expected) `do { \ int UNIQUE(_actual); \ int UNIQUE(_expected);
\ UNIQUE(_actual) = (actual); \ UNIQUE(_expected) = (expected); \
BTASSERTR(UNIQUE(_actual) operator UNIQUE(_expected), \ #actual " " #operator "
" #expected, \ -1, \ ":: Condition '%d' #operator " %d' ('0x%x " \ #operator " 0x%x') is not
true.", \ UNIQUE(_actual), \ UNIQUE(_expected), \ UNIQUE(_actual), \ UNIQUE(_expected));
\ } while (0)`
Compare two integers `actual` and `expected` with given operator `operator`. Print an error message if the condition is not true and return.

BTASSERTM (actual, expected, size) `do { \ const void *UNIQUE(_actual); \ const void
*UNIQUE(_expected); \ UNIQUE(_actual) = (actual); \ UNIQUE(_expected) = (expected); \
BTASSERTRM(memcmp(UNIQUE(_actual), UNIQUE(_expected), size) == 0, \ "memcmp("
#actual " " #expected " " #size ") == 0", \ -1, \ __ASSERTTHEX(#actual, UNIQUE(_actual), \
#expected, UNIQUE(_expected), \ size)); \ } while (0)`

Compare two memory positions `actual` and `expected`. Print an error message if they are not equal and return.

```
BTASSERTV(cond, ...)  if (!(cond)) { \ std_printf(FSTR(__FILE__ ":" STRINGIFY(__LINE__) "":
    BTASSERT: " #cond " ")); \ _ASSERT_FMT(__VA_ARGS__); \ return; \ }
Assert given condition in a testcase. Print an error message and return -1 on error.
```

```
STUB (function) __stub_ ## function
Stub given function. Used with the make variable STUB to preprocess object file(s).
```

Typedefs

```
typedef int (*harness_testcase_cb_t) (struct harness_t *harness_p)
```

The testcase function callback.

Return zero(0) if the testcase passed, a negative error code if the testcase failed, and a positive value if the testcase was skipped.

Parameters

- *harness_t*: The harness object.

Functions

```
int harness_init (struct harness_t *self_p)
```

Initialize given test harness.

Return zero(0) or negative error code.

Parameters

- *self_p*: Test harness to initialize.

```
int harness_run (struct harness_t *self_p, struct harness_testcase_t *testcases_p)
```

Run given testcases in given test harness.

Return zero(0) or negative error code.

Parameters

- *self_p*: Test harness.
- *testcases_p*: An array of testcases to run. The last element in the array must have `callback` and `name_p` set to NULL.

```
int harness_expect (void *chan_p, const char *pattern_p, const struct time_t *timeout_p)
```

Continuously read from the channel and return when given pattern has been read, or when a timeout occurs.

Return Number of bytes read from the channel when match occurred, or negative error code.

Parameters

- *chan_p*: Channel to read from.
- *pattern_p*: Pattern to wait for.
- *timeout_p*: Timeout, or NULL to wait forever.

`ssize_t harness_mock_write (const char *id_p, const void *buf_p, size_t size)`

Write given data buffer to a mock entry with given id.

Return Number of written words or negative error code.

Parameters

- `id_p`: Mock id string to write.
- `buf_p`: Data for given mock id.
- `size`: Buffer size in words.

`ssize_t harness_mock_read (const char *id_p, void *buf_p, size_t size)`

Read data from mock entry with given id.

Return Number of read words or negative error code.

Parameters

- `id_p`: Mock id string to read.
- `buf_p`: Buffer to read into.
- `size`: Buffer size in words.

`struct harness_testcase_t`

Public Members

harness_testcase_cb_t **callback**

`const char *name_p`

`struct harness_t`

Public Members

`struct uart_driver_t uart`

log — Logging

The logging module consists of log objects and log handlers. A log object filters log entries and a log handler writes log entries to an output channel.

A log object called “log” and a log handler writing to standard output are created during the log module initialization. The log handler can be replaced by calling *log_set_default_handler_output_channel()*.

Normally one log object is created for each subsystem in an application. This gives the user the power to control which parts of the system to debug and/or monitor at runtime.

It’s also possible to print log entries without using log objects, but instead use the current threads’ log mask to filter log entries. Just give NULL as the first argument to *log_object_print()*, and the threads’ log mask will be used. See *thrd — Threads* details on how to change the threads’ log mask.

Sometimes it’s useful to write log entries to multiple channels. This is possible by creating and adding another log handler to the log module.

Log levels

There are five log levels defined; fatal, error, warning, info and debug. The log levels are defined as LOG_<upper case level> in the log module header file.

Log entry format

A log entry consists of a timestamp, log level, thread name, log object name and the message. The timestamp is the log entry creation time and the log level is one of fatal, error, warning, info and debug. The thread name is the name of the thread that created the log entry and the log object name is the name of the log object the entry was printed on. The message is a user defined string.

```
<timestamp>:<log level>:<thread name>:<log object name>: <message>
```

Debug file system commands

Three debug file system commands are available, all located in the directory debug/log/.

Command	Description
list	Print a list of all log objects.
print <string>	Print a log entry using the default log object and log level LOG_INFO. This command has no use except to test that the log module works.
set_log_mask <object> <mask>	Set the log mask to <mask> for log object <object>.

Example output from the shell:

```
$ debug/log/list
    OBJECT NAME  MASK
    default    0x0f
$ debug/log/print "Hello World!"
$ debug/log/set_log_mask default 0x1f
$ debug/log/list
    OBJECT NAME  MASK
    default    0x1f
$ debug/log/print "Hello World!!!"
56:info:main:default: Hello World!!!
```

Example

Here is an example of how to create two log objects; *foo* and *bar*, and then use them and the default log object *default*.

The source code:

```
/* Initialize the log objects foo and bar. */
struct log_object_t foo;
struct log_object_t bar;

log_object_init(&foo, "foo", LOG_UPTO(INFO));
log_object_init(&bar, "bar", LOG_UPTO(DEBUG));

/* Print four log entries. */
log_object_print(&foo, LOG_INFO, OSTR("A foo info message."));
```

```
log_object_print(&bar, LOG_INFO, OSTR("A bar info message.));  
log_object_print(&bar, LOG_DEBUG, OSTR("A bar debug message.));  
log_object_print(NULL, LOG_ERROR, OSTR("A default error message.));
```

All logs are printed from the main thread as can be seen in the third field in the entries in the output below.

```
23.0:info:main:foo: A foo info message.  
24.0:info:main:bar: A bar info message.  
37.0:debug:main:bar: A bar debug message.  
56.0:error:main:default: A default error message.
```

Source code: [src/debug/log.h](#), [src/debug/log.c](#)

Test code: [tst/debug/log/main.c](#)

Test coverage: [src/debug/log.c](#)

Defines

LOG_FATAL 0

LOG_ERROR 1

A handable error conditions.

LOG_WARNING 2

A warning.

LOG_INFO 3

Generic (useful) information about system operation.

LOG_DEBUG 4

Developer debugging messages.

LOG_MASK (level) (1 << (LOG_ ## level))

Create a log mask with given level set.

LOG_UPTO (level) ((1 << (LOG_ ## level + 1)) - 1)

Set all levels up to and including given level.

LOG_ALL LOG_UPTO(DEBUG)

Set all levels.

LOG_NONE 0x00

Clear all levels.

Functions

int **log_module_init** (void)

Initialize the logging module. This function must be called before calling any other function in this module.

The module will only be initialized once even if this function is called multiple times.

Return zero(0) or negative error code.

int **log_object_init** (struct *log_object_t* *self_p, const char *name_p, char mask)
 Initialize given log object with given name and mask.

Return zero(0) or negative error code.

Parameters

- self_p: Log object to initialize.
- name_p: Log object name.
- mask: Log object mask.

int **log_object_set_log_mask** (struct *log_object_t* *self_p, char mask)
 Set given log mask for given log object.

Return zero(0) or negative error code.

Parameters

- self_p: Log object.
- mask: Log object mask.

char **log_object_get_log_mask** (struct *log_object_t* *self_p)
 Get the log mask of given log object.

Return Log mask.

Parameters

- self_p: Log object.

int **log_object_is_enabled_for** (struct *log_object_t* *self_p, int level)
 Check if given log level is enabled in given log object.

Return true(1) if given log level is enabled, false(0) if given log level is disabled, otherwise negative error code.

Parameters

- self_p: Log object, or NULL to check the level in the thread log mask.
- level: Log level to check.

int **log_object_print** (struct *log_object_t* *self_p, int level, const char *fmt_p, ...)
 Check if given log level is set in the log object mask. If so, format a log entry and write it to all log handlers.
 self_p may be NULL, and in that case the current thread's log mask is used instead of the log object mask.

Return zero(0) or negative error code.

Parameters

- self_p: Log object, or NULL to use the thread's log mask.
- level: Log level.
- fmt_p: Log format string.
- . . .: Variable argument list.

int **log_handler_init** (struct *log_handler_t* *self_p, void *chout_p)
 Initialize given log handler with given output channel.

Return zero(0) or negative error code.

Parameters

- `self_p`: Log handler to initialize.
- `chout_p`: Output handler.

int **log_add_handler** (struct *log_handler_t* **handler_p*)

Add given log handler to the list of log handlers. Log entries will be written to all log handlers in the list.

Return zero(0) or negative error code.

Parameters

- `handler_p`: Log handler to add.

int **log_remove_handler** (struct *log_handler_t* **handler_p*)

Remove given log handler from the list of log handlers.

Return zero(0) or negative error code.

Parameters

- `handler_p`: Log handler to remove.

int **log_add_object** (struct *log_object_t* **object_p*)

Add given log object to the list of log objects. There are file system commands to list all log objects in the list and also modify their log mask.

Return zero(0) or negative error code.

Parameters

- `object_p`: Log object to add.

int **log_remove_object** (struct *log_object_t* **object_p*)

Remove given log object from the list of log objects.

Return zero(0) or negative error code.

Parameters

- `object_p`: Object to remove.

int **log_set_default_handler_output_channel** (void **chout_p*)

Set the output channel of the default log handler.

Return zero(0) or negative error code.

Parameters

- `chout_p`: Channel to set as the default output channel. May be NULL if no output should be written.

struct **log_handler_t**

Public Members

```
void *chout_p
struct log_handler_t *next_p
struct log_object_t
```

Public Members

```
const char *name_p
char mask
struct log_object_t *next_p
```

collections

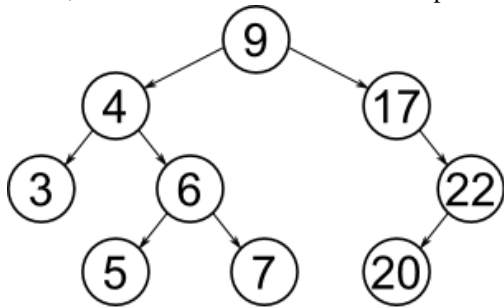
In computer science, a data structure is a particular way of organizing data in a computer so that it can be used efficiently.

The collections package on [Github](#).

binary_tree — Binary tree

A binary search tree consists of nodes, where each node has zero, one or two siblings. The left sibling has a lower value and the right sibling has a higher value than the parent.

Insert, delete and search operations all have the time complexity of $O(\log n)$.



Source code: [src/collections/binary_tree.h](#), [src/collections/binary_tree.c](#)

Test code: [tst/collections/binary_tree/main.c](#)

Test coverage: [src/collections/binary_tree.c](#)

Functions

```
int binary_tree_init (struct binary_tree_t *self_p)
    Initialize given binary tree.
```

Return zero(0) or negative error code.

Parameters

- `self_p`: Binary tree.

int **binary_tree_insert** (struct *binary_tree_t* *`self_p`, struct *binary_tree_node_t* *`node_p`)

Insert given node into given binary tree.

There can not be two or more nodes in the tree with the same key. This function returns -1 if a node with the same key is already in the binary tree.

Return zero(0) on success, -1 if a node with the same key is already in the binary tree, otherwise negative error code.

Parameters

- `self_p`: Binary tree to insert the node into.
- `node_p`: Node to insert.

int **binary_tree_delete** (struct *binary_tree_t* *`self_p`, int `key`)

Delete given node from given binary tree.

Return zero(0) on success, -1 if the node was not found, otherwise negative error code.

Parameters

- `self_p`: Binary tree to delete the node from.
- `key`: Key of the node to delete.

struct *binary_tree_node_t* ***binary_tree_search** (struct *binary_tree_t* *`self_p`, int `key`)

Search the binary tree for the node with given key.

Return Pointer to found node or NULL if a node with given key was not found in the tree.

Parameters

- `self_p`: Binary tree to search in.
- `key`: Key of the binary tree node to search for.

void **binary_tree_print** (struct *binary_tree_t* *`self_p`)

Print given binary tree.

Parameters

- `self_p`: Binary tree to print.

struct **binary_tree_node_t**
#include <binary_tree.h>

Public Members

int **key**

int **height**

struct *binary_tree_node_t* ***left_p**

struct *binary_tree_node_t* ***right_p**

`struct binary_tree_t`

Public Members

`struct binary_tree_node_t *root_p`

bits — Bitwise operations

Source code: [src/collections/bits.h](#)

Test code: [tst/collections/bits/main.c](#)

Functions

`static uint32_t bits_insert_32 (uint32_t dst, int position, int size, uint32_t src)`

circular_buffer — Circular buffer

Source code: [src/collections/circular_buffer.h](#), [src/collections/circular_buffer.c](#)

Test code: [tst/collections/circular_buffer/main.c](#)

Test coverage: [src/collections/circular_buffer.c](#)

Functions

int `circular_buffer_init` (`struct circular_buffer_t *self_p`, void *`buf_p`, size_t `size`)
Initialize given circular buffer.

Return zero(0) or negative error code.

Parameters

- `self_p`: Circular buffer to initialize.
- `buf_p`: Memory buffer.
- `size`: Size of the memory buffer.

ssize_t `circular_buffer_write` (`struct circular_buffer_t *self_p`, const void *`buf_p`, size_t `size`)
Write data to given circular buffer.

Return Number of bytes written or negative error code.

Parameters

- `self_p`: Circular buffer.
- `buf_p`: Memory buffer to write.
- `size`: Size of the memory buffer.

`ssize_t circular_buffer_read (struct circular_buffer_t *self_p, void *buf_p, size_t size)`
Read data from given circular buffer.

Return Number of bytes read or negative error code. The buffer is empty if zero(0) is returned.

Parameters

- `self_p`: Circular buffer to free to.
- `buf_p`: Memory buffer to read into.
- `size`: Size of the memory buffer.

`ssize_t circular_buffer_used_size (struct circular_buffer_t *self_p)`
Returns the number of used bytes in given circular buffer.

Return Number of used bytes.

Parameters

- `self_p`: Circular buffer.

`ssize_t circular_buffer_unused_size (struct circular_buffer_t *self_p)`
Returns the number of unused bytes in given circular buffer.

Return Number of unused bytes.

Parameters

- `self_p`: Circular buffer.

`ssize_t circular_buffer_skip_front (struct circular_buffer_t *self_p, size_t size)`
Skip given number of written bytes at the front of the buffer.

Return Number of skipped bytes or negative error code.

Parameters

- `self_p`: Circular buffer.
- `size`: Number of bytes to skip.

`ssize_t circular_buffer_reverse_skip_back (struct circular_buffer_t *self_p, size_t size)`
Skip given number of written bytes at the back of the buffer.

Return Number of skipped bytes or negative error code.

Parameters

- `self_p`: Circular buffer.
- `size`: Number of bytes to skip.

`ssize_t circular_buffer_array_one (struct circular_buffer_t *self_p, void **buf_pp, size_t size)`
Get a pointer to the next byte to read from the buffer. Use `circular_buffer_array_two()` to get the second array, if there is a wrap around.

Return Number of bytes in array or negative error code.

Parameters

- `self_p`: Circular buffer.

- `buf_pp`: A pointer to the start of the array. Only valid if the return value is greater than zero(0).
- `size`: Number of bytes asked for.

`ssize_t circular_buffer_array_two(struct circular_buffer_t *self_p, void **buf_pp, size_t size)`
 Get a pointer to the next byte to read from the buffer, following a wrap around.

Return Number of bytes in array or negative error code.

Parameters

- `self_p`: Circular buffer.
- `buf_pp`: A pointer to the start of the array. Only valid if the return value is greater than zero(0).
- `size`: Number of bytes asked for.

`struct circular_buffer_t`
`#include <circular_buffer.h>`

Public Members

`char *buf_p`
`size_t size`
`size_t writepos`
`size_t readpos`

`fifo` — First In First Out queuing

Source code: [src/collections/fifo.h](#)

Test code: [tst/collections/fifo/main.c](#)

Defines

FIFO_DEFINE_TEMPLATE (type)

Define the fifo structure and functions for a given type.

```
FIFO_DEFINE_TEMPLATE(int);

int foo()
{
    struct fifo_int_t fifo;
    int buf[4];
    int value;

    fifo_init_int(&fifo, buf, membersof(buf));

    // Put a value into the fifo.
    value = 10;
    fifo_put_int(&fifo, &value);
}
```

```
// Get the value from the fifo.
fifo_get_int(&fifo, &value);

// Prints 'value = 10'.
std_printf(FSTR("value= %d\r\n", value));
}
```

Parameters

- type: Type of the elements in the defined fifo.

Functions

static int `fifo_init` (`struct fifo_t` *self_p, int max)
Initialize given fifo.

Return zero(0) or negative error code.

Parameters

- self_p: Fifo to initialize.
- max: Maximum number of elements in the fifo.

static int `fifo_put` (`struct fifo_t` *self_p)
Put an element in the fifo.

Return Added element index in fifo, or -1 if there are no free positions.

Parameters

- self_p: Initialized fifo.

static int `fifo_get` (`struct fifo_t` *self_p)
Get the next element from the fifo.

Return The fetched element index in fifo , or -1 if the fifo is empty.

Parameters

- self_p: Initialized fifo.

struct `fifo_t`
`#include <fifo.h>`

Public Members

int **rdpos**

int **wrpos**

void ***buf_p**

int **max**

hash_map — Hash map

Source code: [src/collections/hash_map.h](#), [src/collections/hash_map.c](#)

Test code: [tst/collections/hash_map/main.c](#)

Test coverage: [src/collections/hash_map.c](#)

Typedefs

```
typedef int (*hash_function_t) (long key)
```

Functions

```
int hash_map_init (struct hash_map_t *self_p, struct hash_map_bucket_t *buckets_p, size_t buckets_max,
                  struct hash_map_entry_t *entries_p, size_t entries_max, hash_function_t hash)
    Initialize hash map with given parameters.
```

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized hash map.
- `buckets_p`: Array of buckets.
- `buckets_max`: Number of entries in `buckets_p`.
- `entries_p`: Array of empty entries.
- `entries_max`: Number of entries in `entries_p`.
- `hash`: Hash function.

```
int hash_map_add (struct hash_map_t *self_p, long key, void *value_p)
    Add given key-value pair into hash map. Overwrites old value if the key is already present in map.
```

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized hash map.
- `key`: Key to hash.
- `value_p`: Value to insert for key.

```
int hash_map_remove (struct hash_map_t *self_p, long key)
    Remove given key from hash map.
```

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized hash map.
- `key`: Key to hash.

`void *hash_map_get (struct hash_map_t *self_p, long key)`
Get value for given key.

Return Value for key or NULL if key was not found in the map.

Parameters

- `self_p`: Initialized hash map.
- `key`: Key to hash.

`struct hash_map_entry_t`

Public Members

`struct hash_map_entry_t *next_p`

`long key`

`void *value_p`

`struct hash_map_bucket_t`

Public Members

`struct hash_map_entry_t *list_p`

`struct hash_map_t`

Public Members

`struct hash_map_bucket_t *buckets_p`

`size_t buckets_max`

`struct hash_map_entry_t *entries_p`

`hash_function_t hash`

list — Abstract lists

Source code: <src/collections/list.h>

Defines

LIST_SL_INIT (`list_p`) do { \ (`list_p`)->`head_p` = NULL; \ (`list_p`)->`tail_p` = NULL; \ } while (0);
Initialize given singly linked list object.

Parameters

- `list_p`: List object to initialize.

LIST_SL_INIT_STRUCT { `.head_p` = NULL, `.tail_p` = NULL }

LIST_SL_PEEK_HEAD (list_p, element_pp) do { \ *(element_pp) = (list_p)->head_p; \ } while (0);
 Peek at the first element in the list.

Parameters

- list_p: List object.
- element_pp: First element of the list.

LIST_SL_ADD_HEAD (list_p, element_p) do { \ (element_p)->next_p = (list_p)->head_p; \ (list_p)->head_p = element_p; \ if ((list_p)->tail_p == NULL) { \ (list_p)->tail_p = (element_p); \ } \ } while (0);
 Add given element to the beginning of given list.

Parameters

- list_p: List object.
- element_p: Element to add.

LIST_SL_ADD_TAIL (list_p, element_p) do { \ (element_p)->next_p = NULL; \ if ((list_p)->tail_p != NULL) { \ ((struct *list_next_t* *)((list_p)->tail_p))->next_p = element_p; \ } else if ((list_p)->head_p == NULL) { \ (list_p)->head_p = (element_p); \ } \ (list_p)->tail_p = element_p; \ } while (0);
 Add given element to the end of given list.

Parameters

- list_p: List object.
- element_p: Element to add.

LIST_SL_REMOVE_HEAD (list_p, element_pp) do { \ *(element_pp) = (list_p)->head_p; \ if (*(element_pp) != NULL) { \ (list_p)->head_p = (void *) (*(element_pp))->next_p; \ (*(element_pp))->next_p = NULL; \ if ((list_p)->tail_p == *(element_pp)) { \ (list_p)->tail_p = NULL; \ } \ } \ } while (0);
 Get the first element of given list and then remove it from given list.

Parameters

- list_p: List object.
- element_pp: First element of the list.

LIST_SL_ITERATOR_INIT (iterator_p, list_p) do { \ (iterator_p)->next_p = (list_p)->head_p; \ } while (0)
 Initialize given iterator object.

Parameters

- iterator_p: Iterator to initialize.
- list_p: List object to iterate over.

LIST_SL_ITERATOR_NEXT (iterator_p, element_pp) do { \ *(element_pp) = (iterator_p)->next_p; \ if ((iterator_p)->next_p != NULL) { \ (iterator_p)->next_p = \ ((struct *list_sl_iterator_t* *)((iterator_p)->next_p))->next_p; \ } \ } while (0)
 Get the next element from given iterator object.

Parameters

- `iterator_p`: Iterator object.
- `element_pp`: Next element of the list.

```
LIST_SL_REMOVE_ELEM(list_p, iterator_p, element_p, iterator_element_p, previous_element_p)
    LIST_SL_ITERATOR_INIT((iterator_p), (list_p)); \ (previous_element_p)
    = NULL; \ while (1) { \ LIST_SL_ITERATOR_NEXT((iterator_p), &(iter-
    ator_element_p)); \ if ((iterator_element_p) == NULL) { \ /* Element not
    found.*/ \ break; \ } else if ((iterator_element_p) == (element_p)) { \ /*
    Element found. Remove it. */ \ if ((previous_element_p) != NULL) { \
    (previous_element_p)->next_p = (element_p)->next_p; \ } else { \ (list_p)-
    >head_p = (void *)((element_p)->next_p); \ } \ if ((element_p)->next_p ==
    NULL) { \ (list_p)->tail_p = NULL; \ } \ break; \ } \ (previous_element_p) =
    (iterator_element_p); \ }
```

Remove given element from given list.

Parameters

- `list_p`: List object.
- `iterator_p`: Used internally.
- `element_p`: Element to remove.
- `iterator_element_p`: Used internally.
- `previous_element_p`: Used internally.

```
struct list_next_t
#include <list.h>
```

Public Members

void ***next_p**

```
struct list_singly_linked_t
```

Public Members

void ***head_p**

void ***tail_p**

```
struct list_sl_iterator_t
```

Public Members

void ***next_p**

alloc

Memory management is the act of managing computer memory. The essential requirement of memory management is to provide ways to dynamically allocate portions of memory to programs at their request, and free it for reuse when no longer needed.

The alloc package on [Github](#).

circular_heap — Circular heap

The circular heap is a dynamic memory allocator allocating buffers in a circular buffer. This puts a restriction on the user to free allocated buffers in the same order as they were allocated. This allocator is useful if you know the allocation order and need a low memory overhead on each allocated buffer and no memory fragmentation.

Below is an example of the internal state of a circular heap when buffers are allocated and freed.

1. After initialization *begin*, *alloc* and *free* have the same value. All memory is available for allocation.

```
begin
alloc
free                                     end
|-----|
```

2. Allocating a buffer increments *alloc*.

```
begin
free                                     alloc      end
|=====|-----|
```

3. Allocating another buffer increments *alloc* once again.

```
begin
free                                     alloc      end
|=====|-----|
```

4. Freeing the first buffer increments *free* to the position of the first *alloc*.

```
begin          free          alloc      end
|-----|=====|-----|
```

5. Allocating a buffer that is bigger than the available space between *alloc* and *end* results in a buffer starting at *begin*. The memory between the old *alloc* and *end* will be unused.

```
begin          alloc  free          end
|=====|-----|=====|ooooooooo|
```

6. Freeing the second buffer increments *free* to the position of the second *alloc*.

```
begin          alloc          free      end
|=====|-----|ooooooooo|
```

7. Freeing the third buffer sets *free* to *alloc*. All memory is available for allocation once again.

```
          alloc
begin          free          end
|-----|-----|
```

8. Done!

Source code: [src/alloc/circular_heap.h](#), [src/alloc/circular_heap.c](#)

Test code: [tst/alloc/circular_heap/main.c](#)

Test coverage: [src/alloc/circular_heap.c](#)

Functions

int **circular_heap_init** (struct *circular_heap_t* *self_p, void *buf_p, size_t size)
Initialize given circular_heap.

Return zero(0) or negative error code.

Parameters

- self_p: Circular heap to initialize.
- buf_p: Memory buffer.
- size: Size of the memory buffer.

void ***circular_heap_alloc** (struct *circular_heap_t* *self_p, size_t size)
Allocate a buffer of given size from given circular heap.

Return Pointer to allocated buffer, or NULL on failure.

Parameters

- self_p: Circular heap to allocate from.
- size: Number of bytes to allocate.

int **circular_heap_free** (struct *circular_heap_t* *self_p, void *buf_p)
Free the oldest allocated buffer.

Return zero(0) or negative error code.

Parameters

- self_p: Circular heap to free to.
- buf_p: Buffer to free. Must be the oldest allocated buffer.

struct **circular_heap_t**
#include <circular_heap.h>

Public Members

void ***begin_p**

void ***end_p**

void ***alloc_p**

void ***free_p**

heap — Heap

Source code: `src/alloc/heap.h`, `src/alloc/heap.c`

Test code: `tst/alloc/heap/main.c`

Test coverage: `src/alloc/heap.c`

Defines

HEAP_FIXED_SIZES_MAX 8

Functions

int **heap_init** (struct *heap_t* **self_p*, void **buf_p*, size_t *size*, size_t *sizes*[HEAP_FIXED_SIZES_MAX])
Initialize given heap.

Return zero(0) or negative error code.

Parameters

- *self_p*: Heap to initialize.
- *buf_p*: Heap memory buffer.
- *size*: Size of the heap memory buffer.

void ***heap_alloc** (struct *heap_t* **self_p*, size_t *size*)
Allocate a buffer of given size from given heap.

Return Pointer to allocated buffer, or NULL on failure.

Parameters

- *self_p*: Heap to allocate from.
- *size*: Number of bytes to allocate.

int **heap_free** (struct *heap_t* **self_p*, void **buf_p*)
Decrement the share count by once and free the buffer if the count becomes zero(0).

Return Share count after the free, or negative error code.

Parameters

- *self_p*: Heap of given buffer.
- *buf_p*: Memory buffer to free.

int **heap_share** (struct *heap_t* **self_p*, const void **buf_p*, int *count*)
Share given buffer *count* times.

Return zero(0) or negative error code.

Parameters

- *self_p*: Heap of given buffer.

- `buf_p`: Buffer to share.
- `count`: Share count.

struct heap_fixed_t

Public Members

void ***free_p**

size_t **size**

struct heap_dynamic_t

Public Members

void ***free_p**

struct heap_t

Public Members

void ***buf_p**

size_t **size**

void ***next_p**

struct heap_fixed_t **fixed**[HEAP_FIXED_SIZES_MAX]

struct heap_dynamic_t **dynamic**

text

Text parsing, editing and colorization.

The text package on [Github](#).

color — ANSI colors

Source code: [src/text/color.h](#)

Defines

COLOR_RESET “0”

COLOR_BOLD_ON “1”

COLOR_ITALICS_ON “3”

COLOR_UNDERLINE_ON “4”

COLOR_INVERSE_ON “7”

```

COLOR_STRIKETHROUGH_ON "9"
COLOR_BOLD_OFF "22"
COLOR_ITALICS_OFF "23"
COLOR_UNDERLINE_OFF "24"
COLOR_INVERSE_OFF "27"
COLOR_STRIKETHROUGH_OFF "29"
COLOR_FOREGROUND_BLACK "30"
COLOR_FOREGROUND_RED "31"
COLOR_FOREGROUND_GREEN "32"
COLOR_FOREGROUND_YELLOW "33"
COLOR_FOREGROUND_BLUE "34"
COLOR_FOREGROUND_MAGENTA "35"
COLOR_FOREGROUND_CYAN "36"
COLOR_FOREGROUND_WHITE "37"
COLOR_FOREGROUND_DEFAULT "39"
COLOR_BACKGROUND_BLACK "40"
COLOR_BACKGROUND_RED "41"
COLOR_BACKGROUND_GREEN "42"
COLOR_BACKGROUND_YELLOW "43"
COLOR_BACKGROUND_BLUE "44"
COLOR_BACKGROUND_MAGENTA "45"
COLOR_BACKGROUND_CYAN "46"
COLOR_BACKGROUND_WHITE "47"
COLOR_BACKGROUND_DEFAULT "49"
COLOR (...) "\x1b[" __VA_ARGS__ "m"

```

configfile — Configuration file (INI-file)

The INI file format is an informal standard for configuration files for some platforms or software. INI files are simple text files with a basic structure composed of sections, properties, and values.

More information on [Wikipedia](#).

File format description

- Line terminators: `\n`, `\r\n` or `\n\r`.
- Opening bracket (`[`) at the beginning of a line indicates a section. The section name is all characters until a closing bracket (`]`).
- A property line starts with its name, then a colon (`:`) or equal sign (`=`), and then the value.

- Semicolon (;) or number sign (#) at the beginning of a line indicate a comment.

Example file

```
; last modified 1 April 2001 by John Doe
[owner]
name = John Doe
organization = Acme Widgets Inc.

[database]
; use IP address in case network name resolution is not working
server = 192.0.2.62
port = 143
file = "payroll.dat"
```

Source code: [src/text/configfile.h](#), [src/text/configfile.c](#)

Test code: [tst/text/configfile/main.c](#)

Test coverage: [src/text/configfile.c](#)

Functions

int **configfile_init** (struct *configfile_t* *self_p, char *buf_p, size_t size)

Initialize given configuration file object.

Return zero(0) or negative error code.

Parameters

- self_p: Object to initialize.
- buf_p: Configuration file contents as a NULL terminated string.
- size: Size of the configuration file contents.

int **configfile_set** (struct *configfile_t* *self_p, const char *section_p, const char *property_p, const char *value_p)

Set the value of given property in given section.

Return zero(0) or negative error code.

Parameters

- self_p: Initialized parser.
- section_p: Section to set the property from.
- property_p: Property to set the value for.
- value_p: NULL terminated value to set.

char ***configfile_get** (struct *configfile_t* *self_p, const char *section_p, const char *property_p, char *value_p, int length)

Get the value of given property in given section.

Return Value pointer or NULL on failure.

Parameters

- `self_p`: Initialized parser.
- `section_p`: Section to get the property from.
- `property_p`: Property to get the value for.
- `value_p`: Value of given property in given section.
- `size`: Size of the value buffer.

```
int configfile_get_long (struct configfile_t *self_p, const char *section_p, const char *property_p,
                        long *value_p)
```

Get the value of given property in given section, converted to an integer.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized parser.
- `section_p`: Section to get the property from.
- `property_p`: Property to get the value for.
- `value_p`: Value of given property in given section.

```
int configfile_get_float (struct configfile_t *self_p, const char *section_p, const char *property_p,
                          float *value_p)
```

Get the value of given property in given section, converted to a float.

Return zero(0) or negative error code.

Parameters

- `self_p`: Initialized parser.
- `section_p`: Section to get the property from.
- `property_p`: Property to get the value for.
- `value_p`: Value of given property in given section.

```
struct configfile_t
#include <configfile.h>
```

Public Members

```
char *buf_p
size_t size
```

emacs — Emacs text editor

Emacs is a text editor originally written by Richard Stallman and Guy L. Steele, Jr. in 1976. This module contains a minimal functional Emacs called Atto.

Help and key bindings: <https://github.com/erimoq/atto#atto-key-bindings>

Atto Emacs project on GitHub: <https://github.com/hughbarney/atto>

Source code: [src/text/emacs.h](#), [src/text/emacs.c](#)

Functions

int **emacs** (const char *path_p, void *chin_p, void *chout_p)

re — Regular expressions

Source code: [src/text/re.h](#), [src/text/re.c](#)

Test code: [tst/text/re/main.c](#)

Test coverage: [src/text/re.c](#)

Defines

RE_IGNORECASE 0x01

RE_DOTALL 0x02

Make the '.' special character match any character at all, including a newline; without this flag, '.' will match anything except a newline.

RE_MULTILINE 0x04

When specified, the pattern character '^' matches at the beginning of the string and at the beginning of each line (immediately following each newline); and the pattern character '\$' matches at the end of the string and at the end of each line (immediately preceding each newline). By default, '^' matches only at the beginning of the string, and '\$' only at the end of the string and immediately before the newline (if any) at the end of the string.

Functions

char ***re_compile** (char *compiled_p, const char *pattern_p, char flags, size_t size)

Compile given pattern.

Pattern syntax:

- '.' - Any character.
- '^' - Beginning of the string (**not yet supported**).
- '\$' - End of the string (**not yet supported**).
- '?' - Zero or one repetitions (greedy).
- '*' - Zero or more repetitions (greedy).
- '+' - One or more repetitions (greedy).
- '??' - Zero or one repetitions (non-greedy).
- '*?' - Zero or more repetitions (non-greedy).

- `+` - One or more repetitions (non-greedy).
- `{m}` - Exactly `m` repetitions.
- `\\` - Escape character.
- `[]` - Set of characters.
- `'|'` - Alternatives (**not yet supported**).
- `(...)` - Groups (**not yet supported**).
- `\\d` - Decimal digits `[0-9]`.
- `\\w` - Alphanumerical characters `[a-zA-Z0-9_]`.
- `\\s` - Whitespace characters `[\\t\\r\\n\\f\\v]`.

Return Compiled patten, or NULL if the compilation failed.

Parameters

- `compiled_p`: Compiled regular expression pattern.
- `pattern_p`: Regular expression pattern.
- `flags`: A combination of the flags `RE_IGNORECASE`, `RE_DOTALL` and `RE_MULTILINE` (`RE_MULTILINE` is **not yet supported**).
- `size`: Size of the compiled buffer.

`ssize_t re_match(const char *compiled_p, const char *buf_p, size_t size, struct re_group_t *groups_p, size_t *number_of_groups_p)`

Apply given regular expression to the beginning of given string.

Return Number of matched bytes or negative error code.

Parameters

- `compiled_p`: Compiled regular expression pattern. Compile a pattern with `re_compile()`.
- `buf_p`: Buffer to apply the compiled pattern to.
- `size`: Number of bytes in the buffer.
- `groups_p`: Read groups or NULL.
- `number_of_groups_p`: Number of read groups or NULL.

`struct re_group_t`

Public Members

`const char *buf_p`

`ssize_t size`

std — Standard functions

Source code: [src/text/std.h](#), [src/text/std.c](#)

Test code: [tst/text/std/main.c](#)

Test coverage: [src/text/std.c](#)

Functions

int **std_module_init** (void)

ssize_t **std_sprintf**(char * dst_p, FAR const char * fmt_p, ...)

Format and write data to destination buffer. The buffer must be big enough to fit the formatted string. The output is null terminated.

A format specifier has this format:

%[flags][width][length]specifier

where

- flags: 0 or -
- width: 0..127
- length: l for long or nothing
- specifier: c, s, d, i, u, x or f

Return Length of the string written to the destination buffer, not including the null termination, or negative error code.

Parameters

- dst_p: Destination buffer. The formatted string is written to this buffer.
- fmt_p: Format string.
- ...: Variable arguments list.

ssize_t **std_snprintf**(char * dst_p, size_t size, FAR const char * fmt_p, ...)

Format and write data to given buffer. The output is null terminated.

Return Length of the string written to the destination buffer, not including the null termination, or negative error code.

Parameters

- dst_p: Destination buffer. The formatted string is written to this buffer.
- size: Size of the destination buffer.
- fmt_p: Format string.
- ...: Variable arguments list.

ssize_t **std_vsprintf**(char * dst_p, FAR const char * fmt_p, va_list * ap_p)

Format and write data to given buffer. The output is null terminated.

Return Length of the string written to the destination buffer, not including the null termination, or negative error code.

Parameters

- `dst_p`: Destination buffer. The formatted string is written to this buffer.
- `fmt_p`: Format string.
- `ap_p`: Variable arguments list.

ssize_t std_vsnprintf(char * dst_p, size_t size, FAR const char * fmt_p, va_list * ap_p)
Format and write data to given buffer. The output is null terminated.

Return Length of the string written to the destination buffer, not including the null termination, or negative error code.

Parameters

- `dst_p`: Destination buffer. The formatted string is written to this buffer.
- `size`: Size of the destination buffer.
- `fmt_p`: Format string.
- `ap_p`: Variable arguments list.

ssize_t std_printf(far_string_t fmt_p, ...)
Format and print data to standard output. The output is not null terminated.

See `std_sprintf()` for the the format string specification.

Return Number of characters written to standard output, or negative error code.

Parameters

- `fmt_p`: Format string.
- `...:` Variable arguemnts list.

ssize_t std_vprintf(FAR const char * fmt_p, va_list * ap_p)
Format and print data to standard output. The output is not null terminated.

See `std_sprintf()` for the the format string specification.

Return Number of characters written to standard output, or negative error code.

Parameters

- `fmt_p`: Format string.
- `ap_p`: Variable arguemnts list.

ssize_t std_fprintf(void * chan_p, FAR const char * fmt_p, ...)
Format and print data to channel. The output is not null terminated.

See `std_sprintf()` for the the format string specification.

Return Number of characters written to given channel, or negative error code.

Parameters

- `chan_p`: Output channel.
- `fmt_p`: Format string.

- ...: Variable arguments list.

ssize_t std_vfprintf(void * chan_p, FAR const char * fmt_p, va_list * ap_p)

Format and print data to channel. The output is not null terminated.

See `std_sprintf()` for the the format string specification.

Return Number of characters written to given channel, or negative error code.

Parameters

- `chan_p`: Output channel.
- `fmt_p`: Format string.
- ...: Variable arguments list.

const char *std_strtol (const char *str_p, long *value_p)

Convert string to integer.

Return Pointer to the next byte or NULL on failure.

Parameters

- `str_p`: Integer string.
- `value_p`: Integer value.

const char *std_strtod (const char *str_p, double *value_p)

Convert string to double.

Return Pointer to the next byte or NULL on failure.

Parameters

- `str_p`: Double string.
- `value_p`: Double value.

int std_strcpy(char * dst_p, FAR const char * src_p)

Copy string from far memory to memory.

Return String length or negative error code.

Parameters

- `dst_p`: Normal memory string.
- `src_p`: Far memory string.

int std_strcmp(const char * str_p, FAR const char * fstr_p)

Compare a string with a far string.

Return zero(0) if match, otherwise the difference of the mismatched characters

Parameters

- `str_p`: Normal memory string.
- `fstr_p`: Far memory string.

int std_strcmp_f(FAR const char * fstr0_p, FAR const char * fstr1_p)

Compare two far strings.

Return zero(0) if match, otherwise the difference of the mismatched characters.

Parameters

- `fstr0_p`: Far memory string.
- `fstr1_p`: Far memory string.

int std_strncmp(FAR const char * fstr_p, const char * str_p, size_t size)
Compare at most `size` bytes of one far string and one string.

Return zero(0) if match, otherwise the difference of the mismatched characters.

Parameters

- `fstr_p`: Far memory string.
- `str_p`: String.
- `size`: Compare at most `size` number of bytes.

int std_strncmp_f(FAR const char * fstr0_p, FAR const char * fstr1_p, size_t size)
Compare at most `size` bytes of two far strings.

Return zero(0) if match, otherwise the difference of the mismatched characters.

Parameters

- `fstr0_p`: Far memory string.
- `fstr1_p`: Far memory string.
- `size`: Compare at most `size` number of bytes.

int std_strlen(FAR const char * fstr_p)
Get the length in bytes of given far string, not including null termination.

Return String length in number of bytes (not including the null termination).

Parameters

- `fstr_p`: Far memory string.

char *std_strip(char *str_p, const char *strip_p)
Strip leading and trailing characters from a string. The characters to strip are given by `strip_p`.

Return Pointer to the stripped string.

Parameters

- `str_p`: String to strip characters from.
- `strip_p`: Characters to strip or NULL for whitespace characters. Must be null-terminated.

ssize_t std_hexdump(void *chan_p, const void *buf_p, size_t size)
Write a hex dump of given data to given channel.

Return Number of characters written to given channel, or negative error code.

Parameters

- `chan_p`: Channel to write the hexdump to.
- `buf_p`: Buffer to dump.

- `size`: Size of buffer.

encode

In computing, a character encoding is used to represent a repertoire of characters by some kind of an encoding system. The encode package on [Github](#).

base64 — Base64 encoding and decoding.

Source code: [src/encode/base64.h](#), [src/encode/base64.c](#)

Test code: [tst/encode/base64/main.c](#)

Test coverage: [src/encode/base64.c](#)

Functions

int **base64_encode** (char **dst_p*, const void **src_p*, size_t *size*)

int **base64_decode** (void **dst_p*, const char **src_p*, size_t *size*)

Decode given base64 encoded buffer. The decoded data will be ~25% smaller than the destination data. Choose the destination buffer size accordingly.

Return zero(0) or negative error code.

Parameters

- `dst_p`: Output data.
- `src_p`: Encoded input data.
- `size`: Number of bytes in the encoded input data.

json — JSON encoding and decoding

Source code: [src/encode/json.h](#), [src/encode/json.c](#)

Test code: [tst/encode/json/main.c](#)

Test coverage: [src/encode/json.c](#)

Enums

enum **json_type_t**

Values:

JSON_UNDEFINED = 0

Undefined type.

JSON_OBJECT = 1

Object, { }.

```
JSON_ARRAY = 2
    Array, [].

JSON_STRING = 3
    String, \"...\".

JSON_PRIMITIVE = 4
    Other primitive: number, boolean (true/false) or null.
```

```
enum json_err_t
```

Values:

```
JSON_ERROR_NOMEM = -1
    Not enough tokens were provided.

JSON_ERROR_INVALID = -2
    Invalid character inside JSON string.

JSON_ERROR_PART = -3
    The string is not a full JSON packet, more bytes expected.
```

Functions

```
int json_init (struct json_t *self_p, struct json_tok_t *tokens_p, int num_tokens)
```

Initialize given JSON object. The JSON object must be initialized before it can be used to parse and dump JSON data.

Return zero(0) or negative error code.

Parameters

- `self_p`: JSON object to initialize.
- `tokens_p`: Array of tokens. The tokens are either filled by the parsing function `json_parse()`, or already filled by the user when calling this function. The latter can be used to dump the tokens as a string by calling `json_dump()` or `json_dumps()`.
- `num_tokens`: Number of tokens in the array.

```
int json_parse (struct json_t *self_p, const char *js_p, size_t len)
```

Parse given JSON data string into and array of tokens, each describing a single JSON object.

Return Number of decoded tokens or negative error code.

Parameters

- `self_p`: JSON object.
- `js_p`: JSON string to parse.
- `len`: JSON string length in bytes.

```
ssize_t json_dumps (struct json_t *self_p, struct json_tok_t *tokens_p, char *js_p)
```

Format and write given JSON tokens into a string.

Return Dumped string length (not including termination) or negative error code.

Parameters

- `self_p`: JSON object.

- `tokens_p`: Root token to dump. Set to NULL to dump the whole object.
- `js_p`: Dumped null terminated JSON string.

`ssize_t json_dump (struct json_t *self_p, struct json_tok_t *tokens_p, void *out_p)`
Format and write given JSON tokens to given channel.

Return Dumped string length (not including termination) or negative error code.

Parameters

- `self_p`: JSON object.
- `tokens_p`: Root token to dump. Set to NULL to dump the whole object.
- `out_p`: Channel to dump the null terminated JSON string to.

`struct json_tok_t *json_root (struct json_t *self_p)`
Get the root token.

Return The root token or NULL on failure.

Parameters

- `self_p`: JSON object.

`struct json_tok_t *json_object_get (struct json_t *self_p, const char *key_p, struct json_tok_t *object_p)`
Get the value the string token with given key.

Return Token or NULL on error.

Parameters

- `self_p`: JSON object.
- `key_p`: Key of the value to get.
- `object_p`: The object to get the value from.

`struct json_tok_t *json_object_get_primitive (struct json_t *self_p, const char *key_p, struct json_tok_t *object_p)`
Get the value of the primitive token with given key.

Return Token or NULL on error.

Parameters

- `self_p`: JSON object.
- `key_p`: Key of the value to get.
- `object_p`: The object to get the value from.

`struct json_tok_t *json_array_get (struct json_t *self_p, int index, struct json_tok_t *array_p)`
Get the token of given array index.

Return Token or NULL on error.

Parameters

- `self_p`: JSON object.

- `index`: Index to get.
- `array_p`: The array to get the element from.

void **json_token_object** (**struct** *json_tok_t* **token_p*, int *num_keys*)
Initialize a JSON object token.

Parameters

- `token_p`: Initialized token.
- `num_keys`: Number of keys in the object.

void **json_token_array** (**struct** *json_tok_t* **token_p*, int *num_elements*)
Initialize a JSON array token.

Parameters

- `token_p`: Initialized token.
- `num_elements`: Number of array elements.

void **json_token_true** (**struct** *json_tok_t* **token_p*)
Initialize a JSON boolean true token.

Parameters

- `token_p`: Initialized token.

void **json_token_false** (**struct** *json_tok_t* **token_p*)
Initialize a JSON boolean false token.

Parameters

- `token_p`: Initialized token.

void **json_token_null** (**struct** *json_tok_t* **token_p*)
Initialize a JSON null token.

Parameters

- `token_p`: Initialized token.

void **json_token_number** (**struct** *json_tok_t* **token_p*, **const** char **buf_p*, size_t *size*)
Initialize a JSON number (integer/float) token.

Parameters

- `token_p`: Initialized token.
- `buf_p`: Number as a string.
- `size`: String length.

void **json_token_string** (**struct** *json_tok_t* **token_p*, **const** char **buf_p*, size_t *size*)
Initialize a JSON string token.

Parameters

- `token_p`: Initialized token.

- `buf_p`: String.
- `size`: String length.

struct json_tok_t

Public Members

json_type_t **type**

const char ***buf_p**

size_t **size**

int **num_tokens**

struct json_t

Public Members

unsigned int **pos**

Offset in the JSON string.

unsigned int **toknext**

Next token to allocate.

int **toksuper**

Superior token node, e.g parent object or array.

struct json_tok_t ***tokens_p**

Array of tokens.

int **num_tokens**

Number of tokens in the tokens array.

hash

A hash function is any function that can be used to map data of arbitrary size to data of fixed size.

The hash package on [Github](#).

crc — Cyclic Redundancy Checks

Source code: [src/hash/crc.h](#), [src/hash/crc.c](#)

Test code: [tst/hash/crc/main.c](#)

Test coverage: [src/hash/crc.c](#)

Defines

CRC_8_POLYNOMIAL_8_5_4_0 0x8c

Functions

`uint32_t crc_32 (uint32_t crc, const void *buf_p, size_t size)`

Calculate a 32 bits crc using the polynomial $x^{32}+x^{26}+x^{23}+x^{22}+x^{16}+x^{12}+x^{11}+x^{10}+x^8+x^7+x^5+x^4+x$

Return Calculated crc.

Parameters

- `crc`: Initial crc. Often 0x00000000.
- `buf_p`: Buffer to calculate crc of.
- `size`: Size of the buffer.

`uint16_t crc_ccitt (uint16_t crc, const void *buf_p, size_t size)`

Calculate a 16 bits crc using the CCITT algorithm (polynomial $x^{16}+x^{12}+x^5+x^1$).

Return Calculated crc.

Parameters

- `crc`: Initial crc. Should be 0xffff for CCITT.
- `buf_p`: Buffer to calculate crc of.
- `size`: Size of the buffer.

`uint16_t crc_xmodem (uint16_t crc, const void *buf_p, size_t size)`

Calculate a 16 bits crc using the XModem algorithm (polynomial $x^{16}+x^{12}+x^5+x^1$).

Return Calculated crc.

Parameters

- `crc`: Initial crc. Should be 0x0000 for XModem.
- `buf_p`: Buffer to calculate crc of.
- `size`: Size of the buffer.

`uint8_t crc_7 (const void *buf_p, size_t size)`

Calculate a 8 bits crc using the CRC-7 algorithm (polynomial x^7+x^3+1).

Return Calculated crc.

Parameters

- `buf_p`: Buffer to calculate crc of.
- `size`: Size of the buffer.

`uint8_t crc_8 (uint8_t crc, uint8_t polynomial, const void *buf_p, size_t size)`

Calculate a 8 bits crc using given polynomial.

Return Calculated crc.

Parameters

- `crc`: Initial crc. Must be 0x00 on first call.
- `polynomial`: CRC polynomial.

- `buf_p`: Buffer to calculate crc of.
- `size`: Size of the buffer.

sha1 — SHA1

Source code: [src/hash/sha1.h](#), [src/hash/sha1.c](#)

Test code: [tst/hash/main.c](#)

Test coverage: [src/hash/sha1.c](#)

Functions

`int sha1_init (struct sha1_t *self_p)`
Initialize given SHA1 object.

Return zero(0) or negative error code.

Parameters

- `self_p`: SHA1 object.

`int sha1_update (struct sha1_t *self_p, void *buf_p, size_t size)`
Update the sha object with the given buffer. Repeated calls are equivalent to a single call with the concatenation of all the arguments.

Return zero(0) or negative error code.

Parameters

- `self_p`: SHA1 object.
- `buf_p`: Buffer to update the sha object with.
- `size`: Size of the buffer.

`int sha1_digest (struct sha1_t *self_p, uint8_t *hash_p)`
Return the digest of the strings passed to the `sha1_update()` method so far. This is a 20-byte value which may contain non-ASCII characters, including null bytes.

Return zero(0) or negative error code.

Parameters

- `self_p`: SHA1 object.
- `hash_p`: Hash sum.

`struct sha1_t`
#include <sha1.h>

Public Members

```

uint8_t buf[64]
uint32_t size
struct sha1_t::@37  sha1_t::block
uint32_t h[5]
uint64_t size

```

multimedia

The multimedia package on [Github](#).

midi — Musical Instrument Digital Interface

Source code: [src/multimedia/midi.h](#), [src/multimedia/midi.c](#)

Test code: [tst/multimedia/midi/main.c](#)

Test coverage: [src/multimedia/midi.c](#)

Defines

```

MIDI_BAUDRATE 31250
MIDI_NOTE_OFF 0x80
MIDI_NOTE_ON 0x90
MIDI_POLYPHONIC_KEY_PRESSURE 0xa0
MIDI_CONTROL_CHANGE 0xb0
MIDI_PROGRAM_CHANGE 0xc0
MIDI_CHANNEL_PRESSURE 0xd0
MIDI_PITCH_BEND_CHANGE 0xe0
MIDI_SET_INTRUMENT 0xc0
MIDI_PERC 0x99
MIDI_NOTE_MAX 128
MIDI_NOTE_A0 21
MIDI_NOTE_B0 23
MIDI_NOTE_C1 24
MIDI_NOTE_D1 26
MIDI_NOTE_E1 28
MIDI_NOTE_F1 29
MIDI_NOTE_G1 31

```

MIDI_NOTE_A1 33
MIDI_NOTE_B1 35
MIDI_NOTE_C2 36
MIDI_NOTE_D2 38
MIDI_NOTE_E2 40
MIDI_NOTE_F2 41
MIDI_NOTE_G2 43
MIDI_NOTE_A2 45
MIDI_NOTE_B2 47
MIDI_NOTE_C3 48
MIDI_NOTE_D3 50
MIDI_NOTE_E3 52
MIDI_NOTE_F3 53
MIDI_NOTE_G3 55
MIDI_NOTE_A3 57
MIDI_NOTE_B3 59
MIDI_NOTE_C4 60
MIDI_NOTE_D4 62
MIDI_NOTE_E4 64
MIDI_NOTE_F4 65
MIDI_NOTE_G4 67
MIDI_NOTE_A4 69
MIDI_NOTE_B4 71
MIDI_NOTE_C5 72
MIDI_NOTE_D5 74
MIDI_NOTE_E5 76
MIDI_NOTE_F5 77
MIDI_NOTE_G5 79
MIDI_NOTE_A5 81
MIDI_NOTE_B5 83
MIDI_NOTE_C6 84
MIDI_NOTE_D6 86
MIDI_NOTE_E6 88
MIDI_NOTE_F6 89
MIDI_NOTE_G6 91
MIDI_NOTE_A6 93

MIDI_NOTE_B6 95
MIDI_NOTE_C7 96
MIDI_NOTE_D7 98
MIDI_NOTE_E7 100
MIDI_NOTE_F7 101
MIDI_NOTE_G7 103
MIDI_NOTE_A7 105
MIDI_NOTE_B7 107
MIDI_NOTE_C8 108
MIDI_PERC_ACOUSTIC_BASS_DRUM 35
MIDI_PERC_BASS_DRUM_1 36
MIDI_PERC_SIDE_STICK 37
MIDI_PERC_ACOUSTIC_SNARE 38
MIDI_PERC_HAND_CLAP 39
MIDI_PERC_ELECTRIC_SNARE 40
MIDI_PERC_LOW_FLOOR_TOM 41
MIDI_PERC_CLOSED_HI_HAT 42
MIDI_PERC_HIGH_FLOOR_TOM 43
MIDI_PERC_PEDAL_HI_HAT 44
MIDI_PERC_LOW_TOM 45
MIDI_PERC_OPEN_HI_HAT 46
MIDI_PERC_LOW_MID_TOM 47
MIDI_PERC_HI_MID_TOM 48
MIDI_PERC_CRASH_CYMBAL_1 49
MIDI_PERC_HIGH_TOM 50
MIDI_PERC_RIDE_CYMBAL_1 51
MIDI_PERC_CHINESE_CYMBAL 52
MIDI_PERC_RIDE_BELL 53
MIDI_PERC_TAMBOURINE 54
MIDI_PERC_SPLASH_CYMBAL 55
MIDI_PERC_COWBELL 56
MIDI_PERC_CRASH_CYMBAL_2 57
MIDI_PERC_VIBRASLAP 58
MIDI_PERC_RIDE_CYMBAL_2 59
MIDI_PERC_HI_BONGO 60
MIDI_PERC_LOW_BONGO 61

MIDI_PERC_MUTE_HI_CONGA 62
MIDI_PERC_OPEN_HI_CONGA 63
MIDI_PERC_LOW_CONGA 64
MIDI_PERC_HIGH_TIMBALE 65
MIDI_PERC_LOW_TIMBALE 66
MIDI_PERC_HIGH_AGOGO 67
MIDI_PERC_LOW_AGOGO 68
MIDI_PERC_CABASA 69
MIDI_PERC_MARACAS 70
MIDI_PERC_SHORT_WHISTLE 71
MIDI_PERC_LONG_WHISTLE 72
MIDI_PERC_SHORT_GUIRO 73
MIDI_PERC_LONG_GUIRO 74
MIDI_PERC_CLAVES 75
MIDI_PERC_HI_WOOD_BLOCK 76
MIDI_PERC_LOW_WOOD_BLOCK 77
MIDI_PERC_MUTE_CUICA 78
MIDI_PERC_OPEN_CUICA 79
MIDI_PERC_MUTE_TRIANGLE 80
MIDI_PERC_OPEN_TRIANGLE 81

Functions

float **midi_note_to_frequency** (int *note*)
Get the frequency for given note.

Return Note frequency.

Parameters

- *note*: MIDI note.

boards

The boards supported by *Simba*.

The boards on [Github](#).

arduino_due — Arduino Due

Source code: [src/boards/arduino_due/board.h](#), [src/boards/arduino_due/board.c](#)

Hardware reference: [Arduino Due](#)

Defines

```
pin_d0_dev pin_device[SAM_PA+8]
pin_d1_dev pin_device[SAM_PA+9]
pin_d2_dev pin_device[SAM_PB+25]
pin_d3_dev pin_device[SAM_PC+28]
pin_d4_dev pin_device[SAM_PC+26]
pin_d5_dev pin_device[SAM_PC+25]
pin_d6_dev pin_device[SAM_PC+24]
pin_d7_dev pin_device[SAM_PC+23]
pin_d8_dev pin_device[SAM_PC+22]
pin_d9_dev pin_device[SAM_PC+21]
pin_d10_dev pin_device[SAM_PA+28]
pin_d11_dev pin_device[SAM_PD+7]
pin_d12_dev pin_device[SAM_PD+8]
pin_d13_dev pin_device[SAM_PB+27]
pin_d14_dev pin_device[SAM_PD+4]
pin_d15_dev pin_device[SAM_PD+5]
pin_d16_dev pin_device[SAM_PA+13]
pin_d17_dev pin_device[SAM_PA+12]
pin_d18_dev pin_device[SAM_PA+11]
pin_d19_dev pin_device[SAM_PA+10]
pin_d20_dev pin_device[SAM_PB+12]
pin_d21_dev pin_device[SAM_PB+13]
pin_d22_dev pin_device[SAM_PB+26]
pin_d23_dev pin_device[SAM_PA+14]
pin_d24_dev pin_device[SAM_PA+15]
pin_d25_dev pin_device[SAM_PD+0]
pin_d26_dev pin_device[SAM_PD+1]
pin_d27_dev pin_device[SAM_PD+2]
pin_d28_dev pin_device[SAM_PD+3]
pin_d29_dev pin_device[SAM_PD+6]
pin_d30_dev pin_device[SAM_PD+9]
pin_d31_dev pin_device[SAM_PA+7]
pin_d32_dev pin_device[SAM_PD+10]
pin_d33_dev pin_device[SAM_PC+1]
pin_d34_dev pin_device[SAM_PC+2]
```

```
pin_d35_dev pin_device[SAM_PC+3]
pin_d36_dev pin_device[SAM_PC+4]
pin_d37_dev pin_device[SAM_PC+5]
pin_d38_dev pin_device[SAM_PC+6]
pin_d39_dev pin_device[SAM_PC+7]
pin_d40_dev pin_device[SAM_PC+8]
pin_d41_dev pin_device[SAM_PC+9]
pin_d42_dev pin_device[SAM_PA+19]
pin_d43_dev pin_device[SAM_PA+20]
pin_d44_dev pin_device[SAM_PC+19]
pin_d45_dev pin_device[SAM_PC+18]
pin_d46_dev pin_device[SAM_PC+17]
pin_d47_dev pin_device[SAM_PC+16]
pin_d48_dev pin_device[SAM_PC+15]
pin_d49_dev pin_device[SAM_PC+14]
pin_d50_dev pin_device[SAM_PC+13]
pin_d51_dev pin_device[SAM_PC+12]
pin_d52_dev pin_device[SAM_PB+21]
pin_d53_dev pin_device[SAM_PB+14]
pin_a0_dev pin_device[SAM_PA+16]
pin_a1_dev pin_device[SAM_PA+24]
pin_a2_dev pin_device[SAM_PA+23]
pin_a3_dev pin_device[SAM_PA+22]
pin_a4_dev pin_device[SAM_PA+6]
pin_a5_dev pin_device[SAM_PA+4]
pin_a6_dev pin_device[SAM_PA+3]
pin_a7_dev pin_device[SAM_PA+2]
pin_a8_dev pin_device[SAM_PB+17]
pin_a9_dev pin_device[SAM_PB+18]
pin_a10_dev pin_device[SAM_PB+19]
pin_a11_dev pin_device[SAM_PB+20]
pin_led_dev pin_d13_dev
pin_dac0_dev pin_device[SAM_PB+15]
pin_dac1_dev pin_device[SAM_PB+16]
exti_d0_dev exti_device[SAM_PA+8]
exti_d1_dev exti_device[SAM_PA+9]
```



```
exti_d2_dev exti_device[SAM_PB+25]
exti_d3_dev exti_device[SAM_PC+28]
exti_d4_dev exti_device[SAM_PC+26]
exti_d5_dev exti_device[SAM_PC+25]
exti_d6_dev exti_device[SAM_PC+24]
exti_d7_dev exti_device[SAM_PC+23]
exti_d8_dev exti_device[SAM_PC+22]
exti_d9_dev exti_device[SAM_PC+21]
exti_d10_dev exti_device[SAM_PA+28]
exti_d11_dev exti_device[SAM_PD+7]
exti_d12_dev exti_device[SAM_PD+8]
exti_d13_dev exti_device[SAM_PB+27]
exti_d14_dev exti_device[SAM_PD+4]
exti_d15_dev exti_device[SAM_PD+5]
exti_d16_dev exti_device[SAM_PA+13]
exti_d17_dev exti_device[SAM_PA+12]
exti_d18_dev exti_device[SAM_PA+11]
exti_d19_dev exti_device[SAM_PA+10]
exti_d20_dev exti_device[SAM_PB+12]
exti_d21_dev exti_device[SAM_PB+13]
exti_d22_dev exti_device[SAM_PB+26]
exti_d23_dev exti_device[SAM_PA+14]
exti_d24_dev exti_device[SAM_PA+15]
exti_d25_dev exti_device[SAM_PD+0]
exti_d26_dev exti_device[SAM_PD+1]
exti_d27_dev exti_device[SAM_PD+2]
exti_d28_dev exti_device[SAM_PD+3]
exti_d29_dev exti_device[SAM_PD+6]
exti_d30_dev exti_device[SAM_PD+9]
exti_d31_dev exti_device[SAM_PA+7]
exti_d32_dev exti_device[SAM_PD+10]
exti_d33_dev exti_device[SAM_PC+1]
exti_d34_dev exti_device[SAM_PC+2]
exti_d35_dev exti_device[SAM_PC+3]
exti_d36_dev exti_device[SAM_PC+4]
exti_d37_dev exti_device[SAM_PC+5]
```

```
exti_d38_dev exti_device[SAM_PC+6]
exti_d39_dev exti_device[SAM_PC+7]
exti_d40_dev exti_device[SAM_PC+8]
exti_d41_dev exti_device[SAM_PC+9]
exti_d42_dev exti_device[SAM_PA+19]
exti_d43_dev exti_device[SAM_PA+20]
exti_d44_dev exti_device[SAM_PC+19]
exti_d45_dev exti_device[SAM_PC+18]
exti_d46_dev exti_device[SAM_PC+17]
exti_d47_dev exti_device[SAM_PC+16]
exti_d48_dev exti_device[SAM_PC+15]
exti_d49_dev exti_device[SAM_PC+14]
exti_d50_dev exti_device[SAM_PC+13]
exti_d51_dev exti_device[SAM_PC+12]
exti_d52_dev exti_device[SAM_PB+21]
exti_d53_dev exti_device[SAM_PB+14]
exti_a0_dev exti_device[SAM_PA+16]
exti_a1_dev exti_device[SAM_PA+24]
exti_a2_dev exti_device[SAM_PA+23]
exti_a3_dev exti_device[SAM_PA+22]
exti_a4_dev exti_device[SAM_PA+6]
exti_a5_dev exti_device[SAM_PA+4]
exti_a6_dev exti_device[SAM_PA+3]
exti_a7_dev exti_device[SAM_PA+2]
exti_a8_dev exti_device[SAM_PB+17]
exti_a9_dev exti_device[SAM_PB+18]
exti_a10_dev exti_device[SAM_PB+19]
exti_a11_dev exti_device[SAM_PB+20]
exti_led_dev exti_d13_dev
exti_dac0_dev exti_device[SAM_PB+15]
exti_dac1_dev exti_device[SAM_PB+16]
pwm_d2_dev pwm_device[0]
pwm_d3_dev pwm_device[1]
pwm_d5_dev pwm_device[2]
pwm_d6_dev pwm_device[3]
pwm_d7_dev pwm_device[4]
```

```
pwm_d8_dev pwm_device[5]
pwm_d9_dev pwm_device[6]
pwm_d10_dev pwm_device[7]
pwm_d11_dev pwm_device[8]
pwm_d12_dev pwm_device[9]
adc_0_dev adc_device[0]
dac_0_dev dac_device[0]
flash_0_dev flash_device[0]
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

arduino_mega — Arduino Mega

Source code: [src/boards/arduino_mega/board.h](#), [src/boards/arduino_mega/board.c](#)

Hardware reference: [Arduino Mega](#)

Defines

```
pin_d0_dev pin_device[0]
pin_d1_dev pin_device[1]
pin_d2_dev pin_device[2]
pin_d3_dev pin_device[3]
pin_d4_dev pin_device[4]
pin_d5_dev pin_device[5]
pin_d6_dev pin_device[6]
pin_d7_dev pin_device[7]
pin_d8_dev pin_device[8]
pin_d9_dev pin_device[9]
pin_d10_dev pin_device[10]
pin_d11_dev pin_device[11]
pin_d12_dev pin_device[12]
```

```
pin_d13_dev pin_device[13]
pin_d14_dev pin_device[14]
pin_d15_dev pin_device[15]
pin_d16_dev pin_device[16]
pin_d17_dev pin_device[17]
pin_d18_dev pin_device[18]
pin_d19_dev pin_device[19]
pin_d20_dev pin_device[20]
pin_d21_dev pin_device[21]
pin_d22_dev pin_device[22]
pin_d23_dev pin_device[23]
pin_d24_dev pin_device[24]
pin_d25_dev pin_device[25]
pin_d26_dev pin_device[26]
pin_d27_dev pin_device[27]
pin_d28_dev pin_device[28]
pin_d29_dev pin_device[29]
pin_d30_dev pin_device[30]
pin_d31_dev pin_device[31]
pin_d32_dev pin_device[32]
pin_d33_dev pin_device[33]
pin_d34_dev pin_device[34]
pin_d35_dev pin_device[35]
pin_d36_dev pin_device[36]
pin_d37_dev pin_device[37]
pin_d38_dev pin_device[38]
pin_d39_dev pin_device[39]
pin_d40_dev pin_device[40]
pin_d41_dev pin_device[41]
pin_d42_dev pin_device[42]
pin_d43_dev pin_device[43]
pin_d44_dev pin_device[44]
pin_d45_dev pin_device[45]
pin_d46_dev pin_device[46]
pin_d47_dev pin_device[47]
pin_d48_dev pin_device[48]
```

```
pin_d49_dev pin_device[49]
pin_d50_dev pin_device[50]
pin_d51_dev pin_device[51]
pin_d52_dev pin_device[52]
pin_d53_dev pin_device[53]
pin_a0_dev pin_device[54]
pin_a1_dev pin_device[55]
pin_a2_dev pin_device[56]
pin_a3_dev pin_device[57]
pin_a4_dev pin_device[58]
pin_a5_dev pin_device[59]
pin_a6_dev pin_device[60]
pin_a7_dev pin_device[61]
pin_a8_dev pin_device[62]
pin_a9_dev pin_device[63]
pin_a10_dev pin_device[64]
pin_a11_dev pin_device[65]
pin_a12_dev pin_device[66]
pin_a13_dev pin_device[67]
pin_a14_dev pin_device[68]
pin_a15_dev pin_device[69]
pin_led_dev pin_d13_dev
exti_d2_dev exti_device[4]
exti_d3_dev exti_device[5]
exti_d18_dev exti_device[3]
exti_d19_dev exti_device[2]
exti_d20_dev exti_device[1]
exti_d21_dev exti_device[0]
pwm_d2_dev pwm_device[0]
pwm_d3_dev pwm_device[1]
pwm_d5_dev pwm_device[2]
pwm_d6_dev pwm_device[3]
pwm_d7_dev pwm_device[4]
pwm_d8_dev pwm_device[5]
pwm_d9_dev pwm_device[6]
pwm_d10_dev pwm_device[7]
```

```
pwm_d11_dev pwm_device[8]
pwm_d12_dev pwm_device[9]
adc_0_dev adc_device[0]
i2c_0_dev i2c_device[0]
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

arduino_nano — Arduino Nano

Source code: [src/boards/arduino_nano/board.h](#), [src/boards/arduino_nano/board.c](#)

Hardware reference: *Arduino Nano*

Defines

```
pin_d2_dev pin_device[2]
pin_d3_dev pin_device[3]
pin_d4_dev pin_device[4]
pin_d5_dev pin_device[5]
pin_d6_dev pin_device[6]
pin_d7_dev pin_device[7]
pin_d8_dev pin_device[8]
pin_d9_dev pin_device[9]
pin_d10_dev pin_device[10]
pin_d11_dev pin_device[11]
pin_d12_dev pin_device[12]
pin_d13_dev pin_device[13]
pin_a0_dev pin_device[14]
pin_a1_dev pin_device[15]
pin_a2_dev pin_device[16]
pin_a3_dev pin_device[17]
pin_a4_dev pin_device[18]
```

```
pin_a5_dev pin_device[19]
pin_led_dev pin_d13_dev
exti_d2_dev exti_device[0]
exti_d3_dev exti_device[1]
pwm_d3_dev pwm_device[3]
pwm_d9_dev pwm_device[0]
pwm_d10_dev pwm_device[1]
pwm_d11_dev pwm_device[2]
adc_0_dev adc_device[0]
i2c_0_dev i2c_device[0]
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)

Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

arduino_pro_micro — Arduino Pro Micro

Source code: [src/boards/arduino_pro_micro/board.h](#), [src/boards/arduino_pro_micro/board.c](#)

Hardware reference: *Arduino Pro Micro*

Defines

```
pin_d2_dev pin_device[11]
pin_d3_dev pin_device[10]
pin_d4_dev pin_device[14]
pin_d5_dev pin_device[8]
pin_d6_dev pin_device[17]
pin_d7_dev pin_device[18]
pin_d8_dev pin_device[4]
pin_d9_dev pin_device[5]
pin_d10_dev pin_device[6]
pin_d14_dev pin_device[3]
pin_d15_dev pin_device[1]
```

```
pin_d16_dev pin_device[2]
pin_a0_dev pin_device[24]
pin_a1_dev pin_device[23]
pin_a2_dev pin_device[22]
pin_a3_dev pin_device[21]
pin_led_dev pin_device[0]
exti_d2_dev exti_device[0]
exti_d3_dev exti_device[1]
pwm_d3_dev pwm_device[3]
pwm_d9_dev pwm_device[0]
pwm_d10_dev pwm_device[1]
pwm_d11_dev pwm_device[2]
adc_0_dev adc_device[0]
i2c_0_dev i2c_device[0]
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

arduino_uno — Arduino Uno

Source code: [src/boards/arduino_uno/board.h](#), [src/boards/arduino_uno/board.c](#)

Hardware reference: *Arduino Uno*

Defines

```
pin_d2_dev pin_device[2]
pin_d3_dev pin_device[3]
pin_d4_dev pin_device[4]
pin_d5_dev pin_device[5]
pin_d6_dev pin_device[6]
pin_d7_dev pin_device[7]
pin_d8_dev pin_device[8]
```



```
pin_d9_dev pin_device[9]
pin_d10_dev pin_device[10]
pin_d11_dev pin_device[11]
pin_d12_dev pin_device[12]
pin_d13_dev pin_device[13]
pin_a0_dev pin_device[14]
pin_a1_dev pin_device[15]
pin_a2_dev pin_device[16]
pin_a3_dev pin_device[17]
pin_a4_dev pin_device[18]
pin_a5_dev pin_device[19]
pin_led_dev pin_d13_dev
exti_d2_dev exti_device[0]
exti_d3_dev exti_device[1]
pwm_d3_dev pwm_device[3]
pwm_d9_dev pwm_device[0]
pwm_d10_dev pwm_device[1]
pwm_d11_dev pwm_device[2]
adc_0_dev adc_device[0]
i2c_0_dev i2c_device[0]
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

esp01 — ESP8266 Development Board

Source code: [src/boards/esp01/board.h](#), [src/boards/esp01/board.c](#)

Hardware reference: [ESP-01](#)

Defines

```
pin_gpio0_dev pin_device[0]
pin_gpio1_dev pin_device[1]
pin_gpio2_dev pin_device[2]
pin_d0_dev pin_device[0]
pin_d1_dev pin_device[1]
pin_d2_dev pin_device[2]
pin_led_dev pin_device[1]
flash_0_dev flash_device[0]
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

esp12e — ESP8266 Development Board

Source code: [src/boards/esp12e/board.h](#), [src/boards/esp12e/board.c](#)

Hardware reference: *ESP-12E Development Board*

Defines

```
pin_gpio0_dev pin_device[0]
pin_gpio2_dev pin_device[2]
pin_gpio4_dev pin_device[5]
pin_gpio5_dev pin_device[4]
pin_gpio12_dev pin_device[12]
pin_gpio13_dev pin_device[13]
pin_gpio14_dev pin_device[14]
pin_gpio15_dev pin_device[15]
pin_gpio16_dev pin_device[16]
pin_d0_dev pin_device[0]
pin_d2_dev pin_device[2]
pin_d4_dev pin_device[5]
```

```
pin_d5_dev pin_device[4]
pin_d12_dev pin_device[12]
pin_d13_dev pin_device[13]
pin_d14_dev pin_device[14]
pin_d15_dev pin_device[15]
pin_d16_dev pin_device[16]
pin_led_dev pin_d2_dev
pin_a0_dev pin_device[0]
adc_0_dev adc_device[0]
flash_0_dev flash_device[0]
ADC_PINS_MAX 1
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

esp32_devkitc — ESP32-DevKitC

Source code: [src/boards/esp32_devkitc/board.h](#), [src/boards/esp32_devkitc/board.c](#)

Hardware reference: [ESP32-DevKitC](#)

Defines

```
pin_gpio00_dev pin_device[0]
pin_gpio01_dev pin_device[1]
pin_gpio02_dev pin_device[2]
pin_gpio03_dev pin_device[3]
pin_gpio04_dev pin_device[4]
pin_gpio05_dev pin_device[5]
pin_gpio06_dev pin_device[6]
pin_gpio07_dev pin_device[7]
pin_gpio08_dev pin_device[8]
pin_gpio09_dev pin_device[9]
```

```
pin_gpio10_dev pin_device[10]
pin_gpio11_dev pin_device[11]
pin_gpio12_dev pin_device[12]
pin_gpio13_dev pin_device[13]
pin_gpio14_dev pin_device[14]
pin_gpio15_dev pin_device[15]
pin_gpio16_dev pin_device[16]
pin_gpio17_dev pin_device[17]
pin_gpio18_dev pin_device[18]
pin_gpio19_dev pin_device[19]
pin_gpio21_dev pin_device[21]
pin_gpio22_dev pin_device[22]
pin_gpio23_dev pin_device[23]
pin_gpio25_dev pin_device[25]
pin_gpio26_dev pin_device[26]
pin_gpio27_dev pin_device[27]
pin_gpio32_dev pin_device[28]
pin_gpio33_dev pin_device[29]
pin_gpio34_dev pin_device[30]
pin_gpio35_dev pin_device[31]
pin_gpio36_dev pin_device[32]
pin_gpio39_dev pin_device[35]
pin_led_dev pin_gpio16_dev
pin_dac1_dev pin_gpio25_dev
pin_dac2_dev pin_gpio26_dev
pin_a0_dev pin_gpio36_dev
pin_a3_dev pin_gpio39_dev
pin_a4_dev pin_gpio32_dev
pin_a5_dev pin_gpio33_dev
pin_a6_dev pin_gpio34_dev
pin_a7_dev pin_gpio35_dev
i2c_dev i2c_device[0]
spi_h_dev spi_device[1]
spi_v_dev spi_device[2]
adc_0_dev adc_device[0]
adc_1_dev adc_device[1]
```

```
flash_0_dev flash_device[0]
dac_0_dev dac_device[0]
ADC_PINS_MAX 16
```

Functions

int **board_pin_string_to_device_index** (const char *str_p)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- str_p: Pin as a string.

huzzah — Huzzah

Source code: [src/boards/huzzah/board.h](#), [src/boards/huzzah/board.c](#)

Hardware reference: *Adafruit HUZZAH ESP8266 breakout*

Defines

```
pin_gpio0_dev pin_device[0]
pin_gpio2_dev pin_device[2]
pin_gpio4_dev pin_device[5]
pin_gpio5_dev pin_device[4]
pin_gpio12_dev pin_device[12]
pin_gpio13_dev pin_device[13]
pin_gpio14_dev pin_device[14]
pin_gpio15_dev pin_device[15]
pin_gpio16_dev pin_device[16]
pin_d0_dev pin_device[0]
pin_d2_dev pin_device[2]
pin_d4_dev pin_device[5]
pin_d5_dev pin_device[4]
pin_d12_dev pin_device[12]
pin_d13_dev pin_device[13]
pin_d14_dev pin_device[14]
pin_d15_dev pin_device[15]
pin_d16_dev pin_device[16]
```

```
pin_led_dev pin_d2_dev
pin_a0_dev pin_device[0]
adc_0_dev adc_device[0]
flash_0_dev flash_device[0]
ADC_PINS_MAX 1
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

linux — Linux

Source code: [src/boards/linux/board.h](#), [src/boards/linux/board.c](#)

Defines

```
PIN_DEVICE_BASE 2
pin_d2_dev pin_device[2 - PIN_DEVICE_BASE]
pin_d3_dev pin_device[3 - PIN_DEVICE_BASE]
pin_d4_dev pin_device[4 - PIN_DEVICE_BASE]
pin_d5_dev pin_device[5 - PIN_DEVICE_BASE]
pin_d6_dev pin_device[6 - PIN_DEVICE_BASE]
pin_d7_dev pin_device[7 - PIN_DEVICE_BASE]
pin_d8_dev pin_device[8 - PIN_DEVICE_BASE]
pin_d9_dev pin_device[9 - PIN_DEVICE_BASE]
pin_d10_dev pin_device[10 - PIN_DEVICE_BASE]
pin_d11_dev pin_device[11 - PIN_DEVICE_BASE]
pin_d12_dev pin_device[12 - PIN_DEVICE_BASE]
pin_d13_dev pin_device[13 - PIN_DEVICE_BASE]
pin_a0_dev pin_device[14 - PIN_DEVICE_BASE]
pin_a1_dev pin_device[15 - PIN_DEVICE_BASE]
pin_a2_dev pin_device[16 - PIN_DEVICE_BASE]
pin_a3_dev pin_device[17 - PIN_DEVICE_BASE]
```

```
pin_a4_dev pin_device[18 - PIN_DEVICE_BASE]
pin_a5_dev pin_device[19 - PIN_DEVICE_BASE]
pin_a6_dev pin_device[20 - PIN_DEVICE_BASE]
pin_a7_dev pin_device[21 - PIN_DEVICE_BASE]
pin_led_dev pin_d13_dev
pwm_d3_dev pwm_device[3]
pwm_d9_dev pwm_device[0]
pwm_d10_dev pwm_device[1]
pwm_d11_dev pwm_device[2]
adc_0_dev adc_device[0]
pin_dac0_dev pin_device[10]
pin_dac1_dev pin_device[11]
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

maple_esp32 — Maple Esp32

Source code: [src/boards/maple_esp32/board.h](#), [src/boards/maple_esp32/board.c](#)

Hardware reference: [Maple-ESP32](#)

Defines

```
pin_gpio00_dev pin_device[0]
pin_gpio01_dev pin_device[1]
pin_gpio02_dev pin_device[2]
pin_gpio03_dev pin_device[3]
pin_gpio04_dev pin_device[4]
pin_gpio05_dev pin_device[5]
pin_gpio06_dev pin_device[6]
pin_gpio07_dev pin_device[7]
pin_gpio08_dev pin_device[8]
```

```
pin_gpio09_dev pin_device[9]
pin_gpio10_dev pin_device[10]
pin_gpio11_dev pin_device[11]
pin_gpio12_dev pin_device[12]
pin_gpio13_dev pin_device[13]
pin_gpio14_dev pin_device[14]
pin_gpio15_dev pin_device[15]
pin_gpio16_dev pin_device[16]
pin_gpio17_dev pin_device[17]
pin_gpio18_dev pin_device[18]
pin_gpio19_dev pin_device[19]
pin_gpio21_dev pin_device[21]
pin_gpio22_dev pin_device[22]
pin_gpio23_dev pin_device[23]
pin_gpio25_dev pin_device[25]
pin_gpio26_dev pin_device[26]
pin_gpio27_dev pin_device[27]
pin_gpio32_dev pin_device[28]
pin_gpio33_dev pin_device[29]
pin_gpio34_dev pin_device[30]
pin_gpio35_dev pin_device[31]
pin_gpio36_dev pin_device[32]
pin_gpio39_dev pin_device[35]
pin_led_dev pin_gpio16_dev
pin_dac1_dev pin_gpio25_dev
pin_dac2_dev pin_gpio26_dev
pin_a0_dev pin_gpio36_dev
pin_a3_dev pin_gpio39_dev
pin_a4_dev pin_gpio32_dev
pin_a5_dev pin_gpio33_dev
pin_a6_dev pin_gpio34_dev
pin_a7_dev pin_gpio35_dev
i2c_dev i2c_device[0]
spi_h_dev spi_device[1]
spi_v_dev spi_device[2]
adc_0_dev adc_device[0]
```



```
adc_1_dev adc_device[1]
flash_0_dev flash_device[0]
dac_0_dev dac_device[0]
ADC_PINS_MAX 16
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

nano32 — Nano32

Source code: [src/boards/nano32/board.h](#), [src/boards/nano32/board.c](#)

Hardware reference: *Nano32*

Defines

```
pin_gpio00_dev pin_device[0]
pin_gpio01_dev pin_device[1]
pin_gpio02_dev pin_device[2]
pin_gpio03_dev pin_device[3]
pin_gpio04_dev pin_device[4]
pin_gpio05_dev pin_device[5]
pin_gpio06_dev pin_device[6]
pin_gpio07_dev pin_device[7]
pin_gpio08_dev pin_device[8]
pin_gpio09_dev pin_device[9]
pin_gpio10_dev pin_device[10]
pin_gpio11_dev pin_device[11]
pin_gpio12_dev pin_device[12]
pin_gpio13_dev pin_device[13]
pin_gpio14_dev pin_device[14]
pin_gpio15_dev pin_device[15]
pin_gpio16_dev pin_device[16]
```

```
pin_gpio17_dev pin_device[17]
pin_gpio18_dev pin_device[18]
pin_gpio19_dev pin_device[19]
pin_gpio21_dev pin_device[21]
pin_gpio22_dev pin_device[22]
pin_gpio23_dev pin_device[23]
pin_gpio25_dev pin_device[25]
pin_gpio26_dev pin_device[26]
pin_gpio27_dev pin_device[27]
pin_gpio32_dev pin_device[28]
pin_gpio33_dev pin_device[29]
pin_gpio34_dev pin_device[30]
pin_gpio35_dev pin_device[31]
pin_gpio36_dev pin_device[32]
pin_gpio39_dev pin_device[35]
pin_led_dev pin_gpio16_dev
pin_dac1_dev pin_gpio25_dev
pin_dac2_dev pin_gpio26_dev
pin_a0_dev pin_gpio36_dev
pin_a3_dev pin_gpio39_dev
pin_a4_dev pin_gpio32_dev
pin_a5_dev pin_gpio33_dev
pin_a6_dev pin_gpio34_dev
pin_a7_dev pin_gpio35_dev
i2c_dev i2c_device[0]
spi_h_dev spi_device[1]
spi_v_dev spi_device[2]
adc_0_dev adc_device[0]
adc_1_dev adc_device[1]
flash_0_dev flash_device[0]
dac_0_dev dac_device[0]
ADC_PINS_MAX 16
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)

Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

nodemcu — NodeMCU

Source code: [src/boards/nodemcu/board.h](#), [src/boards/nodemcu/board.c](#)

Hardware reference: *NodeMCU*

Defines

```
pin_d0_dev pin_device[16]
pin_d1_dev pin_device[5]
pin_d2_dev pin_device[4]
pin_d3_dev pin_device[0]
pin_d4_dev pin_device[2]
pin_d5_dev pin_device[14]
pin_d6_dev pin_device[12]
pin_d7_dev pin_device[13]
pin_d8_dev pin_device[15]
pin_d9_dev pin_device[3]
pin_d10_dev pin_device[1]
pin_led_dev pin_d4_dev
pin_a0_dev pin_device[0]
adc_0_dev adc_device[0]
flash_0_dev flash_device[0]
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)

Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

photon — Photon

Source code: [src/boards/photon/board.h](#), [src/boards/photon/board.c](#)

Hardware reference: *Photon*

Defines

```
pin_d0_dev pin_device[23]
pin_d1_dev pin_device[22]
pin_d2_dev pin_device[21]
pin_d3_dev pin_device[20]
pin_d4_dev pin_device[19]
pin_d5_dev pin_device[15]
pin_d6_dev pin_device[14]
pin_d7_dev pin_device[13]
pin_a0_dev pin_device[37]
pin_a1_dev pin_device[35]
pin_a2_dev pin_device[34]
pin_a3_dev pin_device[5]
pin_a4_dev pin_device[6]
pin_a5_dev pin_device[7]
pin_led_dev pin_d7_dev
pin_dac0_dev pin_device[4]
pin_dac1_dev pin_device[5]
pwm_d0_dev pwm_device[0]
pwm_d1_dev pwm_device[1]
pwm_d2_dev pwm_device[2]
pwm_d3_dev pwm_device[3]
pwm_a4_dev pwm_device[4]
pwm_a5_dev pwm_device[5]
flash_0_dev flash_device[0]
```

Functions

```
int board_pin_string_to_device_index (const char *str_p)
    Convert given pin string to the pin number.
```

Return Pin number or negative error code.

Parameters

- `str_p`: Pin as a string.

`spc56ddiscovery` — SPC56D-Discovery

Source code: [src/boards/spc56ddiscovery/board.h](#), [src/boards/spc56ddiscovery/board.c](#)

Hardware reference: *SPC56D Discovery*

Defines

```
pin_pa0_dev pin_device[0]
pin_pa1_dev pin_device[1]
pin_pa2_dev pin_device[2]
pin_pa3_dev pin_device[3]
pin_pa4_dev pin_device[4]
pin_pa5_dev pin_device[5]
pin_pa6_dev pin_device[6]
pin_pa7_dev pin_device[7]
pin_pa8_dev pin_device[8]
pin_pa9_dev pin_device[9]
pin_pa10_dev pin_device[10]
pin_pa11_dev pin_device[11]
pin_pa12_dev pin_device[12]
pin_pa13_dev pin_device[13]
pin_pa14_dev pin_device[14]
pin_pa15_dev pin_device[15]
pin_pb0_dev pin_device[16]
pin_pb1_dev pin_device[17]
pin_pb2_dev pin_device[18]
pin_pb3_dev pin_device[19]
pin_pb4_dev pin_device[20]
pin_pb5_dev pin_device[21]
pin_pb6_dev pin_device[22]
pin_pb7_dev pin_device[23]
pin_pb8_dev pin_device[24]
pin_pb9_dev pin_device[25]
```

```
pin_pb10_dev pin_device[26]
pin_pb11_dev pin_device[27]
pin_pb12_dev pin_device[28]
pin_pb13_dev pin_device[29]
pin_pb14_dev pin_device[30]
pin_pb15_dev pin_device[31]
pin_pc0_dev pin_device[32]
pin_pc1_dev pin_device[33]
pin_pc2_dev pin_device[34]
pin_pc3_dev pin_device[35]
pin_pc4_dev pin_device[36]
pin_pc5_dev pin_device[37]
pin_pc6_dev pin_device[38]
pin_pc7_dev pin_device[39]
pin_pc8_dev pin_device[40]
pin_pc9_dev pin_device[41]
pin_pc10_dev pin_device[42]
pin_led_dev pin_pc2_dev
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)

Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

stm32f3discovery — STM32F3DISCOVERY

Source code: [src/boards/stm32f3discovery/board.h](#), [src/boards/stm32f3discovery/board.c](#)

Hardware reference: *STM32F3DISCOVERY*

Defines

```
pin_pa0_dev pin_device[]
pin_pa1_dev pin_device[]
pin_pa2_dev pin_device[]
```

```
pin_pa3_dev pin_device[]
pin_pa4_dev pin_device[]
pin_pa5_dev pin_device[]
pin_pa6_dev pin_device[]
pin_pa7_dev pin_device[]
pin_pa8_dev pin_device[]
pin_pa9_dev pin_device[]
pin_pa10_dev pin_device[]
pin_pa11_dev pin_device[]
pin_pa12_dev pin_device[]
pin_pa13_dev pin_device[]
pin_pa14_dev pin_device[]
pin_pa15_dev pin_device[]
pin_pb0_dev pin_device[]
pin_pb1_dev pin_device[]
pin_pb2_dev pin_device[]
pin_pb3_dev pin_device[]
pin_pb4_dev pin_device[]
pin_pb5_dev pin_device[]
pin_pb6_dev pin_device[]
pin_pb7_dev pin_device[]
pin_pb8_dev pin_device[]
pin_pb9_dev pin_device[]
pin_pb10_dev pin_device[]
pin_pb11_dev pin_device[]
pin_pb12_dev pin_device[]
pin_pb13_dev pin_device[]
pin_pb14_dev pin_device[]
pin_pb15_dev pin_device[]
pin_pc0_dev pin_device[]
pin_pc1_dev pin_device[]
pin_pc2_dev pin_device[]
pin_pc3_dev pin_device[]
pin_pc4_dev pin_device[]
pin_pc5_dev pin_device[]
pin_pc6_dev pin_device[]
```

```
pin_pc7_dev pin_device[]
pin_pc8_dev pin_device[]
pin_pc9_dev pin_device[]
pin_pc10_dev pin_device[]
pin_pc11_dev pin_device[]
pin_pc12_dev pin_device[]
pin_pc13_dev pin_device[]
pin_pc14_dev pin_device[]
pin_pc15_dev pin_device[]
pin_pd0_dev pin_device[]
pin_pd1_dev pin_device[]
pin_pd2_dev pin_device[]
pin_pd3_dev pin_device[]
pin_pd4_dev pin_device[]
pin_pd5_dev pin_device[]
pin_pd6_dev pin_device[]
pin_pd7_dev pin_device[]
pin_pd8_dev pin_device[]
pin_pd9_dev pin_device[]
pin_pd10_dev pin_device[]
pin_pd11_dev pin_device[]
pin_pd12_dev pin_device[]
pin_pd13_dev pin_device[]
pin_pd14_dev pin_device[]
pin_pd15_dev pin_device[]
pin_pe0_dev pin_device[]
pin_pe1_dev pin_device[]
pin_pe2_dev pin_device[]
pin_pe3_dev pin_device[]
pin_pe4_dev pin_device[]
pin_pe5_dev pin_device[]
pin_pe6_dev pin_device[]
pin_pe7_dev pin_device[]
pin_pe8_dev pin_device[]
pin_pe9_dev pin_device[]
pin_pe10_dev pin_device[]
```



```
pin_pe11_dev pin_device[]
pin_pe12_dev pin_device[]
pin_pe13_dev pin_device[]
pin_pe14_dev pin_device[]
pin_pe15_dev pin_device[]
uart_0_dev uart_device[0]
uart_1_dev uart_device[1]
uart_2_dev uart_device[2]
spi_0_dev spi_device[0]
spi_1_dev spi_device[1]
spi_2_dev spi_device[2]
i2c_0_dev i2c_device[0]
i2c_1_dev i2c_device[1]
can_0_dev can_device[0]
flash_0_dev flash_device[0]
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)
Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

stm32vldiscovery — STM32VLDISCOVERY

Source code: [src/boards/stm32vldiscovery/board.h](#), [src/boards/stm32vldiscovery/board.c](#)

Hardware reference: [STM32VLDISCOVERY](#)

Defines

```
pin_pa0_dev pin_device[0]
pin_pa1_dev pin_device[1]
pin_pa2_dev pin_device[2]
pin_pa3_dev pin_device[3]
pin_pa4_dev pin_device[4]
pin_pa5_dev pin_device[5]
```

```
pin_pa6_dev pin_device[6]
pin_pa7_dev pin_device[7]
pin_pa8_dev pin_device[8]
pin_pa9_dev pin_device[9]
pin_pa10_dev pin_device[10]
pin_pa11_dev pin_device[11]
pin_pa12_dev pin_device[12]
pin_pa13_dev pin_device[13]
pin_pa14_dev pin_device[14]
pin_pa15_dev pin_device[15]
pin_pb0_dev pin_device[16]
pin_pb1_dev pin_device[17]
pin_pb2_dev pin_device[18]
pin_pb3_dev pin_device[19]
pin_pb4_dev pin_device[20]
pin_pb5_dev pin_device[21]
pin_pb6_dev pin_device[22]
pin_pb7_dev pin_device[23]
pin_pb8_dev pin_device[24]
pin_pb9_dev pin_device[25]
pin_pb10_dev pin_device[26]
pin_pb11_dev pin_device[27]
pin_pb12_dev pin_device[28]
pin_pb13_dev pin_device[29]
pin_pb14_dev pin_device[30]
pin_pb15_dev pin_device[31]
pin_pc0_dev pin_device[32]
pin_pc1_dev pin_device[33]
pin_pc2_dev pin_device[34]
pin_pc3_dev pin_device[35]
pin_pc4_dev pin_device[36]
pin_pc5_dev pin_device[37]
pin_pc6_dev pin_device[38]
pin_pc7_dev pin_device[39]
pin_pc8_dev pin_device[40]
pin_pc9_dev pin_device[41]
```

```
pin_pc10_dev pin_device[42]
pin_pc11_dev pin_device[43]
pin_pc12_dev pin_device[44]
pin_pc13_dev pin_device[45]
pin_pc14_dev pin_device[46]
pin_pc15_dev pin_device[47]
pin_pd0_dev pin_device[48]
pin_pd1_dev pin_device[49]
pin_pd2_dev pin_device[50]
pin_led_dev pin_pc9_dev
pin_ld3_dev pin_led_dev
pin_ld4_dev pin_pc8_dev
uart_0_dev uart_device[0]
uart_1_dev uart_device[1]
uart_2_dev uart_device[2]
spi_0_dev spi_device[0]
spi_1_dev spi_device[1]
spi_2_dev spi_device[2]
i2c_0_dev i2c_device[0]
i2c_1_dev i2c_device[1]
flash_0_dev flash_device[0]
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)

Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

wemos_d1_mini — WEMOS D1 Mini

Source code: [src/boards/wemos_d1_mini/board.h](#), [src/boards/wemos_d1_mini/board.c](#)

Hardware reference: [WEMOS D1 mini](#)

Defines

```
pin_gpio0_dev pin_device[0]
pin_gpio2_dev pin_device[2]
pin_gpio4_dev pin_device[4]
pin_gpio5_dev pin_device[5]
pin_gpio12_dev pin_device[12]
pin_gpio13_dev pin_device[13]
pin_gpio14_dev pin_device[14]
pin_gpio15_dev pin_device[15]
pin_gpio16_dev pin_device[16]
pin_d0_dev pin_device[16]
pin_d1_dev pin_device[5]
pin_d2_dev pin_device[4]
pin_d3_dev pin_device[0]
pin_d4_dev pin_device[2]
pin_d5_dev pin_device[14]
pin_d6_dev pin_device[12]
pin_d7_dev pin_device[13]
pin_d8_dev pin_device[15]
pin_led_dev pin_d4_dev
pin_a0_dev pin_device[0]
adc_0_dev adc_device[0]
flash_0_dev flash_device[0]
ADC_PINS_MAX 1
```

Functions

int **board_pin_string_to_device_index** (const char **str_p*)

Convert given pin string to the pin number.

Return Pin number or negative error code.

Parameters

- *str_p*: Pin as a string.

mcus

The Micro Controller Units (MCU:s) supported by *Simba*.

The MCU:s on [Github](#).

atmega2560 — ATmega2560

Source code: [src/mcus/atmega2560/mcu.h](#)

Defines

PIN_DEVICE_MAX 70

EXTI_DEVICE_MAX 6

SPI_DEVICE_MAX 1

UART_DEVICE_MAX 4

PWM_DEVICE_MAX 10

ADC_DEVICE_MAX 1

I2C_DEVICE_MAX 1

atmega328p — ATmega328p

Source code: [src/mcus/atmega328p/mcu.h](#)

Defines

PIN_DEVICE_MAX 20

EXTI_DEVICE_MAX 2

SPI_DEVICE_MAX 1

UART_DEVICE_MAX 1

PWM_DEVICE_MAX 4

ADC_DEVICE_MAX 1

I2C_DEVICE_MAX 1

USART0_TX_vect USART_TX_vect

USART0_RX_vect USART_RX_vect

USART0_UDRE_vect USART_UDRE_vect

atmega32u4 — ATmega32u4

Source code: [src/mcus/atmega32u4/mcu.h](#)

Defines

`PIN_DEVICE_MAX` 25
`EXTI_DEVICE_MAX` 2
`SPI_DEVICE_MAX` 1
`UART_DEVICE_MAX` 1
`PWM_DEVICE_MAX` 4
`ADC_DEVICE_MAX` 1
`I2C_DEVICE_MAX` 1
`USB_DEVICE_MAX` 1
`USART0_TX_vect` USART1_TX_vect
`USART0_RX_vect` USART1_RX_vect
`USART0_UDRE_vect` USART1_UDRE_vect
`UCSZ00` UCSZ10
`UCSZ01` UCSZ11
`UCSZ02` UCSZ12
`UPM00` UPM10
`UPM01` UPM11
`USBS0` USBS1
`U2X0` U2X1
`UPE0` UPE1
`DOR0` DOR1
`FE0` FE1
`TXC0` TXC1
`RXCIE0` RXCIE1
`RXEN0` RXEN1
`TXEN0` TXEN1
`UDRE0` UDRE1
`UDRIE0` UDRIE1
`TXCIE0` TXCIE1

esp32 — Esp32

Hardware reference: <https://github.com/eerimog/hardware-reference/tree/master/esp32>

Source code: <src/mcus/esp32/mcu.h>

Defines

`PIN_DEVICE_MAX` 36
`EXTI_DEVICE_MAX` 1
`SPI_DEVICE_MAX` 3
`UART_DEVICE_MAX` 3
`ADC_DEVICE_MAX` 2
`I2C_DEVICE_MAX` 1
`FLASH_DEVICE_MAX` 1
`CAN_DEVICE_MAX` 1
`DAC_DEVICE_MAX` 1

esp8266 — Esp8266

Hardware reference: <https://github.com/erimoq/hardware-reference/tree/master/esp8266>

Source code: [src/mcus/esp8266/mcu.h](#)

Defines

`PIN_DEVICE_MAX` 17
`EXTI_DEVICE_MAX` 16
`SPI_DEVICE_MAX` 1
`UART_DEVICE_MAX` 2
`ADC_DEVICE_MAX` 1
`FLASH_DEVICE_MAX` 1
`I2C_DEVICE_MAX` 2

linux — Linux

Source code: [src/mcus/linux/mcu.h](#)

Defines

`PIN_DEVICE_MAX` 128
`EXTI_DEVICE_MAX` 32
`SPI_DEVICE_MAX` 16
`UART_DEVICE_MAX` 16

`CAN_DEVICE_MAX` 16
`PWM_DEVICE_MAX` 128
`ADC_DEVICE_MAX` 16
`FLASH_DEVICE_MAX` 16
`DAC_DEVICE_MAX` 16
`I2C_DEVICE_MAX` 16

`sam3x8e` — **SAM3X8E**

Source code: [src/mcus/sam/mcu.h](#)

Defines

`SAM_PA` 0
`SAM_PB` 30
`SAM_PC` 62
`SAM_PD` 93

`spc56d4011` — **SPC56D40L1**

Source code: [src/mcus/spc56d4011/mcu.h](#)

Defines

`PIN_DEVICE_MAX` 45
`UART_DEVICE_MAX` 3
`FLASH_DEVICE_MAX` 2
`CAN_DEVICE_MAX` 1
`I2C_DEVICE_MAX` 1

`stm32f100rb` — **STM32F100RB**

Source code: [src/mcus/stm32f100rb/mcu.h](#)

Defines

`PIN_DEVICE_MAX` 51
`UART_DEVICE_MAX` 3
`SPI_DEVICE_MAX` 3
`I2C_DEVICE_MAX` 2
`CAN_DEVICE_MAX` 1
`FLASH_DEVICE_MAX` 1

`stm32f205rg` — **STM32F205RG**

Source code: <src/mcus/stm32f205rg/mcu.h>

Defines

`PIN_DEVICE_MAX` 51
`UART_DEVICE_MAX` 3
`SPI_DEVICE_MAX` 3
`I2C_DEVICE_MAX` 2
`CAN_DEVICE_MAX` 1
`FLASH_DEVICE_MAX` 1

`stm32f303vc` — **STM32F303VC**

Source code: <src/mcus/stm32f303vc/mcu.h>

Defines

`PIN_DEVICE_MAX` 70
`UART_DEVICE_MAX` 3
`SPI_DEVICE_MAX` 3
`I2C_DEVICE_MAX` 2
`CAN_DEVICE_MAX` 1
`FLASH_DEVICE_MAX` 1

License

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The following files are subjected to other licenses:

- 3pp/*: Various licenses.
- src/filesystems/fat16.*: GNU LGPL License

Videos

#6 Simba: CAN client-server test suite on Nano32 (ESP32) and Arduino Due.

Transmit CAN frames between a Nano32 and an Arduino Due.

#5 Simba: Room temperature (DS18B20).

Read and print the room temperature measured with a DS18B20 sensor.

#4 Simba: Hello world.

This application prints “Hello world!” to standard output.

#3 Simba: Analog read.

Read the value of an analog pin periodically once every second and print the read value to standard output.

#2 Simba: Blink example.

This video demonstrates the classic blink application. It’s run on a Arduino Due that has a SAM2X8E ARM MCU.

#1 Simba: Gource of the Simba repository.

Gource visualizes the Simba Git repository file tree over time. In this project the source, test and documentation was written simultaneously, a perfect school book example of software development.

Links

This page contains links to external websites that are related to Simba.

Feel free to add your project to the list by submitting a pull request of [this page](#) on Github.

Pumbaa - MicroPython on Simba

Python on microcontrollers thanks to MicroPython (and in this case Simba).

Documentation: <http://pumbaa.readthedocs.io>

Github: <https://github.com/eerimoq/pumbaa>

MicroPython: <http://www.micropython.org>

Wingfence

A BWF for a home made robot mower.

Github: <https://github.com/wingstar74/wingfence>

- *Threads* scheduled by a priority based cooperative or preemptive scheduler.
- Channels for inter-thread communication (*Queue*, *Event*).
- *Timers*.
- *Counting semaphores*.
- Device drivers (*SPI*, *UART*, ...)
- A simple *shell*.
- *Logging*.
- Internet protocols (*TCP*, *UDP*, *HTTP*, ...).
- *Debug file system*.
- File systems (*FAT16*, *SPIFFS*).

See the *Library Reference* for a full list of features.

CHAPTER 3

Testing

To ensure high code quality each module is tested extensively by many test suites. See [Testing](#) for details.

CHAPTER 4

Design goals

- Rapid development.
- Clean interfaces.
- Small memory footprint.
- No dynamic memory allocation.
- Portability.

CHAPTER 5

Indices and tables

- `genindex`
- `modindex`
- `search`

a

adc, 220
analog_input_pin, 222
analog_output_pin, 223
arduino_due, 422
arduino_mega, 427
arduino_nano, 430
arduino_pro_micro, 431
arduino_uno, 432
assert, 178
atmega2560, 453
atmega328p, 453
atmega32u4, 453

b

base64, 412
binary_tree, 389
bits, 391
bus, 203

c

can, 224
chan, 205
chipid, 226
circular_buffer, 391
circular_heap, 399
color, 402
configfile, 403
console, 362
crc, 416

d

dac, 226
ds18b20, 227
ds3231, 229

e

eprom_soft, 230
emacs, 405

errno, 179
esp01, 433
esp12e, 434
esp32, 454
esp32_devkitc, 435
esp8266, 455
esp_wifi, 232
esp_wifi_softap, 232
esp_wifi_station, 234
event, 211
exti, 237

f

fat16, 294
fifo, 393
flash, 238
fs, 305

h

harness, 380
hash_map, 395
heap, 401
http_server, 330
http_websocket_client, 334
http_websocket_server, 336
huzzah, 437

i

i2c, 240
i2c_soft, 242
inet, 337
isotp, 338

j

json, 412

l

led_7seg_ht16k33, 244
linux, 455

list, 396
log, 384

m

maple_esp32, 439
mcp2515, 247
midi, 419
mqtt_client, 340

n

nano32, 441
network_interface, 344
network_interface_driver_esp, 346
network_interface_slip, 344
network_interface_wifi, 346
nodemcu, 443
nrf24l01, 249
nvm, 363

o

owi, 251

p

photon, 444
pin, 252
ping, 351
pwm, 255
pwm_soft, 257

q

queue, 213

r

random, 260
re, 406
rwlock, 216

s

sam3x8e, 456
sd, 260
sem, 218
service, 364
settings, 367
sha1, 418
shell, 370
sht3xd, 265
soam, 373
socket, 351
spc56d4011, 456
spc56ddiscovery, 445
spi, 267
spiffs, 316
ssl, 357
std, 408

stm32f100rb, 456
stm32f205rg, 457
stm32f303vc, 457
stm32f3discovery, 446
stm32vldiscovery, 449
sys, 186

t

tftp_server, 361
thrd, 190
time, 197
timer, 199
types, 201

u

uart, 270
uart_soft, 273
upgrade, 376
usb, 274
usb_device, 282
usb_device_class_cdc, 282
usb_host, 285
usb_host_class_hid, 285
usb_host_class_mass_storage, 287

w

watchdog, 291
wemos_d1_mini, 451
ws2812, 292

Symbols

`_ASSERTFMT` (C macro), 382
`_ASSERTHEX` (C macro), 382

A

`adc` (module), 220
`adc_0_dev` (C macro), 427, 430–433, 435, 436, 438–440, 442, 443, 452
`adc_1_dev` (C macro), 436, 440, 442
`adc_async_convert` (C++ function), 221
`adc_async_wait` (C++ function), 221
`adc_convert` (C++ function), 221
`adc_convert_isr` (C++ function), 221
`adc_device` (C++ member), 222
`ADC_DEVICE_MAX` (C macro), 453–456
`adc_init` (C++ function), 220
`adc_is_valid_device` (C++ function), 221
`adc_module_init` (C++ function), 220
`ADC_PINS_MAX` (C macro), 435, 437, 438, 441, 442, 452
`ADC_REFERENCE_VCC` (C macro), 220
`analog_input_pin` (module), 222
`analog_input_pin_init` (C++ function), 222
`analog_input_pin_module_init` (C++ function), 222
`analog_input_pin_read` (C++ function), 222
`analog_input_pin_read_isr` (C++ function), 222
`analog_input_pin_t` (C++ class), 222
`analog_input_pin_t::adc` (C++ member), 223
`analog_output_pin` (module), 223
`analog_output_pin_init` (C++ function), 223
`analog_output_pin_module_init` (C++ function), 223
`analog_output_pin_read` (C++ function), 223
`analog_output_pin_t` (C++ class), 223
`analog_output_pin_t::pwm` (C++ member), 224
`analog_output_pin_write` (C++ function), 223
`arduino_due` (module), 422
`arduino_mega` (module), 427
`arduino_nano` (module), 430
`arduino_pro_micro` (module), 431

`arduino_uno` (module), 432
`ASSERT` (C macro), 178
`assert` (module), 178
`ASSERTN` (C macro), 178
`ASSERTNR` (C macro), 178
`ASSERTNRN` (C macro), 179
`ASSERTNRV` (C macro), 179
`ASSERTRN` (C macro), 178
`ASSERTRV` (C macro), 178
`atmega2560` (module), 453
`atmega328p` (module), 453
`atmega32u4` (module), 453

B

`base64` (module), 412
`base64_decode` (C++ function), 412
`base64_encode` (C++ function), 412
`binary_tree` (module), 389
`binary_tree_delete` (C++ function), 390
`binary_tree_init` (C++ function), 389
`binary_tree_insert` (C++ function), 390
`binary_tree_node_t` (C++ class), 390
`binary_tree_node_t::height` (C++ member), 390
`binary_tree_node_t::key` (C++ member), 390
`binary_tree_node_t::left_p` (C++ member), 390
`binary_tree_node_t::right_p` (C++ member), 390
`binary_tree_print` (C++ function), 390
`binary_tree_search` (C++ function), 390
`binary_tree_t` (C++ class), 390
`binary_tree_t::root_p` (C++ member), 391
`BIT` (C macro), 202
`BITFIELD_GET` (C macro), 202
`BITFIELD_SET` (C macro), 202
`bits` (module), 391
`bits_insert_32` (C++ function), 391
`board_pin_string_to_device_index` (C++ function), 427, 430–435, 437–439, 441, 443, 444, 446, 449, 451, 452
`bpb_t` (C++ class), 300
`bpb_t::bytes_per_sector` (C++ member), 301

- bpb_t::fat_count (C++ member), 301
- bpb_t::head_count (C++ member), 301
- bpb_t::hiddedn_sectors (C++ member), 301
- bpb_t::media_type (C++ member), 301
- bpb_t::reserved_sector_count (C++ member), 301
- bpb_t::root_dir_entry_count (C++ member), 301
- bpb_t::sectors_per_cluster (C++ member), 301
- bpb_t::sectors_per_fat (C++ member), 301
- bpb_t::sectors_per_track (C++ member), 301
- bpb_t::total_sectors_large (C++ member), 301
- bpb_t::total_sectors_small (C++ member), 301
- BTASSERT (C macro), 382
- BTASSERTI (C macro), 382
- BTASSERTM (C macro), 382
- BTASSERTN (C macro), 382
- BTASSERTR (C macro), 382
- BTASSERTRM (C macro), 382
- BTASSERTTV (C macro), 383
- bus (module), 203
- bus_attach (C++ function), 204
- bus_detach (C++ function), 204
- bus_init (C++ function), 203
- bus_listener_init (C++ function), 203
- bus_listener_t (C++ class), 205
- bus_listener_t::base (C++ member), 205
- bus_listener_t::chan_p (C++ member), 205
- bus_listener_t::id (C++ member), 205
- bus_listener_t::next_p (C++ member), 205
- bus_module_init (C++ function), 203
- bus_t (C++ class), 204
- bus_t::listeners (C++ member), 205
- bus_t::rwlock (C++ member), 205
- bus_write (C++ function), 204

C

- can (module), 224
- can_0_dev (C macro), 449
- can_device (C++ member), 226
- CAN_DEVICE_MAX (C macro), 455–457
- can_frame_t (C++ class), 226
- can_frame_t::extended_frame (C++ member), 226
- can_frame_t::id (C++ member), 226
- can_frame_t::rtr (C++ member), 226
- can_frame_t::size (C++ member), 226
- can_frame_t::u32 (C++ member), 226
- can_frame_t::u8 (C++ member), 226
- can_init (C++ function), 224
- can_module_init (C++ function), 224
- can_read (C++ function), 225
- CAN_SPEED_1000KBPS (C macro), 224
- CAN_SPEED_250KBPS (C macro), 224
- CAN_SPEED_500KBPS (C macro), 224
- can_start (C++ function), 225
- can_stop (C++ function), 225

- can_write (C++ function), 225
- chan (module), 205
- chan_control (C++ function), 208
- chan_control_fn_t (C++ type), 206
- CHAN_CONTROL_LOG_BEGIN (C macro), 205
- CHAN_CONTROL_LOG_END (C macro), 205
- chan_control_null (C++ function), 210
- CHAN_CONTROL_PRINTF_BEGIN (C macro), 205
- CHAN_CONTROL_PRINTF_END (C macro), 206
- chan_init (C++ function), 207
- chan_is_polled_isr (C++ function), 209
- chan_list_add (C++ function), 209
- chan_list_destroy (C++ function), 209
- chan_list_init (C++ function), 209
- chan_list_poll (C++ function), 210
- chan_list_remove (C++ function), 209
- chan_list_t (C++ class), 210
- chan_list_t::chans_pp (C++ member), 211
- chan_list_t::flags (C++ member), 211
- chan_list_t::len (C++ member), 211
- chan_list_t::max (C++ member), 211
- chan_module_init (C++ function), 207
- chan_null (C++ function), 210
- chan_poll (C++ function), 210
- chan_read (C++ function), 208
- chan_read_fn_t (C++ type), 206
- chan_read_null (C++ function), 210
- chan_set_control_cb (C++ function), 208
- chan_set_write_filter_cb (C++ function), 207
- chan_set_write_filter_isr_cb (C++ function), 207
- chan_set_write_isr_cb (C++ function), 207
- chan_size (C++ function), 208
- chan_size_fn_t (C++ type), 206
- chan_size_null (C++ function), 210
- chan_t (C++ class), 211
- chan_t::control (C++ member), 211
- chan_t::list_p (C++ member), 211
- chan_t::read (C++ member), 211
- chan_t::reader_p (C++ member), 211
- chan_t::size (C++ member), 211
- chan_t::write (C++ member), 211
- chan_t::write_filter_cb (C++ member), 211
- chan_t::write_filter_isr_cb (C++ member), 211
- chan_t::write_isr (C++ member), 211
- chan_write (C++ function), 208
- chan_write_filter_fn_t (C++ type), 206
- chan_write_fn_t (C++ type), 206
- chan_write_isr (C++ function), 208
- chan_write_null (C++ function), 210
- chipid (module), 226
- chipid_read (C++ function), 226
- circular_buffer (module), 391
- circular_buffer_array_one (C++ function), 392
- circular_buffer_array_two (C++ function), 393

- circular_buffer_init (C++ function), 391
- circular_buffer_read (C++ function), 391
- circular_buffer_reverse_skip_back (C++ function), 392
- circular_buffer_skip_front (C++ function), 392
- circular_buffer_t (C++ class), 393
- circular_buffer_t::buf_p (C++ member), 393
- circular_buffer_t::readpos (C++ member), 393
- circular_buffer_t::size (C++ member), 393
- circular_buffer_t::writepos (C++ member), 393
- circular_buffer_unused_size (C++ function), 392
- circular_buffer_used_size (C++ function), 392
- circular_buffer_write (C++ function), 391
- circular_heap (module), 399
- circular_heap_alloc (C++ function), 400
- circular_heap_free (C++ function), 400
- circular_heap_init (C++ function), 400
- circular_heap_t (C++ class), 400
- circular_heap_t::alloc_p (C++ member), 400
- circular_heap_t::begin_p (C++ member), 400
- circular_heap_t::end_p (C++ member), 400
- circular_heap_t::free_p (C++ member), 400
- COLOR (C macro), 403
- color (module), 402
- COLOR_BACKGROUND_BLACK (C macro), 403
- COLOR_BACKGROUND_BLUE (C macro), 403
- COLOR_BACKGROUND_CYAN (C macro), 403
- COLOR_BACKGROUND_DEFAULT (C macro), 403
- COLOR_BACKGROUND_GREEN (C macro), 403
- COLOR_BACKGROUND_MAGENTA (C macro), 403
- COLOR_BACKGROUND_RED (C macro), 403
- COLOR_BACKGROUND_WHITE (C macro), 403
- COLOR_BACKGROUND_YELLOW (C macro), 403
- COLOR_BOLD_OFF (C macro), 403
- COLOR_BOLD_ON (C macro), 402
- COLOR_FOREGROUND_BLACK (C macro), 403
- COLOR_FOREGROUND_BLUE (C macro), 403
- COLOR_FOREGROUND_CYAN (C macro), 403
- COLOR_FOREGROUND_DEFAULT (C macro), 403
- COLOR_FOREGROUND_GREEN (C macro), 403
- COLOR_FOREGROUND_MAGENTA (C macro), 403
- COLOR_FOREGROUND_RED (C macro), 403
- COLOR_FOREGROUND_WHITE (C macro), 403
- COLOR_FOREGROUND_YELLOW (C macro), 403
- COLOR_INVERSE_OFF (C macro), 403
- COLOR_INVERSE_ON (C macro), 402
- COLOR_ITALICS_OFF (C macro), 403
- COLOR_ITALICS_ON (C macro), 402
- COLOR_RESET (C macro), 402
- COLOR_STRIKETHROUGH_OFF (C macro), 403
- COLOR_STRIKETHROUGH_ON (C macro), 402
- COLOR_UNDERLINE_OFF (C macro), 403
- COLOR_UNDERLINE_ON (C macro), 402
- CONFIG_ADC (C macro), 11
- CONFIG_ANALOG_INPUT_PIN (C macro), 11
- CONFIG_ANALOG_OUTPUT_PIN (C macro), 11
- CONFIG_ASSERT (C macro), 10
- CONFIG_ASSERT_FORCE_FATAL (C macro), 11
- CONFIG_CAN (C macro), 11
- CONFIG_CAN_FRAME_TIMESTAMP (C macro), 11
- CONFIG_CHIPID (C macro), 11
- CONFIG_CRC_TABLE_LOOKUP (C macro), 20
- CONFIG_DAC (C macro), 11
- CONFIG_DEBUG (C macro), 11
- CONFIG_DS18B20 (C macro), 11
- CONFIG_DS3231 (C macro), 11
- CONFIG_EEPROM_SOFT_CRC (C macro), 20
- CONFIG_EEPROM_SOFT_CRC_32 (C macro), 20
- CONFIG_EEPROM_SOFT_CRC_CCITT (C macro), 20
- CONFIG_EEPROM_SOFT_SEMAPHORE (C macro), 20
- CONFIG_EMACS_COLUMNS_MAX (C macro), 19
- CONFIG_EMACS_HEAP_SIZE (C macro), 19
- CONFIG_EMACS_ROWS_MAX (C macro), 19
- CONFIG_ESP_WIFI (C macro), 11
- CONFIG_EXTERNAL_OSCILLATOR_FREQUENCY_HZ (C macro), 20
- CONFIG_EXTI (C macro), 11
- CONFIG_FAT16 (C macro), 17
- CONFIG_FATAL_ASSERT (C macro), 11
- CONFIG_FILESYSTEM_GENERIC (C macro), 17
- CONFIG_FLASH (C macro), 11
- CONFIG_FLASH_DEVICE_SEMAPHORE (C macro), 20
- CONFIG_FLOAT (C macro), 19
- CONFIG_FS_CMD_DS18B20_LIST (C macro), 14
- CONFIG_FS_CMD_ESP_WIFI_STATUS (C macro), 14
- CONFIG_FS_CMD_FS_APPEND (C macro), 14
- CONFIG_FS_CMD_FS_COUNTERS_LIST (C macro), 14
- CONFIG_FS_CMD_FS_COUNTERS_RESET (C macro), 15
- CONFIG_FS_CMD_FS_FILESYSTEMS_LIST (C macro), 15
- CONFIG_FS_CMD_FS_FORMAT (C macro), 15
- CONFIG_FS_CMD_FS_LIST (C macro), 15
- CONFIG_FS_CMD_FS_PARAMETERS_LIST (C macro), 15
- CONFIG_FS_CMD_FS_READ (C macro), 15
- CONFIG_FS_CMD_FS_REMOVE (C macro), 15
- CONFIG_FS_CMD_FS_WRITE (C macro), 15
- CONFIG_FS_CMD_I2C_READ (C macro), 15
- CONFIG_FS_CMD_I2C_WRITE (C macro), 15
- CONFIG_FS_CMD_LOG_LIST (C macro), 15
- CONFIG_FS_CMD_LOG_PRINT (C macro), 15
- CONFIG_FS_CMD_LOG_SET_LOG_MASK (C macro), 15
- CONFIG_FS_CMD_NETWORK_INTERFACE_LIST (C macro), 15

CONFIG_FS_CMD_NVM_READ (C macro), 16
CONFIG_FS_CMD_NVM_WRITE (C macro), 16
CONFIG_FS_CMD_PIN_READ (C macro), 15
CONFIG_FS_CMD_PIN_SET_MODE (C macro), 15
CONFIG_FS_CMD_PIN_WRITE (C macro), 15
CONFIG_FS_CMD_PING_PING (C macro), 15
CONFIG_FS_CMD_SERVICE_LIST (C macro), 15
CONFIG_FS_CMD_SERVICE_START (C macro), 15
CONFIG_FS_CMD_SERVICE_STOP (C macro), 15
CONFIG_FS_CMD_SETTINGS_LIST (C macro), 16
CONFIG_FS_CMD_SETTINGS_READ (C macro), 16
CONFIG_FS_CMD_SETTINGS_RESET (C macro), 16
CONFIG_FS_CMD_SETTINGS_WRITE (C macro), 16
CONFIG_FS_CMD_SYS_BACKTRACE (C macro), 16
CONFIG_FS_CMD_SYS_CONFIG (C macro), 16
CONFIG_FS_CMD_SYS_INFO (C macro), 16
CONFIG_FS_CMD_SYS_PANIC (C macro), 16
CONFIG_FS_CMD_SYS_REBOOT (C macro), 16
CONFIG_FS_CMD_SYS_RESET_CAUSE (C macro), 16
CONFIG_FS_CMD_SYS_UPTIME (C macro), 16
CONFIG_FS_CMD_THRD_LIST (C macro), 16
CONFIG_FS_CMD_THRD_SET_LOG_MASK (C macro), 16
CONFIG_FS_CMD_UPGRADE_APPLICATION_ENTER (C macro), 16
CONFIG_FS_CMD_UPGRADE_APPLICATION_ERASE (C macro), 16
CONFIG_FS_CMD_UPGRADE_APPLICATION_IS_VALID (C macro), 16
CONFIG_FS_CMD_UPGRADE_BOOTLOADER_ENTER (C macro), 16
CONFIG_FS_CMD_USB_DEVICE_LIST (C macro), 16
CONFIG_FS_CMD_USB_HOST_LIST (C macro), 16
CONFIG_FS_PATH_MAX (C macro), 17
CONFIG_HARNESS_EXPECT_BUFFER_SIZE (C macro), 20
CONFIG_HARNESS_HEAP_MAX (C macro), 20
CONFIG_HARNESS MOCK_VERBOSE (C macro), 20
CONFIG_HARNESS_SLEEP_MS (C macro), 20
CONFIG_HTTP_SERVER_REQUEST_BUFFER_SIZE (C macro), 20
CONFIG_HTTP_SERVER_SSL (C macro), 20
CONFIG_I2C (C macro), 11
CONFIG_I2C_SOFT (C macro), 12
CONFIG_LED_7SEG_HT16K33 (C macro), 11
CONFIG_LINUX_SOCKET_DEVICE (C macro), 11
CONFIG_MCP2515 (C macro), 12
CONFIG_MODULE_INIT_ADC (C macro), 13
CONFIG_MODULE_INIT_ANALOG_INPUT_PIN (C macro), 13
CONFIG_MODULE_INIT_ANALOG_OUTPUT_PIN (C macro), 13
CONFIG_MODULE_INIT_BUS (C macro), 14
CONFIG_MODULE_INIT_CAN (C macro), 13
CONFIG_MODULE_INIT_CHAN (C macro), 13
CONFIG_MODULE_INIT_CHIPID (C macro), 13
CONFIG_MODULE_INIT_DAC (C macro), 13
CONFIG_MODULE_INIT_DS18B20 (C macro), 13
CONFIG_MODULE_INIT_DS3231 (C macro), 13
CONFIG_MODULE_INIT_ESP_WIFI (C macro), 13
CONFIG_MODULE_INIT_EXTI (C macro), 13
CONFIG_MODULE_INIT_FLASH (C macro), 13
CONFIG_MODULE_INIT_FS (C macro), 12
CONFIG_MODULE_INIT_I2C (C macro), 13
CONFIG_MODULE_INIT_I2C_SOFT (C macro), 13
CONFIG_MODULE_INIT_INET (C macro), 14
CONFIG_MODULE_INIT_LOG (C macro), 13
CONFIG_MODULE_INIT_MCP2515 (C macro), 13
CONFIG_MODULE_INIT_NETWORK_INTERFACE (C macro), 14
CONFIG_MODULE_INIT_NRF24L01 (C macro), 13
CONFIG_MODULE_INIT_OWI (C macro), 13
CONFIG_MODULE_INIT_PIN (C macro), 13
CONFIG_MODULE_INIT_PING (C macro), 14
CONFIG_MODULE_INIT_PWM (C macro), 14
CONFIG_MODULE_INIT_PWM_SOFT (C macro), 14
CONFIG_MODULE_INIT_RANDOM (C macro), 13
CONFIG_MODULE_INIT_RWLOCK (C macro), 12
CONFIG_MODULE_INIT_SD (C macro), 14
CONFIG_MODULE_INIT_SEM (C macro), 12
CONFIG_MODULE_INIT_SETTINGS (C macro), 12
CONFIG_MODULE_INIT_SOCKET (C macro), 14
CONFIG_MODULE_INIT_SPI (C macro), 14
CONFIG_MODULE_INIT_SSL (C macro), 14
CONFIG_MODULE_INIT_STD (C macro), 12
CONFIG_MODULE_INIT_THRD (C macro), 13
CONFIG_MODULE_INIT_TIMER (C macro), 12
CONFIG_MODULE_INIT_UART (C macro), 14
CONFIG_MODULE_INIT_UART_SOFT (C macro), 14
CONFIG_MODULE_INIT_UPGRADE (C macro), 14
CONFIG_MODULE_INIT_USB (C macro), 14
CONFIG_MODULE_INIT_USB_DEVICE (C macro), 14
CONFIG_MODULE_INIT_USB_HOST (C macro), 14
CONFIG_MODULE_INIT_WATCHDOG (C macro), 14
CONFIG_MONITOR_THREAD (C macro), 17
CONFIG_MONITOR_THREAD_PERIOD_US (C macro), 17
CONFIG_NRF24L01 (C macro), 12
CONFIG_NVM_EEPROM_SOFT (C macro), 18
CONFIG_NVM_EEPROM_SOFT_BLOCK_0_SIZE (C macro), 18
CONFIG_NVM_EEPROM_SOFT_BLOCK_1_SIZE (C macro), 18

CONFIG_NVM_EEPROM_SOFT_CHUNK_SIZE (C macro), 18
 CONFIG_NVM_EEPROM_SOFT_FLASH_DEVICE_INDEX (C macro), 18
 CONFIG_NVM_SIZE (C macro), 18
 CONFIG_OWI (C macro), 12
 CONFIG_PANIC_ASSERT (C macro), 11
 CONFIG_PIN (C macro), 12
 CONFIG_PREEMPTIVE_SCHEDULER (C macro), 17
 CONFIG_PROFILE_STACK (C macro), 17
 CONFIG_PWM (C macro), 12
 CONFIG_PWM_SOFT (C macro), 12
 CONFIG_RANDOM (C macro), 11
 CONFIG_SD (C macro), 12
 CONFIG_SETTINGS_AREA_SIZE (C macro), 17
 CONFIG_SETTINGS_BLOB (C macro), 17
 CONFIG_SHELL_COMMAND_MAX (C macro), 17
 CONFIG_SHELL_HISTORY_SIZE (C macro), 17
 CONFIG_SHELL_MINIMAL (C macro), 17
 CONFIG_SHELL_PROMPT (C macro), 17
 CONFIG_SHT3XD (C macro), 11
 CONFIG_SOAM_EMBEDDED_DATABASE (C macro), 20
 CONFIG_SOCKET_RAW (C macro), 17
 CONFIG_SPC5_BOOT_ENTRY_RCHW (C macro), 20
 CONFIG_SPC5_RAM_CLEAR_ALL (C macro), 20
 CONFIG_SPI (C macro), 12
 CONFIG_SPIFFS (C macro), 17
 CONFIG_START_CONSOLE (C macro), 17
 CONFIG_START_CONSOLE_DEVICE_INDEX (C macro), 17
 CONFIG_START_CONSOLE_UART_BAUDRATE (C macro), 17
 CONFIG_START_CONSOLE_UART_RX_BUFFER_SIZE (C macro), 17
 CONFIG_START_CONSOLE_USB_CDC_CONTROL_INTERFACE (C macro), 17
 CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_INDEX (C macro), 17
 CONFIG_START_CONSOLE_USB_CDC_ENDPOINT_OFFSET (C macro), 18
 CONFIG_START_CONSOLE_USB_CDC_WAIT_FOR_CONNECTION (C macro), 18
 CONFIG_START_FILESYSTEM (C macro), 18
 CONFIG_START_FILESYSTEM_ADDRESS (C macro), 18
 CONFIG_START_FILESYSTEM_SIZE (C macro), 18
 CONFIG_START_NETWORK (C macro), 18
 CONFIG_START_NETWORK_INTERFACE_WIFI_CONNECTION_TIMEOUT (C macro), 18
 CONFIG_START_NETWORK_INTERFACE_WIFI_PASSWORD (C macro), 18
 CONFIG_START_NETWORK_INTERFACE_WIFI_SSID (C macro), 18
 CONFIG_START_NVM (C macro), 18
 CONFIG_START_SHELL (C macro), 18
 CONFIG_START_SHELL_PRIO (C macro), 18
 CONFIG_START_SHELL_STACK_SIZE (C macro), 18
 CONFIG_START_SOAM (C macro), 18
 CONFIG_START_SOAM_PRIO (C macro), 18
 CONFIG_START_SOAM_STACK_SIZE (C macro), 19
 CONFIG_STD_OUTPUT_BUFFER_MAX (C macro), 19
 CONFIG_SYS_CONFIG_STRING (C macro), 10
 CONFIG_SYS_LOG_MASK (C macro), 20
 CONFIG_SYS_PANIC_KICK_WATCHDOG (C macro), 10
 CONFIG_SYS_RESET_CAUSE (C macro), 10
 CONFIG_SYS_SIMBA_MAIN_STACK_MAX (C macro), 10
 CONFIG_SYSTEM_INTERRUPT_STACK_SIZE (C macro), 19
 CONFIG_SYSTEM_INTERRUPTS (C macro), 19
 CONFIG_SYSTEM_TICK_FREQUENCY (C macro), 19
 CONFIG_SYSTEM_TICK_SOFTWARE (C macro), 19
 CONFIG_THRD_CPU_USAGE (C macro), 19
 CONFIG_THRD_DEFAULT_LOG_MASK (C macro), 19
 CONFIG_THRD_ENV (C macro), 19
 CONFIG_THRD_IDLE_STACK_SIZE (C macro), 19
 CONFIG_THRD_MONITOR_STACK_SIZE (C macro), 19
 CONFIG_THRD_SCHEDULED (C macro), 19
 CONFIG_THRD_STACK_HEAP (C macro), 19
 CONFIG_THRD_STACK_HEAP_SIZE (C macro), 19
 CONFIG_THRD_TERMINATE (C macro), 19
 CONFIG_TIME_UNIX_TIME_TO_DATE (C macro), 20
 CONFIG_UART (C macro), 12
 CONFIG_UART_SOFT (C macro), 12
 CONFIG_USB (C macro), 12
 CONFIG_USB_DEVICE (C macro), 12
 CONFIG_USB_DEVICE_PID (C macro), 19
 CONFIG_USB_DEVICE_VID (C macro), 19
 CONFIG_USB_HOST (C macro), 12
 CONFIG_WATCHDOG (C macro), 12
 configfile (module), 403
 configfile_get (C++ function), 404
 configfile_get_float (C++ function), 405
 configfile_get_long (C++ function), 405
 configfile_init (C++ function), 404
 configfile_init_time (C++ function), 404
 configfile_t (C++ class), 405
 configfile_t::buf_p (C++ member), 405
 configfile_t::size (C++ member), 405
 CONFIGURATION_ATTRIBUTES_BUS_POWERED (C macro), 275

console (module), 362
 console_get_input_channel (C++ function), 363
 console_get_output_channel (C++ function), 363
 console_init (C++ function), 363
 console_module_init (C++ function), 363
 console_set_input_channel (C++ function), 363
 console_set_output_channel (C++ function), 363
 console_start (C++ function), 363
 console_stop (C++ function), 363
 container_of (C macro), 201
 cpu_usage_t (C++ type), 186
 crc (module), 416
 crc_32 (C++ function), 417
 crc_7 (C++ function), 417
 crc_8 (C++ function), 417
 CRC_8_POLYNOMIAL_8_5_4_0 (C macro), 416
 crc_ccitt (C++ function), 417
 crc_xmodem (C++ function), 417
 CSTR (C macro), 202

D

dac (module), 226
 dac_0_dev (C macro), 427, 437, 441, 442
 dac_async_convert (C++ function), 227
 dac_async_wait (C++ function), 227
 dac_convert (C++ function), 227
 dac_device (C++ member), 227
 DAC_DEVICE_MAX (C macro), 455, 456
 dac_init (C++ function), 226
 dac_module_init (C++ function), 226
 date_t (C++ class), 199
 date_t::date (C++ member), 199
 date_t::day (C++ member), 199
 date_t::hour (C++ member), 199
 date_t::minute (C++ member), 199
 date_t::month (C++ member), 199
 date_t::second (C++ member), 199
 date_t::year (C++ member), 199
 DESCRIPTOR_TYPE_CDC (C macro), 275
 DESCRIPTOR_TYPE_CONFIGURATION (C macro), 274
 DESCRIPTOR_TYPE_DEVICE (C macro), 274
 DESCRIPTOR_TYPE_ENDPOINT (C macro), 274
 DESCRIPTOR_TYPE_INTERFACE (C macro), 274
 DESCRIPTOR_TYPE_INTERFACE_ASSOCIATION (C macro), 274
 DESCRIPTOR_TYPE_RPIPE (C macro), 275
 DESCRIPTOR_TYPE_STRING (C macro), 274
 DIR_ATTR_ARCHIVE (C macro), 295
 DIR_ATTR_DIRECTORY (C macro), 295
 DIR_ATTR_HIDDEN (C macro), 295
 DIR_ATTR_READ_ONLY (C macro), 295
 DIR_ATTR_SYSTEM (C macro), 295
 DIR_ATTR_VOLUME_ID (C macro), 295

dir_t (C++ class), 302
 dir_t::attributes (C++ member), 303
 dir_t::creation_date (C++ member), 303
 dir_t::creation_time (C++ member), 303
 dir_t::creation_time_tenths (C++ member), 303
 dir_t::file_size (C++ member), 303
 dir_t::first_cluster_high (C++ member), 303
 dir_t::first_cluster_low (C++ member), 303
 dir_t::last_access_date (C++ member), 303
 dir_t::last_write_date (C++ member), 303
 dir_t::last_write_time (C++ member), 303
 dir_t::name (C++ member), 303
 dir_t::reserved1 (C++ member), 303
 DIV_CEIL (C macro), 202
 DIV_ROUND (C macro), 202
 DOR0 (C macro), 454
 ds18b20 (module), 227
 ds18b20_convert (C++ function), 228
 ds18b20_driver_t (C++ class), 229
 ds18b20_driver_t::next_p (C++ member), 229
 ds18b20_driver_t::owi_p (C++ member), 229
 DS18B20_FAMILY_CODE (C macro), 228
 ds18b20_get_temperature (C++ function), 228
 ds18b20_get_temperature_str (C++ function), 228
 ds18b20_init (C++ function), 228
 ds18b20_module_init (C++ function), 228
 ds3231 (module), 229
 ds3231_driver_t (C++ class), 229
 ds3231_driver_t::i2c_p (C++ member), 230
 ds3231_get_date (C++ function), 229
 ds3231_init (C++ function), 229
 ds3231_set_date (C++ function), 229

E

E2BIG (C macro), 179
 EACCES (C macro), 180
 EADDRINUSE (C macro), 184
 EADDRNOTAVAIL (C macro), 184
 EADV (C macro), 182
 EAFNOSUPBOARD (C macro), 184
 EAGAIN (C macro), 180
 EALREADY (C macro), 185
 EASSERT (C macro), 185
 EBADE (C macro), 182
 EBADF (C macro), 180
 EBADFD (C macro), 183
 EBADMSG (C macro), 183
 EBADR (C macro), 182
 EBADRQC (C macro), 182
 EBADSLT (C macro), 182
 EBFONT (C macro), 182
 EBTASSERT (C macro), 185
 EBUSY (C macro), 180
 ECANCELED (C macro), 185

- ECHILD (C macro), 180
- ECHRN (C macro), 181
- ECOMM (C macro), 182
- ECONNABORTED (C macro), 184
- ECONNREFUSED (C macro), 184
- ECONNRESET (C macro), 184
- EDEADLK (C macro), 181
- EDEADLOCK (C macro), 182
- EDESTADDRREQ (C macro), 183
- EDOM (C macro), 181
- EDOTDOT (C macro), 183
- EDQUOT (C macro), 185
- eeeprom_soft (module), 230
- eeeprom_soft_block_t (C++ class), 231
- eeeprom_soft_block_t::address (C++ member), 231
- eeeprom_soft_block_t::size (C++ member), 231
- eeeprom_soft_driver_t (C++ class), 231
- eeeprom_soft_driver_t::block_p (C++ member), 231
- eeeprom_soft_driver_t::blocks_p (C++ member), 231
- eeeprom_soft_driver_t::chunk_address (C++ member), 231
- eeeprom_soft_driver_t::chunk_size (C++ member), 231
- eeeprom_soft_driver_t::eeeprom_size (C++ member), 231
- eeeprom_soft_driver_t::flash_p (C++ member), 231
- eeeprom_soft_driver_t::number_of_blocks (C++ member), 231
- eeeprom_soft_driver_t::revision (C++ member), 231
- eeeprom_soft_format (C++ function), 230
- eeeprom_soft_init (C++ function), 230
- eeeprom_soft_module_init (C++ function), 230
- eeeprom_soft_mount (C++ function), 230
- eeeprom_soft_read (C++ function), 230
- eeeprom_soft_write (C++ function), 231
- EEXIST (C macro), 180
- EFAULT (C macro), 180
- EFBIG (C macro), 180
- EHOSTDOWN (C macro), 184
- EHOSTUNREACH (C macro), 184
- EIDRM (C macro), 181
- EILSEQ (C macro), 183
- EINPROGRESS (C macro), 185
- EINTR (C macro), 179
- EINVAL (C macro), 180
- EIO (C macro), 179
- EISCONN (C macro), 184
- EISDIR (C macro), 180
- EISNAM (C macro), 185
- EKEYEXPIRED (C macro), 185
- EKEYREJECTED (C macro), 185
- EKEYREVOKED (C macro), 185
- EL2HLT (C macro), 182
- EL2NSYNC (C macro), 181
- EL3HLT (C macro), 181
- EL3RST (C macro), 181
- ELIBACC (C macro), 183
- ELIBBAD (C macro), 183
- ELIBEXEC (C macro), 183
- ELIBMAX (C macro), 183
- ELIBSCN (C macro), 183
- ELNRNG (C macro), 181
- ELOOP (C macro), 181
- emacs (C++ function), 406
- emacs (module), 405
- EMEDIUMTYPE (C macro), 185
- EMFILE (C macro), 180
- EMLINK (C macro), 181
- EMSGSIZE (C macro), 183
- EMULTIHOP (C macro), 183
- ENAMETOOLONG (C macro), 181
- ENAVAIL (C macro), 185
- ENDPOINT_ATTRIBUTES_SYNCHRONISATION_TYPE (C macro), 275
- ENDPOINT_ATTRIBUTES_TRANSFER_TYPE (C macro), 275
- ENDPOINT_ATTRIBUTES_TRANSFER_TYPE_BULK (C macro), 275
- ENDPOINT_ATTRIBUTES_TRANSFER_TYPE_CONTROL (C macro), 275
- ENDPOINT_ATTRIBUTES_TRANSFER_TYPE_INTERRUPT (C macro), 275
- ENDPOINT_ATTRIBUTES_TRANSFER_TYPE_ISOCHRONOUS (C macro), 275
- ENDPOINT_ATTRIBUTES_USAGE_TYPE (C macro), 275
- ENDPOINT_ENDPOINT_ADDRESS_DIRECTION (C macro), 275
- ENDPOINT_ENDPOINT_ADDRESS_NUMBER (C macro), 275
- ENETDOWN (C macro), 184
- ENETRESET (C macro), 184
- ENETUNREACH (C macro), 184
- ENFILE (C macro), 180
- ENOANO (C macro), 182
- ENOBUFFS (C macro), 184
- ENOCOMMAND (C macro), 185
- ENOCSI (C macro), 181
- ENODATA (C macro), 182
- ENODEV (C macro), 180
- ENOENT (C macro), 179
- ENOEXEC (C macro), 180
- ENOKEY (C macro), 185
- ENOLCK (C macro), 181
- ENOLINK (C macro), 182
- ENOMEDIUM (C macro), 185
- ENOMEM (C macro), 180
- ENOMSG (C macro), 181
- ENONET (C macro), 182
- ENOPKG (C macro), 182

ENOPROTOOPT (C macro), 183
ENOSPC (C macro), 180
ENOSR (C macro), 182
ENOSTR (C macro), 182
ENOSYS (C macro), 181
ENOTBLK (C macro), 180
ENOTCONN (C macro), 184
ENOTDIR (C macro), 180
ENOTEMPTY (C macro), 181
ENOTNAM (C macro), 185
ENOTSOCK (C macro), 183
ENOTTY (C macro), 180
ENOTUNIQ (C macro), 183
ENXIO (C macro), 179
EOPNOTSUPP (C macro), 184
EOVERFLOW (C macro), 183
EPERM (C macro), 179
EPFNOSUPBOARD (C macro), 184
EPIPE (C macro), 181
EPROTO (C macro), 182
EPROTONOSUPBOARD (C macro), 184
EPROTOTYPE (C macro), 183
ERANGE (C macro), 181
EREMCHG (C macro), 183
EREMOTE (C macro), 182
EREMOTEIO (C macro), 185
ERESTART (C macro), 183
EROFS (C macro), 181
errno (module), 179
ESHUTDOWN (C macro), 184
ESOCKTNOSUPBOARD (C macro), 184
esp01 (module), 433
esp12e (module), 434
esp32 (module), 454
esp32_devkitc (module), 435
esp8266 (module), 455
esp_wifi (module), 232
esp_wifi_dhcp_status_running_t (C++ class), 236
esp_wifi_dhcp_status_stopped_t (C++ class), 236
esp_wifi_dhcp_status_t (C++ type), 236
esp_wifi_get_op_mode (C++ function), 236
esp_wifi_get_phy_mode (C++ function), 237
esp_wifi_module_init (C++ function), 236
esp_wifi_op_mode_max_t (C++ class), 236
esp_wifi_op_mode_null_t (C++ class), 236
esp_wifi_op_mode_softap_t (C++ class), 236
esp_wifi_op_mode_station_softap_t (C++ class), 236
esp_wifi_op_mode_station_t (C++ class), 236
esp_wifi_op_mode_t (C++ type), 236
esp_wifi_phy_mode_11b_t (C++ class), 236
esp_wifi_phy_mode_11g_t (C++ class), 236
esp_wifi_phy_mode_11n_t (C++ class), 236
esp_wifi_phy_mode_t (C++ type), 236
esp_wifi_print (C++ function), 237
esp_wifi_set_op_mode (C++ function), 236
esp_wifi_set_phy_mode (C++ function), 236
esp_wifi_softap (module), 232
esp_wifi_softap_dhcp_server_start (C++ function), 233
esp_wifi_softap_dhcp_server_status (C++ function), 233
esp_wifi_softap_dhcp_server_stop (C++ function), 233
esp_wifi_softap_get_ip_info (C++ function), 233
esp_wifi_softap_get_number_of_connected_stations (C++ function), 233
esp_wifi_softap_get_station_info (C++ function), 233
esp_wifi_softap_init (C++ function), 232
esp_wifi_softap_set_ip_info (C++ function), 233
esp_wifi_softap_station_info_t (C++ class), 233
esp_wifi_softap_station_info_t::bssid (C++ member), 233
esp_wifi_softap_station_info_t::ip_address (C++ member), 233
esp_wifi_station (module), 234
esp_wifi_station_connect (C++ function), 234
esp_wifi_station_dhcp_client_start (C++ function), 235
esp_wifi_station_dhcp_client_status (C++ function), 235
esp_wifi_station_dhcp_client_stop (C++ function), 235
esp_wifi_station_disconnect (C++ function), 234
esp_wifi_station_get_ip_info (C++ function), 235
esp_wifi_station_get_reconnect_policy (C++ function), 235
esp_wifi_station_get_status (C++ function), 235
esp_wifi_station_init (C++ function), 234
esp_wifi_station_set_ip_info (C++ function), 234
esp_wifi_station_set_reconnect_policy (C++ function), 235
esp_wifi_station_status_as_string (C++ function), 235
esp_wifi_station_status_auth_failure_t (C++ class), 234
esp_wifi_station_status_connect_fail_t (C++ class), 234
esp_wifi_station_status_connected_t (C++ class), 234
esp_wifi_station_status_connecting_t (C++ class), 234
esp_wifi_station_status_got_ip_t (C++ class), 234
esp_wifi_station_status_idle_t (C++ class), 234
esp_wifi_station_status_no_ap_found_t (C++ class), 234
esp_wifi_station_status_t (C++ type), 234
ESPIPE (C macro), 180
ESRCH (C macro), 179
ESRMNT (C macro), 182
ESTACK (C macro), 185
ESTALE (C macro), 185
ESTRPIPE (C macro), 183
ETIME (C macro), 182
ETIMEDOUT (C macro), 184
ETOOMANYREFS (C macro), 184
ETXTBSY (C macro), 180
EUCLEAN (C macro), 185
EUNATCH (C macro), 181
EUSERS (C macro), 183
event (module), 211

- event_init (C++ function), 211
 - event_read (C++ function), 211
 - event_size (C++ function), 212
 - event_t (C++ class), 212
 - event_t::base (C++ member), 212
 - event_t::mask (C++ member), 212
 - event_t::reader_mask (C++ member), 212
 - event_write (C++ function), 212
 - event_write_isr (C++ function), 212
 - EWOULDBLOCK (C macro), 181
 - EXDEV (C macro), 180
 - EXFULL (C macro), 182
 - exti (module), 237
 - exti_a0_dev (C macro), 426
 - exti_a10_dev (C macro), 426
 - exti_a11_dev (C macro), 426
 - exti_a1_dev (C macro), 426
 - exti_a2_dev (C macro), 426
 - exti_a3_dev (C macro), 426
 - exti_a4_dev (C macro), 426
 - exti_a5_dev (C macro), 426
 - exti_a6_dev (C macro), 426
 - exti_a7_dev (C macro), 426
 - exti_a8_dev (C macro), 426
 - exti_a9_dev (C macro), 426
 - exti_clear (C++ function), 238
 - exti_d0_dev (C macro), 424
 - exti_d10_dev (C macro), 425
 - exti_d11_dev (C macro), 425
 - exti_d12_dev (C macro), 425
 - exti_d13_dev (C macro), 425
 - exti_d14_dev (C macro), 425
 - exti_d15_dev (C macro), 425
 - exti_d16_dev (C macro), 425
 - exti_d17_dev (C macro), 425
 - exti_d18_dev (C macro), 425, 429
 - exti_d19_dev (C macro), 425, 429
 - exti_d1_dev (C macro), 424
 - exti_d20_dev (C macro), 425, 429
 - exti_d21_dev (C macro), 425, 429
 - exti_d22_dev (C macro), 425
 - exti_d23_dev (C macro), 425
 - exti_d24_dev (C macro), 425
 - exti_d25_dev (C macro), 425
 - exti_d26_dev (C macro), 425
 - exti_d27_dev (C macro), 425
 - exti_d28_dev (C macro), 425
 - exti_d29_dev (C macro), 425
 - exti_d2_dev (C macro), 424, 429, 431–433
 - exti_d30_dev (C macro), 425
 - exti_d31_dev (C macro), 425
 - exti_d32_dev (C macro), 425
 - exti_d33_dev (C macro), 425
 - exti_d34_dev (C macro), 425
 - exti_d35_dev (C macro), 425
 - exti_d36_dev (C macro), 425
 - exti_d37_dev (C macro), 425
 - exti_d38_dev (C macro), 425
 - exti_d39_dev (C macro), 426
 - exti_d3_dev (C macro), 425, 429, 431–433
 - exti_d40_dev (C macro), 426
 - exti_d41_dev (C macro), 426
 - exti_d42_dev (C macro), 426
 - exti_d43_dev (C macro), 426
 - exti_d44_dev (C macro), 426
 - exti_d45_dev (C macro), 426
 - exti_d46_dev (C macro), 426
 - exti_d47_dev (C macro), 426
 - exti_d48_dev (C macro), 426
 - exti_d49_dev (C macro), 426
 - exti_d4_dev (C macro), 425
 - exti_d50_dev (C macro), 426
 - exti_d51_dev (C macro), 426
 - exti_d52_dev (C macro), 426
 - exti_d53_dev (C macro), 426
 - exti_d5_dev (C macro), 425
 - exti_d6_dev (C macro), 425
 - exti_d7_dev (C macro), 425
 - exti_d8_dev (C macro), 425
 - exti_d9_dev (C macro), 425
 - exti_dac0_dev (C macro), 426
 - exti_dac1_dev (C macro), 426
 - exti_device (C++ member), 238
 - EXTI_DEVICE_MAX (C macro), 453–455
 - exti_init (C++ function), 237
 - exti_led_dev (C macro), 426
 - exti_module_init (C++ function), 237
 - exti_start (C++ function), 238
 - exti_stop (C++ function), 238
 - EXTI_TRIGGER_BOTH_EDGES (C macro), 237
 - EXTI_TRIGGER_FALLING_EDGE (C macro), 237
 - EXTI_TRIGGER_RISING_EDGE (C macro), 237
- ## F
- fat16 (module), 294
 - fat16_cache16_t (C++ type), 303
 - fat16_cache16_t::data (C++ member), 303
 - fat16_cache16_t::dir (C++ member), 303
 - fat16_cache16_t::fat (C++ member), 303
 - fat16_cache16_t::fbs (C++ member), 303
 - fat16_cache16_t::mbr (C++ member), 303
 - fat16_cache_t (C++ class), 303
 - fat16_cache_t::block_number (C++ member), 304
 - fat16_cache_t::buffer (C++ member), 304
 - fat16_cache_t::dirty (C++ member), 304
 - fat16_cache_t::mirror_block (C++ member), 304
 - fat16_date_t (C++ type), 299
 - fat16_date_t::as_uint16 (C++ member), 300

fat16_date_t::day (C++ member), 300
fat16_date_t::month (C++ member), 300
fat16_date_t::year (C++ member), 300
fat16_dir_close (C++ function), 298
fat16_dir_entry_t (C++ class), 305
fat16_dir_entry_t::is_dir (C++ member), 305
fat16_dir_entry_t::latest_mod_date (C++ member), 305
fat16_dir_entry_t::name (C++ member), 305
fat16_dir_entry_t::size (C++ member), 305
fat16_dir_open (C++ function), 298
fat16_dir_read (C++ function), 299
fat16_dir_t (C++ class), 304
fat16_dir_t::file (C++ member), 305
fat16_dir_t::root_index (C++ member), 305
FAT16_EOF (C macro), 295
fat16_file_close (C++ function), 297
fat16_file_open (C++ function), 297
fat16_file_read (C++ function), 297
fat16_file_seek (C++ function), 297
fat16_file_size (C++ function), 298
fat16_file_sync (C++ function), 298
fat16_file_t (C++ class), 304
fat16_file_t::cur_cluster (C++ member), 304
fat16_file_t::cur_position (C++ member), 304
fat16_file_t::dir_entry_block (C++ member), 304
fat16_file_t::dir_entry_index (C++ member), 304
fat16_file_t::fat16_p (C++ member), 304
fat16_file_t::file_size (C++ member), 304
fat16_file_t::first_cluster (C++ member), 304
fat16_file_t::flags (C++ member), 304
fat16_file_tell (C++ function), 297
fat16_file_truncate (C++ function), 298
fat16_file_write (C++ function), 297
fat16_format (C++ function), 296
fat16_init (C++ function), 296
fat16_mount (C++ function), 296
fat16_print (C++ function), 296
fat16_read_t (C++ type), 295
FAT16_SEEK_CUR (C macro), 294
FAT16_SEEK_END (C macro), 295
FAT16_SEEK_SET (C macro), 294
fat16_stat (C++ function), 299
fat16_stat_t (C++ class), 305
fat16_stat_t::is_dir (C++ member), 305
fat16_stat_t::size (C++ member), 305
fat16_t (C++ class), 304
fat16_t::arg_p (C++ member), 304
fat16_t::blocks_per_cluster (C++ member), 304
fat16_t::blocks_per_fat (C++ member), 304
fat16_t::cache (C++ member), 304
fat16_t::cluster_count (C++ member), 304
fat16_t::data_start_block (C++ member), 304
fat16_t::fat_count (C++ member), 304
fat16_t::fat_start_block (C++ member), 304
fat16_t::partition (C++ member), 304
fat16_t::read (C++ member), 304
fat16_t::root_dir_entry_count (C++ member), 304
fat16_t::root_dir_start_block (C++ member), 304
fat16_t::volume_start_block (C++ member), 304
fat16_t::write (C++ member), 304
fat16_time_t (C++ type), 299
fat16_time_t::as_uint16 (C++ member), 299
fat16_time_t::hours (C++ member), 299
fat16_time_t::minutes (C++ member), 299
fat16_time_t::seconds (C++ member), 299
fat16_unmount (C++ function), 296
fat16_write_t (C++ type), 295
fat_t (C++ type), 295
FATAL (C macro), 178
FATAL_ASSERT (C macro), 179
FATAL_ASSERTN (C macro), 179
fbs_t (C++ class), 301
fbs_t::boot_code (C++ member), 302
fbs_t::boot_sector_sig (C++ member), 302
fbs_t::boot_signature (C++ member), 302
fbs_t::bpb (C++ member), 302
fbs_t::drive_number (C++ member), 302
fbs_t::file_system_type (C++ member), 302
fbs_t::jmp_to_boot_code (C++ member), 302
fbs_t::oem_name (C++ member), 302
fbs_t::reserved1 (C++ member), 302
fbs_t::volume_label (C++ member), 302
fbs_t::volume_serial_number (C++ member), 302
FE0 (C macro), 454
fifo (module), 393
FIFO_DEFINE_TEMPLATE (C macro), 393
fifo_get (C++ function), 394
fifo_init (C++ function), 394
fifo_put (C++ function), 394
fifo_t (C++ class), 394
fifo_t::buf_p (C++ member), 394
fifo_t::max (C++ member), 394
fifo_t::rdpos (C++ member), 394
fifo_t::wrpos (C++ member), 394
flash (module), 238
flash_0_dev (C macro), 427, 434–436, 438, 441–444, 449, 451, 452
flash_device (C++ member), 239
FLASH_DEVICE_MAX (C macro), 455–457
flash_erase (C++ function), 239
flash_init (C++ function), 239
flash_module_init (C++ function), 238
flash_read (C++ function), 239
flash_write (C++ function), 239
fs (module), 305
FS_APPEND (C macro), 307
fs_auto_complete (C++ function), 311
fs_call (C++ function), 308

- fs_callback_t (C++ type), 307
 - fs_close (C++ function), 309
 - fs_command_deregister (C++ function), 313
 - fs_command_register (C++ function), 313
 - fs_command_t (C++ class), 315
 - fs_command_t::arg_p (C++ member), 315
 - fs_command_t::callback (C++ member), 315
 - fs_command_t::next_p (C++ member), 315
 - fs_counter_deregister (C++ function), 313
 - fs_counter_increment (C++ function), 313
 - fs_counter_register (C++ function), 313
 - fs_counter_t (C++ class), 315
 - fs_counter_t::command (C++ member), 315
 - fs_counter_t::next_p (C++ member), 315
 - FS_CREAT (C macro), 307
 - fs_dir_close (C++ function), 310
 - fs_dir_entry_t (C++ class), 316
 - fs_dir_entry_t::latest_mod_date (C++ member), 316
 - fs_dir_entry_t::name (C++ member), 316
 - fs_dir_entry_t::size (C++ member), 316
 - fs_dir_entry_t::type (C++ member), 316
 - fs_dir_open (C++ function), 310
 - fs_dir_read (C++ function), 310
 - fs_dir_t (C++ class), 316
 - fs_dir_t::filesystem_p (C++ member), 316
 - FS_EXCL (C macro), 307
 - fs_file_t (C++ class), 315
 - fs_file_t::filesystem_p (C++ member), 315
 - fs_filesystem_deregister (C++ function), 312
 - fs_filesystem_init_generic (C++ function), 312
 - fs_filesystem_operations_t (C++ class), 316
 - fs_filesystem_operations_t::file_close (C++ member), 316
 - fs_filesystem_operations_t::file_open (C++ member), 316
 - fs_filesystem_operations_t::file_read (C++ member), 316
 - fs_filesystem_operations_t::file_seek (C++ member), 316
 - fs_filesystem_operations_t::file_tell (C++ member), 316
 - fs_filesystem_operations_t::file_write (C++ member), 316
 - fs_filesystem_register (C++ function), 312
 - fs_filesystem_t (C++ class), 314
 - fs_filesystem_t::name_p (C++ member), 315
 - fs_filesystem_t::next_p (C++ member), 315
 - fs_filesystem_t::ops_p (C++ member), 315
 - fs_filesystem_t::type (C++ member), 315
 - fs_format (C++ function), 311
 - fs_list (C++ function), 311
 - fs_ls (C++ function), 311
 - fs_merge (C++ function), 312
 - fs_mkdir (C++ function), 311
 - fs_module_init (C++ function), 308
 - fs_open (C++ function), 308
 - fs_parameter_deregister (C++ function), 314
 - fs_parameter_int_print (C++ function), 314
 - fs_parameter_int_set (C++ function), 314
 - fs_parameter_print_callback_t (C++ type), 307
 - fs_parameter_register (C++ function), 314
 - fs_parameter_set_callback_t (C++ type), 307
 - fs_parameter_t (C++ class), 315
 - fs_parameter_t::command (C++ member), 316
 - fs_parameter_t::next_p (C++ member), 316
 - fs_parameter_t::print_cb (C++ member), 316
 - fs_parameter_t::set_cb (C++ member), 316
 - fs_parameter_t::value_p (C++ member), 316
 - FS_RDWR (C macro), 307
 - FS_READ (C macro), 306
 - fs_read (C++ function), 309
 - fs_read_line (C++ function), 309
 - fs_remove (C++ function), 310
 - fs_seek (C++ function), 309
 - FS_SEEK_CUR (C macro), 306
 - FS_SEEK_END (C macro), 306
 - FS_SEEK_SET (C macro), 306
 - fs_split (C++ function), 311
 - fs_stat (C++ function), 310
 - fs_stat_t (C++ class), 315
 - fs_stat_t::size (C++ member), 315
 - fs_stat_t::type (C++ member), 315
 - FS_SYNC (C macro), 307
 - fs_tell (C++ function), 310
 - FS_TRUNC (C macro), 307
 - FS_TYPE_DIR (C macro), 307
 - fs_type_fat16_t (C++ class), 308
 - FS_TYPE_FILE (C macro), 307
 - fs_type_generic_t (C++ class), 308
 - FS_TYPE_HARD_LINK (C macro), 307
 - FS_TYPE_SOFT_LINK (C macro), 307
 - fs_type_spiffs_t (C++ class), 308
 - fs_type_t (C++ type), 308
 - FS_WRITE (C macro), 306
 - fs_write (C++ function), 309
- ## H
- harness (module), 380
 - harness_expect (C++ function), 383
 - harness_init (C++ function), 383
 - harness_mock_read (C++ function), 384
 - harness_mock_write (C++ function), 383
 - harness_run (C++ function), 383
 - harness_t (C++ class), 384
 - harness_t::uart (C++ member), 384
 - harness_testcase_cb_t (C++ type), 383
 - harness_testcase_t (C++ class), 384
 - harness_testcase_t::callback (C++ member), 384
 - harness_testcase_t::name_p (C++ member), 384
 - hash_function_t (C++ type), 395
 - hash_map (module), 395

[hash_map_add \(C++ function\), 395](#)
[hash_map_bucket_t \(C++ class\), 396](#)
[hash_map_bucket_t::list_p \(C++ member\), 396](#)
[hash_map_entry_t \(C++ class\), 396](#)
[hash_map_entry_t::key \(C++ member\), 396](#)
[hash_map_entry_t::next_p \(C++ member\), 396](#)
[hash_map_entry_t::value_p \(C++ member\), 396](#)
[hash_map_get \(C++ function\), 395](#)
[hash_map_init \(C++ function\), 395](#)
[hash_map_remove \(C++ function\), 395](#)
[hash_map_t \(C++ class\), 396](#)
[hash_map_t::buckets_max \(C++ member\), 396](#)
[hash_map_t::buckets_p \(C++ member\), 396](#)
[hash_map_t::entries_p \(C++ member\), 396](#)
[hash_map_t::hash \(C++ member\), 396](#)
[heap \(module\), 401](#)
[heap_alloc \(C++ function\), 401](#)
[heap_dynamic_t \(C++ class\), 402](#)
[heap_dynamic_t::free_p \(C++ member\), 402](#)
[HEAP_FIXED_SIZES_MAX \(C macro\), 401](#)
[heap_fixed_t \(C++ class\), 402](#)
[heap_fixed_t::free_p \(C++ member\), 402](#)
[heap_fixed_t::size \(C++ member\), 402](#)
[heap_free \(C++ function\), 401](#)
[heap_init \(C++ function\), 401](#)
[heap_share \(C++ function\), 401](#)
[heap_t \(C++ class\), 402](#)
[heap_t::buf_p \(C++ member\), 402](#)
[heap_t::dynamic \(C++ member\), 402](#)
[heap_t::fixed \(C++ member\), 402](#)
[heap_t::next_p \(C++ member\), 402](#)
[heap_t::size \(C++ member\), 402](#)
[http_server \(module\), 330](#)
[http_server_connection_state_allocated_t \(C++ class\), 331](#)
[http_server_connection_state_free_t \(C++ class\), 331](#)
[http_server_connection_state_t \(C++ type\), 331](#)
[http_server_connection_t \(C++ class\), 333](#)
[http_server_connection_t::buf_p \(C++ member\), 333](#)
[http_server_connection_t::chan_p \(C++ member\), 333](#)
[http_server_connection_t::events \(C++ member\), 333](#)
[http_server_connection_t::id_p \(C++ member\), 333](#)
[http_server_connection_t::name_p \(C++ member\), 333](#)
[http_server_connection_t::self_p \(C++ member\), 333](#)
[http_server_connection_t::size \(C++ member\), 333](#)
[http_server_connection_t::socket \(C++ member\), 333](#)
[http_server_connection_t::state \(C++ member\), 333](#)
[http_server_content_type_t \(C++ type\), 330](#)
[http_server_content_type_text_html_t \(C++ class\), 330](#)
[http_server_content_type_text_plain_t \(C++ class\), 330](#)
[http_server_init \(C++ function\), 331](#)
[http_server_listener_t \(C++ class\), 333](#)
[http_server_listener_t::address_p \(C++ member\), 333](#)
[http_server_listener_t::buf_p \(C++ member\), 333](#)
[http_server_listener_t::id_p \(C++ member\), 333](#)
[http_server_listener_t::name_p \(C++ member\), 333](#)
[http_server_listener_t::port \(C++ member\), 333](#)
[http_server_listener_t::size \(C++ member\), 333](#)
[http_server_listener_t::socket \(C++ member\), 333](#)
[http_server_request_action_get_t \(C++ class\), 330](#)
[http_server_request_action_post_t \(C++ class\), 330](#)
[http_server_request_action_t \(C++ type\), 330](#)
[http_server_request_t \(C++ class\), 332](#)
[http_server_request_t::action \(C++ member\), 332](#)
[http_server_request_t::path \(C++ member\), 332](#)
[http_server_request_t::present \(C++ member\), 332](#)
[http_server_request_t::value \(C++ member\), 332](#)
[http_server_response_code_200_ok_t \(C++ class\), 330](#)
[http_server_response_code_400_bad_request_t \(C++ class\), 331](#)
[http_server_response_code_401_unauthorized_t \(C++ class\), 331](#)
[http_server_response_code_404_not_found_t \(C++ class\), 331](#)
[http_server_response_code_t \(C++ type\), 330](#)
[http_server_response_t \(C++ class\), 332](#)
[http_server_response_t::buf_p \(C++ member\), 333](#)
[http_server_response_t::code \(C++ member\), 333](#)
[http_server_response_t::size \(C++ member\), 333](#)
[http_server_response_t::type \(C++ member\), 333](#)
[http_server_response_write \(C++ function\), 332](#)
[http_server_route_callback_t \(C++ type\), 330](#)
[http_server_route_t \(C++ class\), 333](#)
[http_server_route_t::callback \(C++ member\), 334](#)
[http_server_route_t::path_p \(C++ member\), 334](#)
[http_server_start \(C++ function\), 331](#)
[http_server_stop \(C++ function\), 331](#)
[http_server_t \(C++ class\), 334](#)
[http_server_t::connections_p \(C++ member\), 334](#)
[http_server_t::events \(C++ member\), 334](#)
[http_server_t::listener_p \(C++ member\), 334](#)
[http_server_t::on_no_route \(C++ member\), 334](#)
[http_server_t::root_path_p \(C++ member\), 334](#)
[http_server_t::routes_p \(C++ member\), 334](#)
[http_server_t::ssl_context_p \(C++ member\), 334](#)
[http_server_wrap_ssl \(C++ function\), 331](#)
[http_websocket_client \(module\), 334](#)
[http_websocket_client_connect \(C++ function\), 334](#)
[http_websocket_client_disconnect \(C++ function\), 335](#)
[http_websocket_client_init \(C++ function\), 334](#)
[http_websocket_client_read \(C++ function\), 335](#)
[http_websocket_client_t \(C++ class\), 335](#)
[http_websocket_client_t::host_p \(C++ member\), 335](#)
[http_websocket_client_t::left \(C++ member\), 335](#)
[http_websocket_client_t::path_p \(C++ member\), 335](#)
[http_websocket_client_t::port \(C++ member\), 335](#)
[http_websocket_client_t::socket \(C++ member\), 335](#)
[http_websocket_client_write \(C++ function\), 335](#)

http_websocket_server (module), 336
 http_websocket_server_handshake (C++ function), 336
 http_websocket_server_init (C++ function), 336
 http_websocket_server_read (C++ function), 336
 http_websocket_server_t (C++ class), 337
 http_websocket_server_t::socket_p (C++ member), 337
 http_websocket_server_write (C++ function), 336
 huzzah (module), 437

I

i2c (module), 240
 i2c_0_dev (C macro), 430–433, 449, 451
 i2c_1_dev (C macro), 449, 451
 I2C_BAUDRATE_100KBPS (C macro), 240
 I2C_BAUDRATE_1MBPS (C macro), 240
 I2C_BAUDRATE_3_2MBPS (C macro), 240
 I2C_BAUDRATE_400KBPS (C macro), 240
 i2c_dev (C macro), 436, 440, 442
 i2c_device (C++ member), 242
 I2C_DEVICE_MAX (C macro), 453–457
 i2c_init (C++ function), 240
 i2c_module_init (C++ function), 240
 i2c_read (C++ function), 241
 i2c_scan (C++ function), 241
 i2c_slave_read (C++ function), 242
 i2c_slave_start (C++ function), 241
 i2c_slave_stop (C++ function), 242
 i2c_slave_write (C++ function), 242
 i2c_soft (module), 242
 i2c_soft_driver_t (C++ class), 244
 i2c_soft_driver_t::baudrate (C++ member), 244
 i2c_soft_driver_t::baudrate_us (C++ member), 244
 i2c_soft_driver_t::clock_stretching_sleep_us (C++ member), 244
 i2c_soft_driver_t::max_clock_stretching_us (C++ member), 244
 i2c_soft_driver_t::scl_p (C++ member), 244
 i2c_soft_driver_t::sda_p (C++ member), 244
 i2c_soft_init (C++ function), 243
 i2c_soft_module_init (C++ function), 243
 i2c_soft_read (C++ function), 243
 i2c_soft_scan (C++ function), 244
 i2c_soft_start (C++ function), 243
 i2c_soft_stop (C++ function), 243
 i2c_soft_write (C++ function), 244
 i2c_start (C++ function), 240
 i2c_stop (C++ function), 241
 i2c_write (C++ function), 241
 inet (module), 337
 inet_addr_t (C++ class), 338
 inet_addr_t::ip (C++ member), 338
 inet_addr_t::port (C++ member), 338
 inet_aton (C++ function), 337
 inet_checksum (C++ function), 338

inet_if_ip_info_t (C++ class), 338
 inet_if_ip_info_t::address (C++ member), 338
 inet_if_ip_info_t::gateway (C++ member), 338
 inet_if_ip_info_t::netmask (C++ member), 338
 inet_ip_addr_t (C++ class), 338
 inet_ip_addr_t::number (C++ member), 338
 inet_module_init (C++ function), 337
 inet_ntoa (C++ function), 337
 IS_FATAL (C macro), 178
 isotp (module), 338
 ISOTP_FLAGS_NO_FLOW_CONTROL (C macro), 338
 isotp_init (C++ function), 339
 isotp_input (C++ function), 339
 isotp_output (C++ function), 339
 isotp_t (C++ class), 339
 isotp_t::flags (C++ member), 339
 isotp_t::message_p (C++ member), 339
 isotp_t::next_index (C++ member), 340
 isotp_t::offset (C++ member), 340
 isotp_t::size (C++ member), 339
 isotp_t::state (C++ member), 339

J

json (module), 412
 JSON_ARRAY (C++ class), 412
 json_array_get (C++ function), 414
 json_dump (C++ function), 414
 json_dumps (C++ function), 413
 json_err_t (C++ type), 413
 JSON_ERROR_INVALID (C++ class), 413
 JSON_ERROR_NOMEM (C++ class), 413
 JSON_ERROR_PART (C++ class), 413
 json_init (C++ function), 413
 JSON_OBJECT (C++ class), 412
 json_object_get (C++ function), 414
 json_object_get_primitive (C++ function), 414
 json_parse (C++ function), 413
 JSON_PRIMITIVE (C++ class), 413
 json_root (C++ function), 414
 JSON_STRING (C++ class), 413
 json_t (C++ class), 416
 json_t::num_tokens (C++ member), 416
 json_t::pos (C++ member), 416
 json_t::tokens_p (C++ member), 416
 json_t::toknext (C++ member), 416
 json_t::toksuper (C++ member), 416
 json_tok_t (C++ class), 416
 json_tok_t::buf_p (C++ member), 416
 json_tok_t::num_tokens (C++ member), 416
 json_tok_t::size (C++ member), 416
 json_tok_t::type (C++ member), 416
 json_token_array (C++ function), 415
 json_token_false (C++ function), 415
 json_token_null (C++ function), 415

json_token_number (C++ function), 415
json_token_object (C++ function), 415
json_token_string (C++ function), 415
json_token_true (C++ function), 415
json_type_t (C++ type), 412
JSON_UNDEFINED (C++ class), 412

L

led_7seg_ht16k33 (module), 244
led_7seg_ht16k33_brightness (C++ function), 246
LED_7SEG_HT16K33_BRIGHTNESS_MAX (C macro), 245
LED_7SEG_HT16K33_BRIGHTNESS_MIN (C macro), 245
led_7seg_ht16k33_clear (C++ function), 245
LED_7SEG_HT16K33_DEFAULT_I2C_ADDR (C macro), 245
led_7seg_ht16k33_display (C++ function), 245
led_7seg_ht16k33_driver_t (C++ class), 246
led_7seg_ht16k33_driver_t::buf (C++ member), 247
led_7seg_ht16k33_driver_t::i2c_addr (C++ member), 247
led_7seg_ht16k33_driver_t::i2c_p (C++ member), 247
led_7seg_ht16k33_init (C++ function), 245
led_7seg_ht16k33_module_init (C++ function), 245
led_7seg_ht16k33_set_num (C++ function), 246
led_7seg_ht16k33_show_colon (C++ function), 246
led_7seg_ht16k33_show_dot (C++ function), 246
led_7seg_ht16k33_start (C++ function), 245
linux (module), 438, 455
list (module), 396
list_next_t (C++ class), 398
list_next_t::next_p (C++ member), 398
list_singly_linked_t (C++ class), 398
list_singly_linked_t::head_p (C++ member), 398
list_singly_linked_t::tail_p (C++ member), 398
LIST_SL_ADD_HEAD (C macro), 397
LIST_SL_ADD_TAIL (C macro), 397
LIST_SL_INIT (C macro), 396
LIST_SL_INIT_STRUCT (C macro), 396
LIST_SL_ITERATOR_INIT (C macro), 397
LIST_SL_ITERATOR_NEXT (C macro), 397
list_sl_iterator_t (C++ class), 398
list_sl_iterator_t::next_p (C++ member), 398
LIST_SL_PEEK_HEAD (C macro), 396
LIST_SL_REMOVE_ELEM (C macro), 398
LIST_SL_REMOVE_HEAD (C macro), 397
log (module), 384
log_add_handler (C++ function), 388
log_add_object (C++ function), 388
LOG_ALL (C macro), 386
LOG_DEBUG (C macro), 386
LOG_ERROR (C macro), 386
LOG_FATAL (C macro), 386

log_handler_init (C++ function), 387
log_handler_t (C++ class), 388
log_handler_t::chout_p (C++ member), 389
log_handler_t::next_p (C++ member), 389
LOG_INFO (C macro), 386
LOG_MASK (C macro), 386
log_module_init (C++ function), 386
LOG_NONE (C macro), 386
log_object_get_log_mask (C++ function), 387
log_object_init (C++ function), 386
log_object_is_enabled_for (C++ function), 387
log_object_print (C++ function), 387
log_object_set_log_mask (C++ function), 387
log_object_t (C++ class), 389
log_object_t::mask (C++ member), 389
log_object_t::name_p (C++ member), 389
log_object_t::next_p (C++ member), 389
log_remove_handler (C++ function), 388
log_remove_object (C++ function), 388
log_set_default_handler_output_channel (C++ function), 388
LOG_UPTO (C macro), 386
LOG_WARNING (C macro), 386

M

maple_esp32 (module), 439
MAX (C macro), 202
mbr_t (C++ class), 302
mbr_t::codeArea (C++ member), 302
mbr_t::diskSignature (C++ member), 302
mbr_t::mbr_sig (C++ member), 302
mbr_t::part (C++ member), 302
mbr_t::usuallyZero (C++ member), 302
mcp2515 (module), 247
mcp2515_driver_t (C++ class), 248
mcp2515_driver_t::chin_p (C++ member), 249
mcp2515_driver_t::chout (C++ member), 249
mcp2515_driver_t::exti (C++ member), 248
mcp2515_driver_t::isr_sem (C++ member), 249
mcp2515_driver_t::mode (C++ member), 248
mcp2515_driver_t::speed (C++ member), 248
mcp2515_driver_t::spi (C++ member), 248
mcp2515_driver_t::tx_sem (C++ member), 249
mcp2515_frame_t (C++ class), 248
mcp2515_frame_t::data (C++ member), 248
mcp2515_frame_t::id (C++ member), 248
mcp2515_frame_t::rtr (C++ member), 248
mcp2515_frame_t::size (C++ member), 248
mcp2515_frame_t::timestamp (C++ member), 248
mcp2515_init (C++ function), 247
MCP2515_MODE_LOOPBACK (C macro), 247
MCP2515_MODE_NORMAL (C macro), 247
mcp2515_read (C++ function), 248
MCP2515_SPEED_1000KBPS (C macro), 247

-
- MCP2515_SPEED_500KBPS (C macro), 247
 - mcp2515_start (C++ function), 247
 - mcp2515_stop (C++ function), 247
 - mcp2515_write (C++ function), 248
 - MEASUREMENT_DURATION_HIGH_MS (C macro), 266
 - membersof (C macro), 201
 - midi (module), 419
 - MIDI_BAUDRATE (C macro), 419
 - MIDI_CHANNEL_PRESSURE (C macro), 419
 - MIDI_CONTROL_CHANGE (C macro), 419
 - MIDI_NOTE_A0 (C macro), 419
 - MIDI_NOTE_A1 (C macro), 419
 - MIDI_NOTE_A2 (C macro), 420
 - MIDI_NOTE_A3 (C macro), 420
 - MIDI_NOTE_A4 (C macro), 420
 - MIDI_NOTE_A5 (C macro), 420
 - MIDI_NOTE_A6 (C macro), 420
 - MIDI_NOTE_A7 (C macro), 421
 - MIDI_NOTE_B0 (C macro), 419
 - MIDI_NOTE_B1 (C macro), 420
 - MIDI_NOTE_B2 (C macro), 420
 - MIDI_NOTE_B3 (C macro), 420
 - MIDI_NOTE_B4 (C macro), 420
 - MIDI_NOTE_B5 (C macro), 420
 - MIDI_NOTE_B6 (C macro), 420
 - MIDI_NOTE_B7 (C macro), 421
 - MIDI_NOTE_C1 (C macro), 419
 - MIDI_NOTE_C2 (C macro), 420
 - MIDI_NOTE_C3 (C macro), 420
 - MIDI_NOTE_C4 (C macro), 420
 - MIDI_NOTE_C5 (C macro), 420
 - MIDI_NOTE_C6 (C macro), 420
 - MIDI_NOTE_C7 (C macro), 421
 - MIDI_NOTE_C8 (C macro), 421
 - MIDI_NOTE_D1 (C macro), 419
 - MIDI_NOTE_D2 (C macro), 420
 - MIDI_NOTE_D3 (C macro), 420
 - MIDI_NOTE_D4 (C macro), 420
 - MIDI_NOTE_D5 (C macro), 420
 - MIDI_NOTE_D6 (C macro), 420
 - MIDI_NOTE_D7 (C macro), 421
 - MIDI_NOTE_E1 (C macro), 419
 - MIDI_NOTE_E2 (C macro), 420
 - MIDI_NOTE_E3 (C macro), 420
 - MIDI_NOTE_E4 (C macro), 420
 - MIDI_NOTE_E5 (C macro), 420
 - MIDI_NOTE_E6 (C macro), 420
 - MIDI_NOTE_E7 (C macro), 421
 - MIDI_NOTE_F1 (C macro), 419
 - MIDI_NOTE_F2 (C macro), 420
 - MIDI_NOTE_F3 (C macro), 420
 - MIDI_NOTE_F4 (C macro), 420
 - MIDI_NOTE_F5 (C macro), 420
 - MIDI_NOTE_F6 (C macro), 420
 - MIDI_NOTE_F7 (C macro), 421
 - MIDI_NOTE_G1 (C macro), 419
 - MIDI_NOTE_G2 (C macro), 420
 - MIDI_NOTE_G3 (C macro), 420
 - MIDI_NOTE_G4 (C macro), 420
 - MIDI_NOTE_G5 (C macro), 420
 - MIDI_NOTE_G6 (C macro), 420
 - MIDI_NOTE_G7 (C macro), 421
 - MIDI_NOTE_MAX (C macro), 419
 - MIDI_NOTE_OFF (C macro), 419
 - MIDI_NOTE_ON (C macro), 419
 - midi_note_to_frequency (C++ function), 422
 - MIDI_PERC (C macro), 419
 - MIDI_PERC_ACOUSTIC_BASS_DRUM (C macro), 421
 - MIDI_PERC_ACOUSTIC_SNARE (C macro), 421
 - MIDI_PERC_BASS_DRUM_1 (C macro), 421
 - MIDI_PERC_CABASA (C macro), 422
 - MIDI_PERC_CHINESE_CYMBAL (C macro), 421
 - MIDI_PERC_CLAVES (C macro), 422
 - MIDI_PERC_CLOSED_HI_HAT (C macro), 421
 - MIDI_PERC_COWBELL (C macro), 421
 - MIDI_PERC_CRASH_CYMBAL_1 (C macro), 421
 - MIDI_PERC_CRASH_CYMBAL_2 (C macro), 421
 - MIDI_PERC_ELECTRIC_SNARE (C macro), 421
 - MIDI_PERC_HAND_CLAP (C macro), 421
 - MIDI_PERC_HI_BONGO (C macro), 421
 - MIDI_PERC_HI_MID_TOM (C macro), 421
 - MIDI_PERC_HI_WOOD_BLOCK (C macro), 422
 - MIDI_PERC_HIGH_AGOGO (C macro), 422
 - MIDI_PERC_HIGH_FLOOR_TOM (C macro), 421
 - MIDI_PERC_HIGH_TIMBALE (C macro), 422
 - MIDI_PERC_HIGH_TOM (C macro), 421
 - MIDI_PERC_LONG_GUIRO (C macro), 422
 - MIDI_PERC_LONG_WHISTLE (C macro), 422
 - MIDI_PERC_LOW_AGOGO (C macro), 422
 - MIDI_PERC_LOW_BONGO (C macro), 421
 - MIDI_PERC_LOW_CONGA (C macro), 422
 - MIDI_PERC_LOW_FLOOR_TOM (C macro), 421
 - MIDI_PERC_LOW_MID_TOM (C macro), 421
 - MIDI_PERC_LOW_TIMBALE (C macro), 422
 - MIDI_PERC_LOW_TOM (C macro), 421
 - MIDI_PERC_LOW_WOOD_BLOCK (C macro), 422
 - MIDI_PERC_MARACAS (C macro), 422
 - MIDI_PERC_MUTE_CUICA (C macro), 422
 - MIDI_PERC_MUTE_HI_CONGA (C macro), 421
 - MIDI_PERC_MUTE_TRIANGLE (C macro), 422
 - MIDI_PERC_OPEN_CUICA (C macro), 422
 - MIDI_PERC_OPEN_HI_CONGA (C macro), 422
 - MIDI_PERC_OPEN_HI_HAT (C macro), 421
 - MIDI_PERC_OPEN_TRIANGLE (C macro), 422
 - MIDI_PERC_PEDAL_HI_HAT (C macro), 421
 - MIDI_PERC_RIDE_BELL (C macro), 421

MIDI_PERC_RIDE_CYMBAL_1 (C macro), 421
 MIDI_PERC_RIDE_CYMBAL_2 (C macro), 421
 MIDI_PERC_SHORT_GUIRO (C macro), 422
 MIDI_PERC_SHORT_WHISTLE (C macro), 422
 MIDI_PERC_SIDE_STICK (C macro), 421
 MIDI_PERC_SPLASH_CYMBAL (C macro), 421
 MIDI_PERC_TAMBOURINE (C macro), 421
 MIDI_PERC_VIBRASLAP (C macro), 421
 MIDI_PITCH_BEND_CHANGE (C macro), 419
 MIDI_POLYPHONIC_KEY_PRESSURE (C macro), 419
 MIDI_PROGRAM_CHANGE (C macro), 419
 MIDI_SET_INTRUMENT (C macro), 419
 MIN (C macro), 202
 mqtt_application_message_t (C++ class), 344
 mqtt_application_message_t::buf_p (C++ member), 344
 mqtt_application_message_t::qos (C++ member), 344
 mqtt_application_message_t::size (C++ member), 344
 mqtt_client (module), 340
 mqtt_client_connect (C++ function), 342
 mqtt_client_disconnect (C++ function), 342
 mqtt_client_init (C++ function), 342
 mqtt_client_main (C++ function), 342
 mqtt_client_ping (C++ function), 342
 mqtt_client_publish (C++ function), 343
 mqtt_client_state_connected_t (C++ class), 341
 mqtt_client_state_connecting_t (C++ class), 341
 mqtt_client_state_disconnected_t (C++ class), 341
 mqtt_client_state_t (C++ type), 341
 mqtt_client_subscribe (C++ function), 343
 mqtt_client_t (C++ class), 343
 mqtt_client_t::data_p (C++ member), 343
 mqtt_client_t::in (C++ member), 344
 mqtt_client_t::in_p (C++ member), 343
 mqtt_client_t::log_object_p (C++ member), 343
 mqtt_client_t::name_p (C++ member), 343
 mqtt_client_t::on_error (C++ member), 344
 mqtt_client_t::on_publish (C++ member), 344
 mqtt_client_t::out (C++ member), 344
 mqtt_client_t::out_p (C++ member), 343
 mqtt_client_t::state (C++ member), 343
 mqtt_client_t::type (C++ member), 343
 mqtt_client_unsubscribe (C++ function), 343
 mqtt_on_error_t (C++ type), 341
 mqtt_on_publish_t (C++ type), 341
 mqtt_qos_0_t (C++ class), 341
 mqtt_qos_1_t (C++ class), 341
 mqtt_qos_2_t (C++ class), 341
 mqtt_qos_t (C++ type), 341

N

nano32 (module), 441
 network_interface (module), 344
 network_interface_add (C++ function), 349

network_interface_driver_esp (module), 346
 network_interface_get_by_name (C++ function), 350
 network_interface_get_ip_info (C++ function), 350
 network_interface_get_ip_info_t (C++ type), 349
 network_interface_is_up (C++ function), 349
 network_interface_is_up_t (C++ type), 349
 network_interface_module_init (C++ function), 349
 network_interface_set_ip_info (C++ function), 350
 network_interface_set_ip_info_t (C++ type), 349
 network_interface_slip (module), 344
 NETWORK_INTERFACE_SLIP_FRAME_SIZE_MAX (C macro), 344
 network_interface_slip_init (C++ function), 345
 network_interface_slip_input (C++ function), 345
 network_interface_slip_module_init (C++ function), 345
 NETWORK_INTERFACE_SLIP_STATE_ESCAPE (C++ class), 345
 NETWORK_INTERFACE_SLIP_STATE_NORMAL (C++ class), 345
 network_interface_slip_state_t (C++ type), 345
 network_interface_slip_t (C++ class), 345
 network_interface_slip_t::buf_p (C++ member), 345
 network_interface_slip_t::chout_p (C++ member), 346
 network_interface_slip_t::network_interface (C++ member), 346
 network_interface_slip_t::pbuf_p (C++ member), 345
 network_interface_slip_t::size (C++ member), 345
 network_interface_slip_t::state (C++ member), 345
 network_interface_start (C++ function), 349
 network_interface_start_t (C++ type), 349
 network_interface_stop (C++ function), 349
 network_interface_stop_t (C++ type), 349
 network_interface_t (C++ class), 350
 network_interface_t::get_ip_info (C++ member), 350
 network_interface_t::info (C++ member), 350
 network_interface_t::is_up (C++ member), 350
 network_interface_t::name_p (C++ member), 350
 network_interface_t::netif_p (C++ member), 350
 network_interface_t::next_p (C++ member), 350
 network_interface_t::set_ip_info (C++ member), 350
 network_interface_t::start (C++ member), 350
 network_interface_t::stop (C++ member), 350
 network_interface_wifi (module), 346
 network_interface_wifi_driver_esp_softap (C++ member), 346
 network_interface_wifi_driver_esp_station (C++ member), 346
 network_interface_wifi_driver_t (C++ class), 348
 network_interface_wifi_driver_t::get_ip_info (C++ member), 348
 network_interface_wifi_driver_t::init (C++ member), 348
 network_interface_wifi_driver_t::is_up (C++ member), 348

network_interface_wifi_driver_t::set_ip_info (C++ member), 348
network_interface_wifi_driver_t::start (C++ member), 348
network_interface_wifi_driver_t::stop (C++ member), 348
network_interface_wifi_get_ip_info (C++ function), 347
network_interface_wifi_init (C++ function), 346
network_interface_wifi_is_up (C++ function), 347
network_interface_wifi_module_init (C++ function), 346
network_interface_wifi_set_ip_info (C++ function), 347
network_interface_wifi_start (C++ function), 347
network_interface_wifi_stop (C++ function), 347
network_interface_wifi_t (C++ class), 347
network_interface_wifi_t::arg_p (C++ member), 348
network_interface_wifi_t::driver_p (C++ member), 348
network_interface_wifi_t::info_p (C++ member), 348
network_interface_wifi_t::network_interface (C++ member), 348
network_interface_wifi_t::password_p (C++ member), 348
network_interface_wifi_t::ssid_p (C++ member), 348
nodemcu (module), 443
nrf24l01 (module), 249
nrf24l01_driver_t (C++ class), 250
nrf24l01_driver_t::address (C++ member), 250
nrf24l01_driver_t::ce (C++ member), 250
nrf24l01_driver_t::chin (C++ member), 250
nrf24l01_driver_t::chinbuf (C++ member), 250
nrf24l01_driver_t::exti (C++ member), 250
nrf24l01_driver_t::irqbuf (C++ member), 250
nrf24l01_driver_t::irqchan (C++ member), 250
nrf24l01_driver_t::spi (C++ member), 250
nrf24l01_driver_t::stack (C++ member), 250
nrf24l01_driver_t::thrd_p (C++ member), 250
nrf24l01_init (C++ function), 249
nrf24l01_module_init (C++ function), 249
nrf24l01_read (C++ function), 250
nrf24l01_start (C++ function), 249
nrf24l01_stop (C++ function), 249
nrf24l01_write (C++ function), 250
nvm (module), 363
nvm_format (C++ function), 364
nvm_module_init (C++ function), 364
nvm_mount (C++ function), 364
nvm_read (C++ function), 364
nvm_write (C++ function), 364

O

O_APPEND (C macro), 295
O_CREAT (C macro), 295
O_EXCL (C macro), 295
O_RDONLY (C macro), 295
O_RDWR (C macro), 295

O_READ (C macro), 295
O_SYNC (C macro), 295
O_TRUNC (C macro), 295
O_WRITE (C macro), 295
O_WRONLY (C macro), 295
OSTR (C macro), 202
owi (module), 251
OWI_ALARM_SEARCH (C macro), 251
owi_device_t (C++ class), 252
owi_device_t::id (C++ member), 252
owi_driver_t (C++ class), 252
owi_driver_t::devices_p (C++ member), 252
owi_driver_t::len (C++ member), 252
owi_driver_t::nmemb (C++ member), 252
owi_driver_t::pin (C++ member), 252
owi_init (C++ function), 251
OWI_MATCH_ROM (C macro), 251
owi_read (C++ function), 251
OWI_READ_ROM (C macro), 251
owi_reset (C++ function), 251
owi_search (C++ function), 251
OWI_SEARCH_ROM (C macro), 251
OWI_SKIP_ROM (C macro), 251
owi_write (C++ function), 252

P

PACKED (C++ member), 262, 299
PANIC_ASSERT (C macro), 179
PANIC_ASSERTN (C macro), 179
part_t (C++ class), 300
part_t::begin_cylinder_high (C++ member), 300
part_t::begin_cylinder_low (C++ member), 300
part_t::begin_head (C++ member), 300
part_t::begin_sector (C++ member), 300
part_t::boot (C++ member), 300
part_t::end_cylinder_high (C++ member), 300
part_t::end_cylinder_low (C++ member), 300
part_t::end_head (C++ member), 300
part_t::end_sector (C++ member), 300
part_t::first_sector (C++ member), 300
part_t::total_sectors (C++ member), 300
part_t::type (C++ member), 300
photon (module), 444
pin (module), 252
pin_a0_dev (C macro), 424, 429, 430, 432, 433, 435, 436, 438, 440, 442–444, 452
pin_a10_dev (C macro), 424, 429
pin_a11_dev (C macro), 424, 429
pin_a12_dev (C macro), 429
pin_a13_dev (C macro), 429
pin_a14_dev (C macro), 429
pin_a15_dev (C macro), 429
pin_a1_dev (C macro), 424, 429, 430, 432, 433, 438, 444
pin_a2_dev (C macro), 424, 429, 430, 432, 433, 438, 444

[pin_a3_dev](#) (C macro), 424, 429, 430, 432, 433, 436, 438, 440, 442, 444
[pin_a4_dev](#) (C macro), 424, 429, 430, 433, 436, 438, 440, 442, 444
[pin_a5_dev](#) (C macro), 424, 429, 430, 433, 436, 439, 440, 442, 444
[pin_a6_dev](#) (C macro), 424, 429, 436, 439, 440, 442
[pin_a7_dev](#) (C macro), 424, 429, 436, 439, 440, 442
[pin_a8_dev](#) (C macro), 424, 429
[pin_a9_dev](#) (C macro), 424, 429
[pin_d0_dev](#) (C macro), 423, 427, 434, 437, 443, 444, 452
[pin_d10_dev](#) (C macro), 423, 427, 430, 431, 433, 438, 443
[pin_d11_dev](#) (C macro), 423, 427, 430, 433, 438
[pin_d12_dev](#) (C macro), 423, 427, 430, 433, 435, 437, 438
[pin_d13_dev](#) (C macro), 423, 427, 430, 433, 435, 437, 438
[pin_d14_dev](#) (C macro), 423, 428, 431, 435, 437
[pin_d15_dev](#) (C macro), 423, 428, 431, 435, 437
[pin_d16_dev](#) (C macro), 423, 428, 431, 435, 437
[pin_d17_dev](#) (C macro), 423, 428
[pin_d18_dev](#) (C macro), 423, 428
[pin_d19_dev](#) (C macro), 423, 428
[pin_d1_dev](#) (C macro), 423, 427, 434, 443, 444, 452
[pin_d20_dev](#) (C macro), 423, 428
[pin_d21_dev](#) (C macro), 423, 428
[pin_d22_dev](#) (C macro), 423, 428
[pin_d23_dev](#) (C macro), 423, 428
[pin_d24_dev](#) (C macro), 423, 428
[pin_d25_dev](#) (C macro), 423, 428
[pin_d26_dev](#) (C macro), 423, 428
[pin_d27_dev](#) (C macro), 423, 428
[pin_d28_dev](#) (C macro), 423, 428
[pin_d29_dev](#) (C macro), 423, 428
[pin_d2_dev](#) (C macro), 423, 427, 430–432, 434, 437, 438, 443, 444, 452
[pin_d30_dev](#) (C macro), 423, 428
[pin_d31_dev](#) (C macro), 423, 428
[pin_d32_dev](#) (C macro), 423, 428
[pin_d33_dev](#) (C macro), 423, 428
[pin_d34_dev](#) (C macro), 423, 428
[pin_d35_dev](#) (C macro), 424, 428
[pin_d36_dev](#) (C macro), 424, 428
[pin_d37_dev](#) (C macro), 424, 428
[pin_d38_dev](#) (C macro), 424, 428
[pin_d39_dev](#) (C macro), 424, 428
[pin_d3_dev](#) (C macro), 423, 427, 430–432, 438, 443, 444, 452
[pin_d40_dev](#) (C macro), 424, 428
[pin_d41_dev](#) (C macro), 424, 428
[pin_d42_dev](#) (C macro), 424, 428
[pin_d43_dev](#) (C macro), 424, 428
[pin_d44_dev](#) (C macro), 424, 428
[pin_d45_dev](#) (C macro), 424, 428
[pin_d46_dev](#) (C macro), 424, 428
[pin_d47_dev](#) (C macro), 424, 428
[pin_d48_dev](#) (C macro), 424, 428
[pin_d49_dev](#) (C macro), 424, 428
[pin_d4_dev](#) (C macro), 423, 427, 430–432, 434, 437, 438, 443, 444, 452
[pin_d50_dev](#) (C macro), 424, 429
[pin_d51_dev](#) (C macro), 424, 429
[pin_d52_dev](#) (C macro), 424, 429
[pin_d53_dev](#) (C macro), 424, 429
[pin_d5_dev](#) (C macro), 423, 427, 430–432, 435, 437, 438, 443, 444, 452
[pin_d6_dev](#) (C macro), 423, 427, 430–432, 438, 443, 444, 452
[pin_d7_dev](#) (C macro), 423, 427, 430–432, 438, 443, 444, 452
[pin_d8_dev](#) (C macro), 423, 427, 430–432, 438, 443, 452
[pin_d9_dev](#) (C macro), 423, 427, 430–432, 438, 443
[pin_dac0_dev](#) (C macro), 424, 439, 444
[pin_dac1_dev](#) (C macro), 424, 436, 439, 440, 442, 444
[pin_dac2_dev](#) (C macro), 436, 440, 442
[pin_device](#) (C++ member), 255
[PIN_DEVICE_BASE](#) (C macro), 438
[PIN_DEVICE_MAX](#) (C macro), 453–457
[pin_device_read](#) (C++ function), 254
[pin_device_set_mode](#) (C++ function), 254
[pin_device_write_high](#) (C++ function), 254
[pin_device_write_low](#) (C++ function), 254
[pin_gpio00_dev](#) (C macro), 435, 439, 441
[pin_gpio01_dev](#) (C macro), 435, 439, 441
[pin_gpio02_dev](#) (C macro), 435, 439, 441
[pin_gpio03_dev](#) (C macro), 435, 439, 441
[pin_gpio04_dev](#) (C macro), 435, 439, 441
[pin_gpio05_dev](#) (C macro), 435, 439, 441
[pin_gpio06_dev](#) (C macro), 435, 439, 441
[pin_gpio07_dev](#) (C macro), 435, 439, 441
[pin_gpio08_dev](#) (C macro), 435, 439, 441
[pin_gpio09_dev](#) (C macro), 435, 439, 441
[pin_gpio0_dev](#) (C macro), 434, 437, 452
[pin_gpio10_dev](#) (C macro), 435, 440, 441
[pin_gpio11_dev](#) (C macro), 436, 440, 441
[pin_gpio12_dev](#) (C macro), 434, 436, 437, 440, 441, 452
[pin_gpio13_dev](#) (C macro), 434, 436, 437, 440, 441, 452
[pin_gpio14_dev](#) (C macro), 434, 436, 437, 440, 441, 452
[pin_gpio15_dev](#) (C macro), 434, 436, 437, 440, 441, 452
[pin_gpio16_dev](#) (C macro), 434, 436, 437, 440, 441, 452
[pin_gpio17_dev](#) (C macro), 436, 440, 441
[pin_gpio18_dev](#) (C macro), 436, 440, 442
[pin_gpio19_dev](#) (C macro), 436, 440, 442
[pin_gpio1_dev](#) (C macro), 434
[pin_gpio21_dev](#) (C macro), 436, 440, 442
[pin_gpio22_dev](#) (C macro), 436, 440, 442
[pin_gpio23_dev](#) (C macro), 436, 440, 442

pin_gpio25_dev (C macro), 436, 440, 442
 pin_gpio26_dev (C macro), 436, 440, 442
 pin_gpio27_dev (C macro), 436, 440, 442
 pin_gpio2_dev (C macro), 434, 437, 452
 pin_gpio32_dev (C macro), 436, 440, 442
 pin_gpio33_dev (C macro), 436, 440, 442
 pin_gpio34_dev (C macro), 436, 440, 442
 pin_gpio35_dev (C macro), 436, 440, 442
 pin_gpio36_dev (C macro), 436, 440, 442
 pin_gpio39_dev (C macro), 436, 440, 442
 pin_gpio4_dev (C macro), 434, 437, 452
 pin_gpio5_dev (C macro), 434, 437, 452
 pin_init (C++ function), 253
 PIN_INPUT (C macro), 253
 pin_is_valid_device (C++ function), 255
 pin_ld3_dev (C macro), 451
 pin_ld4_dev (C macro), 451
 pin_led_dev (C macro), 424, 429, 431–437, 439, 440, 442–444, 446, 451, 452
 pin_module_init (C++ function), 253
 PIN_OUTPUT (C macro), 253
 pin_pa0_dev (C macro), 445, 446, 449
 pin_pa10_dev (C macro), 445, 447, 450
 pin_pa11_dev (C macro), 445, 447, 450
 pin_pa12_dev (C macro), 445, 447, 450
 pin_pa13_dev (C macro), 445, 447, 450
 pin_pa14_dev (C macro), 445, 447, 450
 pin_pa15_dev (C macro), 445, 447, 450
 pin_pa1_dev (C macro), 445, 446, 449
 pin_pa2_dev (C macro), 445, 446, 449
 pin_pa3_dev (C macro), 445, 446, 449
 pin_pa4_dev (C macro), 445, 447, 449
 pin_pa5_dev (C macro), 445, 447, 449
 pin_pa6_dev (C macro), 445, 447, 449
 pin_pa7_dev (C macro), 445, 447, 450
 pin_pa8_dev (C macro), 445, 447, 450
 pin_pa9_dev (C macro), 445, 447, 450
 pin_pb0_dev (C macro), 445, 447, 450
 pin_pb10_dev (C macro), 445, 447, 450
 pin_pb11_dev (C macro), 446, 447, 450
 pin_pb12_dev (C macro), 446, 447, 450
 pin_pb13_dev (C macro), 446, 447, 450
 pin_pb14_dev (C macro), 446, 447, 450
 pin_pb15_dev (C macro), 446, 447, 450
 pin_pb1_dev (C macro), 445, 447, 450
 pin_pb2_dev (C macro), 445, 447, 450
 pin_pb3_dev (C macro), 445, 447, 450
 pin_pb4_dev (C macro), 445, 447, 450
 pin_pb5_dev (C macro), 445, 447, 450
 pin_pb6_dev (C macro), 445, 447, 450
 pin_pb7_dev (C macro), 445, 447, 450
 pin_pb8_dev (C macro), 445, 447, 450
 pin_pb9_dev (C macro), 445, 447, 450
 pin_pc0_dev (C macro), 446, 447, 450
 pin_pc10_dev (C macro), 446, 448, 450
 pin_pc11_dev (C macro), 448, 451
 pin_pc12_dev (C macro), 448, 451
 pin_pc13_dev (C macro), 448, 451
 pin_pc14_dev (C macro), 448, 451
 pin_pc15_dev (C macro), 448, 451
 pin_pc1_dev (C macro), 446, 447, 450
 pin_pc2_dev (C macro), 446, 447, 450
 pin_pc3_dev (C macro), 446, 447, 450
 pin_pc4_dev (C macro), 446, 447, 450
 pin_pc5_dev (C macro), 446, 447, 450
 pin_pc6_dev (C macro), 446, 447, 450
 pin_pc7_dev (C macro), 446, 447, 450
 pin_pc8_dev (C macro), 446, 448, 450
 pin_pc9_dev (C macro), 446, 448, 450
 pin_pd0_dev (C macro), 448, 451
 pin_pd10_dev (C macro), 448
 pin_pd11_dev (C macro), 448
 pin_pd12_dev (C macro), 448
 pin_pd13_dev (C macro), 448
 pin_pd14_dev (C macro), 448
 pin_pd15_dev (C macro), 448
 pin_pd1_dev (C macro), 448, 451
 pin_pd2_dev (C macro), 448, 451
 pin_pd3_dev (C macro), 448
 pin_pd4_dev (C macro), 448
 pin_pd5_dev (C macro), 448
 pin_pd6_dev (C macro), 448
 pin_pd7_dev (C macro), 448
 pin_pd8_dev (C macro), 448
 pin_pd9_dev (C macro), 448
 pin_pe0_dev (C macro), 448
 pin_pe10_dev (C macro), 448
 pin_pe11_dev (C macro), 448
 pin_pe12_dev (C macro), 449
 pin_pe13_dev (C macro), 449
 pin_pe14_dev (C macro), 449
 pin_pe15_dev (C macro), 449
 pin_pe1_dev (C macro), 448
 pin_pe2_dev (C macro), 448
 pin_pe3_dev (C macro), 448
 pin_pe4_dev (C macro), 448
 pin_pe5_dev (C macro), 448
 pin_pe6_dev (C macro), 448
 pin_pe7_dev (C macro), 448
 pin_pe8_dev (C macro), 448
 pin_pe9_dev (C macro), 448
 pin_read (C++ function), 253
 pin_set_mode (C++ function), 254
 pin_toggle (C++ function), 254
 pin_write (C++ function), 253
 ping (module), 351
 ping_host_by_ip_address (C++ function), 351
 ping_module_init (C++ function), 351

PRINT_FILE_LINE (C macro), 201
pwm (module), 255
pwm_a4_dev (C macro), 444
pwm_a5_dev (C macro), 444
pwm_d0_dev (C macro), 444
pwm_d10_dev (C macro), 427, 429, 431–433, 439
pwm_d11_dev (C macro), 427, 429, 431–433, 439
pwm_d12_dev (C macro), 427, 430
pwm_d1_dev (C macro), 444
pwm_d2_dev (C macro), 426, 429, 444
pwm_d3_dev (C macro), 426, 429, 431–433, 439, 444
pwm_d5_dev (C macro), 426, 429
pwm_d6_dev (C macro), 426, 429
pwm_d7_dev (C macro), 426, 429
pwm_d8_dev (C macro), 426, 429
pwm_d9_dev (C macro), 427, 429, 431–433, 439
pwm_device (C++ member), 257
PWM_DEVICE_MAX (C macro), 453, 454, 456
pwm_duty_cycle (C++ function), 257
pwm_duty_cycle_as_percent (C++ function), 257
pwm_frequency (C++ function), 256
pwm_frequency_as_hertz (C++ function), 256
pwm_get_duty_cycle (C++ function), 256
pwm_get_frequency (C++ function), 256
pwm_init (C++ function), 255
pwm_module_init (C++ function), 255
pwm_pin_to_device (C++ function), 257
pwm_set_duty_cycle (C++ function), 256
pwm_set_frequency (C++ function), 256
pwm_soft (module), 257
pwm_soft_driver_t (C++ class), 259
pwm_soft_driver_t::delta (C++ member), 260
pwm_soft_driver_t::duty_cycle (C++ member), 260
pwm_soft_driver_t::frequency (C++ member), 260
pwm_soft_driver_t::next_p (C++ member), 260
pwm_soft_driver_t::pin_dev_p (C++ member), 260
pwm_soft_driver_t::thrd_p (C++ member), 260
pwm_soft_duty_cycle (C++ function), 259
pwm_soft_duty_cycle_as_percent (C++ function), 259
pwm_soft_get_duty_cycle (C++ function), 259
pwm_soft_get_frequency (C++ function), 258
pwm_soft_init (C++ function), 258
pwm_soft_module_init (C++ function), 258
pwm_soft_set_duty_cycle (C++ function), 259
pwm_soft_set_frequency (C++ function), 258
pwm_soft_start (C++ function), 258
pwm_soft_stop (C++ function), 259
pwm_start (C++ function), 255
pwm_stop (C++ function), 255

Q

queue (module), 213
queue_buffer_t (C++ class), 215
queue_buffer_t::begin_p (C++ member), 216

queue_buffer_t::end_p (C++ member), 216
queue_buffer_t::read_p (C++ member), 216
queue_buffer_t::size (C++ member), 216
queue_buffer_t::write_p (C++ member), 216
queue_init (C++ function), 214
QUEUE_INIT_DECL (C macro), 213
queue_read (C++ function), 214
queue_size (C++ function), 215
queue_start (C++ function), 214
QUEUE_STATE_INITIALIZED (C++ class), 214
QUEUE_STATE_RUNNING (C++ class), 214
QUEUE_STATE_STOPPED (C++ class), 214
queue_state_t (C++ type), 214
queue_stop (C++ function), 214
queue_stop_isr (C++ function), 214
queue_t (C++ class), 216
queue_t::base (C++ member), 216
queue_t::buf_p (C++ member), 216
queue_t::buffer (C++ member), 216
queue_t::left (C++ member), 216
queue_t::size (C++ member), 216
queue_t::state (C++ member), 216
queue_t::writer_p (C++ member), 216
queue_t::writers (C++ member), 216
queue_unused_size (C++ function), 215
queue_unused_size_isr (C++ function), 215
queue_write (C++ function), 215
queue_write_isr (C++ function), 215
queue_writer_elem_t (C++ class), 216
queue_writer_elem_t::base (C++ member), 216
queue_writer_elem_t::buf_p (C++ member), 216
queue_writer_elem_t::left (C++ member), 216
queue_writer_elem_t::size (C++ member), 216

R

random (module), 260
random_module_init (C++ function), 260
random_read (C++ function), 260
re (module), 406
re_compile (C++ function), 406
RE_DOTALL (C macro), 406
re_group_t (C++ class), 407
re_group_t::buf_p (C++ member), 407
re_group_t::size (C++ member), 407
RE_IGNORECASE (C macro), 406
re_match (C++ function), 407
RE_MULTILINE (C macro), 406
REQUEST_GET_DESCRIPTOR (C macro), 274
REQUEST_GET_STATUS (C macro), 274
REQUEST_SET_ADDRESS (C macro), 274
REQUEST_SET_CONFIGURATION (C macro), 274
REQUEST_TYPE_DATA_DIRECTION_DEVICE_TO_HOST
(C macro), 274

REQUEST_TYPE_DATA_DIRECTION_HOST_TO_DEVICE (C macro), 274
 REQUEST_TYPE_DATA_MASK (C macro), 274
 REQUEST_TYPE_RECIPIENT_DEVICE (C macro), 274
 REQUEST_TYPE_RECIPIENT_ENDPOINT (C macro), 274
 REQUEST_TYPE_RECIPIENT_INTERFACE (C macro), 274
 REQUEST_TYPE_RECIPIENT_MASK (C macro), 274
 REQUEST_TYPE_RECIPIENT_OTHER (C macro), 274
 REQUEST_TYPE_TYPE_CLASS (C macro), 274
 REQUEST_TYPE_TYPE_MASK (C macro), 274
 REQUEST_TYPE_TYPE_STANDARD (C macro), 274
 REQUEST_TYPE_TYPE_VENDOR (C macro), 274
 rlock (module), 216
 rlock_init (C++ function), 217
 rlock_module_init (C++ function), 217
 rlock_reader_give (C++ function), 217
 rlock_reader_give_isr (C++ function), 217
 rlock_reader_take (C++ function), 217
 rlock_t (C++ class), 218
 rlock_t::number_of_readers (C++ member), 218
 rlock_t::number_of_writers (C++ member), 218
 rlock_t::readers_p (C++ member), 218
 rlock_t::writers_p (C++ member), 218
 rlock_writer_give (C++ function), 217
 rlock_writer_give_isr (C++ function), 218
 rlock_writer_take (C++ function), 217
 RXCIE0 (C macro), 454
 RXEN0 (C macro), 454

S

s16_t (C++ type), 202
 s32_t (C++ type), 202
 s8_t (C++ type), 202
 sam3x8e (module), 456
 SAM_PA (C macro), 456
 SAM_PB (C macro), 456
 SAM_PC (C macro), 456
 SAM_PD (C macro), 456
 sd (module), 260
 SD_BLOCK_SIZE (C macro), 261
 SD_C_SIZE (C macro), 261
 SD_C_SIZE_MULT (C macro), 261
 SD_CCC (C macro), 261
 sd_cid_t (C++ class), 262
 sd_cid_t::crc (C++ member), 262
 sd_cid_t::mdt (C++ member), 262
 sd_cid_t::mid (C++ member), 262
 sd_cid_t::oid (C++ member), 262
 sd_cid_t::pnm (C++ member), 262
 sd_cid_t::prv (C++ member), 262
 sd_cid_t::psn (C++ member), 262
 SD_CSD_STRUCTURE_V1 (C macro), 261
 SD_CSD_STRUCTURE_V2 (C macro), 261
 sd_csd_t (C++ type), 265
 sd_csd_t::v1 (C++ member), 265
 sd_csd_t::v2 (C++ member), 265
 sd_csd_v1_t (C++ class), 263
 sd_csd_v1_t::c_size_high (C++ member), 263
 sd_csd_v1_t::c_size_low (C++ member), 263
 sd_csd_v1_t::c_size_mid (C++ member), 263
 sd_csd_v1_t::c_size_mult_high (C++ member), 263
 sd_csd_v1_t::c_size_mult_low (C++ member), 263
 sd_csd_v1_t::ccc_high (C++ member), 263
 sd_csd_v1_t::ccc_low (C++ member), 263
 sd_csd_v1_t::copy (C++ member), 264
 sd_csd_v1_t::crc (C++ member), 264
 sd_csd_v1_t::csd_structure (C++ member), 263
 sd_csd_v1_t::dsr_imp (C++ member), 263
 sd_csd_v1_t::erase_blk_en (C++ member), 263
 sd_csd_v1_t::file_format (C++ member), 264
 sd_csd_v1_t::file_format_grp (C++ member), 264
 sd_csd_v1_t::nsac (C++ member), 263
 sd_csd_v1_t::perm_write_protect (C++ member), 264
 sd_csd_v1_t::r2w_factor (C++ member), 263
 sd_csd_v1_t::read_bl_len (C++ member), 263
 sd_csd_v1_t::read_bl_partial (C++ member), 263
 sd_csd_v1_t::read_blk_misalign (C++ member), 263
 sd_csd_v1_t::reserved1 (C++ member), 263
 sd_csd_v1_t::reserved2 (C++ member), 263
 sd_csd_v1_t::reserved3 (C++ member), 263
 sd_csd_v1_t::reserved4 (C++ member), 263
 sd_csd_v1_t::reserved5 (C++ member), 264
 sd_csd_v1_t::sector_size_high (C++ member), 263
 sd_csd_v1_t::sector_size_low (C++ member), 263
 sd_csd_v1_t::taac (C++ member), 263
 sd_csd_v1_t::tmp_write_protect (C++ member), 264
 sd_csd_v1_t::tran_speed (C++ member), 263
 sd_csd_v1_t::vdd_r_curr_max (C++ member), 263
 sd_csd_v1_t::vdd_r_curr_min (C++ member), 263
 sd_csd_v1_t::vdd_w_curr_max (C++ member), 263
 sd_csd_v1_t::vdd_w_curr_min (C++ member), 263
 sd_csd_v1_t::wp_grp_enable (C++ member), 263
 sd_csd_v1_t::wp_grp_size (C++ member), 263
 sd_csd_v1_t::write_bl_len_high (C++ member), 263
 sd_csd_v1_t::write_bl_len_low (C++ member), 263
 sd_csd_v1_t::write_bl_partial (C++ member), 263
 sd_csd_v1_t::write_blk_misalign (C++ member), 263
 sd_csd_v2_t (C++ class), 264
 sd_csd_v2_t::c_size_high (C++ member), 264
 sd_csd_v2_t::c_size_low (C++ member), 264
 sd_csd_v2_t::c_size_mid (C++ member), 264
 sd_csd_v2_t::ccc_high (C++ member), 264
 sd_csd_v2_t::ccc_low (C++ member), 264
 sd_csd_v2_t::copy (C++ member), 265

sd_csd_v2_t::crc (C++ member), 265
 sd_csd_v2_t::csd_structure (C++ member), 264
 sd_csd_v2_t::dsr_imp (C++ member), 264
 sd_csd_v2_t::erase_blk_en (C++ member), 264
 sd_csd_v2_t::file_format (C++ member), 265
 sd_csd_v2_t::file_format_grp (C++ member), 265
 sd_csd_v2_t::nsac (C++ member), 264
 sd_csd_v2_t::perm_write_protect (C++ member), 265
 sd_csd_v2_t::r2w_factor (C++ member), 264
 sd_csd_v2_t::read_bl_len (C++ member), 264
 sd_csd_v2_t::read_bl_partial (C++ member), 264
 sd_csd_v2_t::read_blk_misalign (C++ member), 264
 sd_csd_v2_t::reserved1 (C++ member), 264
 sd_csd_v2_t::reserved2 (C++ member), 264
 sd_csd_v2_t::reserved3 (C++ member), 264
 sd_csd_v2_t::reserved4 (C++ member), 264
 sd_csd_v2_t::reserved5 (C++ member), 264
 sd_csd_v2_t::reserved6 (C++ member), 265
 sd_csd_v2_t::reserved7 (C++ member), 265
 sd_csd_v2_t::sector_size_high (C++ member), 264
 sd_csd_v2_t::sector_size_low (C++ member), 264
 sd_csd_v2_t::taac (C++ member), 264
 sd_csd_v2_t::tmp_write_protect (C++ member), 265
 sd_csd_v2_t::tran_speed (C++ member), 264
 sd_csd_v2_t::wp_grp_enable (C++ member), 264
 sd_csd_v2_t::wp_grp_size (C++ member), 264
 sd_csd_v2_t::write_bl_len_high (C++ member), 264
 sd_csd_v2_t::write_bl_len_low (C++ member), 265
 sd_csd_v2_t::write_bl_partial (C++ member), 265
 sd_csd_v2_t::write_blk_misalign (C++ member), 264
 sd_driver_t (C++ class), 265
 sd_driver_t::spi_p (C++ member), 265
 sd_driver_t::type (C++ member), 265
 SD_ERR_CHECK_PATTERN (C macro), 260
 SD_ERR_CRC_ON_OFF (C macro), 260
 SD_ERR_GO_IDLE_STATE (C macro), 260
 SD_ERR_NORESPONSE_WAIT_FOR_DATA_START_BLOCKING (C macro), 260
 SD_ERR_READ_COMMAND (C macro), 260
 SD_ERR_READ_DATA_START_BLOCK (C macro), 260
 SD_ERR_READ_OCR (C macro), 260
 SD_ERR_READ_WRONG_DATA_CRC (C macro), 260
 SD_ERR_SD_SEND_OP_COND (C macro), 260
 SD_ERR_SEND_IF_COND (C macro), 260
 SD_ERR_WRITE_BLOCK (C macro), 261
 SD_ERR_WRITE_BLOCK_SEND_STATUS (C macro), 261
 SD_ERR_WRITE_BLOCK_TOKEN_DATA_RES_ACCELERATED (C macro), 261
 SD_ERR_WRITE_BLOCK_WAIT_NOT_BUSY (C macro), 261
 sd_init (C++ function), 261
 sd_read_block (C++ function), 262
 sd_read_cid (C++ function), 261
 sd_read_csd (C++ function), 262
 SD_SECTOR_SIZE (C macro), 261
 sd_start (C++ function), 261
 sd_stop (C++ function), 261
 SD_WRITE_BL_LEN (C macro), 261
 sd_write_block (C++ function), 262
 sem (module), 218
 sem_give (C++ function), 219
 sem_give_isr (C++ function), 219
 sem_init (C++ function), 219
 SEM_INIT_DECL (C macro), 218
 sem_module_init (C++ function), 219
 sem_t (C++ class), 220
 sem_t::count (C++ member), 220
 sem_t::count_max (C++ member), 220
 sem_t::waiters (C++ member), 220
 sem_take (C++ function), 219
 service (module), 364
 SERVICE_CONTROL_EVENT_START (C macro), 365
 SERVICE_CONTROL_EVENT_STOP (C macro), 365
 service_deregister (C++ function), 366
 service_get_status_cb_t (C++ type), 365
 service_init (C++ function), 365
 service_module_init (C++ function), 365
 service_register (C++ function), 366
 service_start (C++ function), 366
 service_status_running_t (C++ class), 365
 service_status_stopped_t (C++ class), 365
 service_status_t (C++ type), 365
 service_stop (C++ function), 366
 service_t (C++ class), 366
 service_t::control (C++ member), 366
 service_t::name_p (C++ member), 366
 service_t::next_p (C++ member), 367
 service_t::status_cb (C++ member), 366
 setting_t (C++ class), 370
 setting_t::address (C++ member), 370
 setting_t::size (C++ member), 370
 setting_t::type (C++ member), 370
 setting_type_blob_t (C++ class), 369
 setting_type_int32_t (C++ class), 369
 setting_type_string_t (C++ class), 369
 setting_type_t (C++ type), 369
 settings (module), 367
 SETTINGS_AREA_CRC_OFFSET (C macro), 368
 settings_module_init (C++ function), 369
 settings_read (C++ function), 369
 settings_read_by_name (C++ function), 369
 settings_reset (C++ function), 370
 settings_write (C++ function), 369
 settings_write_by_name (C++ function), 369
 sha1 (module), 418
 sha1_digest (C++ function), 418

- sha1_init (C++ function), 418
- sha1_t (C++ class), 418
- sha1_t::buf (C++ member), 419
- sha1_t::h (C++ member), 419
- sha1_t::size (C++ member), 419
- sha1_update (C++ function), 418
- shell (module), 370
- shell_history_elem_t (C++ class), 371
- shell_history_elem_t::buf (C++ member), 372
- shell_history_elem_t::next_p (C++ member), 372
- shell_history_elem_t::prev_p (C++ member), 372
- shell_init (C++ function), 371
- shell_line_t (C++ class), 372
- shell_line_t::buf (C++ member), 372
- shell_line_t::cursor (C++ member), 372
- shell_line_t::length (C++ member), 372
- shell_main (C++ function), 371
- shell_module_init (C++ function), 371
- shell_t (C++ class), 372
- shell_t::arg_p (C++ member), 372
- shell_t::authorized (C++ member), 372
- shell_t::buf (C++ member), 372
- shell_t::carriage_return_received (C++ member), 372
- shell_t::chin_p (C++ member), 372
- shell_t::chout_p (C++ member), 372
- shell_t::current_p (C++ member), 372
- shell_t::head_p (C++ member), 372
- shell_t::heap (C++ member), 372
- shell_t::line (C++ member), 372
- shell_t::line_valid (C++ member), 372
- shell_t::match (C++ member), 372
- shell_t::name_p (C++ member), 372
- shell_t::newline_received (C++ member), 372
- shell_t::password_p (C++ member), 372
- shell_t::pattern (C++ member), 372
- shell_t::prev_line (C++ member), 372
- shell_t::tail_p (C++ member), 372
- shell_t::username_p (C++ member), 372
- SHT3X_DIS_I2C_ADDR_A (C macro), 266
- SHT3X_DIS_I2C_ADDR_B (C macro), 266
- sht3xd (module), 265
- sht3xd_driver_t (C++ class), 267
- sht3xd_driver_t::i2c_addr (C++ member), 267
- sht3xd_driver_t::i2c_p (C++ member), 267
- sht3xd_driver_t::serial (C++ member), 267
- sht3xd_get_serial (C++ function), 267
- sht3xd_get_temp_humid (C++ function), 266
- sht3xd_init (C++ function), 266
- sht3xd_module_init (C++ function), 266
- sht3xd_start (C++ function), 266
- soam (module), 373
- soam_get_log_input_channel (C++ function), 375
- soam_get_stdout_input_channel (C++ function), 375
- soam_init (C++ function), 374
- soam_input (C++ function), 374
- soam_module_init (C++ function), 374
- soam_t (C++ class), 376
- soam_t::buf_p (C++ member), 376
- soam_t::chout_p (C++ member), 376
- soam_t::command_chan (C++ member), 376
- soam_t::is_printf (C++ member), 376
- soam_t::log_chan (C++ member), 376
- soam_t::packet_index (C++ member), 376
- soam_t::pos (C++ member), 376
- soam_t::sem (C++ member), 376
- soam_t::size (C++ member), 376
- soam_t::stdout_chan (C++ member), 376
- soam_t::transaction_id (C++ member), 376
- soam_write (C++ function), 375
- soam_write_begin (C++ function), 374
- soam_write_chunk (C++ function), 375
- soam_write_end (C++ function), 375
- socket (module), 351
- socket_accept (C++ function), 354
- socket_bind (C++ function), 354
- socket_close (C++ function), 353
- socket_connect (C++ function), 354
- socket_connect_by_hostname (C++ function), 354
- SOCKET_DOMAIN_INET (C macro), 352
- socket_listen (C++ function), 354
- socket_module_init (C++ function), 353
- socket_open (C++ function), 353
- socket_open_raw (C++ function), 353
- socket_open_tcp (C++ function), 353
- socket_open_udp (C++ function), 353
- SOCKET_PROTO_ICMP (C macro), 353
- socket_read (C++ function), 355
- socket_recvfrom (C++ function), 355
- socket_sendto (C++ function), 355
- socket_size (C++ function), 356
- socket_t (C++ class), 356
- socket_t::args_p (C++ member), 356
- socket_t::base (C++ member), 356
- socket_t::closed (C++ member), 356
- socket_t::left (C++ member), 356
- socket_t::pbuf_p (C++ member), 356
- socket_t::pcb_p (C++ member), 356
- socket_t::remote_addr (C++ member), 356
- socket_t::state (C++ member), 356
- socket_t::thrd_p (C++ member), 356
- socket_t::type (C++ member), 356
- SOCKET_TYPE_DGRAM (C macro), 353
- SOCKET_TYPE_RAW (C macro), 353
- SOCKET_TYPE_STREAM (C macro), 352
- socket_write (C++ function), 355
- spc56d4011 (module), 456
- spc56ddiscovery (module), 445
- spi (module), 267

`spi_0_dev` (C macro), 449, 451
`spi_1_dev` (C macro), 449, 451
`spi_2_dev` (C macro), 449, 451
`spi_deselect` (C++ function), 269
`spi_device` (C++ member), 270
`SPI_DEVICE_MAX` (C macro), 453–455, 457
`spi_get` (C++ function), 270
`spi_give_bus` (C++ function), 268
`spi_h_dev` (C macro), 436, 440, 442
`spi_init` (C++ function), 268
`SPI_MODE_MASTER` (C macro), 267
`SPI_MODE_SLAVE` (C macro), 267
`spi_module_init` (C++ function), 268
`spi_put` (C++ function), 270
`spi_read` (C++ function), 269
`spi_select` (C++ function), 269
`SPI_SPEED_125KBPS` (C macro), 267
`SPI_SPEED_1MBPS` (C macro), 267
`SPI_SPEED_250KBPS` (C macro), 267
`SPI_SPEED_2MBPS` (C macro), 267
`SPI_SPEED_4MBPS` (C macro), 267
`SPI_SPEED_500KBPS` (C macro), 267
`SPI_SPEED_8MBPS` (C macro), 267
`spi_start` (C++ function), 268
`spi_stop` (C++ function), 268
`spi_take_bus` (C++ function), 268
`spi_transfer` (C++ function), 269
`spi_v_dev` (C macro), 436, 440, 442
`spi_write` (C++ function), 269
`spiffs` (C++ type), 320
`spiffs` (module), 316
`SPIFFS_APPEND` (C macro), 318
`spiffs_block_ix` (C++ type), 320
`SPIFFS_CACHE_DBG` (C macro), 318
`SPIFFS_CB_CREATED` (C++ class), 321
`SPIFFS_CB_DELETED` (C++ class), 321
`SPIFFS_CB_UPDATED` (C++ class), 321
`spiffs_check` (C++ function), 325
`spiffs_check_callback` (C++ type), 320
`spiffs_check_callback_t` (C++ type), 319
`SPIFFS_CHECK_DBG` (C macro), 318
`SPIFFS_CHECK_DELETE_BAD_FILE` (C++ class), 320
`SPIFFS_CHECK_DELETE_ORPHANED_INDEX` (C++ class), 320
`SPIFFS_CHECK_DELETE_PAGE` (C++ class), 320
`SPIFFS_CHECK_ERROR` (C++ class), 320
`SPIFFS_CHECK_FIX_INDEX` (C++ class), 320
`SPIFFS_CHECK_FIX_LOOKUP` (C++ class), 320
`SPIFFS_CHECK_INDEX` (C++ class), 320
`SPIFFS_CHECK_LOOKUP` (C++ class), 320
`SPIFFS_CHECK_PAGE` (C++ class), 320
`SPIFFS_CHECK_PROGRESS` (C++ class), 320
`spiffs_check_report_t` (C++ type), 320
`spiffs_check_type_t` (C++ type), 320
`spiffs_clearerr` (C++ function), 325
`spiffs_close` (C++ function), 324
`spiffs_closedir` (C++ function), 325
`spiffs_config` (C++ type), 320
`spiffs_config_t` (C++ class), 327
`spiffs_config_t::hal_erase_f` (C++ member), 328
`spiffs_config_t::hal_read_f` (C++ member), 328
`spiffs_config_t::hal_write_f` (C++ member), 328
`spiffs_config_t::log_block_size` (C++ member), 328
`spiffs_config_t::log_page_size` (C++ member), 328
`spiffs_config_t::phys_addr` (C++ member), 328
`spiffs_config_t::phys_erase_block` (C++ member), 328
`spiffs_config_t::phys_size` (C++ member), 328
`SPIFFS_CREAT` (C macro), 318
`spiffs_creat` (C++ function), 321
`SPIFFS_DBG` (C macro), 318
`spiffs_DIR` (C++ type), 320
`spiffs_dir_t` (C++ class), 329
`spiffs_dir_t::block` (C++ member), 330
`spiffs_dir_t::entry` (C++ member), 330
`spiffs_dir_t::fs` (C++ member), 330
`SPIFFS_DIRECT` (C macro), 319
`spiffs_dirent` (C++ type), 320
`spiffs_dirent_t` (C++ class), 329
`spiffs_dirent_t::name` (C++ member), 329
`spiffs_dirent_t::obj_id` (C++ member), 329
`spiffs_dirent_t::pix` (C++ member), 329
`spiffs_dirent_t::size` (C++ member), 329
`spiffs_dirent_t::type` (C++ member), 329
`spiffs_eof` (C++ function), 327
`spiffs_erase_cb_t` (C++ type), 319
`SPIFFS_ERR_BAD_DESCRIPTOR` (C macro), 317
`SPIFFS_ERR_CONFLICTING_NAME` (C macro), 318
`SPIFFS_ERR_DATA_SPAN_MISMATCH` (C macro), 317
`SPIFFS_ERR_DELETED` (C macro), 317
`SPIFFS_ERR_END_OF_OBJECT` (C macro), 317
`SPIFFS_ERR_ERASE_FAIL` (C macro), 318
`SPIFFS_ERR_FILE_CLOSED` (C macro), 317
`SPIFFS_ERR_FILE_DELETED` (C macro), 317
`SPIFFS_ERR_FILE_EXISTS` (C macro), 318
`SPIFFS_ERR_FULL` (C macro), 317
`SPIFFS_ERR_INDEX_FREE` (C macro), 317
`SPIFFS_ERR_INDEX_INVALID` (C macro), 318
`SPIFFS_ERR_INDEX_LU` (C macro), 317
`SPIFFS_ERR_INDEX_REF_FREE` (C macro), 317
`SPIFFS_ERR_INDEX_REF_INVALID` (C macro), 317
`SPIFFS_ERR_INDEX_REF_LU` (C macro), 317
`SPIFFS_ERR_INDEX_SPAN_MISMATCH` (C macro), 317
`SPIFFS_ERR_INTERNAL` (C macro), 318
`SPIFFS_ERR_IS_FREE` (C macro), 317
`SPIFFS_ERR_IS_INDEX` (C macro), 317

SPIFFS_ERR_MAGIC_NOT_POSSIBLE (C macro), 318
 SPIFFS_ERR_MOUNTED (C macro), 318
 SPIFFS_ERR_NAME_TOO_LONG (C macro), 318
 SPIFFS_ERR_NO_DELETED_BLOCKS (C macro), 318
 SPIFFS_ERR_NOT_A_FILE (C macro), 318
 SPIFFS_ERR_NOT_A_FS (C macro), 318
 SPIFFS_ERR_NOT_CONFIGURED (C macro), 318
 SPIFFS_ERR_NOT_FINALIZED (C macro), 317
 SPIFFS_ERR_NOT_FOUND (C macro), 317
 SPIFFS_ERR_NOT_INDEX (C macro), 317
 SPIFFS_ERR_NOT_MOUNTED (C macro), 317
 SPIFFS_ERR_NOT_READABLE (C macro), 318
 SPIFFS_ERR_NOT_WRITABLE (C macro), 318
 SPIFFS_ERR_OUT_OF_FILE_DESCS (C macro), 317
 SPIFFS_ERR_PROBE_NOT_A_FS (C macro), 318
 SPIFFS_ERR_PROBE_TOO_FEW_BLOCKS (C macro), 318
 SPIFFS_ERR_RO_ABORTED_OPERATION (C macro), 318
 SPIFFS_ERR_RO_NOT_IMPL (C macro), 318
 SPIFFS_ERR_TEST (C macro), 318
 spiffs_errno (C++ function), 325
 SPIFFS_EXCL (C macro), 319
 spiffs_fflush (C++ function), 324
 spiffs_file (C++ type), 320
 spiffs_file_callback (C++ type), 320
 spiffs_file_callback_t (C++ type), 319
 spiffs_file_t (C++ type), 319
 spiffs_fileop_type (C++ type), 320
 spiffs_fileop_type_t (C++ type), 320
 spiffs_flags (C++ type), 320
 spiffs_flags_t (C++ type), 319
 spiffs_format (C++ function), 326
 spiffs_fremove (C++ function), 323
 spiffs_fstat (C++ function), 324
 spiffs_gc (C++ function), 327
 SPIFFS_GC_DBG (C macro), 318
 spiffs_gc_quick (C++ function), 326
 spiffs_info (C++ function), 326
 SPIFFS_LOCK (C macro), 319
 spiffs_lseek (C++ function), 323
 spiffs_mode (C++ type), 320
 spiffs_mode_t (C++ type), 319
 spiffs_mount (C++ function), 321
 spiffs_mounted (C++ function), 326
 SPIFFS_O_APPEND (C macro), 318
 SPIFFS_O_CREAT (C macro), 318
 SPIFFS_O_DIRECT (C macro), 319
 SPIFFS_O_EXCL (C macro), 319
 SPIFFS_O_RDONLY (C macro), 318
 SPIFFS_O_RDWR (C macro), 319
 SPIFFS_O_TRUNC (C macro), 318
 SPIFFS_O_WRONLY (C macro), 318
 spiffs_obj_id (C++ type), 320
 spiffs_obj_type (C++ type), 320
 spiffs_obj_type_t (C++ type), 319
 SPIFFS_OK (C macro), 317
 spiffs_open (C++ function), 322
 spiffs_open_by_dirent (C++ function), 322
 spiffs_open_by_page (C++ function), 322
 spiffs_opendir (C++ function), 325
 spiffs_page_ix (C++ type), 320
 SPIFFS_RDONLY (C macro), 318
 SPIFFS_RDWR (C macro), 319
 spiffs_read (C++ function), 322
 spiffs_read_cb_t (C++ type), 319
 spiffs_readdir (C++ function), 325
 spiffs_remove (C++ function), 323
 spiffs_rename (C++ function), 324
 SPIFFS_SEEK_CUR (C macro), 319
 SPIFFS_SEEK_END (C macro), 319
 SPIFFS_SEEK_SET (C macro), 319
 spiffs_set_file_callback_func (C++ function), 327
 spiffs_span_ix (C++ type), 320
 spiffs_stat (C++ function), 324
 spiffs_stat_t (C++ class), 329
 spiffs_stat_t::name (C++ member), 329
 spiffs_stat_t::obj_id (C++ member), 329
 spiffs_stat_t::pix (C++ member), 329
 spiffs_stat_t::size (C++ member), 329
 spiffs_stat_t::type (C++ member), 329
 spiffs_t (C++ class), 328
 spiffs_t::block_count (C++ member), 328
 spiffs_t::cfg (C++ member), 328
 spiffs_t::check_cb_f (C++ member), 329
 spiffs_t::cleaning (C++ member), 329
 spiffs_t::config_magic (C++ member), 329
 spiffs_t::cursor_block_ix (C++ member), 328
 spiffs_t::cursor_obj_lu_entry (C++ member), 328
 spiffs_t::err_code (C++ member), 329
 spiffs_t::fd_count (C++ member), 328
 spiffs_t::fd_space (C++ member), 328
 spiffs_t::file_cb_f (C++ member), 329
 spiffs_t::free_blocks (C++ member), 329
 spiffs_t::free_cursor_block_ix (C++ member), 328
 spiffs_t::free_cursor_obj_lu_entry (C++ member), 328
 spiffs_t::lu_work (C++ member), 328
 spiffs_t::max_erase_count (C++ member), 329
 spiffs_t::mounted (C++ member), 329
 spiffs_t::stats_p_allocated (C++ member), 329
 spiffs_t::stats_p_deleted (C++ member), 329
 spiffs_t::user_data (C++ member), 329
 spiffs_t::work (C++ member), 328
 spiffs_tell (C++ function), 327
 SPIFFS_TRUNC (C macro), 318
 SPIFFS_TYPE_DIR (C macro), 319

SPIFFS_TYPE_FILE (C macro), 319
 SPIFFS_TYPE_HARD_LINK (C macro), 319
 SPIFFS_TYPE_SOFT_LINK (C macro), 319
 SPIFFS_UNLOCK (C macro), 319
 spiffs_unmount (C++ function), 321
 spiffs_write (C++ function), 323
 spiffs_write_cb_t (C++ type), 319
 SPIFFS_WRONLY (C macro), 318
 ssl (module), 357
 ssl_context_destroy (C++ function), 358
 ssl_context_init (C++ function), 358
 ssl_context_load_cert_chain (C++ function), 358
 ssl_context_load_verify_location (C++ function), 359
 ssl_context_set_verify_mode (C++ function), 359
 ssl_context_t (C++ class), 361
 ssl_context_t::conf_p (C++ member), 361
 ssl_context_t::protocol (C++ member), 361
 ssl_context_t::server_side (C++ member), 361
 ssl_context_t::verify_mode (C++ member), 361
 ssl_module_init (C++ function), 358
 ssl_protocol_t (C++ type), 358
 ssl_protocol_tls_v1_0 (C++ class), 358
 ssl_socket_close (C++ function), 359
 ssl_socket_get_cipher (C++ function), 360
 ssl_socket_get_server_hostname (C++ function), 360
 ssl_socket_open (C++ function), 359
 ssl_socket_read (C++ function), 360
 SSL_SOCKET_SERVER_SIDE (C macro), 358
 ssl_socket_size (C++ function), 360
 ssl_socket_t (C++ class), 361
 ssl_socket_t::base (C++ member), 361
 ssl_socket_t::socket_p (C++ member), 361
 ssl_socket_t::ssl_p (C++ member), 361
 ssl_socket_write (C++ function), 360
 ssl_verify_mode_cert_none_t (C++ class), 358
 ssl_verify_mode_cert_required_t (C++ class), 358
 ssl_verify_mode_t (C++ type), 358
 st2t (C++ function), 186
 std (module), 408
 std_hexdump (C++ function), 411
 std_module_init (C++ function), 408
 std_printf (C++ function), 409
 STD_PRINTF_DEBUG (C macro), 201
 std_strip (C++ function), 411
 std_strtod (C++ function), 410
 std_strtol (C++ function), 410
 stm32f100rb (module), 456
 stm32f205rg (module), 457
 stm32f303vc (module), 457
 stm32f3discovery (module), 446
 stm32vldiscovery (module), 449
 STRINGIFY (C macro), 201
 STRINGIFY2 (C macro), 201
 STUB (C macro), 383

sys (C++ member), 189
 sys (module), 186
 sys_backtrace (C++ function), 187
 sys_get_config (C++ function), 189
 sys_get_info (C++ function), 189
 sys_get_stdin (C++ function), 188
 sys_get_stdout (C++ function), 188
 sys_interrupt_cpu_usage_get (C++ function), 189
 sys_interrupt_cpu_usage_reset (C++ function), 189
 sys_lock (C++ function), 188
 sys_lock_isr (C++ function), 189
 sys_module_init (C++ function), 186
 sys_panic (C++ function), 187
 sys_reboot (C++ function), 187
 sys_reset_cause (C++ function), 187
 sys_reset_cause_external_t (C++ class), 186
 sys_reset_cause_jtag_t (C++ class), 186
 sys_reset_cause_max_t (C++ class), 186
 sys_reset_cause_power_on_t (C++ class), 186
 sys_reset_cause_software_t (C++ class), 186
 sys_reset_cause_string_map (C++ member), 189
 sys_reset_cause_t (C++ type), 186
 sys_reset_cause_unknown_t (C++ class), 186
 sys_reset_cause_watchdog_timeout_t (C++ class), 186
 sys_set_on_fatal_callback (C++ function), 188
 sys_set_stdin (C++ function), 188
 sys_set_stdout (C++ function), 188
 sys_start (C++ function), 187
 sys_stop (C++ function), 187
 sys_t (C++ class), 189
 sys_t::on_fatal_callback (C++ member), 190
 sys_t::start (C++ member), 190
 sys_t::stdin_p (C++ member), 190
 sys_t::stdout_p (C++ member), 190
 sys_t::time (C++ member), 190
 SYS_TICK_MAX (C macro), 186
 sys_tick_t (C++ type), 186
 sys_unlock (C++ function), 189
 sys_unlock_isr (C++ function), 189
 sys_uptime (C++ function), 187
 sys_uptime_isr (C++ function), 188

T

t2st (C++ function), 186
 tftp_server (module), 361
 tftp_server_init (C++ function), 361
 tftp_server_start (C++ function), 362
 tftp_server_t (C++ class), 362
 tftp_server_t::addr (C++ member), 362
 tftp_server_t::listener (C++ member), 362
 tftp_server_t::name_p (C++ member), 362
 tftp_server_t::root_p (C++ member), 362
 tftp_server_t::stack_p (C++ member), 362
 tftp_server_t::stack_size (C++ member), 362

tftp_server_t::thrd_p (C++ member), 362
 tftp_server_t::timeout_ms (C++ member), 362
 thrd (module), 190
 THRD_CONTEXT_LOAD_ISR (C macro), 191
 THRD_CONTEXT_STORE_ISR (C macro), 191
 thrd_environment_t (C++ class), 196
 thrd_environment_t::max_number_of_variables (C++ member), 197
 thrd_environment_t::number_of_variables (C++ member), 197
 thrd_environment_t::variables_p (C++ member), 197
 thrd_environment_variable_t (C++ class), 196
 thrd_environment_variable_t::name_p (C++ member), 196
 thrd_environment_variable_t::value_p (C++ member), 196
 thrd_get_bottom_of_stack (C++ function), 195
 thrd_get_by_name (C++ function), 193
 thrd_get_env (C++ function), 195
 thrd_get_global_env (C++ function), 194
 thrd_get_log_mask (C++ function), 193
 thrd_get_name (C++ function), 193
 thrd_get_prio (C++ function), 194
 thrd_get_top_of_stack (C++ function), 196
 thrd_init_env (C++ function), 194
 thrd_init_global_env (C++ function), 194
 thrd_join (C++ function), 192
 thrd_module_init (C++ function), 191
 thrd_prio_list_elem_t (C++ class), 202
 thrd_prio_list_elem_t::next_p (C++ member), 202
 thrd_prio_list_elem_t::thrd_p (C++ member), 202
 thrd_prio_list_init (C++ function), 196
 thrd_prio_list_pop_isr (C++ function), 196
 thrd_prio_list_push_isr (C++ function), 196
 thrd_prio_list_remove_isr (C++ function), 196
 thrd_prio_list_t (C++ class), 202
 thrd_prio_list_t::head_p (C++ member), 202
 THRD_RESCHEDULE_ISR (C macro), 191
 thrd_resume (C++ function), 192
 thrd_resume_isr (C++ function), 195
 thrd_self (C++ function), 193
 thrd_set_env (C++ function), 194
 thrd_set_global_env (C++ function), 194
 thrd_set_log_mask (C++ function), 193
 thrd_set_name (C++ function), 193
 thrd_set_prio (C++ function), 193
 thrd_sleep (C++ function), 192
 thrd_sleep_ms (C++ function), 192
 thrd_sleep_us (C++ function), 193
 thrd_spawn (C++ function), 191
 THRD_STACK (C macro), 191
 thrd_stack_alloc (C++ function), 195
 thrd_stack_free (C++ function), 195
 thrd_suspend (C++ function), 192
 thrd_suspend_isr (C++ function), 195
 thrd_t (C++ class), 197
 thrd_t::elem (C++ member), 197
 thrd_t::err (C++ member), 197
 thrd_t::log_mask (C++ member), 197
 thrd_t::name_p (C++ member), 197
 thrd_t::next_p (C++ member), 197
 thrd_t::port (C++ member), 197
 thrd_t::prio (C++ member), 197
 thrd_t::stack_size (C++ member), 197
 thrd_t::state (C++ member), 197
 thrd_t::timer_p (C++ member), 197
 thrd_yield (C++ function), 192
 thrd_yield_isr (C++ function), 195
 time (module), 197
 time_add (C++ function), 198
 time_busy_wait_us (C++ function), 198
 time_get (C++ function), 197
 time_set (C++ function), 197
 time_subtract (C++ function), 198
 time_t (C++ class), 198
 time_t::nanoseconds (C++ member), 199
 time_t::seconds (C++ member), 199
 time_unix_time_to_date (C++ function), 198
 timer (module), 199
 timer_callback_t (C++ type), 200
 timer_init (C++ function), 200
 timer_module_init (C++ function), 200
 TIMER_PERIODIC (C macro), 199
 timer_start (C++ function), 200
 timer_start_isr (C++ function), 200
 timer_stop (C++ function), 200
 timer_stop_isr (C++ function), 200
 timer_t (C++ class), 201
 timer_t::arg_p (C++ member), 201
 timer_t::callback (C++ member), 201
 timer_t::delta (C++ member), 201
 timer_t::flags (C++ member), 201
 timer_t::next_p (C++ member), 201
 timer_t::timeout (C++ member), 201
 TOKENPASTE (C macro), 201
 TOKENPASTE2 (C macro), 201
 TXC0 (C macro), 454
 TXCIE0 (C macro), 454
 TXEN0 (C macro), 454
 types (module), 201

U

u16_t (C++ type), 202
 U2X0 (C macro), 454
 u32_t (C++ type), 202
 u8_t (C++ type), 202
 uart (module), 270
 uart_0_dev (C macro), 449, 451

uart_1_dev (C macro), 449, 451
uart_2_dev (C macro), 449, 451
uart_device (C++ member), 272
UART_DEVICE_MAX (C macro), 453–457
uart_device_read (C++ function), 272
uart_device_start (C++ function), 272
uart_device_stop (C++ function), 272
uart_device_write (C++ function), 272
uart_init (C++ function), 271
uart_module_init (C++ function), 271
uart_read (C macro), 270
uart_rx_filter_cb_t (C++ type), 271
uart_set_rx_filter_cb (C++ function), 271
uart_soft (module), 273
uart_soft_driver_t (C++ class), 273
uart_soft_driver_t::baudrate (C++ member), 274
uart_soft_driver_t::chin (C++ member), 274
uart_soft_driver_t::chout (C++ member), 274
uart_soft_driver_t::rx_exti (C++ member), 274
uart_soft_driver_t::rx_pin (C++ member), 274
uart_soft_driver_t::sample_time (C++ member), 274
uart_soft_driver_t::tx_pin (C++ member), 274
uart_soft_init (C++ function), 273
uart_soft_read (C macro), 273
uart_soft_write (C macro), 273
uart_start (C++ function), 271
uart_stop (C++ function), 271
uart_write (C macro), 270
UCSZ00 (C macro), 454
UCSZ01 (C macro), 454
UCSZ02 (C macro), 454
UDRE0 (C macro), 454
UDRIE0 (C macro), 454
UNIQUE (C macro), 201
UNUSED (C macro), 201
UPE0 (C macro), 454
upgrade (module), 376
upgrade_application_enter (C++ function), 379
upgrade_application_erase (C++ function), 379
upgrade_application_is_valid (C++ function), 379
upgrade_binary_upload (C++ function), 379
upgrade_binary_upload_begin (C++ function), 379
upgrade_binary_upload_end (C++ function), 380
upgrade_bootloader_enter (C++ function), 379
upgrade_bootloader_stay_clear (C++ function), 379
upgrade_bootloader_stay_get (C++ function), 379
upgrade_bootloader_stay_set (C++ function), 379
upgrade_module_init (C++ function), 379
UPM00 (C macro), 454
UPM01 (C macro), 454
USART0_RX_vect (C macro), 453, 454
USART0_TX_vect (C macro), 453, 454
USART0_UDRE_vect (C macro), 453, 454
usb (module), 274
USB_CDC_CONTROL_LINE_STATE (C macro), 275
USB_CDC_LINE_CODING (C macro), 275
usb_cdc_line_info_t (C++ class), 281
usb_cdc_line_info_t::char_format (C++ member), 281
usb_cdc_line_info_t::data_bits (C++ member), 281
usb_cdc_line_info_t::dte_rate (C++ member), 281
usb_cdc_line_info_t::parity_type (C++ member), 281
USB_CDC_SEND_BREAK (C macro), 275
USB_CLASS_APPLICATION_SPECIFIC (C macro), 275
USB_CLASS_AUDIO (C macro), 275
USB_CLASS_AUDIO_VIDEO_DEVICES (C macro), 275
USB_CLASS_BILLBOARD_DEVICE_CLASS (C macro), 275
USB_CLASS_CDC_CONTROL (C macro), 275
USB_CLASS_CDC_DATA (C macro), 275
USB_CLASS_CONTENT_SECURITY (C macro), 275
USB_CLASS_DIAGNOSTIC_DEVICE (C macro), 275
USB_CLASS_HID (C macro), 275
USB_CLASS_HID_PROTOCOL_KEYBOARD (C macro), 286
USB_CLASS_HID_PROTOCOL_MOUSE (C macro), 286
USB_CLASS_HID_PROTOCOL_NONE (C macro), 286
USB_CLASS_HID_SUBCLASS_BOOT_INTERFACE (C macro), 286
USB_CLASS_HID_SUBCLASS_NONE (C macro), 286
USB_CLASS_HUB (C macro), 275
USB_CLASS_IMAGE (C macro), 275
USB_CLASS_MASS_STORAGE (C macro), 275
USB_CLASS_MISCELLANEOUS (C macro), 275
USB_CLASS_PERSONAL_HEALTHCARE (C macro), 275
USB_CLASS_PHYSICAL (C macro), 275
USB_CLASS_PRINTER (C macro), 275
USB_CLASS_SMART_CARD (C macro), 275
USB_CLASS_USE_INTERFACE (C macro), 275
USB_CLASS_VENDOR_SPECIFIC (C macro), 275
USB_CLASS_VIDEO (C macro), 275
USB_CLASS_WIRELESS_CONTROLLER (C macro), 275
usb_desc_get_class (C++ function), 277
usb_desc_get_configuration (C++ function), 276
usb_desc_get_endpoint (C++ function), 276
usb_desc_get_interface (C++ function), 276
usb_descriptor_cdc_acm_t (C++ class), 280
usb_descriptor_cdc_acm_t::capabilities (C++ member), 280
usb_descriptor_cdc_acm_t::descriptor_type (C++ member), 280
usb_descriptor_cdc_acm_t::length (C++ member), 280
usb_descriptor_cdc_acm_t::sub_type (C++ member), 280
usb_descriptor_cdc_call_management_t (C++ class), 280

[usb_descriptor_cdc_call_management_t::capabilities](#)
(C++ member), 280

[usb_descriptor_cdc_call_management_t::data_interface](#)
(C++ member), 280

[usb_descriptor_cdc_call_management_t::descriptor_type](#)
(C++ member), 280

[usb_descriptor_cdc_call_management_t::length](#) (C++ member), 280

[usb_descriptor_cdc_call_management_t::sub_type](#) (C++ member), 280

[usb_descriptor_cdc_header_t](#) (C++ class), 280

[usb_descriptor_cdc_header_t::bcd](#) (C++ member), 280

[usb_descriptor_cdc_header_t::descriptor_type](#) (C++ member), 280

[usb_descriptor_cdc_header_t::length](#) (C++ member), 280

[usb_descriptor_cdc_header_t::sub_type](#) (C++ member), 280

[usb_descriptor_cdc_union_t](#) (C++ class), 280

[usb_descriptor_cdc_union_t::descriptor_type](#) (C++ member), 280

[usb_descriptor_cdc_union_t::length](#) (C++ member), 280

[usb_descriptor_cdc_union_t::master_interface](#) (C++ member), 280

[usb_descriptor_cdc_union_t::slave_interface](#) (C++ member), 280

[usb_descriptor_cdc_union_t::sub_type](#) (C++ member), 280

[usb_descriptor_configuration_t](#) (C++ class), 278

[usb_descriptor_configuration_t::configuration](#) (C++ member), 278

[usb_descriptor_configuration_t::configuration_attributes](#)
(C++ member), 278

[usb_descriptor_configuration_t::configuration_value](#)
(C++ member), 278

[usb_descriptor_configuration_t::descriptor_type](#) (C++ member), 278

[usb_descriptor_configuration_t::length](#) (C++ member), 278

[usb_descriptor_configuration_t::max_power](#) (C++ member), 279

[usb_descriptor_configuration_t::num_interfaces](#) (C++ member), 278

[usb_descriptor_configuration_t::total_length](#) (C++ member), 278

[usb_descriptor_device_t](#) (C++ class), 278

[usb_descriptor_device_t::bcd_device](#) (C++ member), 278

[usb_descriptor_device_t::bcd_usb](#) (C++ member), 278

[usb_descriptor_device_t::descriptor_type](#) (C++ member), 278

[usb_descriptor_device_t::device_class](#) (C++ member), 278

[usb_descriptor_device_t::device_protocol](#) (C++ member), 278

[usb_descriptor_device_t::device_subclass](#) (C++ member), 278

[usb_descriptor_device_t::id_product](#) (C++ member), 278

[usb_descriptor_device_t::id_vendor](#) (C++ member), 278

[usb_descriptor_device_t::length](#) (C++ member), 278

[usb_descriptor_device_t::manufacturer](#) (C++ member), 278

[usb_descriptor_device_t::max_packet_size_0](#) (C++ member), 278

[usb_descriptor_device_t::num_configurations](#) (C++ member), 278

[usb_descriptor_device_t::product](#) (C++ member), 278

[usb_descriptor_device_t::serial_number](#) (C++ member), 278

[usb_descriptor_endpoint_t](#) (C++ class), 279

[usb_descriptor_endpoint_t::attributes](#) (C++ member), 279

[usb_descriptor_endpoint_t::descriptor_type](#) (C++ member), 279

[usb_descriptor_endpoint_t::endpoint_address](#) (C++ member), 279

[usb_descriptor_endpoint_t::interval](#) (C++ member), 279

[usb_descriptor_endpoint_t::length](#) (C++ member), 279

[usb_descriptor_endpoint_t::max_packet_size](#) (C++ member), 279

[usb_descriptor_header_t](#) (C++ class), 278

[usb_descriptor_header_t::descriptor_type](#) (C++ member), 278

[usb_descriptor_header_t::length](#) (C++ member), 278

[usb_descriptor_interface_association_t](#) (C++ class), 279

[usb_descriptor_interface_association_t::descriptor_type](#)
(C++ member), 279

[usb_descriptor_interface_association_t::first_interface](#)
(C++ member), 279

[usb_descriptor_interface_association_t::function](#) (C++ member), 280

[usb_descriptor_interface_association_t::function_class](#)
(C++ member), 280

[usb_descriptor_interface_association_t::function_protocol](#)
(C++ member), 280

[usb_descriptor_interface_association_t::function_subclass](#)
(C++ member), 280

[usb_descriptor_interface_association_t::interface_count](#)
(C++ member), 279

[usb_descriptor_interface_association_t::length](#) (C++ member), 279

[usb_descriptor_interface_t](#) (C++ class), 279

[usb_descriptor_interface_t::alternate_setting](#) (C++ member), 279

[usb_descriptor_interface_t::descriptor_type](#) (C++ member), 279

[usb_descriptor_interface_t::interface](#) (C++ member), 279

[usb_descriptor_interface_t::interface_class](#) (C++ member), 279

[usb_descriptor_interface_t::interface_number](#) (C++ member), 279

- member), 279
- usb_descriptor_interface_t::interface_protocol (C++ member), 279
- usb_descriptor_interface_t::interface_subclass (C++ member), 279
- usb_descriptor_interface_t::length (C++ member), 279
- usb_descriptor_interface_t::num_endpoints (C++ member), 279
- usb_descriptor_string_t (C++ class), 279
- usb_descriptor_string_t::descriptor_type (C++ member), 279
- usb_descriptor_string_t::length (C++ member), 279
- usb_descriptor_string_t::string (C++ member), 279
- usb_descriptor_t (C++ type), 280
- usb_descriptor_t::configuration (C++ member), 281
- usb_descriptor_t::device (C++ member), 281
- usb_descriptor_t::endpoint (C++ member), 281
- usb_descriptor_t::header (C++ member), 281
- usb_descriptor_t::interface (C++ member), 281
- usb_descriptor_t::string (C++ member), 281
- usb_device (C++ member), 277
- usb_device (module), 282
- usb_device_class_cdc (module), 282
- usb_device_class_cdc_driver_t (C++ class), 283
- usb_device_class_cdc_driver_t::base (C++ member), 283
- usb_device_class_cdc_driver_t::chin (C++ member), 283
- usb_device_class_cdc_driver_t::chout (C++ member), 283
- usb_device_class_cdc_driver_t::control_interface (C++ member), 283
- usb_device_class_cdc_driver_t::drv_p (C++ member), 283
- usb_device_class_cdc_driver_t::endpoint_in (C++ member), 283
- usb_device_class_cdc_driver_t::endpoint_out (C++ member), 283
- usb_device_class_cdc_driver_t::line_info (C++ member), 283
- usb_device_class_cdc_driver_t::line_state (C++ member), 283
- usb_device_class_cdc_init (C++ function), 283
- usb_device_class_cdc_input_isr (C++ function), 283
- usb_device_class_cdc_is_connected (C++ function), 283
- usb_device_class_cdc_module_init (C++ function), 283
- usb_device_class_cdc_read (C macro), 282
- usb_device_class_cdc_write (C macro), 282
- USB_DEVICE_MAX (C macro), 454
- usb_device_module_init (C++ function), 284
- usb_device_read_isr (C++ function), 285
- usb_device_start (C++ function), 284
- usb_device_stop (C++ function), 284
- usb_device_write (C++ function), 284
- usb_device_write_isr (C++ function), 285
- usb_format_descriptors (C++ function), 276
- usb_host (module), 285
- usb_host_class_hid (module), 285
- usb_host_class_hid_device_t (C++ class), 286
- usb_host_class_hid_device_t::buf (C++ member), 286
- usb_host_class_hid_driver_t (C++ class), 286
- usb_host_class_hid_driver_t::device_driver (C++ member), 287
- usb_host_class_hid_driver_t::devices_p (C++ member), 287
- usb_host_class_hid_driver_t::length (C++ member), 287
- usb_host_class_hid_driver_t::size (C++ member), 287
- usb_host_class_hid_driver_t::usb_p (C++ member), 287
- usb_host_class_hid_init (C++ function), 286
- usb_host_class_hid_start (C++ function), 286
- usb_host_class_hid_stop (C++ function), 286
- usb_host_class_mass_storage (module), 287
- usb_host_class_mass_storage_device_read (C++ function), 287
- usb_host_class_mass_storage_device_t (C++ class), 287
- usb_host_class_mass_storage_device_t::buf (C++ member), 287
- usb_host_class_mass_storage_driver_t (C++ class), 287
- usb_host_class_mass_storage_driver_t::device_driver (C++ member), 288
- usb_host_class_mass_storage_driver_t::devices_p (C++ member), 288
- usb_host_class_mass_storage_driver_t::length (C++ member), 288
- usb_host_class_mass_storage_driver_t::size (C++ member), 288
- usb_host_class_mass_storage_driver_t::usb_p (C++ member), 288
- usb_host_class_mass_storage_init (C++ function), 287
- usb_host_class_mass_storage_start (C++ function), 287
- usb_host_class_mass_storage_stop (C++ function), 287
- usb_host_device_close (C++ function), 289
- usb_host_device_control_transfer (C++ function), 290
- usb_host_device_driver_t (C++ class), 291
- usb_host_device_driver_t::enumerate (C++ member), 291
- usb_host_device_driver_t::next_p (C++ member), 291
- usb_host_device_driver_t::supports (C++ member), 291
- usb_host_device_open (C++ function), 289
- usb_host_device_read (C++ function), 290
- usb_host_device_set_configuration (C++ function), 290
- USB_HOST_DEVICE_STATE_ATTACHED (C macro), 288
- USB_HOST_DEVICE_STATE_NONE (C macro), 288
- usb_host_device_t (C++ class), 291
- usb_host_device_t::address (C++ member), 291
- usb_host_device_t::buf (C++ member), 291
- usb_host_device_t::conf_p (C++ member), 291
- usb_host_device_t::configuration (C++ member), 291
- usb_host_device_t::description_p (C++ member), 291

[usb_host_device_t::dev_p \(C++ member\), 291](#)
[usb_host_device_t::id \(C++ member\), 291](#)
[usb_host_device_t::max_packet_size \(C++ member\), 291](#)
[usb_host_device_t::pid \(C++ member\), 291](#)
[usb_host_device_t::pipes \(C++ member\), 291](#)
[usb_host_device_t::self_p \(C++ member\), 291](#)
[usb_host_device_t::size \(C++ member\), 291](#)
[usb_host_device_t::state \(C++ member\), 291](#)
[usb_host_device_t::vid \(C++ member\), 291](#)
[usb_host_device_write \(C++ function\), 290](#)
[usb_host_driver_add \(C++ function\), 289](#)
[usb_host_driver_remove \(C++ function\), 289](#)
[usb_host_init \(C++ function\), 288](#)
[usb_host_module_init \(C++ function\), 288](#)
[usb_host_start \(C++ function\), 288](#)
[usb_host_stop \(C++ function\), 289](#)
[usb_message_add_t \(C++ class\), 281](#)
[usb_message_add_t::device \(C++ member\), 281](#)
[usb_message_add_t::header \(C++ member\), 281](#)
[usb_message_header_t \(C++ class\), 281](#)
[usb_message_header_t::type \(C++ member\), 281](#)
[usb_message_t \(C++ type\), 281](#)
[usb_message_t::add \(C++ member\), 281](#)
[usb_message_t::header \(C++ member\), 281](#)
[USB_MESSAGE_TYPE_ADD \(C macro\), 276](#)
[USB_MESSAGE_TYPE_REMOVE \(C macro\), 276](#)
[USB_PIPE_TYPE_BULK \(C macro\), 288](#)
[USB_PIPE_TYPE_CONTROL \(C macro\), 288](#)
[USB_PIPE_TYPE_INTERRUPT \(C macro\), 288](#)
[USB_PIPE_TYPE_ISOCHRONOUS \(C macro\), 288](#)
[usb_setup_t \(C++ class\), 277](#)
[usb_setup_t::configuration_value \(C++ member\), 277](#)
[usb_setup_t::descriptor_index \(C++ member\), 277](#)
[usb_setup_t::descriptor_type \(C++ member\), 277](#)
[usb_setup_t::device_address \(C++ member\), 277](#)
[usb_setup_t::feature_selector \(C++ member\), 277](#)
[usb_setup_t::index \(C++ member\), 277](#)
[usb_setup_t::language_id \(C++ member\), 277](#)
[usb_setup_t::length \(C++ member\), 278](#)
[usb_setup_t::request \(C++ member\), 277](#)
[usb_setup_t::request_type \(C++ member\), 277](#)
[usb_setup_t::value \(C++ member\), 277](#)
[usb_setup_t::zero \(C++ member\), 277](#)
[usb_setup_t::zero0 \(C++ member\), 277](#)
[usb_setup_t::zero1 \(C++ member\), 277](#)
[usb_setup_t::zero_interface_endpoint \(C++ member\), 277](#)
[USBS0 \(C macro\), 454](#)

V

[VERSION_STR \(C macro\), 186](#)

W

[watchdog \(module\), 291](#)